Image Mosaic and Stitching

Yiren(Max) Lu - 11/29/2016



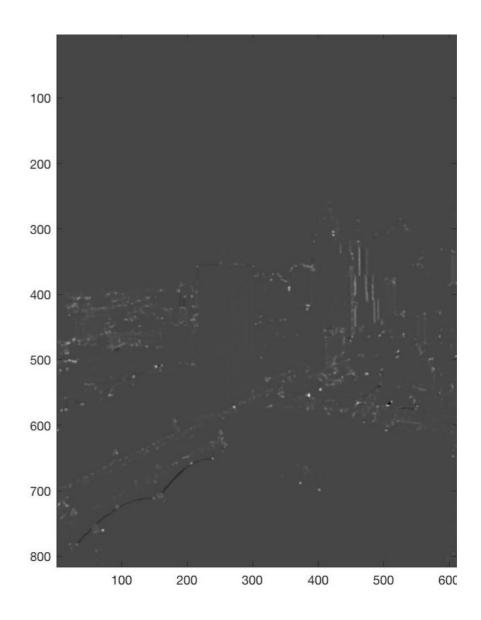
Image Mosaic Overview

- 1. Harris Corner Detection
- 2. Adaptive Non-Maximum Suppression (ANMS)
- 3. Feature Descriptors Extraction
- 4. Features Matching
- 5. Outliers Rejection (RANSAC)
- 6. Final Image Stitching (Homographic Trans.)



Harris Corner Detection



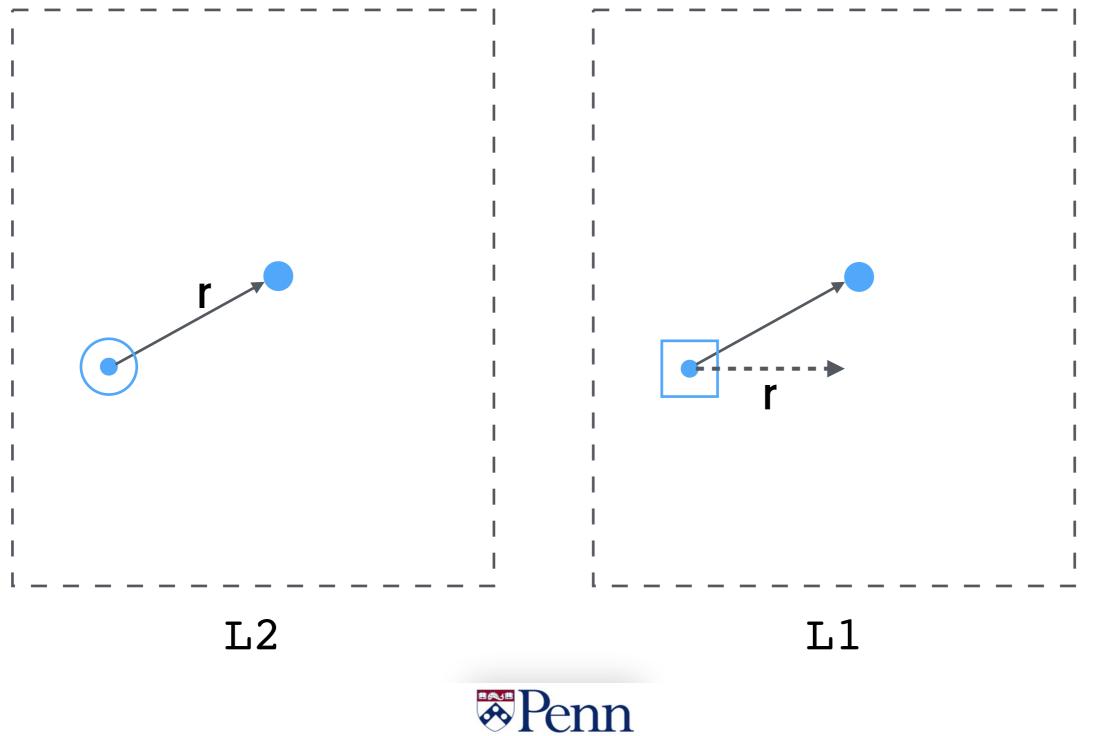


cimg = cornermetric(img, 'Harris');



