Intro to Al lab3 - MineSweeper with Logic Agent

1	1	1	1	x	1	0	0	0
1	x	1	1	1	1	1	1	1
1	1	2	1	1	0	1	x	1
0	0	1	x	1	0	2	2	2
0	0	1	1	1	0	1	x	1
0	0	0	0	0	0	1	1	1
0	0	1	1	2	1	2	1	1
0	0	1	X	4	X	3	X	1
0	0	1	2	X	X	3	1	1

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Task description

- develop a Minesweeper Al based on (propositional) logic agent
- develop the environment for the agent

Proposed Algorithm

• as described in the assignment spec.

Implementation

General

- Programming Language: python
- IDE: jupyter notebook
- Version Control: git and github

Game control module

- Board(n,m,nmine) generate a random board corresponding to the parameter
- board.get_start(start=sqrt) return a list of starting safe positions
- LogicAgent.solve(board) will solve the problem for the board

OOP design (logic inference part)

• Variable/Literal(var)

- o a class
 - pos(position of variable, pair of (x,y)
 - T(mine or safe)
- Clause is set/frozenset of variable ⇒ Var need to be hashable
 - hash with x * 1000 * 10+y * 10+T to avoid collision
 - a slight improvement on performance than hash(repr)
 - use repr in python to print it
- Clause(cls)
 - o not a class
 - o direct use python set/frozenset
 - ∘ KB is set of clause ⇒ Clause need to be hashable
 - o frozenset is hashable but immutable
 - o set is mutable unhashable
 - o store in KB as frozenset, and change as set
- Knowledge Base(KB)
 - treat as a ADT(abstract data type)
 - o define insert(), match()... key function for it
 - o used by agent to do inference

logic agent

- · singleton clause meams ground truth
- do matching until it get a singleton clause (or fail with MATCHING LIMIT EXCEED)
- · apply changes corresponding to the singleton clause
- · algorithm detail is as described in assignment descrition
- some setting for hyperparams:
 - CHECK_SUB_WHEN_INSERT:
 - this can reduce the insert complex to O(|KB0|) from O(|KB|+|KB0|)
 - but may not be a good trade since max_kb/kb_inserted records indicate this can cause the kb to grow faster
 - however, checking subsumption before matching should relieve a little(since the most time spent correspodint to |KB| is matching)
 - MAX_ITER = 3:
 - max iteration of matching permmited
 - 3 is enough for solving most puzzles while keeping running time acceptable
 - MATCH SIZE LIMIT = 2:
 - max size for one side of matching
 - set to 2 can
 - extra experiment can be done on this parameter
 - GLOBAL LIMIT = 1000:
 - when to add in global limit
 - was set to 5000 but cause heavy time comsumption
 - a small experiment showed time is influenced a lot by this factor
- · No time for cross validation for limited time
 - o may not be the optimal set of hyper params

Experiment Results and Discussion

Evaluation Criterion

definition

o n,m: board width and length

o nmine: # of mine

T: testcases

• grid success(win) rate

∘ ∑|KB0|Tnm

o percentage of KB0(inferenced ground truth) to all grids

• board success(win) rate

- # of success boardsT
- o percentage that the agent completes the whole game

max KB size(max_kb)

- how many clauses is in the KB of agent at the same time(count on insert)
 - the maximum of this value indicate the max memory usage during the process
- o a measurement for memory used

• inserted clauses(inserted cls)

- how many clauses is put into KB(count on insert)
- o a evaluation of time used
 - but since matching step takes O(|KB|²) should be the dominating term
 - this may be positive related to execution time but not linearly

Winrate / Board Size

- · compare (grid) success rate on different board setting
- evaluate by 100 random generated board for each setting

	(9,9), 10	(16,16), 25	(32,16), 99
Grid Winrate	0.9888	0.9989	0.9779
Board Winrate	0.93	0.92	0.48

Discussion

observations

- o board winrate drop dramatically in bigger map
- o grid winrate is similar for 3 cases

• about ambiguity

- o both winrate is associated with "ambiguity" (multiple solution of a board),
 - ambiguity ⇒ logic agent cannot get a deterministic result
- the ambiguity case happens in the corners in most cases
 - so the grid winrate is similar between groups

• about global constraint

 I guess the lower success rate of big map is caused by the global constraint is added too late compared to small boards

