aramebtech@gmail.com

Profile

- Interested in: deep learning, optimization, planning, data structures, epistemology, educational game design
- World-class performance record in algorithmic computing competitions
- Enjoy bridging theoretical tools, exploring novel approaches, and collaborating to turn visions into reality
- Proficient in C++, Java, Rust, Python, and TensorFlow (github.com/EbTech)
- Canadian citizen fluent in English, French and Farsi; elementary knowledge of Spanish, Mandarin, Japanese

Work Experience

2016 - current

• AI Researcher/Engineer at Waymo: designing new algorithms for optimization, geometry, and machine learning to enable detailed real-time predictions of behaviors on the road.

Education

Lifelong Learning

2016 - present

• Independent study of Mandarin Chinese, phonetics, finance theory, stochastic calculus, variational calculus, deep learning, deep reinforcement learning, and Rust programming

Carnegie Mellon University

2012 - 2015

- Ph.D. candidate in Computer Science (dropped with M.S.)
- Teaching Assistant for 15-451/651 (Algorithms) taught by Avrim Blum and Anupam Gupta
- Completed the 2012 Summer School in Algorithmic Economics
- NSERC Alexander Graham Bell Canada Graduate Scholarship
- Memberships: Graduate Student Assembly departmental representative, Ballroom Dance Club, School of Computer Science musical performances

University of British Columbia

2008 - 2012

- B.Sc. Combined Honours in Computer Science and Mathematics with Distinction
- 92% (A+) GPA, Dean's Honour List and Science Scholar standing
- President's Entrance Scholarship (top tier), Trek Excellence Scholarship, CPSC Scholarship
- 8-month game development internship at Electronic Arts, working on Need For Speed: World

Research and Personal Projects

- Elo-R rating system: derived a Bayesian model and implemented a simple rating system for competitions in which the outcome is a total ordering among players, proposed as an improvement over the systems used to track players' skill in online programming competitions
- Cooperative multi-agent planning: proved NP-hardness of planning with very simple constraints on visitation order, then proposed two heuristic search algorithms to handle a more general set of constraints with guarantees on the suboptimality factor of the path length; advised by Prof. Maxim Likhachev
- Parallel A* framework: developed a theoretical framework that generalizes A* search; applications include anytime dynamic multi-heuristic or multi-processor search; advised by Prof. Maxim Likhachev

Research and Personal Projects (continued)

- Dynamic Łukasiewicz Game Logic: generalized hybrid games with binary outcomes to a formal specification of zero-sum hybrid games with extended real outcomes, and derived its sequent calculus for semi-automated theorem proving; advised by Prof. André Platzer
- Linking population dynamics: proposed a new population model to represent social interactions in the context of natural selection; theoretical and experimental analyses found the emergence of a nontrivial form of cooperation in scenarios resembling the Prisoner's Dilemma
- U! Robot!: lead programmer in a team of 8 developers, completing a platformer game that was showcased at the end of the 48-hour Global Game Jam
- Equitable clustering: derived an approximation algorithm for quantizing distributions on Euclidean space, with applications to image stippling; advised by Profs. David Kirkpatrick and William Evans
- Alspace.org contributions: developed practice exercises and sample solutions to reinforce key concepts for students in undergraduate artificial intelligence courses
- Cybersword Duels: a pair of sword-dueling video game engines, one in 2D and one in 3D, that map mouse movements intuitively into fully controllable sword motions, with collision physics; the 2D game has an opponent trained to beat humans by reinforcement learning

Contest Achievements

- 61st place among over 50,000 registrants in the Google Code Jam
- 57th place in the TopCoder Open Algorithm Competition
- 6th place in the North American Invitational Programming Contest's Open Division, competing solo against teams of up to three
- Achieved Codeforces Grandmaster title, peak rating 2400+ on both Codeforces and TopCoder
- 18th place in the ACM ICPC World Finals in Warsaw, Poland
- Top 250, Team Honorable Mention in the William Lowell Putnam Mathematical Competition
- Member of the UBC Thunderbots, which placed **9th** in the **RoboCup** SSL international robot soccer competition; I developed some AI algorithms, e.g. filters for ball and robot tracking

Sample Coursework (grad-level marked with *)

- Math Statistical Inference*; Evolutionary Dynamics*; Number Theory*; Intro Topology; Advanced Linear Algebra; Mechanics; Algebra, Coding Theory and Cryptography
- Computational Complexity Theory*; Type Systems for Programming Languages*; Advanced Algorithm Design and Analysis; Graph Theory; Functional and Logic Programming
- AI Statistical Machine Learning*; Multimedia Databases and Data Mining*; Kinematics, Dynamic Systems and Control*; Intelligent Systems

Sample Coursework (grad-level marked with *) (continued)

• Advanced Distributed Operating Systems*; RPG Writing Workshop*; Computer Graphics

• Adaptive Control & Reinforcement Learning*; Planning, Execution & Learning*; String Algorithms*; Information Theory*; Design Educational Games*; Experimental Game Design

Volunteering

• ACM ICPC problem setter: authored the problems J,L,N in the Pacific Northwest regional programming contest, and helped with additional writing/reviewing/testing; our aim is to raise the bar for programming contest quality in North America, for experts and novices alike

• FIRST Lego League research judge: judged and gave feedback on research project presentations by teams of children aged 9-14 aimed at solving global issues using STEM principles

2006 • Science AL!VE summer camp assistant: helped run activities to encourage scientific curiosity in young children