Pickupdropoff - goToPickupLocation(MoveBaseGoal &goal): bool - gitToTargetLocation(MoveBaseGoal &goal): bool + <<constructor>> Pickupdropoff()

Location - n: NodeHandle - vmarker_pub:Publisher - sub: Subscriber - odom_x:float - odom_y:float - count:uint8_t - marker:Marker - pickup: vector<double> - dropoff: vector<double> - setMarkerProperties():int - setDefaultPickAndDropLocation():int - odomCallback(const nav_msgs::Odometry::ConstPtr& msg):void + setPickupLocation(double x, double y, double z): int + setDropOffLocation(double x, double y, double z): int + visualizeLocation(int argc, char** argv): int +<<constructor>> Location()