Adaptive Non-Maximum Suppression (ANMS)

Breath-First Search





Adaptive Non-Maximum Suppression (ANMS)

Vectorization

```
for i = 1:H
for j = 1:W
  for r = 1:min(H,W)
    if cimg(i, j) == 0
        r_mat(i, j) = 1;
        break;
end
  if any(cimg(max(1,i-r):min(H,i+r), max(1,j-r)) > cimg(i,j)) > 0 | ...
        any(cimg(max(1,i-r):min(H,i+r), min(W,j+r)) > cimg(i,j)) > 0 | ...
        any(cimg(max(1,i-r), max(1,j-r):min(W,j+r)) > cimg(i,j)) > 0 | ...
        any(cimg(min(H,i+r), max(1,j-r):min(W,j+r)) > cimg(i,j)) > 0
        r_mat(i, j) = r;
        break;
    end
end
```

640x480 img: 52s -> 1s

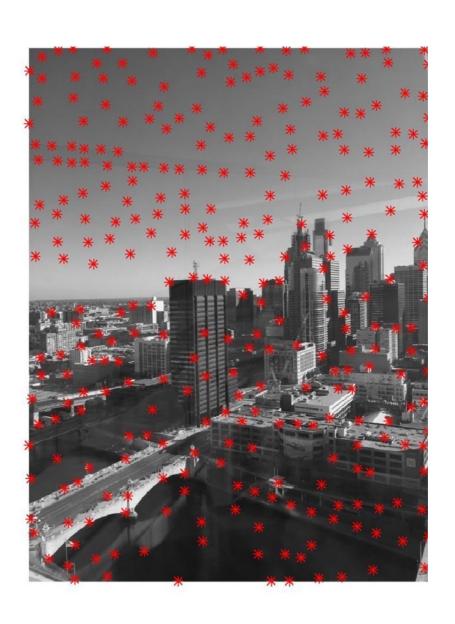


end

en

Adaptive Non-Maximum Suppression (ANMS)





