

**ECE236B homework #7 solutions**

1. *Exercise A4.22.* We make a change of variables  $u_i = \log x_i$ ,  $v_j = \log y_j$  and define  $\alpha_{ij} = \log A_{ij}$ . The GP in convex form is

$$\begin{aligned} & \text{minimize} && \log \left( \sum_{i=1}^n \sum_{j=1}^n e^{\alpha_{ij} + u_i + v_j} \right) \\ & \text{subject to} && c^T u = 0 \\ & && d^T v = 0, \end{aligned}$$

with variables  $u, v \in \mathbf{R}^n$ . The optimality conditions are

$$c^T u = d^T v = 0, \quad \nabla_u L(u, v, \lambda, \gamma) = \nabla_v L(u, v, \lambda, \gamma) = 0$$

where  $L$  is the Lagrangian

$$L(u, v, \lambda) = \log \left( \sum_{i=1}^n \sum_{j=1}^n e^{\alpha_{ij} + u_i + v_j} \right) - \lambda c^T u - \gamma d^T v.$$

The optimal  $u$  and  $v$  therefore satisfy

$$\frac{e^{u_i} \sum_{j=1}^n e^{\alpha_{ij}} e^{v_j}}{\sum_{k=1}^n \sum_{l=1}^n e^{\alpha_{kl} + u_k + v_l}} = \lambda c_i, \quad i = 1, \dots, n,$$

and

$$\frac{e^{v_j} \sum_{i=1}^n e^{\alpha_{ij}} e^{u_i}}{\sum_{k=1}^n \sum_{l=1}^n e^{\alpha_{kl} + u_k + v_l}} = \gamma d_j, \quad j = 1, \dots, n$$

for some scalars  $\lambda, \gamma$ . In the original variables  $x_i = e^{u_i}$ ,  $y_i = e^{v_i}$ , these equations are

$$\frac{1}{x^T A y} \mathbf{diag}(x) A y = \lambda c, \quad \frac{1}{x^T A y} \mathbf{diag}(y) A^T x = \gamma d.$$

Taking the inner product with  $\mathbf{1}$  (and using the fact that  $\mathbf{1}^T c = \mathbf{1}^T d = 1$ ) shows  $\lambda = \gamma = 1$ . Therefore

$$\frac{1}{x^T A y} \mathbf{diag}(x) A \mathbf{diag}(y) \mathbf{1} = c, \quad \frac{1}{x^T A y} \mathbf{diag}(y) A^T \mathbf{diag}(x) \mathbf{1} = d.$$

2. In the primal SDP we must have  $x_1 = 0$  at any feasible point. Therefore the optimal value is  $p^* = 0$ .

The Lagrangian is

$$\begin{aligned} L(x, Z) &= x_1 - \mathbf{tr}\left(\begin{bmatrix} Z_{11} & Z_{12} & Z_{13} \\ Z_{12} & Z_{22} & Z_{23} \\ Z_{13} & Z_{23} & Z_{33} \end{bmatrix} \begin{bmatrix} 0 & x_1 & 0 \\ x_1 & x_2 & 0 \\ 0 & 0 & x_1 + 1 \end{bmatrix}\right) \\ &= (1 - 2Z_{12} - Z_{33})x_1 - Z_{22}x_2 - Z_{33}. \end{aligned}$$

The infimum over  $x$  is minus infinity unless  $1 - 2Z_{12} - Z_{33} = Z_{22} = 0$ , and equal to  $-Z_{33}$  otherwise. Therefore the dual SDP is

$$\begin{aligned} &\text{maximize} && -Z_{33} \\ &\text{subject to} && 2Z_{12} + Z_{33} = 1 \\ &&& Z_{22} = 0 \\ &&& \begin{bmatrix} Z_{11} & Z_{12} & Z_{13} \\ Z_{12} & Z_{22} & Z_{23} \\ Z_{13} & Z_{23} & Z_{33} \end{bmatrix} \succeq 0. \end{aligned}$$

Since  $Z_{22} = 0$ , we have  $Z_{12} = Z_{23} = 0$  at any feasible point. The first equality constraint then implies that  $Z_{33} = 1$ , so the optimal value is  $d^* = -1$ .

We see that there is a finite nonzero gap  $p^* - d^* = 1$ . We can also note that the primal and dual problems are feasible but not strictly feasible.

