

## MEMS Automotive Collision Avoidance Radar beamformer

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#### **Overview**

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#### Introduction

- Rotman lens works by summing or focusing N in-phase samples of a wavefront at a focal point.
- It can be considered to be a true time-delay multiple beamformer.
- Currentlly used Rotman lens types
  - Parallel plates (wave guide feed lines)
  - \_ Microstrip lens (stripline microwave printed circuit techniques to construct the feed section).
- For use in automotive collision avoidance systems
  - Position/Proximity sensors
  - Blind spot Measurements
  - Parking aid
  - Reverse aid
  - Pre crash
  - Stop/go sensor



#### State-of-the-Art

- The most common Rotman lens used in automotive collision detection are microstrip lens.
- Microstrip Rotman lens used in the industry have the following specifications:

Parameter	Value
Operating Frequency	77 GHz
Operating Range	100 m
Voltage	60 V
Size	5 to 10 cm
Gain of Main lobe	> 25 db
Side lobe	< -15 db
Beam width	40



#### State-of-the-Art

- Advantages of Rotman lens:
- Monolithic construction
- Ease of manufacture
- Low cost
- Light weight
- · Simultaneous availability of many beams.
- Because it is a true time-delay device, the Rotman lens produces frequencyindependent beam steering and is therefore capable of extremely wide-band operation.
- These features make the Rotman lens an attractive candidate for use in multibeam satellite-based applications.



#### **Advantages of Rotman lens**

- The Rotman lens is a true time-delay scanner that can be used either for receiving or transmitting.
- Increased range and detection performance over the ultrasonic sensors currently deployed as reverse parking aids.
- The design was improved by introducing a dielectric material in the parallel plate section (constant  $\varepsilon_r$ ) reducing the dimensions of this section by  $1/\sqrt{\varepsilon_r}$
- This improvement also permitted the use of microstrip and stripline microwave printed circuit techniques to construct the feed section.



## **Design Challenges**

- Port spacing (it have to be in the range of the fractions of the wave length)
- Suppressing and reducing the sidelobes
- Reflections at the beam and array ports
- Isolation of individual beams and cross over levels



#### **Port spacing**

- Port spacing (it have to be in the range of the fractions of the wave length)
- The distance between ports can be minimized by using sidewall layers of a relative permitivity of one forth of the lens dielectric.
- Redirecting the port can reduce the port spacing



## Reducing the sidelobes

- Side lobe level improves (level of side lobe reduces with increase in element spacing).
- The sidelobe level of an array antenna fed by a Roman lens can be reduced if pairs of adjacent beam ports are combined.
- The system is fed through these summing ports.
- This procedure does not reduce the overall antenna gain.

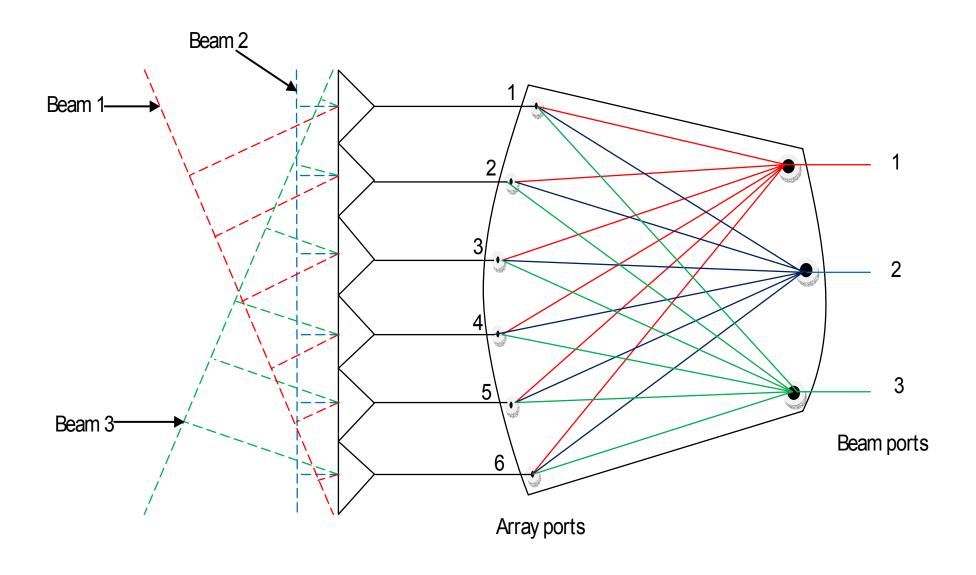


#### Reflections at the beam and array ports

- Reflections at the beam and array ports can be reduced by introducing dummy ports that have matched resistance.
- Increasing element spacing, (but beam width decreases as element spacing increases).