left: 100 key points, right: 300 key points



Feature Descriptors

Geometric Blur

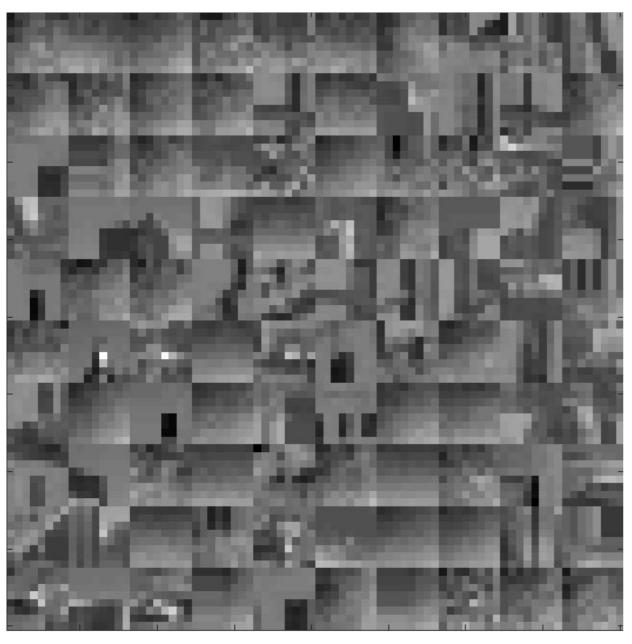


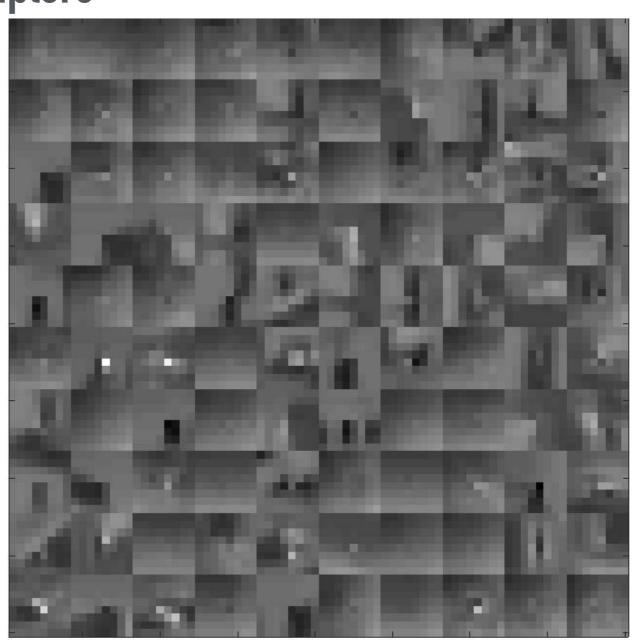




