

**EE236B homework #1 solutions**

1. (a) Expanding the squares in the  $i$ th term of the cost function gives

$$\begin{aligned}(u_i - u_c)^2 + (v_i - v_c)^2 - R^2 &= -2u_i u_c - 2v_i v_c + u_c^2 + v_c^2 - R^2 + u_i^2 + v_i^2 \\ &= -2u_i u_c - 2v_i v_c + w + u_i^2 + v_i^2.\end{aligned}$$

This is linear in  $u_c, v_c, w$ , so we obtain a linear least-squares problem with variables  $x = (u_c, v_c, w)$  and

$$A = \begin{bmatrix} -2u_1 & -2v_1 & 1 \\ -2u_2 & -2v_2 & 1 \\ \vdots & \vdots & \vdots \\ -2u_m & -2v_m & 1 \end{bmatrix}, \quad b = \begin{bmatrix} -u_1^2 - v_1^2 \\ -u_2^2 - v_2^2 \\ \vdots \\ -u_m^2 - v_m^2 \end{bmatrix}.$$

- (b) The property follows from the normal equations  $A^T(Ax - b) = 0$ .  $Ax - b$  is an  $m$ -vector with components  $-2u_i u_c - 2v_i v_c + w + u_i^2 + v_i^2$ . Since the last column of  $A$  is all ones, the last equation of  $A^T(Ax - b) = 0$  gives

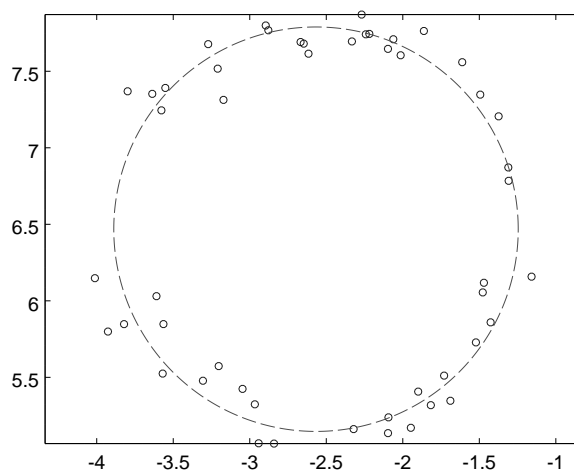
$$\begin{aligned}0 &= \sum_{i=1}^m (-2u_i u_c - 2v_i v_c + w + u_i^2 + v_i^2) \\ &= \sum_{i=1}^m ((u_i - u_c)^2 + (v_i - v_c)^2 + w - u_c^2 - v_c^2) \\ &= \sum_{i=1}^m ((u_i - u_c)^2 + (v_i - v_c)^2) + m(w - u_c^2 - v_c^2).\end{aligned}$$

Therefore

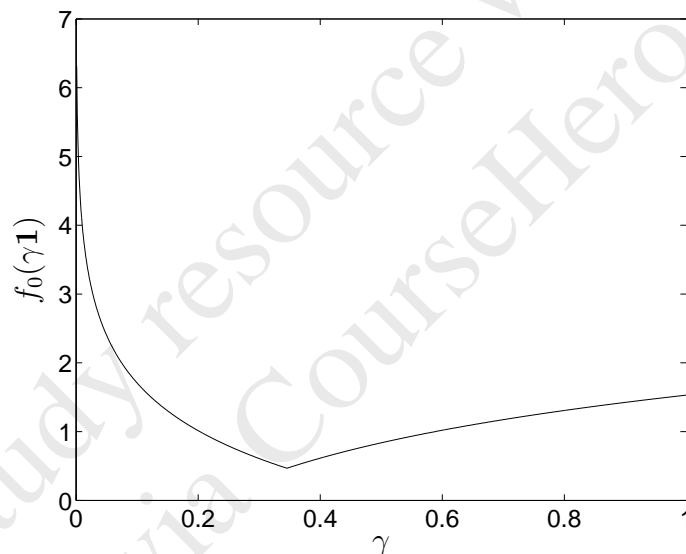
$$u_c^2 + v_c^2 - w = \frac{1}{m} \sum_{i=1}^m ((u_i - u_c)^2 + (v_i - v_c)^2) \geq 0.$$

The solution for the test problem is

$$R = 1.3214, \quad u_c = -2.5671, \quad v_c = 6.468.$$



2. (a) *Equal lamp powers.* The figure shows  $f_0(\gamma \mathbf{1}) = \max_k |\log(\gamma a_k^T \mathbf{1})|$  versus  $\gamma$ .



The minimum is reached at  $\gamma = 0.3453$ .

- (b) *Least-squares with saturation.* We compute  $p$  as

$$p = A \setminus \text{ones}(n, 1).$$

All coefficients of  $p$  are outside the feasible interval  $[0, 1]$  and need to be rounded.