Resources Spent / Board Size

- my language is python3, so execution is slow :(
- evaluate by 100 random generated board for each setting(average)

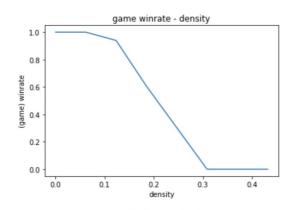
	(9,9), 10	(16,16), 25	(32,16), 99	
Runtime	0.56(sec)	2.19(sec)	8.48(sec)	
max_kb	194.13	338.65	1056.04	
inserted_cls	343.48	762.98	2861.54	

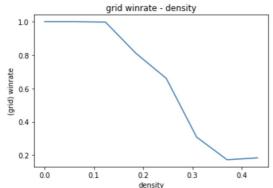
Discussion

- runtime is positively related to boardsize (~O(n*m))
- analytically, runtime should be O(|KB|²)
 - max_kb size show a trend for this
 - using avg_kb may be more useful for time evaluation then max_kb
- notice that inserted kb show linearly dependecy to runtime on the cases (16,16), 25 and (32,16), 99
 - o I geuss it was that inference time is smaller compared to inserting time
- Future Work
 - o conduct experiment to show the ratio of time spent on inference and insertion
 - o add additional statistic avg_kb, matching_size(how match cls generated from matching)...

Winrate / Mine Density

- · compare success rate on different mine density setting
 - (9,9) board with different number of mines with range(0,35, +5)





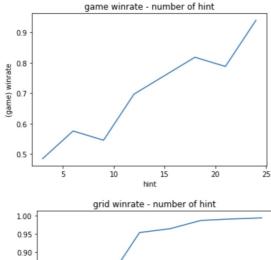
Discussion

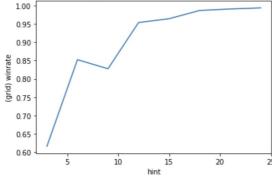
- Observation
 - higher density => lower winrate

- the function seems to be in the shape of logistic function!
- My Conjecture
 - o higher mine density can cause
 - less hint cells
 - higher ambiguity
 - o so higher density results in lower winrate
 - maybe increase MAX_ITERATION_LIMIT on matching can improve winrate when density is high

Winrate / Number of Starting Hints

- · compare success rate on different number of starting hints
 - (9,9), 15 board with different number of hints given with range(3,27, +3)
- take (9,9), 15 because the winrate is close to about 50% given 9 hint according to previous experiments



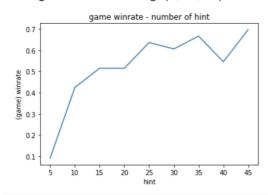


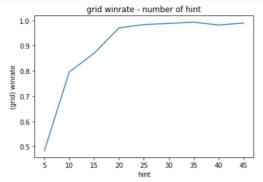
Discussion

- Observation:
 - o winrate acends as number of given hints increases
 - shape of linear function(game winrate)
 - shape of logarithm function (grid winrate)
- My conjecture:
 - o more information means more success rate without a doubt
 - very high grid winrate (>95%) when given >12 hints
 - note that the grid has 81 cells
 - 12 hint means ~1/7 cell is given
 - a cell has 8 neighbor and 72 non-neighbor cells
 - so almost every cell have one neighbor revealed intially(in probability)
 - I think this is one cause of high winrate
 - winrate cease to grow at around 10(~9), which is closed to n(board width)

Redo in 16*16

- for my conjecture, I redo the# of hint experiments to verify ny guess
- setting
 - o 16*16 grid
 - o 50 mines
 - starting hint number = range(5, 50, +5)





- the setting of nmine is calcuted by density ~0.2 for the experiment on density
 - o it shares similar winrate graph as the graph of 9*9 board with same density!
- grid winrate shows shape like logorithm function again
- for 16*16 board with similar density, 20 hints is enough for 95%up (grid) winrate
- reach 90%up winrate for #hint>16
 - o sqrt(grid_size) is enough for success of our logic agent
 - the setting given by TA/Teacher is reasonable!

Bonus Discussion

[Optional / Extra Credits]

These are for discussion only; no implementation/experiments required.

