position

error

GYRO(六軸加速)

bias

kelman

卡爾曼濾波器演算法

<https://ieeexplore.ieee.org/document/6403514>

<https://dl.acm.org/doi/10.1145/3349341.3349496>

<https://ieeexplore.ieee.org/document/9032181>

<https://ieeexplore.ieee.org/document/9177309>

<https://ieeexplore.ieee.org/abstract/document/6138895>

<https://ieeexplore.ieee.org/abstract/document/838301>

<https://www.mdpi.com/1424-8220/8/4/2886>