## Stationarity and Linear filters

Quiz, 6 questions

1 point

1.

Does any stochastic process with the covariance function  $K(t,s)=sin(\lambda(t-s))$  exist?

Yes

O No

1 point

2

Let  $Y_n$  be a stochastic process which is defined as follows:

 $Y_{n+1}=\alpha Y_n+X_n$ , n=0,1,... Assume  $Y_0=0$ ,  $|\alpha|<1$  and  $X_n$  is a sequence of i.i.d. standard normal random random variables for n=0,1,2,... Decide whether  $Y_n$  is stationary and find its mean and variance:

- $Y_n$  is non-stationary,  $\mathbb{E} Y_n = 0$ ,  $Var Y_n = rac{1}{1-lpha^2}$
- $Y_n$  is stationary,  $\mathbb{E} Y_n = 0$ ,  $Var Y_n = rac{1}{1-lpha^2}$
- $Y_n$  is non-stationary,  $\mathbb{E}Y_n=0$ ,  $VarY_n=lpha^2+1+2K(Y_n,X_n)$
- $Y_n$  is stationary,  $\mathbb{E} Y_n = 0$ ,  $Var Y_n = lpha^2 + 1$
- none of above

1 point

3.

Let  $W_t$  be a Brownian Motion. Is  $X_t = (1-t)W_{t/(1-t)}$  a stationary process?

## Stationarity and Linear filters

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- $X_t$  is weakly stationary process
- $X_t$  is strictly stationary process

1 point

4

Let  $W_t$  be a Brownian Motion and h>0 is a fixed number. Find a covariance function of a process  $X_t=W_{t+h}-W_t$ :

- $K(t,s)=0\ orall t,s$
- $K(t,s) = egin{cases} h |t-s|, & if |t-s| \leq h \ 0, & if |t-s| > h \end{cases}$
- $K(t,s) = egin{cases} min(t,s), & if|t-s| \leq h \ 0, & if|t-s| > h \end{cases}$
- none of above

1 point

5.

Let  $X_t$  is a process with independent and stationary increments. Moreover,  $\mathbb{E}X_t=0$  and  $\mathbb{E}X_t^2<\infty$ . Is  $Y_t=X_{t+h}-X_t$  is a wide-sense stationary process  $\forall h>0$ ?

- Yes
- No
- Additional information on  $X_t$  is required

1 point 6.

Let  $X_t$  be a wide-sense stationary process with autocovariance function  $\gamma$ , Stationarity which equals  $T_{\gamma}$  to  $T_{\gamma}$  be a wide-sense stationary process with autocovariance function  $\gamma$ .

Quiz, 6 questions

Find a spectral density  $g_X(u)$  of this process:

- $g_X(u) = rac{1+cosu}{2\pi}$
- $g_X(u) = rac{1 + 2 cos u}{\pi}$
- None of above
- $g_X(u) = rac{1 + 2 cos u}{2\pi}$
- $g_X(u) = rac{1+cosu}{\pi}$
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