- $\hfill\square$ How to use first-order logic here?
- ☐ Discuss whether forward chaining or backward chaining applicable to this problem.
- $\hfill\Box$ Propose some ideas about how to improve the success rate of "guessing" when you want to proceed from a
- "stuck" game.
- □ Discuss ideas of modifying the method in Assignment#2 to solve the current problem.

How to apply FOL

- How to inference with FOL is not covered here(please refer to lecture notes and other references)
- · We decribe the axioms for the task here

Definitions of symbols

- let B[i][j] be the square at the i-th row, j-th column
- we define M(i,i) as an indicator that there is a mine atB[i][i]
- we define A(i,j,k) as an indicator that there is exact k mines in the neighborhood of B[i][i]

Axioms for the inference engine

- M(i, j) is well defined itself
- For A(i, j, k) with domain of k is {0, 1, 2, ..., 8}, we need to define the evaluation of A(i, j, 0) to A(i, j, 8)
- Take domain = {0, 1, 2} as example, domain with higher maximum of k can done similarly
 - o rule of global constraint
 - o rule of A(i, j, 0)
 - rule of A(i, i, 1)
 - o rule of A(i, j, 2)

```
\exists i_1 \exists j_1 \exists i_2 \exists j_2 (M(i_1, j_1) \land M(i_2, j_2) \land (i_1 \neq 1 \lor j_1 \neq 1) \land (i_2 \neq 1 \lor j_2 \neq 1) \land (i_1 \neq i_2 \lor j_1 \neq j_2))
\forall i_1 \forall j_1 \forall i_2 \forall j_2 \forall i' \forall j' (M(i_1, j_1) \land M(i_2, j_2) \land (i_1 \neq i' \lor j_1 \neq j') \land (i_2 \neq i' \lor j_2 \neq j')) \rightarrow \neg M(i', j')
\forall i' \forall j' (\forall i \forall j (|i - i'| \leq 1) \land (|j - j'| \leq 1) \land \neg (i = i' \land j = j') \rightarrow \neg M(i, j)) \rightarrow A(i', j', 0)
\forall i_1 \forall j_1 \forall i' \forall j' (M(i_1, j_1) \land (|i_1 - i'| \leq 1) \land (|j_1 - j'| \leq 1) \land \neg (i_1 = i' \land j_1 = j') \land (\forall i_2 \forall j_2 ((|i_1 - i'| \leq 1) \land (|j_1 - j'| \leq 1) \land (i_1 \neq i_2 \lor j_1 \neq j_2)) \rightarrow M(i_2, j_2))) \rightarrow A(i', j', 1)
\forall i_1 \forall j_1 \forall i_2 \forall j_2 \forall i' \forall j' (M(i_1, j_1) \land M(i_2, j_2) \land (|i_1 - i'| \leq 1) \land (|j_1 - j'| \leq 1)
\land (|i_2 - i'| \leq 1) \land (|j_2 - j'| \leq 1) \land \neg (i_1 = i' \land j_1 = j') \land \neg (i_2 = i' \land j_2 = j') \land \neg (i_1 = i_2 \land j_1 = j_2))
\rightarrow A(i', j', 2)
```

reference: https://www2.cs.duke.edu/courses/spring06/cps102/notes/sweeper.pdf

Forward/backward chainning applicable?

- We "cannnot" apply FC or BC here with original KB "directly"
- Since FC and BC require all clauses to be "horn clause"
 - o horn clause: clauses with exactly one or no positive literal
- The task's KB is made of all positive or all negtive clauses
- However, we can make all clauses horn by negating Mine(x,y) to Safe(x,y) or conversely
- But on doing this, there will beO(|clause|) horn clause generate by a single clause
- The complexity is linear to |KB|, but now size KB is actually bigger(O(# of clause * average|clause|))

How to improve winrate by guessinng when stuck

- When it comes to guessing, it means that:
 - We cannot make a singleton clause out of limited resolutions
- We must do backtraching search in this situation to try to get a solution
- · May use proof contradiction
 - o add not Mine(x,y)to KB0 and do resolution + pairwise matching
 - o see if there is empty clause(negative tautology) generated
 - o if there is, Safe(x,y) is True
- Can use similar concept to CSP solver:
 - MRV
 - Is of no use here, since {0,1} is possible for all non-singleton clasues
 - Degree
 - I think degree heuristic can help a lot
 - Since adding a big degree guess to tmp KB0 can do a lot of resolutions
 - LCV

