

# Physics Problem Solving

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# Water Tank

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*Question.* A tank contains water to a depth of 1.0m. Water emerges from a small hole in the vertical side of the tank at 20cm below the surface.

Determine:

- 1 the speed at which the water emerges from the hole
- 2 the distance from the base of the tank at which the water strikes the floor on which the tank is standing.

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*Question.* A tank contains water to a depth of  $H$ . Water emerges from a small hole in the vertical side of the tank at  $h$  above ground. Determine the envelope formed by the trajectories of the water.

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- ① A circle, bending outwards (convex).
- ② A circle, bending inwards (concave).
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- ④ A straight line.
- ⑤ A hyperbola.

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► Desmos Demo

# Solution

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First, it is not difficult to see that the trajectory of the water satisfies the parametric equation

$$(x, y) = \left( \sqrt{2g(H-h)}t, h - \frac{gt^2}{2} \right).$$

If we re-arrange the equation to find  $t$  in terms of  $x$ , we have

$$t = \frac{x}{\sqrt{2g(H-h)}},$$

and plugging this back for  $y$  gives us the explicit Cartesian equation

$$y = h - \frac{x^2}{4(H-h)}.$$

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# Alternative Approach

We reach the parametric equation

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$$(x, y) = \left( \sqrt{2g(H-h)}t, h - \frac{gt^2}{2} \right).$$

We notice that

$$\begin{aligned} x + y &= -\frac{gt^2}{2} + \sqrt{2g(H-h)}t + h \\ &\leq \frac{-2gh - 2g(H-h)}{-2g} \\ &= H \end{aligned}$$

from basic property of a quadratic curve.

*Quadratic Curve.* For a quadratic curve with equation

$$y = ax^2 + bx + c, a \neq 0$$

its vertex will be the point with coordinate

$$\left( -\frac{b}{2a}, \frac{4ac - b^2}{4a} \right).$$



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# Series Springs

We have learnt in class that the formula for the resultant spring constant  $k$  and resultant initial length  $l$  of springs with spring constants  $k_1, k_2, \dots, k_n$  and initial lengths  $l_1, l_2, \dots, l_n$  being in series satisfies that

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$$\frac{1}{k} = \sum_{i=1}^n \frac{1}{k_i}, l = \sum_{i=1}^n l_i.$$

# Series Springs

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Therefore, the total extension will satisfy

$$x = \sum_{i=1}^n x_i = F \sum_{i=1}^n \frac{1}{k_i},$$

and therefore the resultant spring constant satisfies

$$\frac{1}{k} = \frac{x}{F} = \sum_{i=1}^n \frac{1}{k_i}.$$

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*In some time, we will soon see that the red text is completely useless.*

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and therefore

$$k = \frac{F}{x} = \sum_{i=1}^n k_i.$$

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Naturally, questions will arise to us: if multiple springs are in parallel, with one end connected to a wall, and the other end connected to a, let's say, thin plastic board, and we investigate this resultant spring setup:

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- 1 what will happen if they have **different initial lengths**?
- 2 what will happen if they not only have different initial lengths, but also different spring constants?

*Question.* Say if there are springs with spring constant  $k_1, k_2, \dots, k_n$  and with different initial lengths,  $l_1, l_2, \dots, l_n$  connected together with the previously said setup,

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- ① what is the new initial length of the resultant spring  $l$ ,
- ② what is the new spring constant?

*You may consider that the springs are ideally attached at the same point between the wall and the plastic board, so no rotation has to be taken into account.*

# Solution

*Solution.* Say that the new spring has a new initial length  $l$ . Then the extension in each spring satisfies that

$$x_i = l - l_i,$$

and therefore the force provided by each spring satisfies that

$$F_i = k_i x_i = k_i(l - l_i).$$

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Since it is the new initial length,  $l$  must satisfy that

$$F = \sum_{i=1}^n F_i = 0,$$

which means that

$$\sum_{i=1}^n k_i l = \sum_{i=1}^n k_i l_i,$$

and that  $l$  is the weighted arithmetic mean of the  $l_i$ s.

# Solution

Now consider the new spring constant. If the spring is extended by a new  $\Delta x$ , then the extra force provided by each spring will be equal to

$$\Delta F_i = k_i \Delta x,$$

which results in a resultant change in force of

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This gives the same result of the original formula where they have the same initial lengths.

# Some Comments

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I think one of the most important reasons is that  $F \propto x$ , i.e., the linearity of the Hooke's law gives us a lot of nice properties, including the fact that any resultant combination is in fact obeying the Hooke's law.

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A nice example might be the fact that non-ohmic resistors typically do not observe the series circuit law of resistances (non-linearity).

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## Question 2

The pulley system in the figure consists of two pulleys of radii  $a$  and  $b$  rigidly fixed together, but free to rotate about a common horizontal axis. The weight  $W$  hangs from the axle of a freely suspended pulley  $P$ , which can rotate about its axle. If section  $A$  of a rough rope is pulled down with velocity  $V$ :

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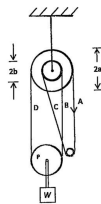


Figure: Pulley System

# Solution

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However, we cannot say that rope  $B$  moves downwards with speed  $V$ .

Since the two pulleys of radii  $a$  and  $b$  are rigidly fixed together, they must rotate with the same angular velocity,  $\omega_a = \omega_b$ .

$$V = \omega_a a \Rightarrow \omega_a = \frac{V}{a} \quad \text{and} \quad V_B = \omega_b b.$$

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Substituting  $\omega_a = \frac{V}{a}$  into the expression for  $V_B$  using  $\omega_a = \omega_b$ ,

$$V_B = \omega_b b = \omega_a b = \frac{V}{a} b.$$

# Solution

$W$  rises as a result of the difference in speeds of ropes  $D$  and  $B$  since a greater length of rope  $D$  is pulled than length of rope  $B$  is pushed in a given time.

Therefore, the centre of  $P$  and  $W$  rise with speed  $V_W$ ,

$$V_W = \frac{1}{2} \left( V - \frac{b}{a} V \right)$$

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$$V_W = V \left( \frac{a - b}{2a} \right).$$

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The factor of a half is required because length of rope on both sides of  $W$  must decrease by a length  $l$  for  $W$  to rise a length  $W$ .