Steady-State

Fixed-point in the absence of shocks

Steady-State Recipe

1.
$$\bar{A} = 1$$

2.
$$M\bar{C} = 1$$

3.
$$\bar{R} = \frac{1}{\beta} + \delta - 1$$

$$4. \quad \frac{\bar{K}}{\bar{L}} = \left(\frac{\bar{\alpha}\bar{A}}{\bar{R}} \right)^{\frac{1}{1-\alpha}}$$

5.
$$\bar{W} = \bar{M}C(1 - \alpha)\bar{A}\left(\frac{\bar{K}}{\bar{L}}\right)^{\alpha}$$

$$6.\frac{\bar{I}}{\bar{L}} = \delta \frac{\bar{K}}{\bar{L}}$$

$$7.\frac{\bar{Y}}{\bar{L}} = \bar{A} \left(\frac{\bar{K}}{\bar{L}}\right)^{\alpha}$$

$$8.\frac{\bar{C}}{\bar{L}} = \frac{\bar{Y}}{\bar{L}} - \frac{\bar{I}}{\bar{L}}$$

Steady-State Recipe

8. Log-utility (determine
$$\bar{L}$$
 analytically): $\bar{L} = \frac{\frac{\gamma}{\psi} \left(\frac{\bar{C}}{\bar{L}}\right)^{-1} \bar{W}}{1 + \frac{\gamma}{\psi} \left(\frac{\bar{C}}{\bar{L}}\right)^{-1} \bar{W}}$

8. CES-utility (determine
$$\bar{L}$$
 numerically): $\bar{W}\left(\frac{\bar{C}}{\bar{L}}\right)^{-\eta_C} = \frac{\psi}{\gamma}(1-\bar{L})^{-\eta_L}\bar{L}^{\eta_C}$

9. Remaining variables:
$$\bar{C} = \frac{\bar{C}}{\bar{L}}\bar{L}$$
, $\bar{I} = \frac{\bar{I}}{\bar{L}}\bar{L}$, $\bar{K} = \frac{\bar{K}}{\bar{L}}\bar{L}$, $\bar{Y} = \frac{\bar{Y}}{\bar{L}}\bar{L}$