Feature Descriptors

Descriptors



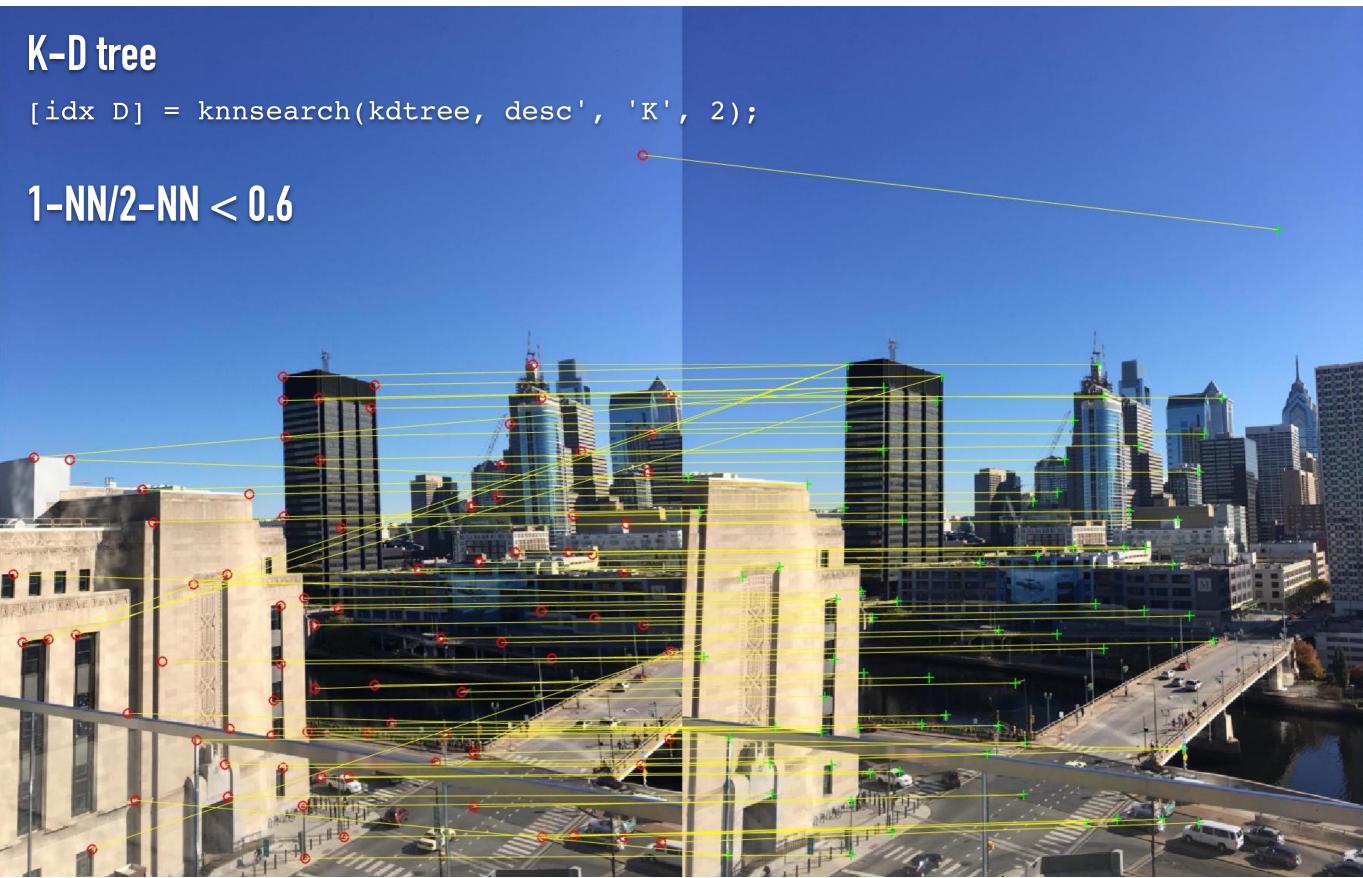


non-geo blur

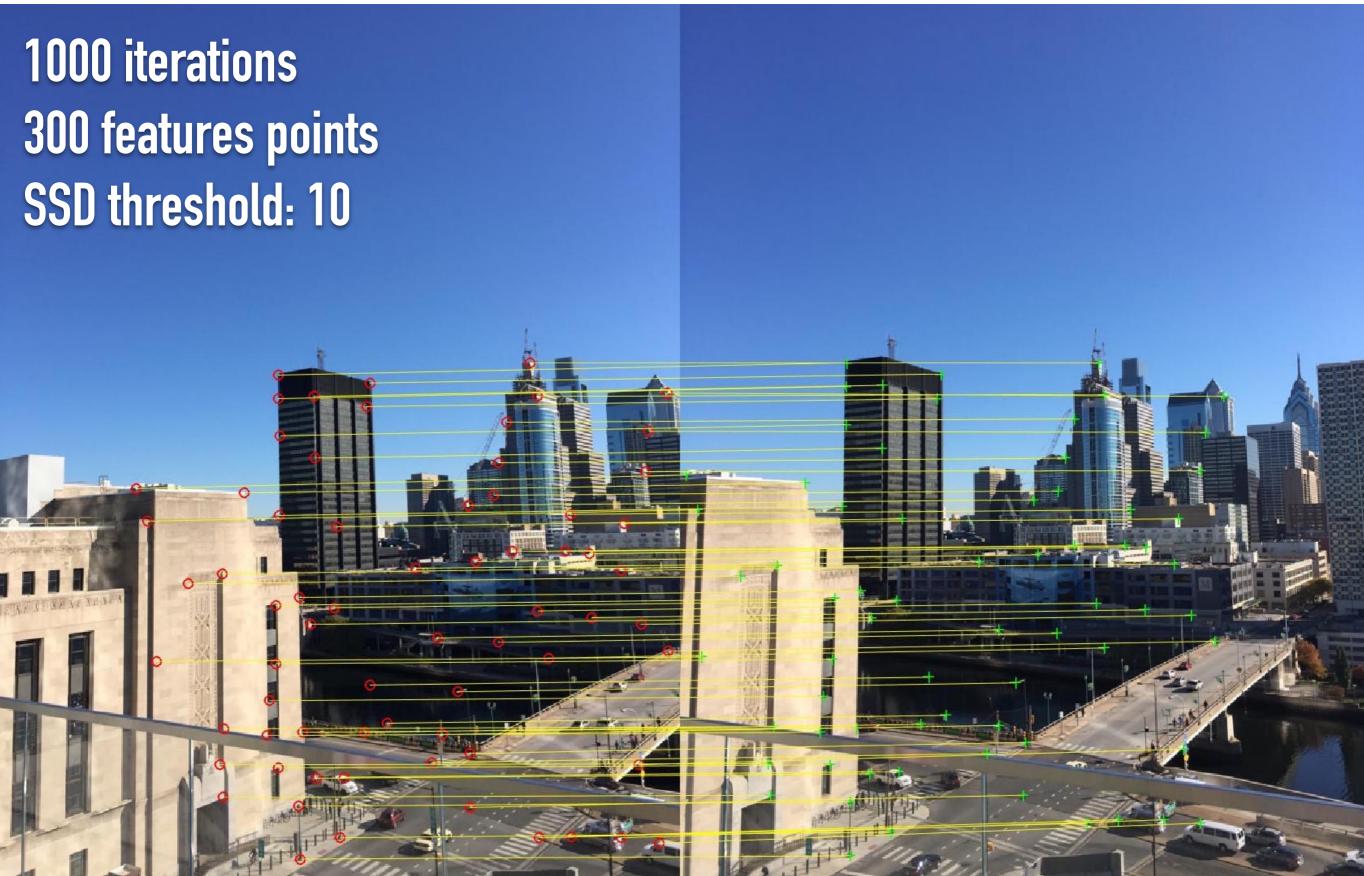
geometric blur



Features Points Matching