3. *Exercise A4.17.*

- (a) Let  $A = V\Lambda V^T = \sum_{k=1}^n \lambda_k v_k v_k^T$  be the eigenvalue decomposition of  $A$ . If we make a change of variables  $Y = V^T X V$  the problem becomes

$$\begin{aligned} &\text{maximize} && \mathbf{tr}(\Lambda Y) \\ &\text{subject to} && \mathbf{tr} Y = r \\ &&& 0 \preceq Y \preceq I. \end{aligned}$$

We can assume that  $Y$  is diagonal at the optimum. To see this, note that the objective function and the first constraint only involve the diagonal elements of  $Y$ . Moreover, if  $Y$  satisfies  $0 \preceq Y \preceq I$ , then its diagonal elements satisfy  $0 \leq Y_{ii} \leq 1$ . Therefore if a non-diagonal  $Y$  is optimal, setting its off-diagonal elements to zero yields another feasible matrix with the same objective value.

To find the optimal value we can therefore solve

$$\begin{aligned} &\text{maximize} && \sum_{i=1}^n \lambda_i Y_{ii} \\ &\text{subject to} && \sum_{i=1}^n Y_{ii} = r \\ &&& 0 \leq Y_{ii} \leq 1, \quad i = 1, \dots, n. \end{aligned}$$

Since the eigenvalues  $\lambda_i$  are sorted in nonincreasing order, an optimal solution is  $Y_{11} = \dots = Y_{rr} = 1$ ,  $Y_{r+1,r+1} = \dots = Y_{nn} = 0$ . Converting back to the original variables gives

$$X = \sum_{k=1}^r v_k v_k^T.$$

- (b) Any function of the form  $\sup_{X \in C} \mathbf{tr}(AX)$  is convex in  $A$ .
- (c) To derive the dual of the problem in part (a), we first write it as a minimization

$$\begin{aligned} & \text{minimize} && -\mathbf{tr}(AX) \\ & \text{subject to} && \mathbf{tr} X = r \\ & && 0 \preceq X \preceq I. \end{aligned}$$

The Lagrangian is

$$\begin{aligned} L(X, \nu, U, V) &= -\mathbf{tr}(AX) + \nu(\mathbf{tr} X - r) - \mathbf{tr}(UX) + \mathbf{tr}(V(X - I)) \\ &= \mathbf{tr}((-A + \nu I - U + V)X) - r\nu - \mathbf{tr} V. \end{aligned}$$

By minimizing over  $X$  we obtain the dual function

$$g(\nu, U, V) = \begin{cases} -r\nu - \mathbf{tr} V & -A + \nu I - U + V = 0 \\ -\infty & \text{otherwise.} \end{cases}$$

The dual problem is

$$\begin{aligned} & \text{maximize} && -r\nu - \mathbf{tr} V \\ & \text{subject to} && A - \nu I = V - U \\ & && U \succeq 0, \quad V \succeq 0. \end{aligned}$$

If we change the dual problem to a minimization and eliminate the variable  $U$ , we obtain a dual problem for the SDP in part (a) of the assignment:

$$\begin{aligned} & \text{minimize} && r\nu + \mathbf{tr} V \\ & \text{subject to} && A - \nu I \preceq V \\ & && V \succeq 0. \end{aligned}$$

By strong duality, the optimal value of this problem is equal to  $f(A)$ . We can therefore minimize  $f(A(x))$  over  $x$  by solving the

$$\begin{aligned} & \text{minimize} && r\nu + \mathbf{tr} V \\ & \text{subject to} && A(x) - \nu I \preceq V \\ & && V \succeq 0, \end{aligned}$$

which is an SDP in the variables  $\nu \in \mathbf{R}$ ,  $V \in \mathbf{S}^n$ ,  $x \in \mathbf{R}^m$ .

4. *Exercise A4.10.*

(a) The Lagrangian is

$$L(x, \nu) = x^T (A^T A + \mathbf{diag}(\nu))x - 2b^T A x + b^T b - \mathbf{1}^T \nu.$$

The dual function is

$$g(\nu) = \begin{cases} -\mathbf{1}^T \nu - b^T A (A^T A + \mathbf{diag}(\nu))^\dagger A^T b + b^T b & A^T A + \mathbf{diag}(\nu) \succeq 0, \\ & A^T b \in \mathcal{R}(A^T A + \mathbf{diag}(\nu)) \\ -\infty & \text{otherwise.} \end{cases}$$

Using Schur complements we can express the dual as an SDP

$$\begin{aligned} & \text{maximize} && -\mathbf{1}^T \nu - t + b^T b \\ & \text{subject to} && \begin{bmatrix} A^T A + \mathbf{diag}(\nu) & -A^T b \\ -b^T A & t \end{bmatrix} \succeq 0 \end{aligned}$$

with variables  $\nu$  and  $t$ .

