



## **Body-Motion Driven MEMS Generator for Implantable Biomedical Devices**

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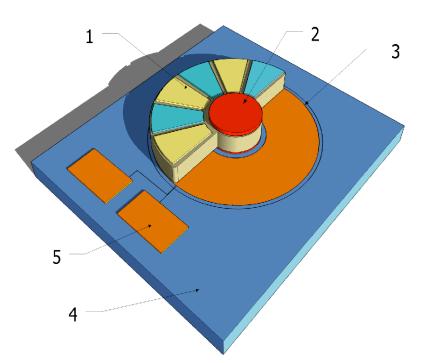


#### **Abstract**

- A MEMS-based axial flux power generator for implantable biomedical devices has been presented
- In the system, a semicircular magnetic pendulum oscillates around a central shaft due to the physiological motion of the body organs to induce a voltage across an underlying copper coil
- The 1.0 mm<sup>2</sup> footprint area device can generate 390 μW RMS power with an open circuit RMS voltage of 1.1 volts
- A number of microgenerators could be stacked vertically or horizontally or a scaled up version can be used if greater amount of power is needed
- The device can provide a greater energy supply per unit volume at a much smaller size and weight and maintenance free longer life compared to conventional batteries
- In this paper, an optimized microgenerator design for cardiac pace maker application has been presented



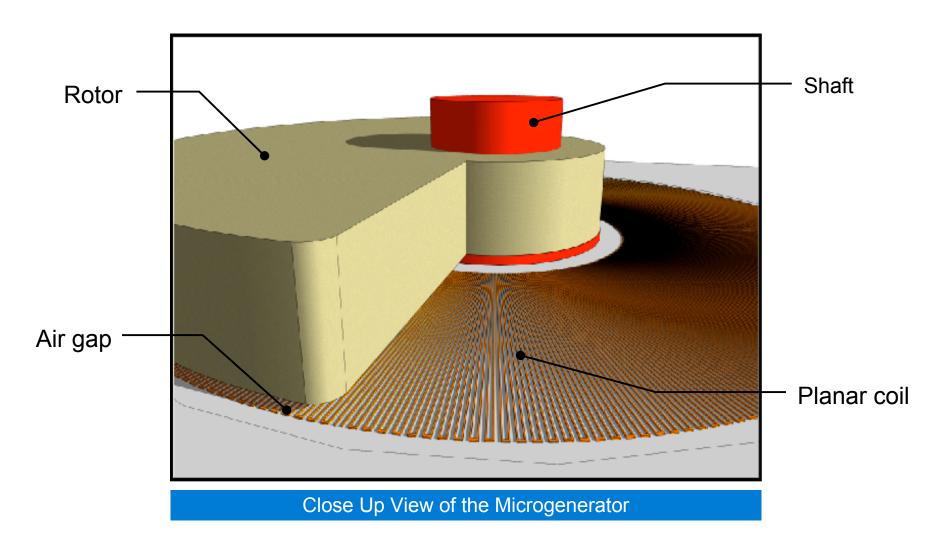
## **Device Operating Principle**



- When the asymmetrical pendulum leaves its initial stable position due to the motion of some body organ, it oscillates for a certain time to finally reach a new stable position
- In the process, a changing axial magnetic field cutting through the underneath planar copper coil induces a voltage across its terminals
- 1. NdFeB embedded SU-8 magnetic pendulum rotor
- 2. Shaft
- 3. Square cross-section planar copper coil
- 4. Substrate
- 5. Contact pads