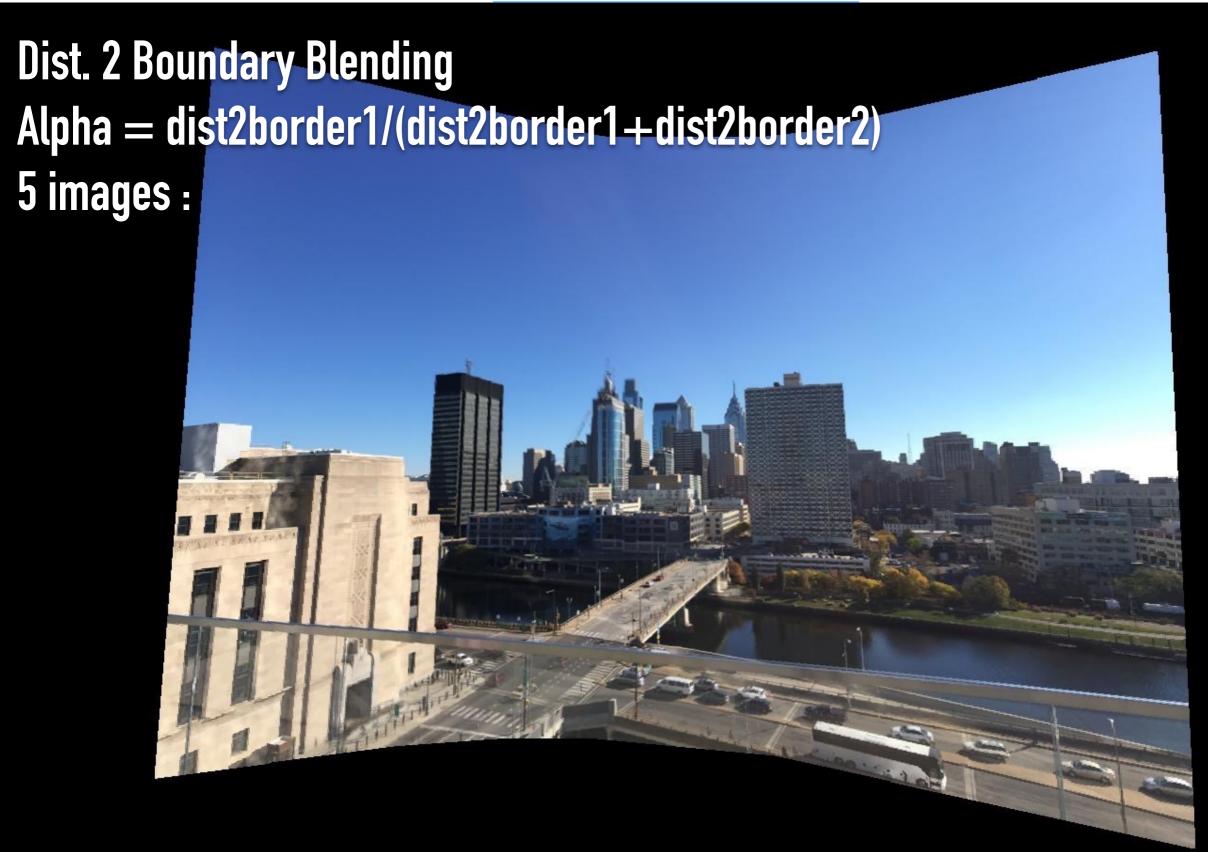
Features Points Matching (RANSAC)



Final Image Stitching

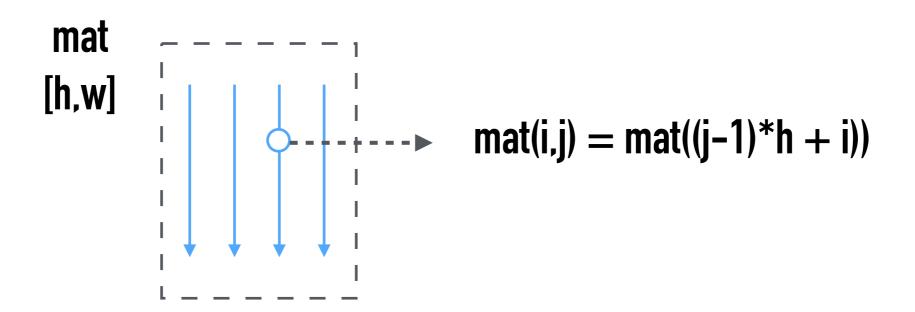


Final Image Stitching (blending)



