1. (a)
$$A(t+1) = \int_{A} A(t)' + K_{A}' A(t)$$

= $\chi A(t)' + A(t) B(t)'$

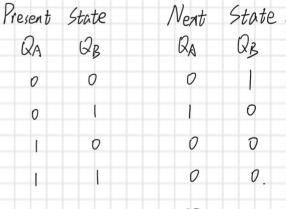
$$B(t+1) = J_B B(t)' + K_B' B(t)$$

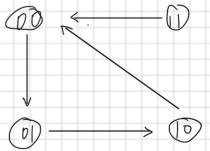
= $x B(t)' + A(t) B(t)$

| ıЬ) | Present | stote | Input | Next | State |
|-----|---------|-------|-------|---------|-------|
| | Qa | QB | 7 | Q_{A} | QB. |
| | 0 | 0 | О | 0 | J |
| | 0 | 0 | 1 | 1 | 1 |
| | 0 | | 0 | 0 | ن |
| | 0 | r | | 1 | D |
| | 1 | O | o | 1 | 0 |
| | t . | O | ſ | 1 | 1 |
| | 1 | 1 | J | 0 | ı |
| | 1 | ı | | O | |

$$\begin{array}{c} 0 \\ S_{3} \\ \hline 0 \\ \hline \end{array} \begin{array}{c} 1 \\ \hline 0 \\ \hline \end{array} \begin{array}{c} S_{1} \\ \hline 0 \\ \hline \end{array}$$

2.
$$T_A = A + B$$
 $T_B = A' + B$.
 $A(t+1) = T_A + B A$
 $= (A+B) + B A$
 $= (A+B) + A + (A+B) + A'$
 $= A'B$



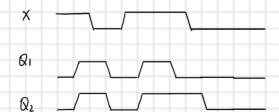


It's a Moore model performs a running LEDs

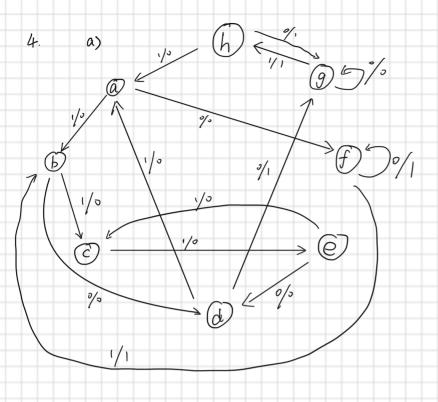
3. (a)
$$J_1 = X$$
 $K_1 = (X Q_2')'$
 $J_2 = X$ $K_2 = (X Q_1)'$
 $F = X \oplus Q_2'$
 $Q_1(t+1) = J_1 Q_1(t) + K_1 Q_1(t)$
 $= X Q_1'(t) + X Q_2(t) Q_1(t)$
 $Q_2(t+1) = J_2 Q_2'(t) + K_2 Q_2(t)$
 $= X Q_2'(t) + X Q_1(t) Q_2(t)$.

| Present | State | Input | Neat | State. | Output |
|-------------------|----------------|-------|------|--------|--------|
| \mathcal{Q}_{l} | Q ₂ | X | Q, | Q2 | F |
| 0 | 0 | 0 | O | O | 1 |
| 0 | 0 | | | L | 0 |
| 0 | 1 | 0 | 0 | J | 0 |
| 0 | [| | | 0 | |
| 1 | 0 | 0 | 0 | D | |
| 1 | 0 | | 1 | | D |
| - 1 | ı | O | 0 | 0 | D |
| 1 | ſ | 1 | 0 | | 1 |
| | 1/2 | | | | |
| 0 |) | →`(i) | | | |

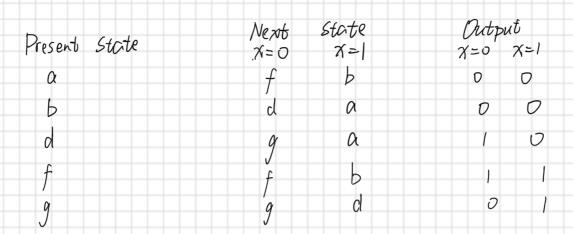
- b) Mealy machine because the output depends on current state and state.
- c) CLK

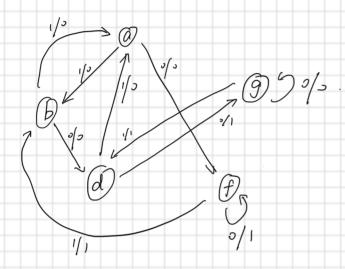


F



| b) | Present State | Next | State | Output | | | |
|----------|---------------|-------------|--------------|-----------|--------------|--|--|
| 1st | | χ=0 | x=1 | χ=0 | x=1 | | |
| | а | f | Ь | D | 0 | | |
| | рЪ | d | С | 0 | 0) | | |
| b==0 | C | f | еЬ | 0 | 0 | | |
| | 7 d | g | а | 1 | O | | |
| | <u></u> | d | С | O | 0) | | |
| d = = h | f | f | Ь | 1 | 1 | | |
| | 9 | 9 | kd | 0 | | | |
| | h | g | α | | 0 | | |
| 200 | Present State | Next X=0 | state x=1 | Ωι χ=0 | tiput X=1 | | |
| | pla | f | Ь | D | D | | |
| () = = C | (b | d | 80 | 0 | D | | |
| | C | f | Ь | 0 | O | | |
| | d | g | ۵ | | 0 | | |
| | f | f | b | | 1 1 | | |
| | g | 9 | d | 1 | o I | | |





c) original state table

| t's | 0 Q | f | 2 D | 3 d | 4 Q | f | bf | 7 b | d 8 | 9 01 | 13 15 | ۵۱۱ |
|-----|--------|---|--------|--------|--------|---|----|--------|--------|---------|----------|-----|
| | | 1 | | | | | | | 1 | 1 | 1 | |
| у | 0 | 1 | 0 | 0 | ס | | | 0 | D | υ | 0 | ļ |

y=01000110000

reduced state table

| t' | Đ | ١ | 2 | 3 | 4 | 5 | Ь | 7 | 8 | 9 | ات | 1 |
|----|---|---|---|---|---|---|---|---|----|---|----|---|
| 3 | a | f | Ь | d | α | f | b | Ь | cl | ۵ | b | Δ |
| X | 0 | ĺ | 0 | ı | 0 | 0 | 1 | 0 | 1 | 1 | 1 | |
| y | 0 | | O | D | 0 | | | 0 | 0' | 0 | O, | |

y= 0/000 110000

5. W

R=0 H=0: Q=0 P=1 Reset output R=0 H=1: $Q_{prev}=0$ $Q_{prev}=1$ Q=0 Q=1 Q=0 Q=0 Q=0 Q=0

Q = aprev Memory

R = 1 H = 0 : Q = 1 P = 1 Invalid R = 1 H = 1 : Q = 1 P = 0 Set output

S R Q P/Q'
0 0 0 | Reset state
0 | last R last P/Q' no charge
1 0 | l for bidden
1 | l 0 Set state

go back to (0,1)

b) 5

R

Q

P