- If the "least constraint" can be well-defined, LCV is going to help in my opinion
- a suitable definition of "constraint" can be the KB's degree of freedom
 - after assgin the guess, want the number of singleton term to be smaller
 - or define a fuction like $f(KB)=\sum w(i)*\#(i)$ where i is the size of a term
- · Another why is to do probabilistic estimation on the chance of there is a mine in certain grid

How to modify Assignment 2 to solve iteractive version

- · we can view the known constraints(hints) as KB
- do backtracking search as we do in programming assignment 2
- for the case that a guess is necessary, can use some approach to estimate the probability of a mine is in the position
- add constraint when accessing a new safe position(insert to KB)
- · with more constraint the domain of variables will change accordingly

Conclusion

- Propositional Logic Agent alone is enough to inference a great percentage of MineSweeper game with smaller board
- · We analysis the following:
 - o the resources spent on different game setting
 - o winrate on different board size
 - winrate on different mine density
 - winrate on different numbers of starting hints
- Future Works
 - There is a lot of method that worth trying in the bonus discussion area.
 - more statistics
 - time on inference(matching), time on insert
 - kb size changes(average, or as graph to how it goes throughout the process of game)
 - experiment on hyperparams
 - maxtching limit of clause size
 - when to put in global constraint
 - maximal iteration constraint
 - o different implementation
 - FOL
 - Propositional logic solver with enumeration of horn clause + FC
 - forward chainning is better than BC since we want the whole result
 - CSP solver
 - add Guessing Stategy
 - calculate Prob
 - calculate heristics
 - I have made most of my conjecture by guessing, should provide more mathematical insights to it!