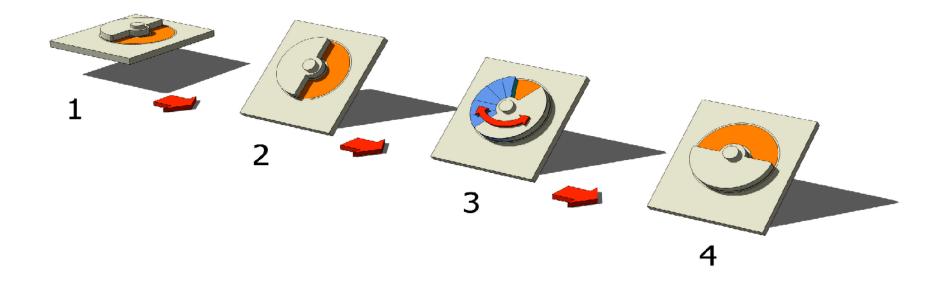


## **Device Operating Principle**





### **Rotor Oscillation**



- 1. Initial stable state
- 2. Excitation
- 3. Oscillation
- 4. New stable state

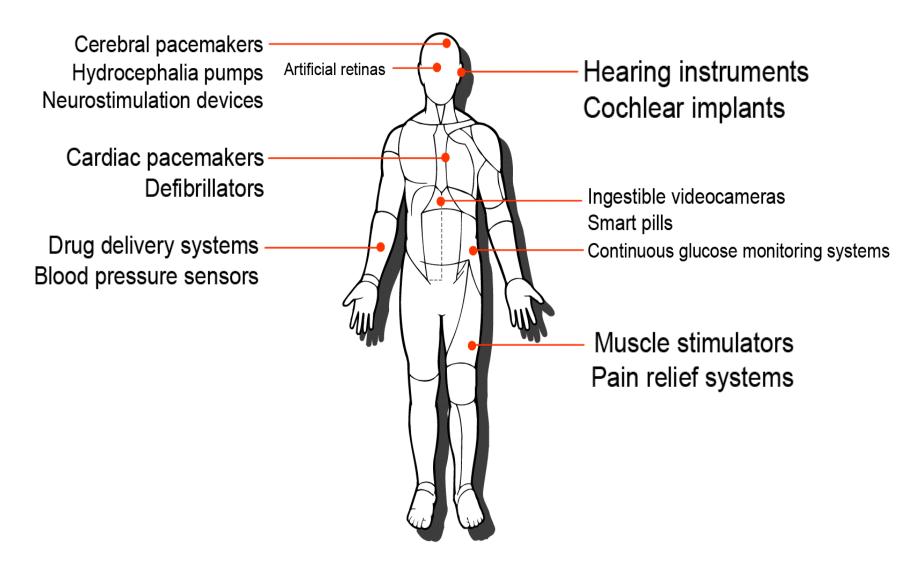


## **Key Advantages**

- A non-toxic clean energy source
- No fluid/gas injection or emissions
- No elastically deformable structures
- Can be completely sealed and shielded in a biocompatible capsule
- High energy density per unit volume
- Much smaller/lighter than existing pacemaker batteries
- Free of self-discharge phenomenon
- Stackable/Scalable to meet higher power demands
- Smaller volume means smaller foreign material inside the body
- Implantation is not restricted to a specific area
- Power generation at any physical posture of a person
- Minimizes frequency of invasive surgery

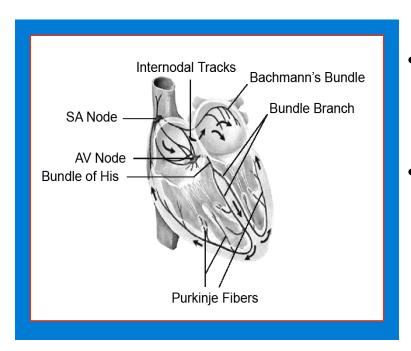


## **Target Applications**





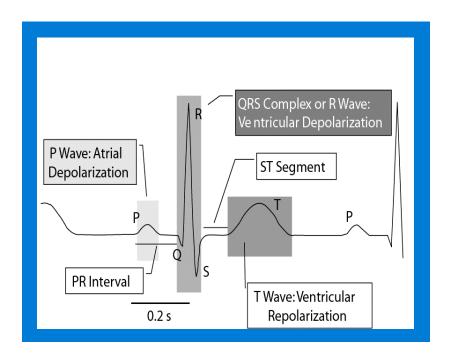
### **Excitation and Conduction System of Human Heart**



- During normal sinus rhythm, the heart is controlled by the Sinoatrial (SA) node (60–100 bpm)
- The right atrial internodal tracks and Bachmann's bundle conduct the SAnodal activation throughout the atria, initiating a coordinated contraction of the atrial walls
- The atrial wall contraction then transfers through the atrioventricular (AV) node
- The Bundle of His then transfers the impulse at a high velocity while splitting the excitation throughout the two ventricles, enabling a coordinated and massive contraction (Ref. [5])



#### **Pacemaker Function**

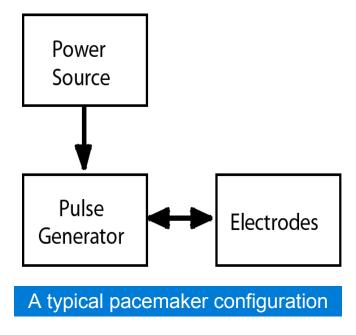


- Arrhythmia entails the abnormal or irregular beating rhythm of the heart due to asynchrony of the cardiac chambers
- A pacemaker is used to restore synchrony between the atria and ventricles by applying controlled electrical pulses to the heart muscles.