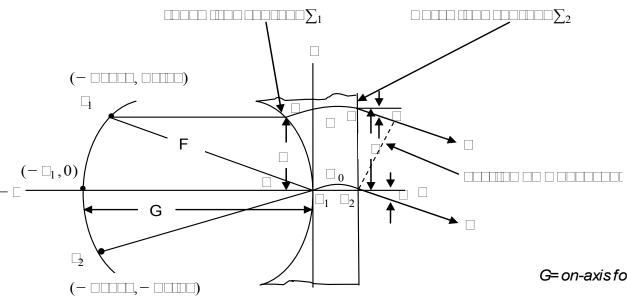
#### **Rotman Lens beamformer**



Linear array fed by a Rotman lens



## **Rotman Lens parameters**



$$\Box_1 \Box + \Box + \Box \Box \Box = \Box + \Box_0 \tag{1}$$

$$\square_2 \square + \square - \square \square \square = \square + \square_0 \tag{2}$$

$$\Box_1 \Box + \Box = \Box + \Box_0 \tag{3}$$

G= on-axis focal length

F= off-axis focal length

W= electrical wire length

α= scanning angle



## **Rotman Lens Design Equations**

$$\eta = \frac{N}{F}, \quad x = \frac{X}{F}, \quad y = \frac{Y}{F}, \quad w = \frac{W - W_0}{F}, \quad g = \frac{G}{F},$$

$$a_0 = \cos \alpha, \quad b_0 = \sin \alpha$$

$$\alpha = \left[1 - \eta^2 - \left(\frac{g - 1}{g - a_0}\right)^2\right]$$

$$b = \left[2g\left(\frac{g - 1}{g - a_0}\right) - \frac{(g - 1)}{(g - a_0)^2}b_0^2\eta^2 + 2\eta^2\right] - 2g$$

$$c = \left[\frac{gb_{0\eta^2}^2}{g - a_0} - \frac{b_0^4\eta^4}{4(g - a_0)^2} - \eta^2\right]$$

$$x = \frac{1 - g}{g - a_0}w - \frac{b_0^2\eta^2}{2(g - a_0)}$$

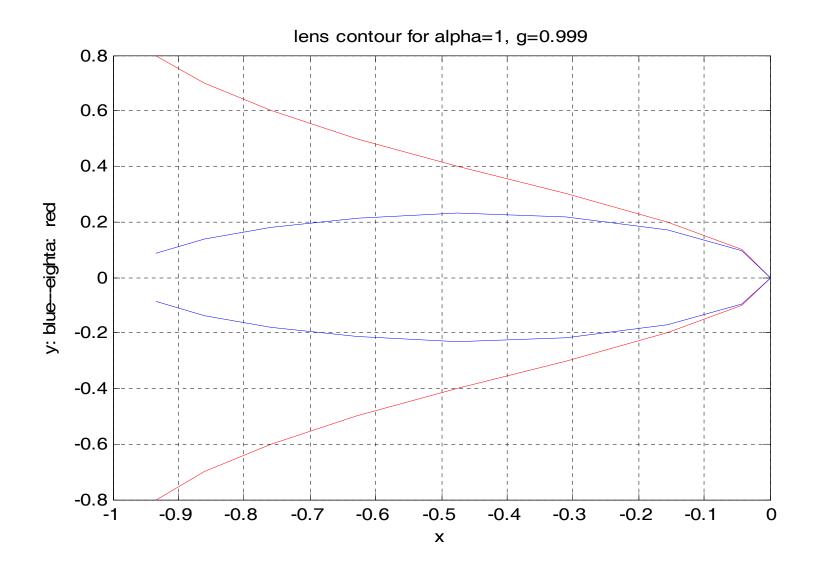
$$y = \eta(1 - w)$$

$$w = \frac{-b + \sqrt{b^2 - 4ac}}{2a}$$

We use Matlab to obtain the lens contours for different values of (G) and ( $\alpha$ ) as shown below.