- (c) *Regularized least-squares.* We compute  $p$  by solving a least-squares problem

$$p = [A; \text{sqrt}(\rho) * \text{eye}(m)] \setminus [\text{ones}(n, 1); \text{sqrt}(\rho) * .5 * \text{ones}(m, 1)].$$

The smallest  $\rho$  that gives a feasible  $p$  is  $\rho = 0.2190$ .

- (d) *Chebyshev approximation.* We solve this problem using `cvx`.

```

cvx_begin
    variable p(m)
    minimize (norm(A*p-b, inf))
    subject to
        p >= 0
        p <= 1
cvx_end

```

(e) *Piecewise-linear approximation.* We solve this problem using `cvx`.

```

cvx_begin
    variable p(m)
    minimize (max( [A*x; 2/0.5 - 1/0.5^2 * (A*x); ...
        2/0.8 - 1/0.8^2 * (A*x); 2 - A*x ]));
    subject to
        p >= 0
        p <= 1
cvx_end

```

(f) *Exact solution.*

```

cvx_begin
    variable p(m)
    minimize (max([A*p; inv_pos(A*p)]))
    subject to
        p >= 0
        p <= 1
cvx_end

```

The results are summarized in the following table.

	Equal power	Sat. LS	Weighted LS	Cheb.	PWL	Exact
$p_1$	0.3448	1	0.5004	1	1	1
$p_2$	0.3448	0	0.4778	0.1165	0.1896	0.2023
$p_3$	0.3448	1	0.0833	0	0	0
$p_4$	0.3448	0	0.0000	0	0	0
$p_5$	0.3448	0	0.4561	1	1	1
$p_6$	0.3448	1	0.4354	0	0	0
$p_7$	0.3448	0	0.4598	1	1	1
$p_8$	0.3448	1	0.4307	0.0249	0.1640	0.1882
$p_9$	0.3448	0	0.4034	0	0	0
$p_{10}$	0.3448	1	0.4526	1	1	1
$f_0(p)$	0.4693	0.8628	0.4439	0.4198	0.3664	0.3575

3. (a) If  $A = 0$ , the matrix  $X$  is positive semidefinite if and only if for all  $u, v$ ,

$$2u^T Bv + v^T C v = \begin{bmatrix} u \\ v \end{bmatrix}^T \begin{bmatrix} 0 & B \\ B^T & C \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} \geq 0.$$

Clearly, a sufficient condition is that  $B = 0$  and  $C$  is positive semidefinite. Taking  $u = 0$  shows that positive semidefiniteness of  $C$  is also necessary. To see that  $B = 0$  is necessary, take any  $v$  with  $Bv \neq 0$  and choose  $u = -tBv$ . The quadratic form then reduces to

$$-2t\|Bv\|_2^2 + v^T C v$$

which is negative for sufficiently large  $t$ .

- (b) We have

$$\begin{aligned} AA^\dagger &= Q_1 \Lambda_1 Q_1^T Q_1 \Lambda_1^{-1} Q_1^T \\ &= Q_1 Q_1^T \\ I - AA^\dagger &= Q_1 Q_1^T + Q_2 Q_2^T - AA^\dagger \\ &= Q_2 Q_2^T. \end{aligned}$$

The proofs of the identities  $A^\dagger A = Q_1 Q_1^T$  and  $I - A^\dagger A = Q_2 Q_2^T$  are similar.

- (c) Suppose we sort the eigenvalues of  $A$  so that its eigenvalue decomposition can be written as

$$A = Q \Lambda Q^T = \begin{bmatrix} Q_1 & Q_2 \end{bmatrix} \begin{bmatrix} \Lambda_1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} Q_1 & Q_2 \end{bmatrix}^T$$

with  $\Lambda_1$  positive diagonal. Following the hint, the question can be reduced to showing that the block matrix

$$\begin{bmatrix} \Lambda_1 & 0 & Q_1^T B \\ 0 & 0 & Q_2^T B \\ B^T Q_1 & B^T Q_2 & C \end{bmatrix}$$

is positive semidefinite. By the result in part (a), the matrix is positive semidefinite if and only if

$$Q_2^T B = 0, \quad \begin{bmatrix} \Lambda_1 & Q_1^T B \\ B^T Q_1 & C \end{bmatrix} \succeq 0.$$

The first condition is equivalent to  $(I - AA^\dagger)B = 0$ . Since  $\Lambda_1$  is nonsingular, we can apply the Schur complement result for nonsingular  $A$  to the  $2 \times 2$  block matrix. This gives the condition

$$C - B^T Q_1 \Lambda^{-1} Q_1^T B = C - B^T A^\dagger B \succeq 0.$$