电力电子公式一览

Fourier Transform

$$f(x) = rac{a_0}{2} + \sum_{n=1}^{\infty} \left[a_n \cos(nx) + b_n \sin(nx)
ight]
onumber \ a_n = rac{2}{T} \int f(t) \cos \omega t \ dt
onumber \ b_n = rac{2}{T} \int f(t) \sin \omega t \ dt$$

DCDC

BUCK

电压变比

$$M = D \tag{1}$$

临界电流

$$I_{OB} = \frac{V_o}{2fL}(1 - D) \tag{2}$$

DCM电压变比

$$M = rac{2}{1 + \sqrt{1 + rac{4I_o^*}{D^2}}} \ I_O^* = rac{I_O}{V_O/2fL}$$
 (3)

BOOST

电压变比

$$M = \frac{1}{1 - D} \tag{4}$$

临界电流

$$I_{OB} = \frac{V_o}{2fL} (1 - D)^2 D \tag{5}$$

DCM电压变比

$$M = \frac{1 + \sqrt{1 + \frac{4D^2}{I_o^*}}}{2} \tag{6}$$

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$$I_O^* = \frac{I_O}{V_o/2fL}$$

Cuk/Buck-Boost

电压变比

$$M = \frac{D}{1 - D} \tag{7}$$

临界电流

$$I_{OB} = \frac{V_o}{2fL} (1 - D)^2 \tag{8}$$

DCM电压变比

$$M = \frac{D}{\sqrt{I_O^*}}$$

$$I_O^* = \frac{I_O}{V_O/2fL}$$
(9)

DCAC

上下方波的傅里叶变换

$$v(t) = \sum_{n=1,3,5}^{\infty} \frac{4V_D}{n\pi} sin(nwt)$$
有效值 $V_1 = 0.9V_D$
接Z阻抗 $(R + wLj)$

$$i_{a1} = \frac{4V_D}{\pi\sqrt{R^2 + (wL)^2}} sin\left(wt - \arctan\left(\frac{wL}{R}\right)\right)$$
(10)

单脉波脉冲宽度调制

$$v_{ab}(wt) = \sum_{n=1,3,4}^{\infty} -(-1)^{(n+2)/2} \frac{4V_D}{n\pi} \sin\frac{n\theta}{2} \sin nwt$$
 (11)

逆变器的性能指标

谐波系数
$$HF_n=rac{V_n}{V_1}$$

总谐波系数 $THD=\sqrt{\sum_{n=1,2,3}^{\infty}(rac{V_n}{V_1})^2-1}$
畸变系数
$$-$$
阶滤波 $DF_1=\sqrt{\sum_{n=2,3,4}^{\infty}(rac{V_n}{nV_1})^2}$
二阶滤波 $DF_2=\sqrt{\sum_{n=2,3,4}^{\infty}(rac{V_n}{nV_1})^2}$

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数据

BSPWM: 0.707VD

方波: 0.9VD

三相SPWM相电压幅值: 0.5

三相SPWM线电压幅值: 0.866

三相方波相电压幅值: 1.1

ACDC公式

不控整流

1. 输出电压:

1. 双半波: $\frac{2\sqrt{2}}{\pi}$ 2. 单相桥 $\frac{2\sqrt{2}}{\pi}$ 3. 三相半桥 $\frac{3\sqrt{6}}{2\pi}$ 4. 三相桥式 $\frac{3\sqrt{6}}{\pi}$

单相相控整流电压

平均值

$$\frac{2\sqrt{2}}{\pi}V_s \frac{1+\cos\alpha}{2} \tag{13}$$

功率因数

$$PF = \sqrt{\frac{\sin 2\alpha}{2\pi} + \frac{\pi - \alpha}{\pi}} \tag{14}$$

电阻负载的电压有效值

$$V_s * PF \tag{15}$$

电阻负载的电流有效值

$$\frac{V_s}{R}PF\tag{16}$$

晶闸管的电流有效值

$$\frac{V_s}{2R}PF\tag{17}$$

三相相控整流电压

平均值

$$\frac{3\sqrt{6}}{\pi}V_s\cos\alpha\tag{18}$$

单相整流器导通角求取(有阻感性负载) ($\alpha>\phi$)

$$\tan\left(\alpha - \phi\right) = \frac{\sin\theta}{e^{-\frac{\theta}{\tan\theta}} - \cos\theta} \tag{19}$$