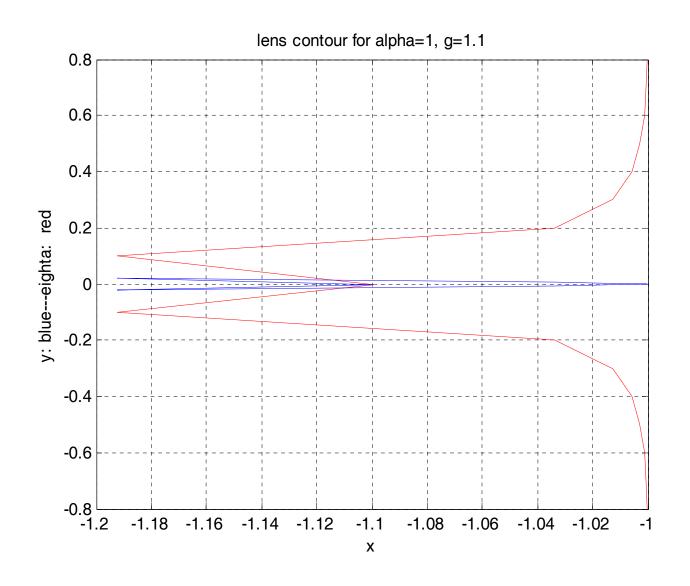


## Lens contour for alpha=1, g=0.999



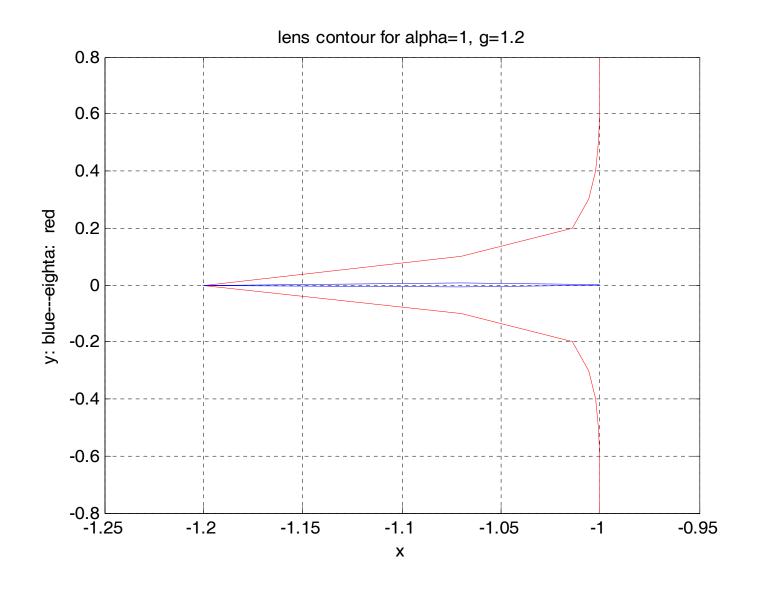


#### Lens contour for alpha=1, g=1.1



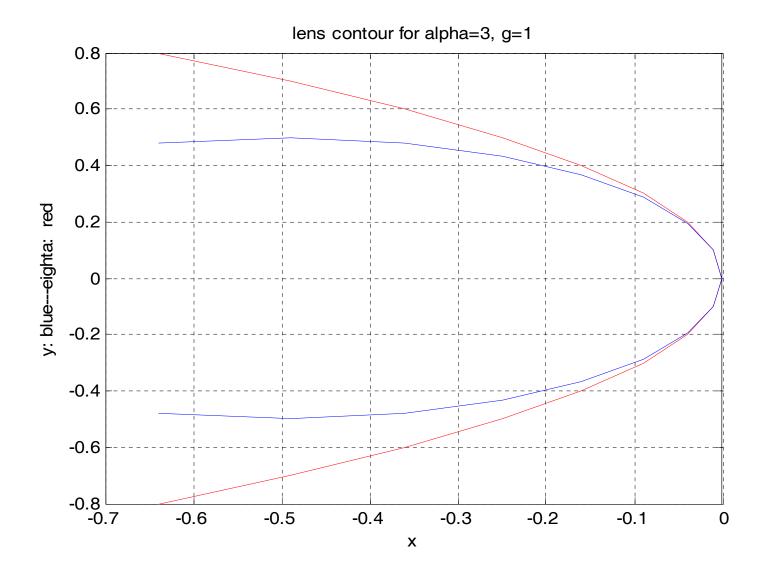


## Lens contour for alpha=1, g=1.2



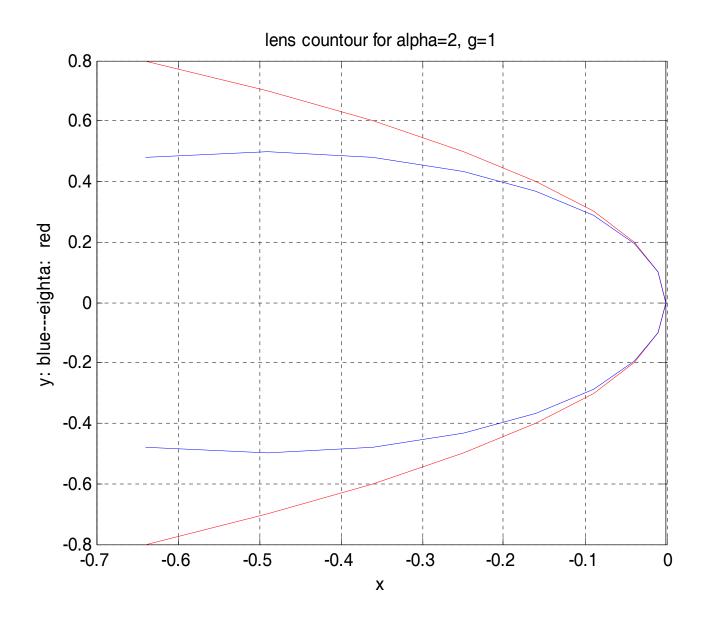


## Lens contour for alpha=3, g=1



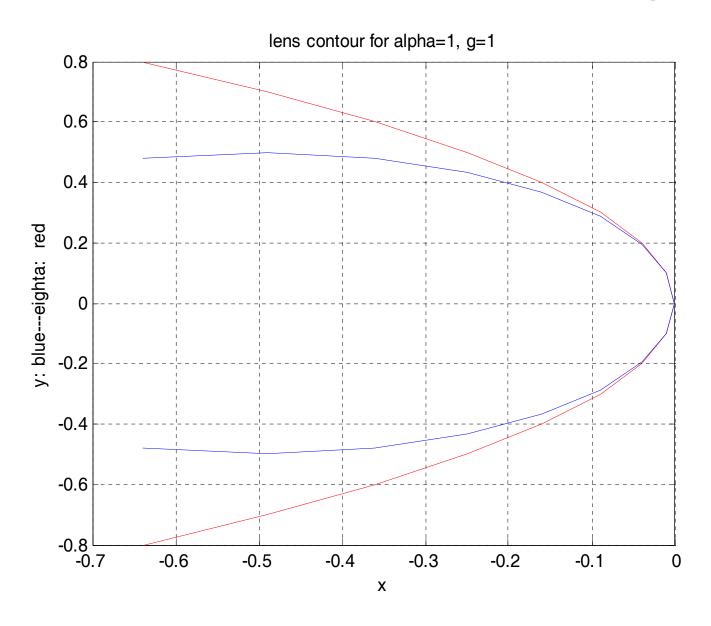


## Lens contour for alpha=2, g=1





## Lens contour for alpha=1, g=1



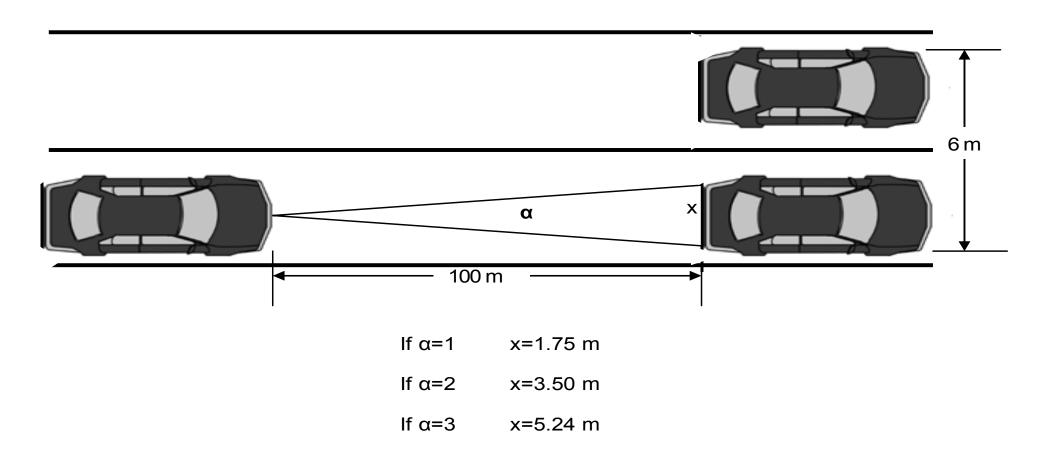


## Why choosing g=1 and alpha=1

- The focal arc is centered at the vertex O₁ of the inner lens contour.
- The central ray paths from all points on the focal arc are equal in length.