Appendix A - Code

lab3_2.py

· core of algorithm and resource/setting exp

version 2(version 1 was bugged)

```
# lab3-2.py
# author = Yan-Tong Lin
# !/usr/bin/env python
# coding: utf-8
import numpy as np
import random
import itertools
from copy import deepcopy
import math
# hyper params
MATCH ITER LIMIT = 3 \# n \Rightarrow n^2 \Rightarrow n^4 \Rightarrow n^8 \Rightarrow n^16, or can use CLS_LIMIT
MATCH_SIZE_LIMIT = 2 # subset with size <= limit can match wih other
{\tt GLOBAL\_LIMIT} = 1000 # when to add global limit, when {\tt C(n,m)} is less than global limit
CLS LIMIT = 1000
MAX GRID = 500 \# check var, use constant there
CHECK SUB ON INSERT = True
# function to print a 2-D board
def printA(A):
   n = len(A)
    # m = len(A[0])
    for i in range(n):
       print(A[i])
    print()
class Board:
    B = None #board
    H = None #hint
    n, m, nmine = None, None, None
    #@staticmethod
    def inrange(self, i, j):
        # print(i, j)
        return i \ge 0 and i < self.n and j \ge 0 and j < self.m
    def __init__(self, n, m, nmine): # return a list of starting hints
        self.n = n
        self.m = m
        self.nmine = nmine
        all coordinate = [(i, j) for j in range(self.m) for i in range(self.n)]
        # print(all coordinate)
        mine_pos = random.sample(all_coordinate, nmine)
        self.B = [[0]*self.m for i in range(self.n)]
        self.H = [[0]*self.m for i in range(self.n)]
        for p in mine_pos:
            self.B[p[0]][p[1]] = 1
        #printA(self.B)
        for i, j in itertools.product(range(self.n), range(self.m)):
            if(self.B[i][j] == 1):
                continue
            for dx, dy in itertools.product (range (-1,2,1), range (-1,2,1)):
                if (not (dx==0 \text{ and } dy==0) and self.inrange(i+dx, j+dy)):
                     self.H[i][j] += self.B[i+dx][j+dy]
        #printA(self.H)
        return
    # for printing
    def repr (self):
        n = self.n
       m = self.m
```

```
ret = ""
        for i in range(n):
          ret += str(self.B[i])
           ret += "\n"
        return ret
    def get start(self, nstart = None):
        # get starting hints(starting safe positions)
        if(nstart == None):
           nstart = int(np.sqrt(self.n*self.m))
       hint coordinate = list(filter(lambda x: self.B[x[0]][x[1]] == 0, [(i, j) for j
        # printA(self.B)
        # print(hint_coordinate)
        start_pos = random.sample(hint_coordinate, nstart)
        \#start = [[-1]*self.m for i in range(self.n)]
        #for p in start pos:
        # start[p[0]][p[1]] = self.H[p[0]][p[1]]
        return start pos
    # query
    def q(self, i, j): #return -1 if is mine, return number if is hint
        return -1 if self.B[i][j] == 1 else self.H[i][j]
    def q(self, p): #return -1 if is mine, return number if is hint
        return -1 if self.B[p[0]][p[1]] == 1 else self.H[p[0]][p[1]]
class VAR:
    pos = None
    T = None # true / false, Mine/ Safe
    def init (self, pos, T):
       self.pos = pos
       self.T = T
    def __repr__(self):
        if self.T :
           return "M(%d,%d)"%(self.pos[0], self.pos[1])
           return "S(%d, %d)"%(self.pos[0], self.pos[1])
    def __eq__(self, rhs):
        if(isinstance(rhs, VAR)):
           return (self.pos == rhs.pos and self.T == rhs.T)
       else:
           return False
    # collision?
    def hash (self):
        return hash(self.pos[0]*1000*10+self.pos[1]*10+self.T)
    def neg(self):
       return VAR(self.pos, not self.T)
class CLS: # Or of Variables
    # use set of variable is enough
    # to insert into KB need to be imutable(frozenset)
    pass
# Treat as an ADT(abstact data structure) that support desired op.s
# store kb and kb0
# kb: And of Variables
# kb0: inferenced ground truth
# fcls is inmmutable(frozen set)
class KB:
  kh = cot /) # cot of ala/fragonact of mariable
```

```
kD = Set() # Set Of CIS(flozenset of variable)
kb0 = set() # set of variable
\max kb = None
cls inserted = None
def __init__(self):
   self.kb = set()
    self.kb0 = set()
    self.max_kb = 0
    self.cls_inserted = 0
# return kb0's size
def atom(self):
    return len(self.kb0)
# return positive kb0's size
def pos_atom(self):
   ret = 0
    for var in self.kb0:
       ret += var.T
    return ret
# return a singleton cls, or None
def get single(self):
   for fcls in self.kb:
       if len(fcls) == 1:
           return next(iter(fcls))
    return None
# add to kb0
def add kb0(self, var):
    assert(var.neg() not in self.kb0)
    self.kb0.add(var) # kb0 is a set
    return
# remove cls from kb
def remove(self, fcls):
    assert(fcls in self.kb)
    self.kb.remove(fcls)
    return
# remove cls and add to kb0 + resolution
def transfer to kb0(self, var):
    self.remove(frozenset([var]))
    self.add kb0(var)
    # resolution
    new kb = []
    for fcls in self.kb:
        if var in fcls:
            #tautology
            continue
        elif var.neg() in fcls:
           cls = set(fcls)
           cls.remove(var.neg())
           fcls = frozenset(cls)
           assert(len(fcls) != 0)
           new_kb.append(fcls)
        else:
           new kb.append(fcls)
    self.kb = set(new_kb)
    return
# insert cls to kb
# resolution with kb0 and check is not supperset(or eq) to other
# assert not negative tautology
def insert(self, cls, CHECKSUB = CHECK_SUB_ON_INSERT):
```

```
# resolutions with kb0
    if(isinstance(cls, frozenset)):
        cls = set(cls)
    for truth in self.kb0:
        if truth in cls:
           # tautology
            return
        elif truth.neg() in self.kb0:
            # this part is never True
            cls.remove(truth) # error handling should be redundunt
    # should not be negative tautology
    assert(len(cls) != 0)
    # check not supper set or equal to other this may be too much cost
    flag = True
    if (CHECKSUB):
        for fcls2 in self.kb:
            if(fcls2.issubset(cls)):
                flag = False
               break
    if flag:
       fcls = frozenset(cls)
       self.kb.add(fcls)
        self.cls inserted += 1
        self.max kb = max(self.max kb, len(self.kb))
    return
@staticmethod
# passing cls2, cls are immutable
# return set
def get_match(cls2, cls):