在有反电动势存在时单相相控整流器停止导电角

$$\sin \delta = \frac{E}{\sqrt{2}V_s} \tag{20}$$

单相桥相控整流时电流连续条件

$$L \ge \frac{\frac{2\sqrt{2}}{\pi}V_s}{wI_D} \tag{21}$$

换相整流区

m脉波整流电路

单相桥式m=2,核心在Vs=2Vs

两相半波m=2

三相半波m=3

三相全桥m=6

换相电阻

$$R = \frac{mwL}{2\pi} \tag{22}$$

换相重叠区角度

$$\cos \alpha - \cos (\alpha + \gamma) = \frac{wL_sI_D}{\sqrt{2}V_s \sin \frac{\pi}{m}}$$
 (23)

有源逆变输出电压

$$\frac{3\sqrt{6}}{\pi}V_s\cos\beta - \frac{3wL_s}{2\pi}I_D * 2\tag{24}$$

电力电子公式推导

DCAC

上下方波的傅里叶变换

$$f(t) = \sum_{n=1,3,5}^{\infty} a_n \sin wt$$

$$a_n = \frac{2}{\pi} \int_0^{\pi} V_D \sin nwt \ d(wt)$$

$$a_n = \frac{4}{n\pi} V_D$$
(25)

三相方波的傅里叶变换

$$v_{ab}(t) = \sum_{n=1,3,5}^{\infty} a_n \sin wt$$

$$a_n = \frac{2}{\pi} \int_{\pi/6}^{5\pi/6} V_D \sin nwt \ d(wt)$$

$$a_n = \frac{2\sqrt{3}}{n\pi}$$

$$(26)$$

ACDC

不控整流平均输出电压计算

单相

$$V_o = \frac{1}{\pi} \int_0^{\pi} \sqrt{2} V_s \sin wt \ d(wt) = \frac{2\sqrt{2}}{\pi} V_s \tag{27}$$

三相

$$V_o = \frac{1}{\pi/3} \int_{\pi/3}^{2\pi/3} \sqrt{3} * \sqrt{2} V_s \sin wt \ d(wt) = \frac{3\sqrt{6}}{\pi} V_s$$
 (28)

相控整流平均电压计算

单相

$$V_o = rac{1}{\pi} \int_{lpha}^{\pi} \sqrt{2} V_s \sin wt \ d(wt) = rac{2\sqrt{2}}{\pi} V_s rac{1 + \cos lpha}{2}$$
 (29)

三相

$$V_o = rac{1}{\pi/3} \int_{\pi/3+lpha}^{2\pi/3+lpha} \sqrt{3} * \sqrt{2} V_s \sin wt \ d(wt) = rac{3\sqrt{6}}{\pi} V_s \cos lpha (lpha < 60^o)$$
 (30)

单相相控整流电压电阻负载的电压有效值计算

$$V_{rms} = \sqrt{rac{1}{\pi} \int_{lpha}^{\pi} [\sqrt{2}V_s \sin wt]^2 d(wt)} = V_s \sqrt{rac{\sin 2lpha}{2\pi} + rac{\pi - lpha}{\pi}}$$
 (31)

单相相控整流电压电阻负载的功率因数计算

$$PF = \frac{P_{in}}{S_{in}} = \frac{P_{out}}{S_{in}} = \frac{V_{orms}^{2}/R}{V_{irms}I_{irms}} = \frac{V_{orms}^{2}/R}{V_{s}V_{orms}/R} = \sqrt{\frac{\sin 2\alpha}{2\pi} + \frac{\pi - \alpha}{\pi}}$$
(32)