(b) We first write the problem as a minimization problem

$$\begin{aligned} & \text{minimize} && \mathbf{1}^T \nu + t - b^T b \\ & \text{subject to} && \begin{bmatrix} A^T A + \mathbf{diag}(\nu) & -A^T b \\ -b^T A & t \end{bmatrix} \succeq 0. \end{aligned}$$

We introduce a Lagrange multiplier

$$\begin{bmatrix} Z & z \\ z^T & \lambda \end{bmatrix}$$

for the constraint and form the Lagrangian

$$\begin{aligned} \tilde{L}(\nu, t, Z, z, \lambda) &= \mathbf{1}^T \nu + t - b^T b - \mathbf{tr}(Z(A^T A + \mathbf{diag}(\nu))) + 2z^T A^T b - t\lambda \\ &= (\mathbf{1} - \mathbf{diag}(Z))^T \nu + t(1 - \lambda) - b^T b - \mathbf{tr}(Z A^T A) + 2z^T A^T b. \end{aligned}$$

This is unbounded below unless  $\mathbf{diag}(Z) = \mathbf{1}$  and  $\lambda = 1$ . The dual problem of the SDP in part (a) is therefore

$$\begin{aligned} & \text{minimize} && \mathbf{tr}(A^T A Z) - 2b^T A z + b^T b \\ & \text{subject to} && \mathbf{diag}(Z) = \mathbf{1} \\ & && \begin{bmatrix} Z & z \\ z^T & 1 \end{bmatrix} \succeq 0. \end{aligned}$$

To see that this is a relaxation of the original problem we note that the binary least-squares problem is equivalent to

$$\begin{aligned} & \text{minimize} && \mathbf{tr}(A^T A Z) - 2b^T A z + b^T b \\ & \text{subject to} && \mathbf{diag}(Z) = \mathbf{1} \\ & && Z = z z^T. \end{aligned}$$

In the relaxation we replace  $Z = zz^T$  by the weaker constraint  $Z \succeq zz^T$ , which is equivalent to

$$\begin{bmatrix} Z & z \\ z^T & 1 \end{bmatrix} \succeq 0.$$

(c) We have  $\mathbf{E} v_k^2 = Z_{kk}$  and

$$\begin{aligned} \mathbf{E} \|Av - b\|_2^2 &= \mathbf{E}(v^T A^T Av - 2b^T A^T v + b^T b) \\ &= \mathbf{tr}(\mathbf{E}(vv^T) A^T A) - 2b^T A^T \mathbf{E} v + b^T b \\ &= \mathbf{tr}(Z A^T A) - 2b^T A^T z + b^T b. \end{aligned}$$

(d) The MATLAB code for solving the SDP is as follows.

```
cvx_begin sdp
    variable z(n);
    variable Z(n,n) symmetric;
    minimize( trace(A'*A*Z) - 2*b'*A*z + b'*b )
    subject to
        [Z, z; z' 1] >= 0
        diag(Z)==1;
cvx_end
```

The table lists, for each  $s$ , the values of  $f(x) = \|Ax - b\|_2$  for  $x = \hat{x}$  and the four approximations, and also the lower bound on the optimal value of

$$\begin{aligned} &\text{minimize} \quad \|Ax - b\|_2 \\ &\text{subject to} \quad x_k^2 = 1, \quad k = 1, \dots, n, \end{aligned}$$

obtained by the SDP relaxation.

$s$	$f(\hat{x})$	$f(x^{(a)})$	$f(x^{(b)})$	$f(x^{(c)})$	$f(x^{(d)})$	lower bound
0.5	4.1623	4.1623	4.1623	4.1623	4.1623	4.0524
1.0	8.3245	12.7299	8.3245	8.3245	8.3245	7.8678
2.0	16.6490	30.1419	16.6490	16.6490	16.6490	15.1804
3.0	24.9735	33.9339	25.9555	25.9555	24.9735	22.1139

- For  $s = 0.5$ , all heuristics return  $\hat{x}$ . This is likely to be the global optimum, but that is not necessarily true. However, from the lower bound we know that the global optimum is in the interval  $[4.0524, 4.1623]$ , so even if 4.1623 is not the global optimum, it is quite close.
- For higher values of  $s$ , the result from the first heuristic ( $x^{(a)}$ ) is substantially worse than the SDP heuristics.
- All three SDP heuristics return  $\hat{x}$  for  $s = 1$  and  $s = 2$ .
- For  $s = 3$ , the randomized rounding method returns  $\hat{x}$ . The other SDP heuristics give slightly higher values.