    if(cls.issubset(cls2)):
       return cls
    elif(cls2.issubset(cls)):
       return cls2
    #check complements
    comp = []
    for var in cls2:
       if(var.neg() in cls):
           comp.append(var)
    if (len(comp) > 1):
       return None
    elif (len(comp) == 1):
       var = comp[0]
       resolution cls = set(cls.union(cls2))
        resolution cls.remove(var)
       resolution cls.remove(var.neg())
        return resolution_cls
    else :
       return None
# do pair wise match for cls with size 2
def match(self):
   self.deal sub()
   kb2 = [fcls for fcls in self.kb if len(fcls) <= 2]</pre>
   match kb = []
    for fcls2 in kb2:
        for fcls in self.kb:
            m = KB.get_match(fcls2, fcls)
            if(m != None):
                match kb.append(m)
    for cls in match_kb:
```

```
self.insert(cls)
        return
    # check pairwise subsumption and remove the less restricting ones
    # no dup in set
    # O(n^2)
    def deal sub(self):
       new kb = []
        n = len(self.kb)
        for fcls1 in self.kb:
            has sub = False
            for fcls2 in self.kb:
                if(fcls1 != fcls2 and fcls2.issubset(fcls1)):
                   has sub = True
            if(not has sub):
               new_kb.append(fcls1)
        self.kb = set(new_kb)
        return
class LogicAgent:
   b = None # game board in agent's hand
    B = None \# solution, not used, will declare in solve as answer and return
    kb = None # current kowledge, include kb0(marked)
    def __init__(self):
       pass
    def solve(self, b, MATCH ITER LIMIT = MATCH ITER LIMIT, PRINT FAIL = True, PRINT=
       # initializing solver
        self.b = b # game engine
        self.kb = KB() # KB
        B = [[-1]*b.m for i in range(b.n)]# answer, -1 not decided, 0 no mine, 1 mine
        kb = self.kb # sugar
        \#b = self.b
        # get init positions
        start_pos = self.b.get_start()
        # add inital safe position to KB
        for p in start pos:
            kb.insert({VAR(p, 0)})
        # start solving
        iteration = 0
        while(1):
            # is done
            if(kb.atom() == b.n*b.m):
               return B, (kb.atom(), b.n*b.m)
            if PRINT:
               iteration += 1
               print("ith iteration, i = ", iteration)
                printA(B)
                print(b)
            # check whether add global constraint now
            def comb(n, r):
               return math.factorial(n) // math.factorial(r) // math.factorial(n-r)
            if(comb(b.n*b.m - kb.atom(), b.nmine - kb.pos atom()) < GLOBAL LIMIT):</pre>
               undecided = []
                V0 = []
               V1 = []
                for i in range(b.n):
               for i in range(b.m):
```

```
if(B[i][j] == -1):
                            undecided.append((i,j))
                            V0.append(VAR((i,j), 0))
                            V1.append(VAR((i,j), 1))
                assert(b.n*b.m - kb.atom() == len(V0))
                m = len(V0)
                n = b.nmine - kb.pos_atom()
                for cmb in itertools.combinations(V1, m-n+1):
                    kb.insert(set(cmb))
                for cmb in itertools.combinations(V0, n+1):
                    kb.insert(set(cmb))
            # get singleton
            cnt = 0
            while(kb.get single() == None and cnt < MATCH ITER LIMIT):</pre>
                kb.match()
                cnt += 1
            if(kb.get_single() == None): # no any sigleton after matching limit
                if PRINT FAIL:
                    print("Matching Limit Exceed!")
                return B, (kb.atom(), b.n*b.m)
            ## deal with sigleton
            a = kb.get single() # a singleton cls's only var
            hint = b.q(a.pos)
            assert((hint == -1 and a.T == 1) or (hint != -1 and a.T == 0))
            ## common
            # 1. move to kb0
            \# 2. matching of new kb0 to remainning cls
            i = a.pos[0]
            j = a.pos[1]
            kb.transfer_to_kb0(a)
            B[i][j] = a.T
            if(a.T == 0): # is safe and with hint res
                i = a.pos[0]
                j = a.pos[1]
                # undecided = []
                V0 = []
                V1 = []
                n = hint # should - positive B
                for dx, dy in itertools.product(range(-1,2,1), range(-1,2,1)):
                    nx, ny = i+dx, j+dy
                    if (not (dx==0 \text{ and } dy==0) and b.inrange(nx, ny)):
                        if (B[nx][ny] == -1):
                            # undecided.append((nx, ny))
                            V0.append(VAR((nx,ny), 0))
                            V1.append(VAR((nx,ny), 1))
                        if (B[nx][ny] == 1):
                            n = 1
                m = len(V0)
                # clause type, C m choose n, now at i, used array
                # use iter tool for higher performance
                for cmb in itertools.combinations(V1, m-n+1):
                    kb.insert(set(cmb))
                for cmb in itertools.combinations(V0, n+1):
                    kb.insert(set(cmb))
def exp(n, m, nmine, T=100, PRINT=100):
   import time
   grid_succ = 0
   grid norm = 0
   all succ = 0
   all norm = 0
  \max kb = 0.0
```

```
inserted cls = 0.0
    elasped\_time = 0.0
    for i in range(T):
       # init
       b = Board(n, m, nmine)
       agent = LogicAgent()
       #timing and solving
       start_time = time.time()
       B, ri = agent.solve(b)
       end time = time.time()
       #statistics
       elasped_time += end_time - start_time
       inserted_cls += agent.kb.cls_inserted
       max_kb += agent.kb.max_kb
       grid succ += ri[0]
       grid_norm += ri[1]
       all_succ += ri[0] == ri[1]
       all_norm += 1
       if(i%PRINT == 0):
           print("inserted cls", agent.kb.cls_inserted)
           print("maximum size of kb", agent.kb.max_kb)
           print("time spent", end_time - start_time)
           print("solution")
           printA(B)
           print("task")
           print(b)
    return (grid_succ, grid_norm), (all_succ,all_norm), (elasped_time/T, inserted_cls
GLOBAL LIMIT = 5000
exp(32, 16, 99, 10, PRINT=10)
```

