

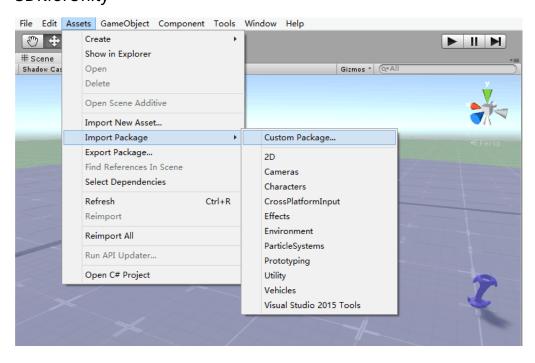
STEPVR SDK 使用说明(C#)

1 运行环境

- 1.1 硬件环境: StepVR 标准件, StepVR 手柄, OculusCV1 头显
- 1.2 软件环境: Unity5.3.4 及以上

2 SDK 导入

在 Unity 中导入 SDK, 点击 Assets->Import Package->Custom Package..., 选择 SDKforUnity





3 SDK 使用

- 3.1 引用命名空间: using StepVRSDKUnity;
- 3.2 数据类型:

```
struct V3 {

public float x;

public float y;

public float z;
}
```

说明:声明三元数的数据类型

```
struct V4 {

public float x;

public float y;

public float z;

public float w;
}
```

说明:声明四元数的数据类型



```
public enum EquipmentNode {
    Head = 6,
    Hand = 4,
    LeftController = 1,
    RightController = 2
}
```

说明:设备类别

3.3 实例化 StepVRManager

实例化 StepVRManager 类后可调用获取 stepVR 硬件数据的方法.(注:只能实例化一次)

3.4 全部方法

```
void StartSDK()
说明:启动 stepVRsdk;
(注:建议在 Awake()或 Start()中调用)
```

```
void StopSDK()
说明:停用 stepVRsdk;
(注:建议在 OnDestroy()中调用)
```



V3 GetPosition(EquipmentNode node)

说明:获取设备位置数据.

参数:设备类别

返回值:V3 类型的 x,y,z 轴坐标

V3 GetRotation(EquipmentNode node)

说明:获取设备姿态数据.

参数:设备类别

返回值:V3 类型的 x,y,z 轴坐标

V4 GetQuaternion(EquipmentNode node)

说明:获取设备姿态数据.

参数:设备类别

返回值:V4 类型的 x,y,z,w 轴坐标

bool GetTriggerDown(EquipmentNode node, string key)

说明:获取按键按下状态(按下)

参数:设备类别,按键名(A,B,C)

返回值:是否按下,按下为 true,未按下为 false



bool GetTrigger(EquipmentNode node, string key)

说明:获取按键按住状态(长按)

参数:设备类别,按键名(A,B,C)

返回值:是否按下,按下为 true,未按下为 false

bool GetTriggerUp(EquipmentNode node, string key);

说明:获取按键抬起状态(抬起)

参数:设备类别,按键名(A,B,C)

返回值:是否抬起,抬起为 true,未抬起为 false

4 示例程序:

4.1 写一个单独脚本 StepVRSingleton.cs,包含如下:

```
//设备的ID
public EquipmentNode gunID;//枪的ID
public EquipmentNode leadID;//头的ID
public EquipmentNode lettControllerID;//左手手柄的ID
public EquipmentNode rightControllerID;//左手手柄的ID
public EquipmentNode rightControllerID;//右手手柄的ID

//两个手柄的按键信息
public bool handAKeyADown;
public bool handAKeyBDown;
public bool handAKeyBDown;
public bool handBKeyDown;
```



```
//实例化一个StepVRManager
StepVRManager manager = new StepVRManager();
public bool Start()
     if (manager == null)
        return false;
        manager.StartSDK();
        return true;
public Vector3 EquipmentPosition(EquipmentNode node) {
    return new Vector3 (manager.GetPosition(node).x, manager.GetPosition(node).y, manager.GetPosition(node).z);
public Quaternion EquipmentRotation(EquipmentNode node)
    return Quaternion. Euler (new Vector3 (manager.GetRotation(node).x, manager.GetRotation(node).y, manager.GetRotation(node).z));
public bool Trigger (EquipmentNode node, string key)
    return manager.GetTrigger(node, key);
public bool TriggerDown (EquipmentNode node, string key)
    return manager.GetTriggerDown(node, key);
public bool TriggerUp(EquipmentNode node, string key)
    return manager.GetTriggerUp(node, key);
```