Vectorization

Vectorization = **Treat Everything as a Vector!**

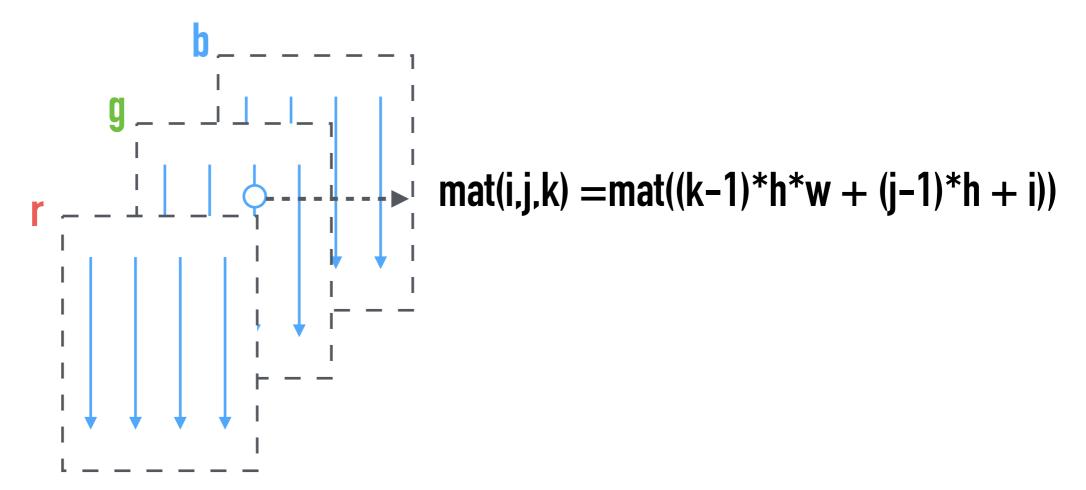




Vectorization

Vectorization = **Treat Everything as a Vector!**

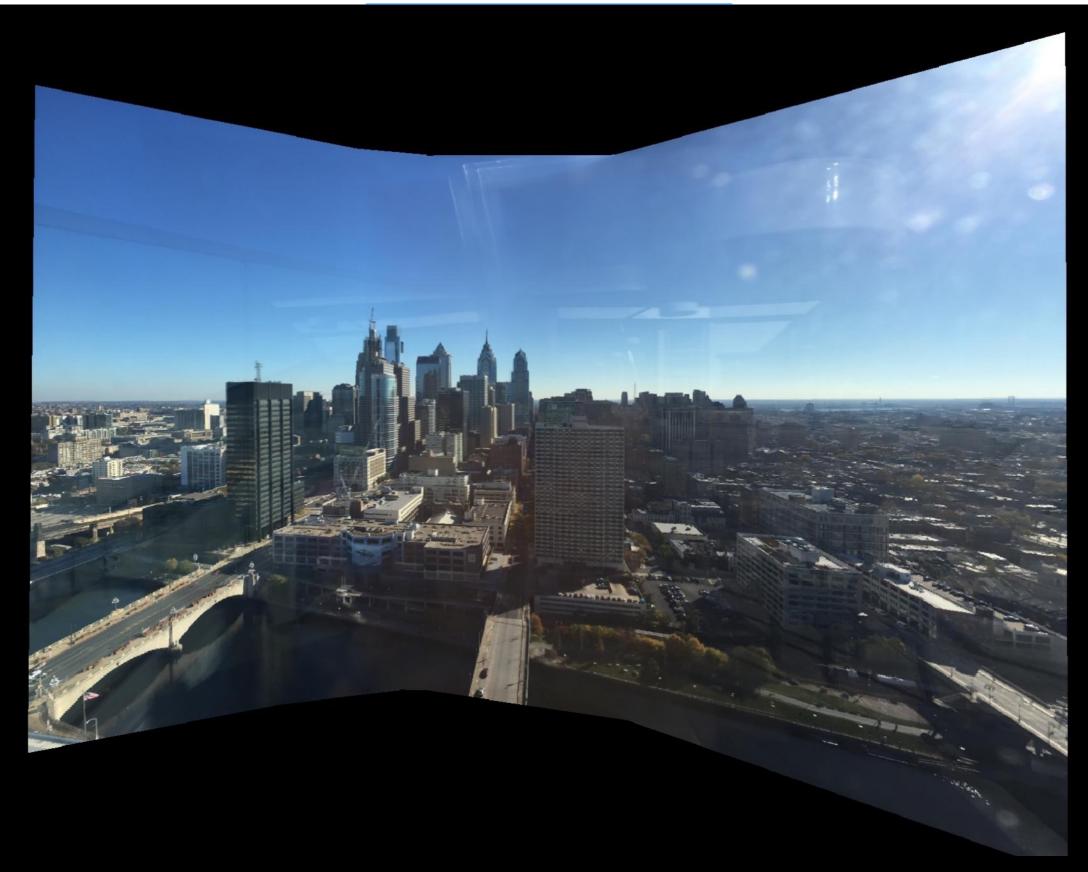
mat [h,w,3]



