CS217 - Data Structures & Algorithm Analysis (DSAA)

Lecture #5



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Reading: Chapter 7

Aims of this lecture

- To introduce the **QuickSort** algorithm: a popular algorithm which is fast in practice, despite a $\Theta(n^2)$ worst case time.
- To show an average-case analysis, revealing why QuickSort is fast in practice.
- To see another example of divide-and-conquer.

Idea behind QuickSort

Divide:

- Pick some element called pivot.
- Move it to its final location in the sorted sequence such that all smaller elements are to its left, larger ones are to its right.

• Conquer:

Recursively sort subarrays for smaller and larger elements

• Combine:

No work needed here – after the recursion the array is sorted.

QuickSort: The Algorithm

```
QuickSort(A, p, r)

1: if p < r then

2: q = \text{Partition}(A, p, r)

3: QuickSort(A, p, q - 1)

4: QuickSort(A, q + 1, r)
```

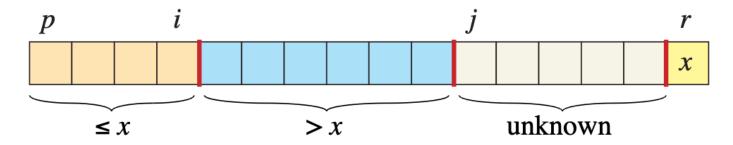
Initial call: QUICKSORT(A, 1, A.length)

Differences to MergeSort:

- Split the array at q, the position of the pivot in sorted array
 - We don't know q in advance, it is revealed by Partition
- No combine step at the end
- Partition plays a similar role to Merge

\triangleright Partition(A, p, r)

- Rearranges the subarray A[p..r] in place, using swaps
- Takes the last element A[r] as pivot element.
- Idea:
 - Scan the subarray from left to right
 - Build up a subarray $A[p \mathinner{\ldotp\ldotp} i]$ of elements smaller or equal to the pivot
 - Build up a subarray A[i+1...j-1] of elements larger than the pivot
 - When reaching the end of the array, put the pivot in the right place



Partition: Pseudocode

$\overline{\mathrm{PARTITION}}(A,p,r)$

```
1: x = A[r]
```

2:
$$i = p - 1$$

3: **for**
$$j = p$$
 to $r - 1$ **do**

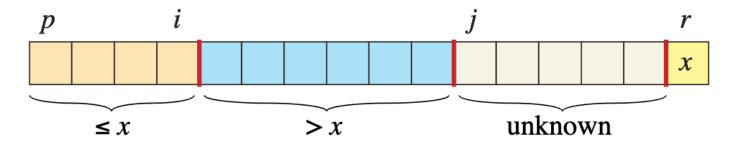
4: if
$$A[j] \leq x$$
 then

5:
$$i = i + 1$$

6: exchange
$$A[i]$$
 with $A[j]$

7: exchange
$$A[i+1]$$
 with $A[r]$

8: **return**
$$i+1$$

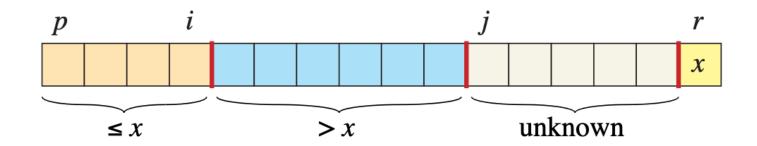


Partition: Example

Partition(A, p, r)

- 1: x = A[r]
- 2: i = p 1
- 3: **for** j = p to r 1 **do**
- 4: **if** $A[j] \leq x$ **then**
- 5: i = i + 1
- 6: exchange A[i] with A[j]
- 7: exchange A[i+1] with A[r]
- 8: return i+1

Partition: Correctness (1)



Partition(A, p, r)

1:
$$x = A[r]$$

2:
$$i = p - 1$$

3: **for**
$$j = p$$
 to $r - 1$ **do**

4: if
$$A[j] \leq x$$
 then

5:
$$i = i + 1$$

6: exchange
$$A[i]$$
 with $A[j]$

7: exchange
$$A[i+1]$$
 with $A[r]$

8: return
$$i+1$$

Loop invariant:

At the beginning of the j_th iteration:

$$A[p]..A[i] \le x$$
and
$$A[i+1]..A[j-1] > x.$$

- See picture above –

> Partition: Initialisation

Partition(A, p, r)

1:
$$x = A[r]$$

2:
$$i = p - 1$$

3: **for**
$$j = p$$
 to $r - 1$ **do**

4: if
$$A[j] \leq x$$
 then

5:
$$i = i + 1$$

6: exchange
$$A[i]$$
 with $A[j]$

7: exchange
$$A[i+1]$$
 with $A[r]$

8: return
$$i+1$$

Loop invariant:

See picture above –

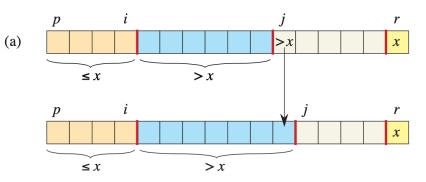
$$A[p]..A[i] \le x$$
 and
$$A[i+1]..A[j-1] > x.$$

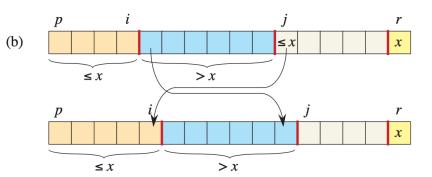
Trivially true at initialisation. (both sets are empty)

> Partition: Maintaining the loop invariant

Partition(A, p, r)

- 1: x = A[r]
- 2: i = p 1
- 3: **for** j = p to r 1 **do**
- 4: **if** $A[j] \leq x$ **then**
- 5: i = i + 1
- 6: exchange A[i] with A[j]
- 7: exchange A[i+1] with A[r]
- 8: **return** i+1





Maintenance:

- If line 4 is false: picture (a)
- If line 4 true: picture (b)
- In both cases after one iteration of *j* the loop invariant is maintained.

Loop invariant:

$$A[p]..A[i] \le x$$
 and
$$A[i+1]..A[j-1] > x.$$

Partition: termination

Partition(A, p, r)

1:
$$x = A[r]$$

2:
$$i = p - 1$$

3: **for**
$$j = p$$
 to $r - 1$ **do**

4: if
$$A[j] \leq x$$
 then

5:
$$i = i + 1$$

6: exchange
$$A[i]$$
 with $A[j]$

7: exchange A[i+1] with A[r]

8: **return** i+1

Loop invariant:

Termination:

After the last swap in line 7, $A[p]..A[i] \le x < A[i+2]..A[r]$ and Partition returns the position of x.

$$A[p]..A[i] \le x$$
 and
$$A[i+1]..A[j-1] > x.$$

Exercise: Analyse the Runtime of Partition

Q: What is the runtime of Partition on a subarray of size n?

Partition(A, p, r)

1:
$$x = A[r]$$

2:
$$i = p - 1$$

3: **for**
$$j = p$$
 to $r - 1$ **do**

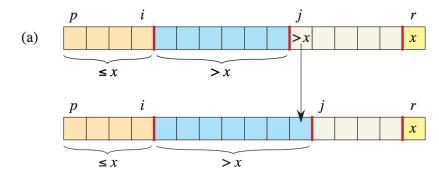
4: **if**
$$A[j] \leq x$$
 then

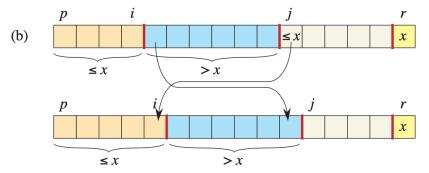
5:
$$i = i + 1$$

6: exchange
$$A[i]$$
 with $A[j]$

7: exchange
$$A[i+1]$$
 with $A[r]$

8: return
$$i+1$$





QuickSort: The Algorithm

QUICKSORT
$$(A, p, r)$$

p,i j

1: if
$$p < r$$
 then

2:
$$q = PARTITION(A, p, r)$$

$$p,i$$
 j r

3: QuickSort
$$(A, p, q - 1)$$

QUICKSORT(A, q + 1, r)4:

Partition(A, p, r)

$$1: x = A[r]$$

(i)

(c)

2:
$$i = p - 1$$

3: for
$$j = p$$
 to $r - 1$ do
4: if $A[j] \le x$ then

5:
$$i = i + 1$$

6: exchange
$$A[i]$$
 with $A[j]$
7: exchange $A[i+1]$ with $A[r]$

8: return
$$i+1$$

Worst-case and Best-case Partitionings

- The overall runtime depends on how the array is partitioned as that determines the sizes q-1 and r-q of the subarray to be sorted recursively.
 - Recall that we don't know in advance where the pivot will end up.

Questions:

- What might be a worst-case partitioning for the runtime?
- What might be a best-case partitioning for the runtime?

```
QuickSort(A, p, r)

1: if p < r then

2: q = \text{Partition}(A, p, r)

3: QuickSort(A, p, q - 1)

4: QuickSort(A, q + 1, r)
```

Worst-case Partitioning

- The worst case is attained when Partition always produces one subproblem with n-1 and one with 0 elements.
- This is the case, for example, when the array is already sorted.
- This leads to the following recurrence:

$$T(n) = T(n-1) + T(0) + \Theta(n)$$
$$= T(n-1) + \Theta(n).$$

• Solving this gives $T(n) = \Theta(n^2)$.

Best-case Partitioning

- Best case: split into two subproblems of sizes $\left\lfloor \frac{n}{2} \right\rfloor$ and $\left\lceil \frac{n}{2} \right\rceil 1$.
- Ignoring floors, ceilings, and -1 we get the recurrence:

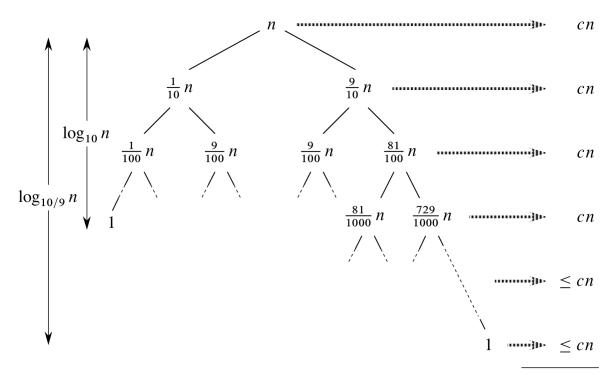
$$T(n) = 2T(n/2) + \Theta(n)$$

- Deja vu?
- This is $\Theta(n \log n)$ from the analysis of MergeSort.
- True to the spirit of divide-and-conquer.

> Towards an average case

- What if the split was always $\frac{9}{10} \cdot n$ and $\frac{1}{10} \cdot n$?
- Getting the recurrence

$$T(n) = T(9n/10) + T(n/10) + cn$$



Average case analysis

- Assume all elements of the array are distinct.
- Assume each split q = 1, 2, ..., n was equally likely.
- This situation occurs when the input is chosen **uniformly at random** amongst all $n! = 1 \cdot 2 \cdot 3 \cdot ... \cdot n$ possible orderings.
- Then

$$T(n) = \frac{1}{n} \cdot \sum_{q=1}^{n} \left(T(q-1) + T(n-q) + \Theta(n) \right)$$

$$= \frac{1}{n} \cdot \sum_{q=1}^{n} T(q-1) + \frac{1}{n} \cdot \sum_{q=1}^{n} T(n-q) + \frac{1}{n} \cdot \sum_{q=1}^{n} \Theta(n)$$

$$= \frac{1}{n} \cdot \sum_{k=0}^{n-1} 2T(k) + \Theta(n)$$

- Average over all problem sizes for 2 subproblems $+\Theta(n)$.
- Solving this recurrence gives a bound of $O(n \log n)$.
- We prove this next!

