



JIBEBE:ELECTRIC VEHICLE PROJECT

Supervisors : Dr Shohei Aoki
Mr Kipkorir Rono
Mr Joseph Kimani

Mechanical Team

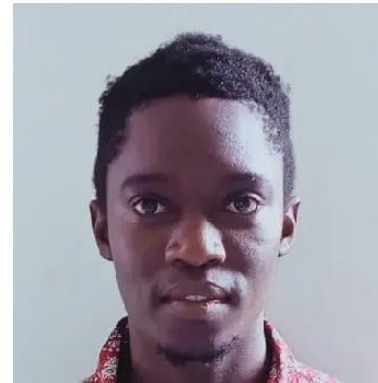
Alex Mburu



Emmanuel Njenga



Brian Muindi



Peter Nzioki



HUMAN POWERED TRICYCLE



Specifications

- ❖ Human powered tricycle
- ❖ Rubber brake shoes-operated by a brake lever

Limitations

- ☐ Tedious
- ☐ Ineffective brake system

Main Objective

Design fabrication and testing of an **electric tricycle**

Specific objectives

- i. Determine the **power requirements** for the **e-tricycle**
- ii. Design and fabricate the **drive train**
- iii. Implement **mechanical disc brakes**

- Power requirements-max speed of **16km/h-1200W**-BLDC Motor
- Drive train

Design of rear axle

At 600rpm for the 1200W , $T_{max}=19.10\text{Nm}$

Using the maximum shear stress theory
(Guest's theory)

$$\sqrt{M^2 + T^2} = \frac{\pi}{16} \times \tau_{max} \times d^3$$

Diameter= 15.62mm



Chain drive design

□ Design for the sprockets

Speed ratio=**3.5**

The larger sprocket=**47T**

Smaller sprocket = **15T**



□ Design for the chain

D=180mm

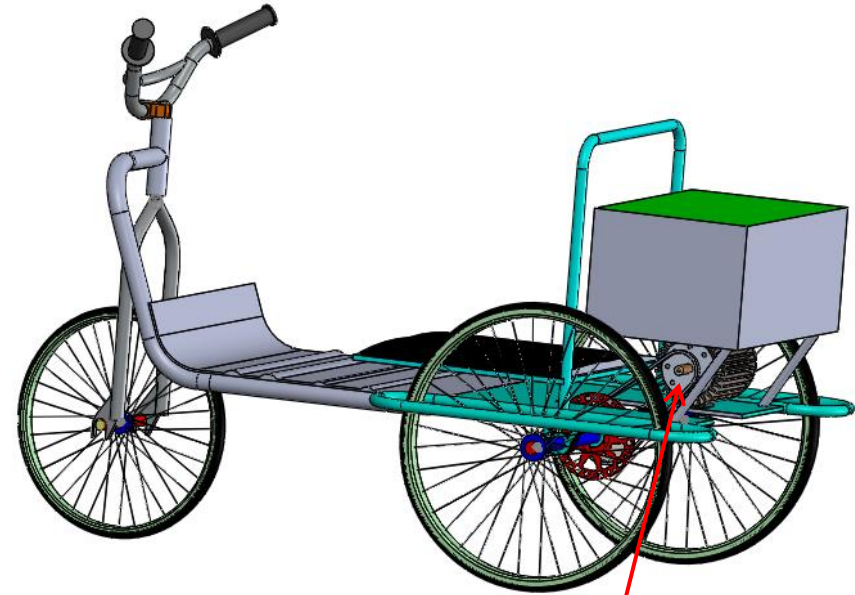
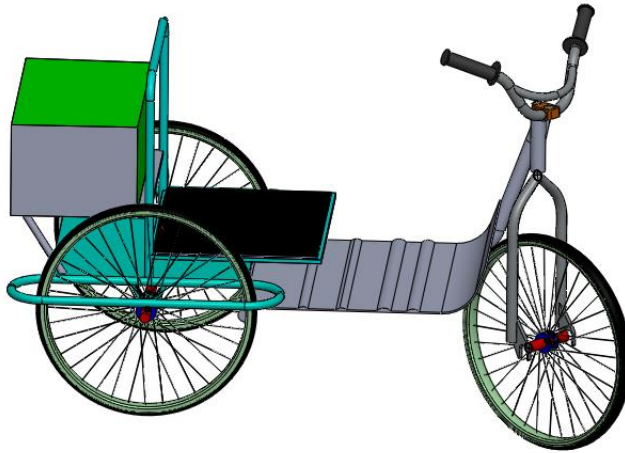
d=70mm