4.2 再写一个 palyer.cs 脚本,绑定在人物上

```
0 个引用
void Start()
{
SetRoomSize(StepVRSingleton.Instance.x, StepVRSingleton.Instance.z);
if (!isSDKStart)
{
//调用SDK, 启用StepVRSdk, StartSDK()函数再Start()函数内
isSDKStart = StepVRSingleton.Instance.Start();
}

Vector3 headPosition = GetNodePosition(StepVRSingleton.Instance.headID);
//输出头部数据,头部定位件的位置信息
txHead.text = "失:\nx: " + headPosition.x + "\ny: " + headPosition.y + "\nz: " + headPosition.z;
//transform.position = new Vector3(0, headPosition.y, 0);
headJoint.localPosition = new Vector3(0, headPosition.y, 0);

//CheckIfOutOfBound(headPosition.x, headPosition.z);
//输出枪的数据,枪上定位件的位置信息
gunJoint.position = GetNodePosition.
txtGun.text = "枪位移:\nx: " + gunJoint.position.x + "\ny: " + gunJoint.position.y + "\nz: " + gunJoint.position.z;
//枪上定位件的姿态信息
gunJoint.rotation = GetNodePosition.(StepVRSingleton.Instance.gunID);
txtGunRot.text = "枪姿态:\nx: " + gunJoint.rotation.x + "\ny: " + gunJoint.rotation.y + "\nz: " + gunJoint.rotation.z;
UpdateText();
CastRay();
```

*此为保密文件。未经北京国承万通信息科技有限公司书面许可,不可分享外流。



```
//开火,枪的按键检测
    | GetKey(StepVRSingleton.Instance.gunID, "A") | GetKey(StepVRSingleton.Instance.gunID, "A") | Input.GetMouseButton(1))
         if (guns[currenGunIndex].isActiveAndEnabled)
  guns[currenGunIndex].Shoot();
         if (currentPointingButton)
             currentPointingButton.ToggleButton();
    //获取手柄信息
    if (leftController.activeSelf && rightController.activeSelf)
         handA.position = GetNodePosition(StepVRSingleton.Instance.leftControllerID);//手柄A的位置
        //判断按键
         if (GetKeyDown(StepVRSingleton. Instance. leftControllerID, "A"))

|| GetKey(StepVRSingleton. Instance. leftControllerID, "A"))
             txtTriggerA.text = "handA技罐信息:A";
Debug.Log("handA技罐信息:A");
StepVRSingleton.Instance.handAKeyADown = true;
         if (GetKeyDown(StepVRSingleton.Instance.leftControllerID, "B"))
|| GetKey(StepVRSingleton.Instance.leftControllerID, "B"))
             txtTriggerB.text = "handA按键信息:B";
Debug.Log("handA按键信息:B");
StepVRSingleton.Instance.handAKeyBDown = true;
         if (GetKeyDown(StepVRSingleton.Instance.leftControllerID, "C") || GetKey(StepVRSingleton.Instance.leftControllerID, "C"))
             txtTriggerC.text = "handA按键信息:C";
Debug.Log("handA按键信息:C");
StepVRSingleton.Instance.handAKeyCDown = true;
Instantiate(ballA, handA.position, Quaternion.identity);//按住则实例化小球
0 个引用
void OnDestroy()
    //关闭SDK,停用StepVRsdk,StopSDK()函数在Stop()函数内
    StepVRSingleton. Instance. Stop();
//获取定位点位置数据,使用GetPosition(EquipmentNode node)
Vector3 GetNodePosition(EquipmentNode node)
    return StepVRSingleton. Instance. EquipmentPosition(node);
//获取定位点姿态数据,使用EquipmentRotation(EquipmentNode node)
Quaternion GetNodeRotation(EquipmentNode nodeIndex)
    return StepVRSingleton.Instance.EquipmentRotation(nodeIndex);
//获取手柄按键状态,使用Trigger(EquipmentNode node, string key)
bool GetKey(EquipmentNode node, string key)
    return StepVRSingleton.Instance.Trigger(node, key);
//获取手柄按键按下状态,使用TriggerDown(EquipmentNode node, string key)
bool GetKeyDown(EquipmentNode node, string key)
    return StepVRSingleton.Instance.TriggerDown(node, key);
,
//获取手柄按键抬起状态,使用TriggerUp(EquipmentNode node, string key)
bool GetKeyUp(EquipmentNode node, string key)
```