### Pacemaker Power Supply: Major Requirements

- For effective pacing, the output pulse should have an appropriate width and sufficient energy to depolarize the myocardial cells close to the electrode
- Many factors affect the longevity of the battery, including primary device settings like pulse amplitude and duration and pacing rate (Ref. [5])



(Ref. [2])



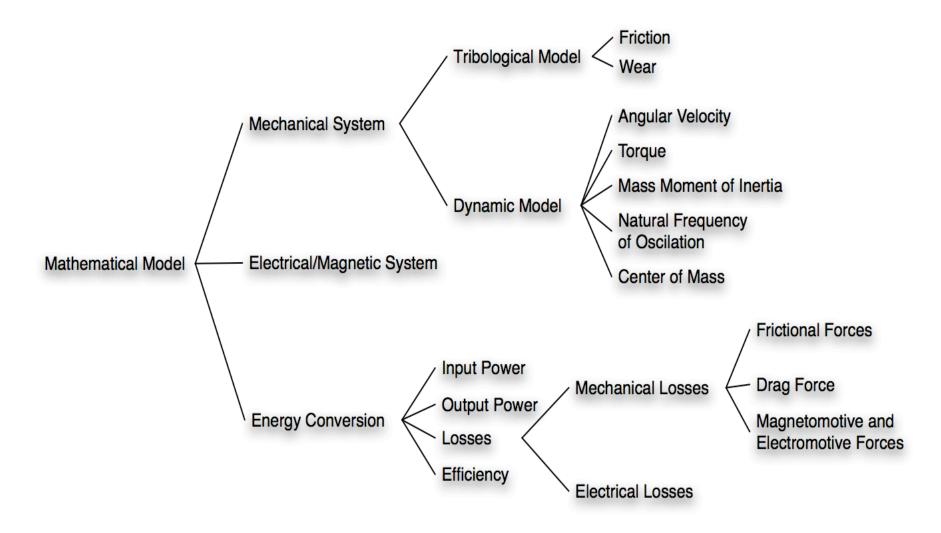
## Typical Commercial Pacemaker Battery Specifications

- Open circuit voltage: 3.0 Volt
- Control circuit minimal voltage: 2.2 Volt
- Control circuit current drain: 10 μA
- Duty cycle: 16.7 %
- Ampere-hour (Ah rating): 2 Ah (typical rating)
- Energy per pulse: 3-6 μJ
- Volume occupied: 5–8 cc
- Effective lifetime: 5 to 7 years

The MEMS microgenerator has been designed to meet the above electrical specifications



## **Design Methodology**





## **Mathematical Modeling**

Induced voltage: 
$$V_{rms} = 2 \beta \sqrt{2} N_p^2 \Omega N_t B S$$

Generated power: 
$$P = \frac{V_{rms}^2}{R}$$

Angular velocity: 
$$\Omega = \frac{4\sqrt{3}}{3} \sqrt{\frac{g \sin(\theta)}{Rp \pi}}$$

- $N_p$  Number of magnetic pole pairs in the pendulum shaped rotor
- $\hat{N_t}$  Number of turns exposed directly to a changing magnetic field
- *B* Magnetic flux density of the air gap
- S Exposed face area
- $\Omega$  Rotor angular velocity
- $\beta$  Shape factor
- R Coil resistance
- *Rp* Radius of pendulum shaped rotor
- $\theta$  Angular displacement

(Ref. [4])