Average case analysis (2): Substitution method

To prove:
$$\frac{1}{n} \cdot \sum_{k=0}^{n-1} 2T(k) + \Theta(n) \leq \mathbf{c} \, \mathbf{n} \ln \mathbf{n}$$

Base case: n=2 Prove: $T(2) \le c2 \ln 2$

$$T(2) = T(0) + T(1) + \Theta(2) = 2c' + c^* \le c 2 \ln 2$$
 (for e.g., $c > 2c' + c^*$)

Inductive case: Assume true for $\langle n | (T(k) \leq c | k | \ln k | \text{for } k | \langle n | n | \text{and prove for } n | \text{otherwise}$

$$T(n) = \frac{2}{n} \left[T(0) + T(1) + \sum_{k=2}^{n-1} c k \ln k \right] + \Theta(n)$$

$$\leq \frac{2}{n} \left[c' + c' + \sum_{k=2}^{n-1} c k \ln k \right] + \Theta(n) =$$

$$= \frac{4c'}{n} + \left(\frac{2c}{n} \sum_{k=2}^{n-1} k \ln k\right) + \Theta(n) \le \frac{4c'}{n} + \frac{2c}{n} \left[\frac{n^2 \ln n}{2} - \frac{n^2}{4}\right] + \Theta(n)$$

$$= c n \ln n - \frac{cn}{2} + \frac{4c'}{n} + \Theta(n) < c n \ln n \iff \frac{cn}{2} > \frac{4c'}{n} + c^* n, \ (e.g. for \ c > 3c^*)$$

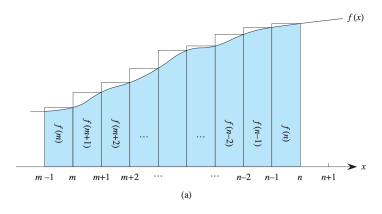
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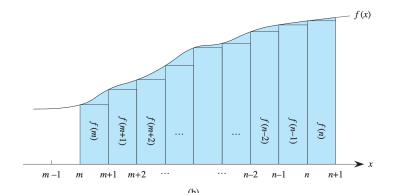
Average case analysis (3)

$$\sum_{k=2}^{n-1} k \ln k \le \int_{2}^{n} k \ln k \, dk = \left[\frac{n^2 \ln n}{2} - \frac{n^2}{4} \right]$$

When a summation has the form $\sum_{k=m}^{n} f(k)$, where f(k) is a monotonically increasing function, you can approximate it by integrals:

$$\int_{m-1}^{n} f(x) \, dx \le \sum_{k=m}^{n} f(k) \le \int_{m}^{n+1} f(x) \, dx \, .$$





Improvements to QuickSort

- QuickSort is fast in practice because of small constants in the asymptotic running time.
- Improvements for handling equal values (exercise)
 - Partition into smaller, equal and larger elements
 - Only need to sort smaller and larger subarrays
- Choose the pivot as **median of 3** elements
 - Slightly faster in practice, but still quadratic worst case
- Dual-Pivot QuickSort by Vladimir Yaroslavskiy
 - Use two pivots instead of one and partition array in 3 areas
 - Used in Java 7

> A Randomised Version of QuickSort

- Choosing the right pivot element can be tricky we have no idea a priori which pivot elements are good.
- Solution: leave it to chance!

Randomised-Partition(A, p, r)

- 1: i = RANDOM(p, r)
- 2: exchange A[r] with A[i]
- 3: **return** Partition(A, p, r)

"Random" picks pivot uniformly at random among all elements.

RANDOMISED-QUICKSORT(A, p, r)

- 1: if p < r then
- 2: q = RANDOMISED-PARTITION(A, p, r)
- 3: RANDOMISED-QUICKSORT(A, p, q-1)
- 4: RANDOMISED-QUICKSORT(A, q+1, r)

Summary

- QuickSort is used in modern programming languages
 - QuickSort has a bad worst-case runtime of $\Theta(n^2)$
 - Average-case performance on **random inputs** is $O(n \log n)$.
- Why is it popular?
 - Constants hidden in the asymptotic terms are small.
- Next week we'll see how randomisation allows to avoid the worst case runtime