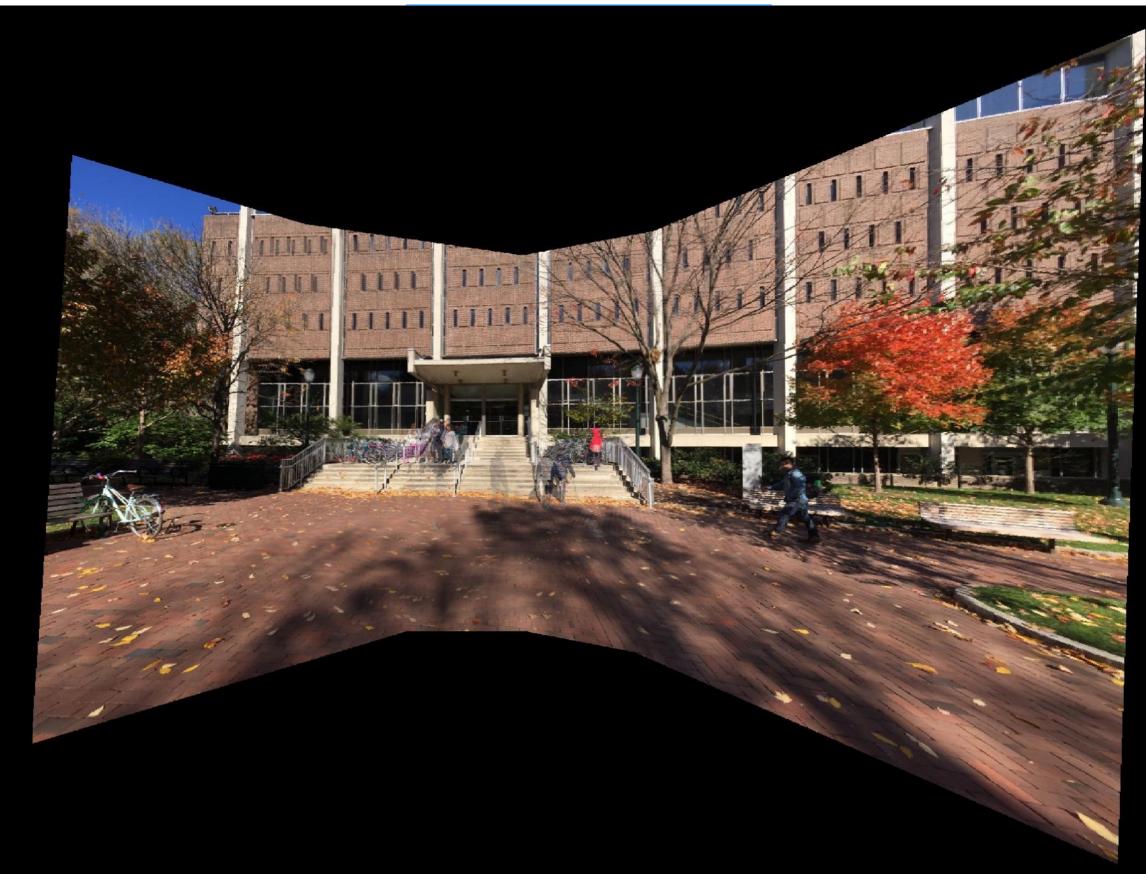
$$mat(i,j,k) = mat((k-1)*h*w + (j-1)*h + i))$$