## **Mathematical Modeling**

Shape factor:

$$\beta = \frac{T_{pm}}{T_{pm} + T_{cl} + T_{ag}}$$

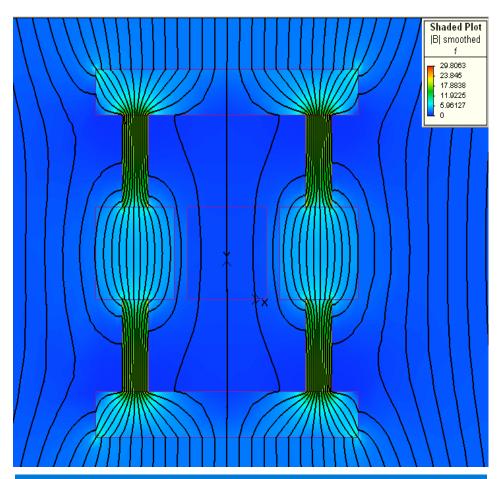
Magnetic flux density of the air gap:  $B = \beta \cdot Br$ 

$$B = \beta \cdot Br$$

 $T_{pm} \\ T_{cl}$ Thickness of permanent magnets Thickness of coil layer Thickness of the air gap  $T_{ag}$ Magnetic pendulum Remanence of the permanent magnets BrShaft  $T_{pm}$ Air gap Planar coil (Ref. [6])



## Magnetization of Pendulum Rotor

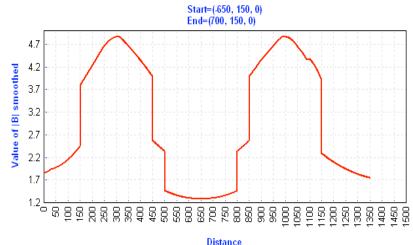


Alternate polarities of NdFeB micromagnets produced by Magnetic Flux Shielding



#### Detail of the Magnetic Pendulum

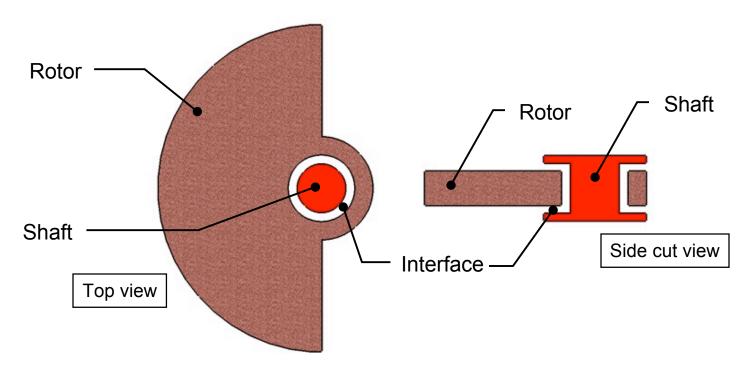
#### **Shaded Plot Field Line Graph**



Magnetic flux density during magnetization



#### Friction Between the Rotor and the Shaft

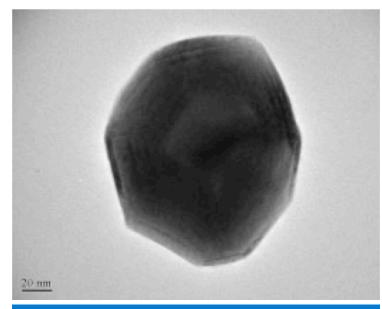


- During operation frictional forces and wear occur at interfacing surfaces of the SU-8 rotor and the shaft.
- A bearing mechanism is necessary to minimize energy losses and excessive wear of the rotor and the shaft.
- A nanotechnology based lubrication system has been chosen instead of conventional microbearings to minimize frictional forces and wear.



## **Lubrication Mechanisms of IF-WS<sub>2</sub> Nanoparticles**

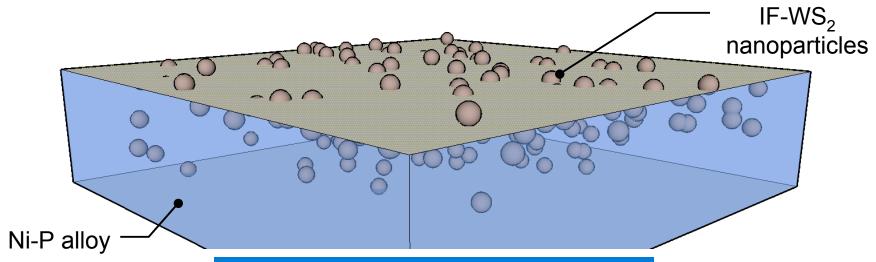
- Inorganic Fullerene-like Tungsten disulphide (IF-WS<sub>2</sub>) nanoparticles blended with a Ni-P alloy are electroless deposited
- During friction, IF-WS<sub>2</sub> particles are slowly released from the Ni-P alloy and serve as sliding spacers between the rotor and the shaft
- Prevent contact between asperities of surfaces and facilitate the removal of wear debris from interface, limiting abrasive wear
- Exfoliation of particles: one-atom thick sheets produce superlubricity effect. (Ref. [7])