exp_density.py

• paste only plotting part for simplification

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
\ensuremath{\text{\#}} when executing I am using copy of ipython notebook
# I paste only plotting part for simplification
from lab3 2.py import *
d \exp = []
for i in range(8):
    expi = exp(9, 9, 5*i, 33, False)
    d_exp.append(expi)
   print(i, "done")
r1 = []
r2 = []
for i in range(8):
    rl.append(d exp[i][0][0]/d exp[i][0][1])
    r2.append(d_exp[i][1][0]/d_exp[i][1][1])
plt.plot(np.asarray(list(range(0,8)))*5/81, r1)
plt.title('grid winrate - density')
plt.xlabel('density')
plt.ylabel('(grid) winrate')
plt.show()
plt.plot(np.asarray(list(range(0,8)))*5/81, r2)
plt.title('game winrate - density')
plt.xlabel('density')
plt.ylabel('(game) winrate')
plt.show()
```

exp_hint.py

• paste only plotting part for simplification

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
\# when executing I am using copy of ipython notebook
# I paste only plotting part for simplification
# there is actually change that NSTART is used for number of starting hints in lab3
from lab3 2.py import *
d \exp = []
for i in range (1, 9):
   NSTART = i*3
   expi = exp(9, 9, 15, 33, False)
   d exp.append(expi)
    print(i, "done")
r1 = []
r2 = []
for i in range(8):
   rl.append(d exp[i][0][0]/d exp[i][0][1])
    r2.append(d exp[i][1][0]/d exp[i][1][1])
plt.plot(np.asarray(list(range(1,9)))*3, r1)
plt.title('grid winrate - number of hint')
plt.xlabel('hint')
plt.ylabel('(grid) winrate')
plt.show()
plt.plot(np.asarray(list(range(1,9)))*3, r2)
plt.title('game winrate - number of hint')
plt.xlabel('hint')
plt.ylabel('(game) winrate')
plt.show()
# redo for bigger size
d2 \exp = []
for i in range(1, 10):
   NSTART = i*5
   expi = exp(16, 16, 50, 33, False)
   d2 exp.append(expi)
   print(i, "done")
r1 = []
r2 = []
for i in range(9):
    r1.append(d2_exp[i][0][0]/d2_exp[i][0][1])
    r2.append(d2 exp[i][1][0]/d2 exp[i][1][1])
plt.plot(np.asarray(list(range(1,10)))*5, r1)
plt.title('grid winrate - number of hint')
plt.xlabel('hint')
plt.ylabel('(grid) winrate')
plt.show()
plt.plot(np.asarray(list(range(1,10)))*5, r2)
plt.title('game winrate - number of hint')
plt.xlabel('hint')
plt.ylabel('(game) winrate')
plt.show()
```