# **Dongho Kang**

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### RESEARCH INTERESTS

My research aims to create legged robots that produces natural and animal-like motions. Thus, my research interests are broad ranging to legged locomotion control, character animation and design optimization for robotics applications.

#### **EDUCATION**

### ETH Zürich, Zurich, Switzerland

Doctoral Student in Computer Science
 Main advisor: Prof. Dr. Stelian Coros

Apr 2020 – Present

Main advisor: Prof. Dr. Stellan Coros
 Second advisor: Prof. Dr. Marco Hutter

■ M.Sc. ETH in Mechanical Engineering Sep 2016 – Aug 2019

Advisor: Prof. Dr. Marco Hutter

· Graduated with distiction

### Seoul National University, Seoul, South Korea

■ B.Sc. in Mechanical Engineering and B.Sc. in Computer Science Mar 2009 – Aug 2016

Dec 2019 – Present

Sep 2014 - Jan 2016

• Advisor: Prof. Dr. Dongjun Lee

• Graduated with honor (Cum Laude)

### RESEARCH EXPERIENCE

### Computational Robotics Lab, ETH Zürich

Scientific Assistant

Supervisor: Prof. Dr. Stelian CorosControl methods for animal-like motions of bio-inspired quadrupedal robots.

Robotic Systems Lab, ETH Zürich

■ Master's Student Sep 2017 – Nov 2019

• Supervisors: David Höller, Dr. Jemin Hwangbo and Prof. Dr. Marco Hutter

• Learning-based collision avoidance for a legged robot.

• Participated in the development of RaiSim: a physics engine for robotics and AI research.

### Interactive & Networked Robotics Lab, Seoul National University

Undergraduate Research Assistant

• Supervisors: Prof. Dr. Dongjun Lee

• State estimation and control strategies for multi-robot cooperative systems

### PROFESSIONAL AFFILIATIONS & ACTIVITIES

### **NVIDIA**, Zurich, Switzerland

■ Deep Learning Intern Jun 2018 – Dec 2018

• Projects: Deep learning-based super-resolution and anti-aliasing.

### LeisureQ Inc., Seoul, South Korea

■ Software Engineer Intern Jan 2016 – Sep 2016

• Projects: Backend web application for E-commerce website Gajago.

### **CNP Technology Inc.**, Seoul, South Korea

■ Hardware and CAD Engineer Jan 2016 – Sep 2016

### PUBLICATIONS CONFERENCES

- [1] Dongho Kang, Flavio De Vincenti, Naomi C. Adam, and Stelian Coros, "Animal Motions on Legged Robots Using Nonlinear Model Predictive Control," in *International Conference on Intelligent Robots and Systems (IROS)*, Oct 2022.
- [2] Dongho Kang, Simon Zimmermann, and Stelian Coros, "Animal Gaits on Quadrupedal Robots using Motion Matching and Model-Based Control," in *International Conference on Intelligent Robots and Systems (IROS)*, Sep 2021.
- [3] Flavio De Vincenti, <u>Dongho Kang</u>, and Stelian Coros, "Control-Aware Design Optimization for Bio-Inspired Quadruped Robots," in *International Conference on Intelligent Robots and Systems (IROS)*, Sep 2021.

[4] Changu Kim, Hyunsoo Yang, Dongho Kang and Dongjun Lee, "2-D Cooperative Localization with Omni-Directional Mobile Robots," in *International Conference on Ubiquitous Robots and Ambient Intelligence*, Goyang, South Korea, Oct 2015.

#### WORKSHOP

[1] Dongho Kang, Flavio De Vincenti, and Stelian Coros, "Nonlinear Model Predictive Control for Quadrupedal Locomotion Using Second-Order Sensitivity Analysis," in *ICRA 2022: 6th Full-Day Workshop on Legged Robots*, May 2022.

### **THESIS**

[1] Dongho Kang, "End-to-End Collision Avoidance from Depth Input with Memory-based Deep RL," Master's thesis, the Department of Mechanical and Process Engineering, ETH Zürich, Aug 2019.

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INVITED TALK

• Robot Intelligence Lab, Korea University, Seoul, South Korea Apr 2021

■ NAVER LABS Corp., Seoul, South Korea Dec 2019

Max Planck ETH Center for Learning Systems Symposium, Tübingen, Germany

## AWARDS & SCHOLARSHIPS

Birkigt Scholarship, ETH Zürich
 Stipendiams scholarship for intermetional masters

Feb 2018

Stipendiary scholarship for international master student.

Aug 2014

Feb 2010

Eminence Scholarship, Seoul National University
 Full-tuition scholarship for one academic semester for outstanding academic performance.

Development Fund Scholarship, Seoul National University

Full-tuition scholarship for one academic year for outstanding academic performance.

### TEACHING EXPERIENCE

### ETH Zürich, Zurich, Switzerland

Teaching Assistant, Linear Algebra (Ö. Imamoglu, O. Sorkine-Hornung)
 Teaching Assistant, Computational Models of Motion (S. Coros, B. Thomaszewski)
 2021 – 2022

■ Teaching Assistant, Visual Computing (S. Coros, M. Pollefeys) 2020 – 2022

### Seoul National University, Seoul, South Korea

Mentor, SNU Samsung Convergence Software Course Program

2015

■ Teaching Assistant, MAE 446.204A: Dynamics 2014

■ Teaching Assistant, PA 034.013: Basic Physics 2 Autumn 2011

### **LANGUAGES**

• Korean: Native language.

• English: Fluent.

# TECHNICAL SKILLS

### **Programming and Software**

C/C++, C#, Python, Matlab/Octave, Unix/Linux, Tensorflow, Pytorch, ROS, Open Dynamics Engine, Unity

### **Experience with Robots**

UnitreeRobotics Aliengo, A1, Go1, ANYbotics ANYmal

### REFERENCES

### ■ Prof. Dr. Stelian Coros

Associate Professor in the Department of Computer Science

ETH Zürich

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### Prof. Dr. Marco Hutter

Associate Professor in the Department of Mechanical and Process Engineering ETH Zürich

Leonhardstrasse 21, 8092 Zurich, Switzerland mahutter@ethz.ch • +41 44 632 74 17

### ■ Prof. Dr. Jemin Hwangbo

Assistant Professor in the Department of Mechanical Engineering Korea Advanced Institute of Science and Technology jhwangbo@kaist.ac.kr

### ■ Prof. Dr. Dongjun Lee

Professor in the Department of Mechanical Engineering Seoul National University 1 Gwanak-Ro, Gwanak-Gu, Seoul, 08826, South Korea djlee@snu.ac.kr • +82 2 880 1724