Fullerane-like IF-WS<sub>2</sub> Nanoparticle (100 nm wide)



## Nanotechnology-Based Lubrication System



3D Model of the Solid Lubricant Thin Film

	Mass loss	
Coating	of block [mg]	Friction Coefficient
Ni-P	15.6	0.090
$Ni-P-(2H-WS_2)$	5.2	0.062
Ni-P-Graphite	4.3	0.067
Ni-P-(IF-WS <sub>2</sub> )	3.0	0.030

Results of Wear and Friction Coefficient

(Ref. [7])

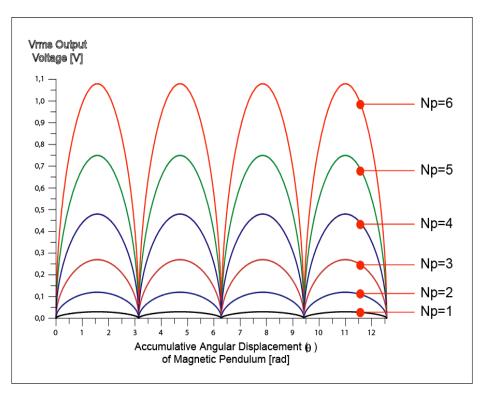


## An Electroless Ni-P-(IF-WS<sub>2</sub>) Composite Coating

- 1. Nickel sulfate: 20-25 g/L
- 2. Sodium hypophosphite: 20-25 g/L
- 3. Sodium acetate: 10-15 g/L
- 4. Acetic acid: 5-10 mL/L
- 5. Surface agent: 200-400 mg/L
- 6. IF-WS<sub>2</sub> Nanoparticles: 6 g/L
- 7. pH: 4.5 5.1
- 8. Temperature: 80 85 °C
- 9. First a Ni-P coating is deposited for 0.5 h
- 10.Then Ni-P-(IF-WS<sub>2</sub>) coating is deposited for 2.5 h
- 11. Annealing for 2 h at 673 °K in vacuum furnace (Ref. [7])



#### **Simulation Results**



Generated Voltage Waveform

The graph shows the quadratic relationship between the output voltage and the angular displacement for different number of magnetic pole pairs inserted in the pendulum



## **Generator Major Design Specifications**

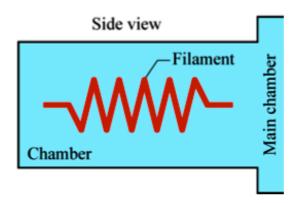
Parameter	Value	
Farameter	Small version	Large version
Generator footprint area	1 mm x 1 mm	2 mm x 2 mm
Magnetic pendulum thickness (μm)	100	100
Pendulum radius (μm)	500	1000
Airgap thickness (μm)	10	10
Coil Cross-section (W x T) (μm)	1 x 1	2 x 2
Number of coil turns under pendulum	259	259
Pendulum angular velocity (max.) (rad/s)	182	129
Total coil reistance ( $k\Omega$ )	3	1.5
Number of pole pairs in pendulum	6	6
Maximum energy product of thin film NdFeB	190 kJ/m <sup>3</sup>	190 kJ/m <sup>3</sup>
RMS output voltage (volts)	1.1	3.0
RMS power	390 μW	6.25 mW



## Deposition of NdFeB thick films

#### NdFeB by Pulsed Laser Deposition

- Deposition rates up to 50 µm / hour
- Remanence up to 1.5 T
- Closely similar composition of target material and prepared films.
- Laser outside chamber allows quick experimentation of laser types and parameters
- Oxidation must be suppressed to preserve magnetic properties

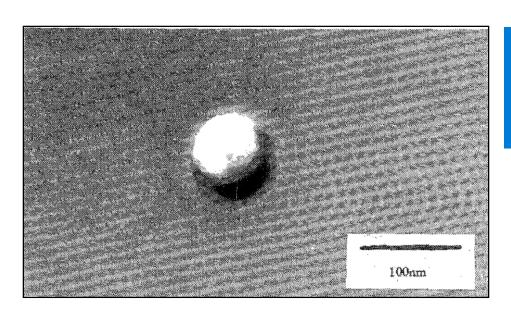


Titanium sublimation vacuum pump for oxidation suppresion

(Ref. [8,10])



## Deposition of NdFeB thick films



Ferrite alpha iron (αFe) droplets on NdFeB film caused by splashing effect of laser ablation.