单相整流器导通角求取(有阻感性负载) $(\alpha > \phi)$

原理

$$\sqrt{2}V_s\sin wt = Lrac{di_D}{dt} + Ri_D$$

$$when wt = \alpha, i_D = 0$$

$$when wt = \alpha + \theta, i_D = 0$$
(33)

求解此方程组可得形式 (齐次解+非齐次解)

.
$$\sqrt{2}V_s\sin\left(wt-\phi
ight)$$
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$$i_D = \frac{1}{Z} + Ae^{-L^2}$$
 (34)

进而可以解得 A, θ

$$\tan\left(\alpha - \phi\right) = \frac{\sin\theta}{e^{-\frac{\theta}{\tan\theta}} - \cos\theta} \tag{35}$$

在有反电动势存在时单相相控整流器停止导电角

易于理解, 画一条线

$$\sin \delta = \frac{E}{\sqrt{2}V_s} \tag{36}$$

单相桥相控整流时电流连续条件

书上官方

取alpha处为时间坐标原点, 在临界连续时有

$$i_D(wt = \pi) = 0 \tag{37}$$

而iD的计算为

$$L\frac{di_D}{dt} + Ri_D = \sqrt{2}V_s \sin(wt + \alpha) - E$$

$$i_D(wt = \pi) = 0$$

$$i_D(wt = 0) = 0$$

$$Ri_D + E = \frac{2\sqrt{2}}{\pi}V_s \cos\alpha$$
(38)

故可解得临界连续时的电流为

$$i_D(t) = \frac{\sqrt{2}V_s}{wL}(\cos\alpha - \cos(wt + \alpha) - \frac{2}{\pi}\cos\alpha * wt)$$
(39)

电流平均值为

$$I_{Dmin} = \int_0^{\pi} i_D(wt)dwt = \frac{2\sqrt{2}}{\pi} V_S \frac{1}{wL} \sin \alpha \tag{40}$$

为使得什么时候都连续,取临界值 $lpha=\pi/2$

则

$$I_{Dmin} = \frac{2\sqrt{2}}{\pi} V_S \frac{1}{wL} \tag{41}$$

直接看 $lpha=\pi/2$

此时输出电压为0

$$L\frac{di_D}{dt} = \sqrt{2}V_s\cos\left(wt\right) \tag{42}$$

则

$$i_D = \frac{\sqrt{2}V_s \sin wt}{wL} \tag{43}$$

平均临界电流为

$$I_D = \frac{2\sqrt{2}}{\pi} \frac{V_s}{wL} \tag{44}$$

换相整流区

注意m为脉波数

原理

$$v_{1} = \sqrt{2}V_{s}\cos\left(wt - \pi/m\right)$$

$$v_{2} = \sqrt{2}V_{s}\cos\left(wt + \pi/m\right)$$

$$v_{D} = \frac{1}{2}(v_{1} + v_{2})$$

$$\Delta V_{S} = \frac{1}{2\pi/m} \int_{\alpha}^{\alpha+\gamma} \frac{1}{2}(v_{b} - v_{a})d(wt) = \frac{m}{\pi}\sqrt{2}V_{s}\sin\frac{\pi}{m}\frac{\cos\alpha - \cos(\alpha + \gamma)}{2}$$

$$I_{D} = \int_{\alpha}^{\alpha+\gamma} \frac{1}{wL_{s}} \frac{1}{2}(v_{b} - v_{a})dwt = \frac{1}{wL_{s}} 2\sqrt{2}V_{s}\sin\frac{\pi}{m}\frac{\cos\alpha - \cos(\alpha + \gamma)}{2}$$

$$(45)$$

则

$$R_{s} = \frac{\Delta V_{S}}{I_{D}} = \frac{mwL_{s}}{2\pi}$$

$$\cos \alpha - \cos (\alpha + \gamma) = \frac{wL_{s}I_{D}}{\sqrt{2}V_{s}\sin \frac{\pi}{m}}$$
(46)