- This setup of the lens is very important in monopulse applications.
- The shape of the lens will be approximated by a segment of a circle.
- The optical abberations are are very low.



## Target scanning overview





#### **Rotman Lens**

We obtain the optimal values for the parameters from our plots as follows:

X = -0.63995

Y=0.49994

W=1.6001

Eighta= 0.7

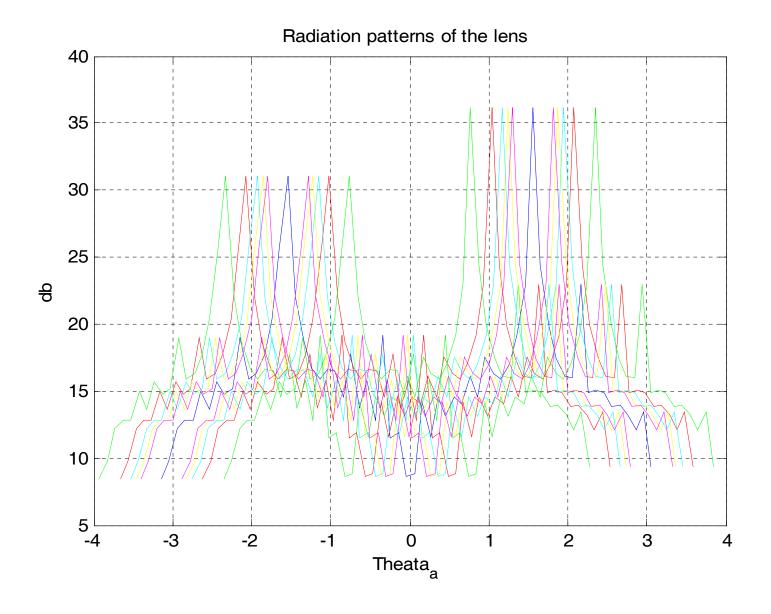
To find the radiation patterns of the lens, we have to plot gain of the lens versus the change of the array port angle.

$$\frac{P_r}{P_t} = \frac{l_a l_b}{\lambda} cos^2 \theta_a cos^2 \theta_b \left[ \frac{\sin \left( \Pi l_a sin \theta_a / \lambda \right)}{\Pi l_a sin \theta_a / \lambda} \right]^2 \left[ \frac{\sin \left( \Pi l_b sin \theta_b / \lambda \right)}{\Pi l_b sin \theta_b / \lambda} \right]^2$$

By taking the log of the equation above and plot it with the array angle, we got the following response.



#### Radiation patterns of the lens





#### Parameters calculation without insulation

we can define the length of the antenna array as

$$L_{1/2} = \frac{(N_a - 1)d}{2} = \frac{(N_a - 1)^{\lambda/2}}{2} = \frac{(5 - 1)0.001945}{2}$$
$$= 3.89 \ mm \ for \ N_a = 5$$

where

 $L_{1/2}$  = half length of array,

 $N_a$  = the number of array elements, and

= Spacing between antenna elements.