#### **Drawbacks of PLD technique**

- Splashing effect
- Substrate must be heated, NdFeB film must be annealed at 600°C.
- Films are uniform over a small central area of substrate
- These disadvantages can be overcome

(Ref. [8,10])



## Micromachining of NdFeB films

# NdFeB is a finely grained strongly bonded nanostructured material highly sensitive to corrosion

### Standard photolithography

- Sputter deposited films of thickness up to 10µm can be patterned
- Etchants are nitric acid (HNO<sub>3</sub>) and other highly oxidizing agents.
- Long exposure to etchant deteriorates magnetic properties
- Thick films cannot be patterned with oxidizing etchants

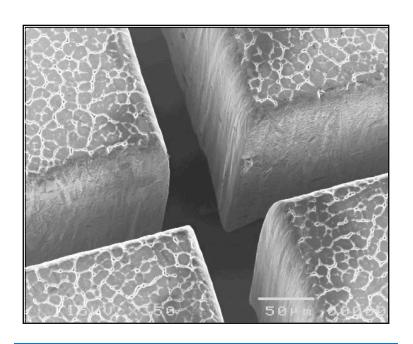
(Ref [8,9])



## Micromachining of NdFeB films

#### Laser micromachining

- Almost any material can be patterned
- Preserves chemical composition and magnetic properties
- Tight tolerance features from a few µm are obtained
- Readily available
- High peak-power short pulses at high pulse repetitions can overcome hardness and transparency of materials.
- No surface pre-treatment is necessary



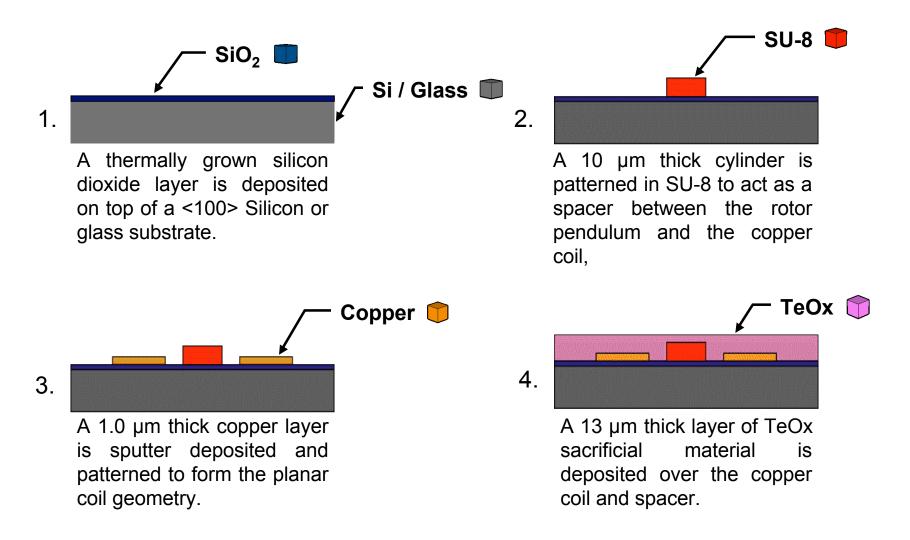
#### Laser machined CVD diamond film

In any case corrosion protective coating must be applied immediately after machining

(Ref [8,9])



#### **Fabrication**





#### **Fabrication**

5.

A 100 µm thick layer of SU-8 is spin deposited and throughetched for subsequent deposition of NdFeB.

7.

A procedure of planarization eliminates the remaining material, exposing the layer of SU-8 again. 6. NdFeB

A thin layer of Tantalum is sputter deposited to act as an adhesion layer for NdFeB. Then, a 100 µm thick NdFeB film is deposited by pulsed laser deposition (PLD) method.

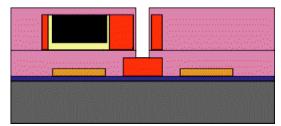
8.

The SU-8 layer is patterned to create the semicircular pendulum-shaped geometry.



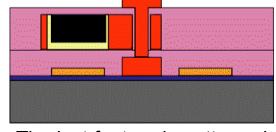
#### **Fabrication**

9.