Center distance , $x = 170\text{mm}$

Chain length= $\pi(R + r) + 2x + \left(\frac{R-r}{x}\right)^2$

L=760mm





Parts redesigned

- Steering
- Braking mechanism
- Rear wheels
- Motor positioning

Motor

Fabrication and assembly of components

1. Steering-handle bars –
easy steering and other attachments i.e
throttle, brake shifters

Brake shifters



2. Braking mechanism

Mechanical brakes-both front and rear



Front Brake
rotor

Brake calipers



Rear Brake
rotor

Drive train



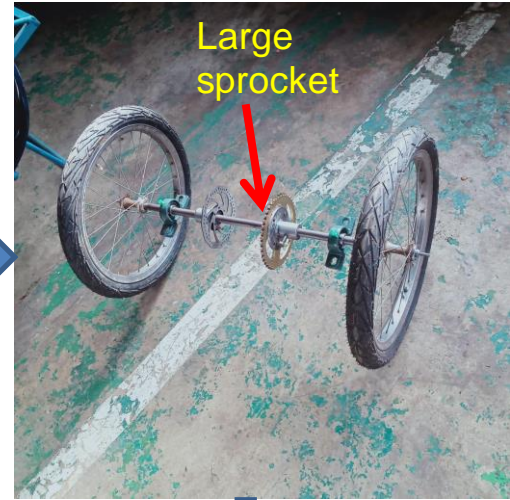
BLDC motor



Attachment on the motor



Chain



Large sprocket



Chain

Sprocket

Assembly and testing of the e-tricycle

Recommendations

1. Implement a suspension system for better ride comfort
2. Centre alignment of the handle bars to improve steering and better handling

Main Objective

Design fabrication and testing of an **electric tractor**

Specific objectives

- i. Determine the **power requirements** for the **e-shujaa tractor**
- ii. Stress and vibrational analysis of the e-tractor chassis
- iii. Redesign the transmission system
- iv. Assembly and testing of the e-tractor

POWER REQUIREMENTS FOR THE SHUJAA E-TRACTOR

Case 1: Working mode

Power required when the tractor is **accelerating**(0-11km/h) and **ploughing**= 6.7923 kw

Case 2: Transport mode

Power required when the tractor is **accelerating**(0-30km/h) but **NOT** ploughing= 6.855kW



15kW motor

TORQUE REQUIREMENTS FOR THE SHUJAA E-TRACTOR

Case 1: Working mode

Working speed=11km/h

Torque from motor=27.28Nm

Torque required at the driving wheels=1800Nm

Gear ratio=47.98

Case 2: Transport mode

Working speed=30km/h

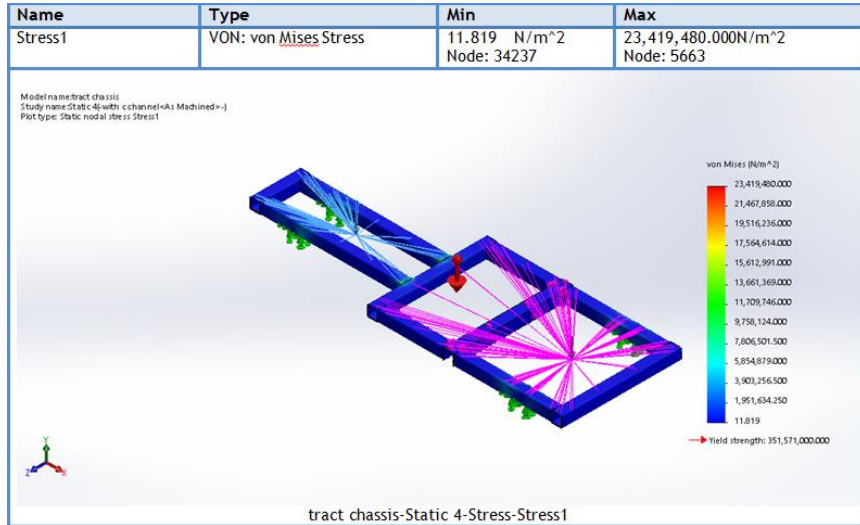
Torque from motor=27.28Nm

Torque required at the driving wheels=479.98Nm

Gear ratio=17.59

Static and vibration analysis of the tractor chassis

Static analysis



FOS=15

Frequency analysis

| Freq No | Rad/sec | Hertz |
|---------|---------|--------|
| 1 | 2986.7 | 475.34 |
| 2 | 5540.9 | 881.86 |
| 3 | 11383 | 1811.7 |
| 4 | 13137 | 2090.9 |
| 5 | 13327 | 2121.1 |

For a top speed of **3500rpm**
Operating frequency of the motor is **58.33Hz**
(**366.52rad/s**)

Thank you