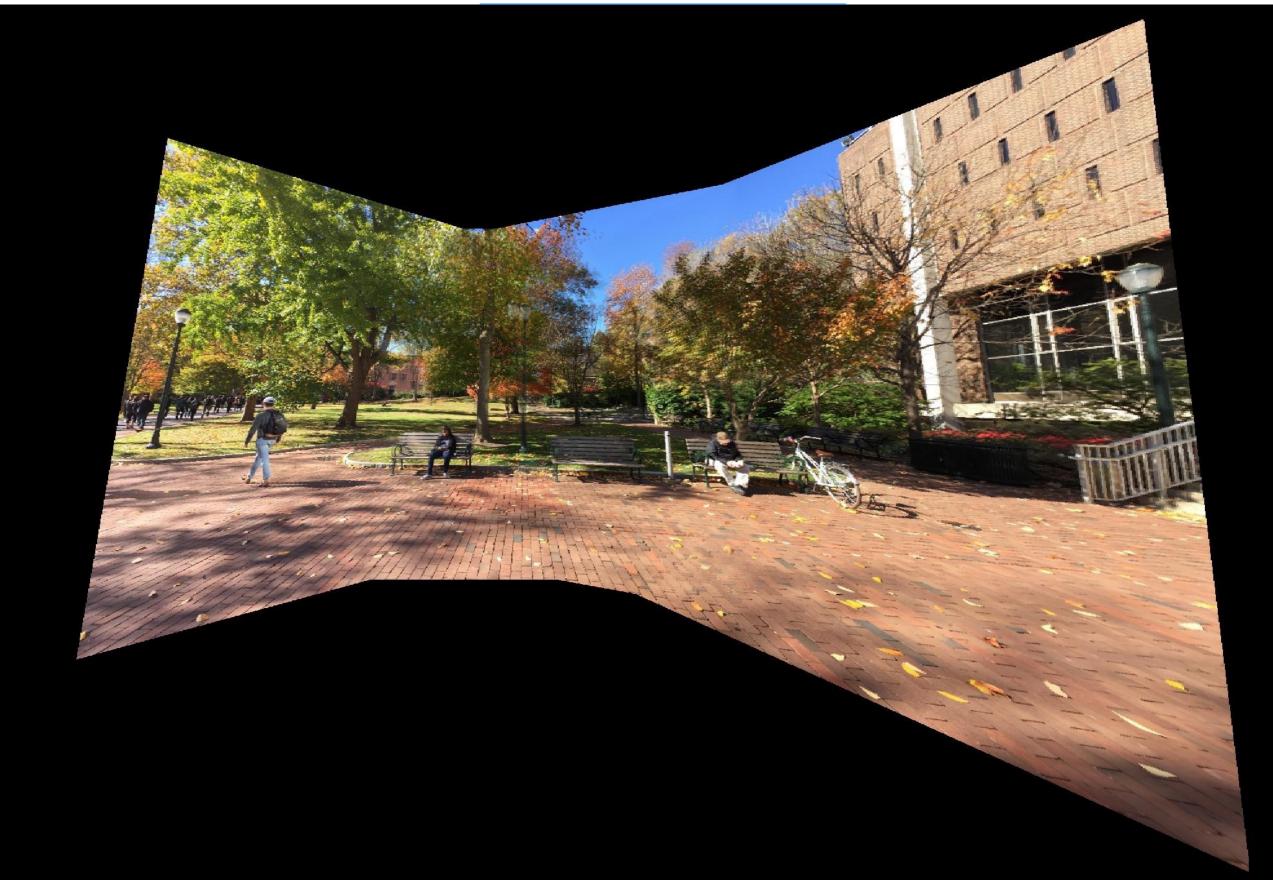
Final Image Stitching (more results)



Final Image Stitching (more results)



Final Image Stitching (more results)



Thank you!

Max Lu - 11/29/2016