5. *Exercise A4.8.* The unconstrained problem can be written as an SDP

$$\begin{aligned} & \text{minimize} && c^T x + t \\ & \text{subject to} && F(x) \preceq tI \\ & && t \geq 0. \end{aligned} \tag{1}$$

The dual of this problem is

$$\begin{aligned} & \text{maximize} && \mathbf{tr}(F_0 Z) \\ & \text{subject to} && \mathbf{tr}(F_i Z) + c_i = 0, \quad i = 1, \dots, m \\ & && \mathbf{tr} Z + s = 1 \\ & && Z \succeq 0, \quad s \geq 0. \end{aligned} \tag{2}$$

The difference with the original dual problem is the addition of an upper bound  $\mathbf{tr} Z \leq 1$  (written as  $\mathbf{tr} Z + s = 1$  for  $s \geq 0$ ). We see that  $Z^*$  satisfies this constraint, with  $s > 0$ . Therefore it is optimal for (2). By complementary slackness we have  $t = 0$  at the optimum of the primal problem (1). The optimal  $x$  for (1) is therefore optimal for the original SDP.

6. *Exercise A4.28.* The  $i$ th constraint

$$\sup_{a_i \in P_i} \max \{a_i^T x - b_i, -a_i^T x + b_i\} = \max \left\{ \sup_{a_i \in P_i} (a_i^T x - b_i), \sup_{a_i \in P_i} (-a_i^T x + b_i) \right\} \leq t_i$$

is satisfied if and only if  $\sup_{a_i \in P_i} (a_i^T x - b_i) \leq t_i$  and  $\sup_{a_i \in P_i} (-a_i^T x + b_i) \leq t_i$ . From duality,

$$\sup_{C_i a_i \preceq d_i} a_i^T x = \inf_{\substack{C_i^T z_i = x \\ z_i \succeq 0}} d_i^T z_i, \quad \sup_{C_i a_i \preceq d_i} -a_i^T x = \inf_{\substack{C_i^T w_i = -x \\ w_i \succeq 0}} d_i^T w_i.$$

So the  $i$  constraint is equivalent to existence of  $z_i, w_i$  with

$$d_i^T z_i - b_i \leq t_i, \quad C_i^T z_i = x, \quad z_i \succeq 0, \quad d_i^T w_i + b_i \leq t_i, \quad C_i^T w_i = -x, \quad w_i \succeq 0.$$

This results in the QP:

$$\begin{aligned} & \text{minimize} && \sum_{i=1}^m t_i^2 \\ & \text{subject to} && d_i^T z_i - b_i \leq t_i, \quad d_i^T w_i + b_i \leq t_i, \quad i = 1, \dots, m \\ & && x = C_i^T z_i = -C_i^T w_i, \quad i = 1, \dots, m \\ & && z_i \succeq 0, \quad w_i \succeq 0, \quad i = 1, \dots, m. \end{aligned}$$

7. *Exercise A4.30.*

(a) The Lagrangian is

$$L(x, y, z) = c^T x + \frac{1}{\mu} \sum_{i=1}^m \log(1 + e^{\mu y_i}) + z^T (Ax - b - y).$$

The minimum over  $x$  is unbounded below unless  $A^T z + c = 0$ . To find the minimum over  $y$  we note the function is separable. Setting the derivative with respect to  $y_i$  to zero gives

$$\frac{e^{\mu y_i}}{1 + e^{\mu y_i}} = z_i, \quad y_i = \frac{1}{\mu} \log \frac{z_i}{1 - z_i}$$

and

$$\begin{aligned} & \inf_{y_i} \left( \frac{1}{\mu} \log(1 + e^{\mu y_i}) - z_i y_i \right) \\ &= \begin{cases} -(1/\mu)(z_i \log z_i + (1 - z_i) \log(1 - z_i)) & 0 \leq z_i \leq 1 \\ -\infty & \text{otherwise} \end{cases} \end{aligned}$$

(with the interpretation  $0 \log 0 = 0$ ). We therefore obtain the dual

$$\begin{aligned} & \text{maximize} && -b^T z - \frac{1}{\mu} \sum_{i=1}^m (z_i \log z_i + (1 - z_i) \log(1 - z_i)) \\ & \text{subject to} && A^T z + c = 0 \\ & && 0 \preceq z \preceq \mathbf{1}. \end{aligned}$$

(b) Plugging in the optimal primal solution  $x^*$  of the LP in (25) gives

$$\begin{aligned} q^* &\leq c^T x^* + \frac{1}{\mu} \sum_{i=1}^m \log(1 + e^{\mu(a_i^T x^* - b_i)}) \\ &\leq p^* + \frac{m \log 2}{\mu} \end{aligned}$$

because  $a_i^T x^* - b_i \leq 0$ . Plugging in the optimal dual solution  $z^*$  of the LP in the dual of (25) gives

$$\begin{aligned} q^* &\geq -b^T z^* - \frac{1}{\mu} \sum_{i=1}^m (z_i^* \log z_i^* + (1 - z_i^*) \log(1 - z_i^*)) \\ &\geq p^* \end{aligned}$$

because  $u \log u \leq 0$  on  $[0, 1]$ .