If we choose the maximum value of  $\eta$  the minimum value of scaling factor F can be obtained as

$$F_{min} = \frac{L_{1/2}}{\eta_{max}} = \frac{(N_a - 1)d}{2\eta_{max}} = \frac{0.00389}{0.7} = 0.00555 \ m = 5.55 \ mm$$



#### Parameters calculation without insulation

$$\eta = N/_F$$
,  $N = F\eta = 5.55 * 0.7 = 3.89 \ mm$   
 $x = X/_F$ ,  $X = Fx = 5.55 * 0.63995 = 3.55 \ mm$   
 $y = Y/_F$ ,  $Y = Fy = 5.55 * 0.49994 = 2.78 \ mm$   
 $w = \frac{W - W_0}{F}$ ,  $W - W_0 = Fw = 6.94 * 1.6001 = 8.89 \ mm$   
 $g = G/_F$ ,  $G = Fg = 5.55 * 1 = 5.55 \ mm$   
When  $g = 1$  then  $R = F = 5.55 \ mm$   
The arc between  $F_1 \& F_2 = r\theta = 2 * \frac{\Pi}{180} * 5.55 * 10^{-3} = 0.1937 \ mm$ 



#### Parameters calculation with insulation

Using a high dielectric material **BaSrTiO**<sub>3</sub> (having a dielectric constant =6000), we can reduce the dimensions by a factor of  $\sqrt{\varepsilon_r}$ .

Paralell plate region height

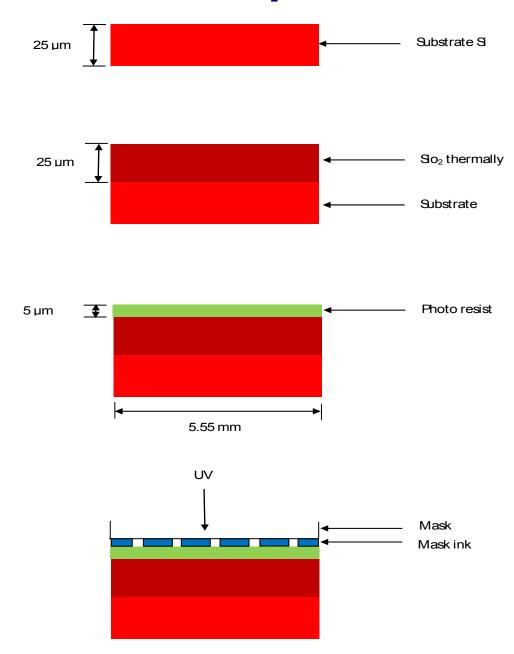
$$< \frac{\lambda_m}{2}$$
  $(\lambda_m = \frac{\lambda_0}{\sqrt{\varepsilon_r}}) = \frac{\frac{c}{f}}{\sqrt{\varepsilon_r}} = \frac{\frac{3*10^8}{77*10^9}}{\sqrt{6000}} = 50 \ \mu m$ 

So the separation of the centres of the lens contours will be

$$\frac{\lambda_m}{2} = \frac{50}{2} = 25 \ \mu m$$

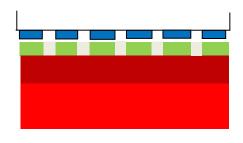


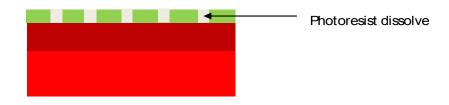
## **Fabrication process**

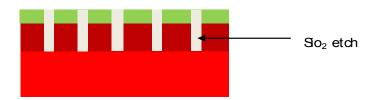


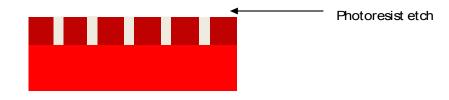


## **Fabrication process**



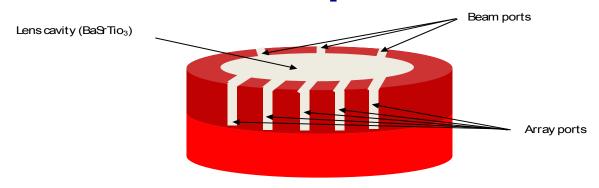




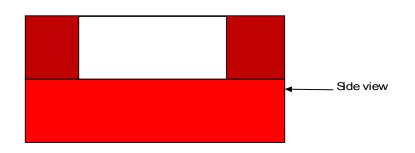




## **Fabrication process**









#### Target design specifications

Building a safety belt around the car am adaptive cruise control Audi Side Vision Reversing Aid Side Vision Courtesy: Audi Occupant Pre-Crash Parking Aid Pre-Crash Pre-Crash Parking Aid Stop / Go Sensor AICC Pre-Crash Courtesy: Mercedes

Courtesy: Cambridge Consultants



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# THANK YOU