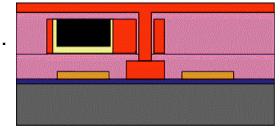
A SiO<sub>2</sub> sacrificial layer is deposited and trenched down to the spacer, leaving a thin film of sacrificial material coating the inner walls of the trench.

11.



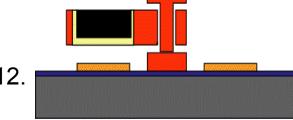
The last feature is patterned on the SU-8 layer to build a cap that holds the pendulum in place.

10.



To form the shaft, a new layer of SU-8 is deposited. The material fills up the trench and reaches the of the spacer same material.

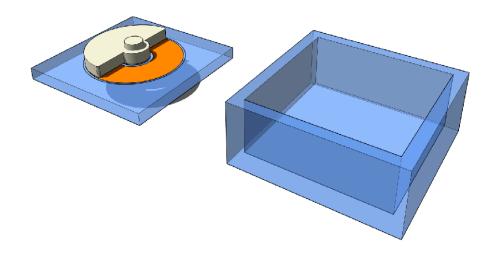
12.



The sacrificial material is dissolved, enabling the pendulum to rotate freely around the shaft.

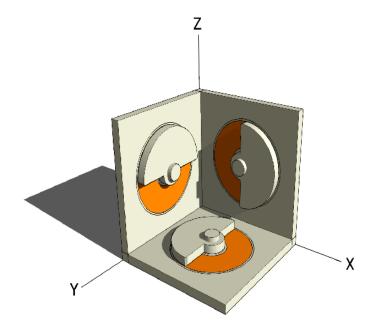


## **Packaging and Mounting**



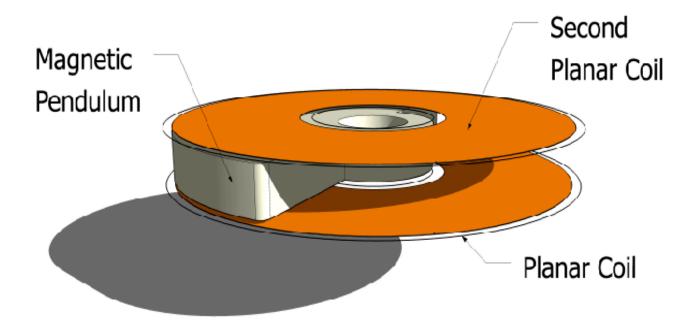
Electromagnetically shielded vacuum sealed package will ensure biocompatibility

A three-axes mounting system will ensure power generation at any physical posture of a person (e.g., standing or laying down on back or on a side)





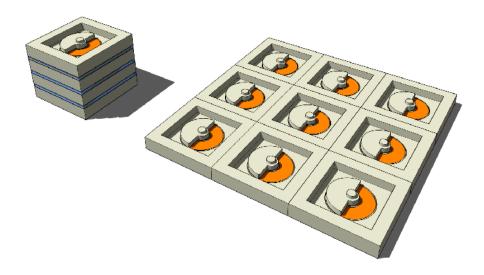
#### **Future Directions**



Two-Coil Microgenerator will be able to generate more power per unit volume



#### **Future Directions**



- Stacks and Arrays of microgenerators will enable to meet higher power demands and fit in a broad number of applications.
- On-board power level sensing: more generators would be cut in to the system by a control circuit if voltage falls below a threshold value.
- Built-in MEMS supercapacitors: energy storage will ensure power availability for the target device over periods of inactivity.



#### **Conclusions**

- The design of a novel MEMS-based axial flux micro power generator for implantable biomedical devices has been presented with a focus on cardiac pacemaker applications
- In the system, a semicircular magnetic pendulum oscillates around a central shaft due to body motion, for example, the thorax movement during breathing or head turning, to induce a voltage across an underlying copper coil
- A 1 mm $^2$  footprint area device can generate 390  $\mu W$  of power with an open circuit RMS voltage of 1.1 volts
- Scaled or stacked versions can be used to satisfy power requirements for other implantable device applications
- The device can provide a greater energy supply per unit volume compared to existing pacemaker batteries and can aid in developing smaller pacemakers
- Maintenance free longer life minimizes frequency of invasive surgery as necessary for conventional pacemaker replacement due to battery exhaust.
- Further development of the device is in progress



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