

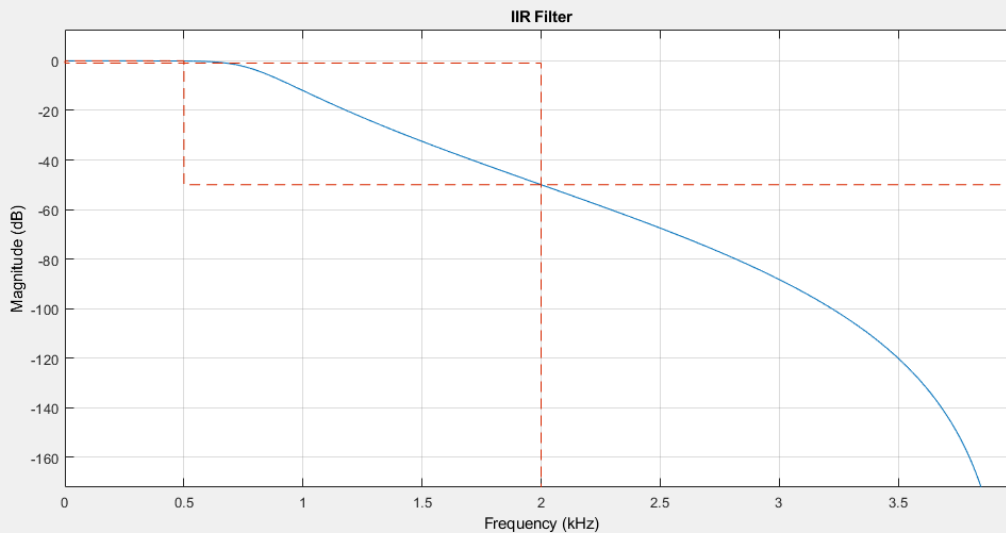
4. An analog signal $x(t) = 10\cos(1000t) + 20\cos(4000t)$ is to be processed using the above effective continuous-time system in which the sampling frequency is 2 kHz.

(a) Design a minimum-order IIR digital filter that will suppress the 2 kHz component down to 50 dB while pass the 500 Hz component with attenuation of less than 1 dB. The digital filter should have an equiripple passband and stopband. Determine the system function of the filter and plot its log-magnitude response in dB.

Eventhough the question asks for a Sample Rate of 2Khz because of stopband at 2Khz the sample rates need to be higher ! Therefore has been set at 8kHz

```
lpFilt_IIR = designfilt('lowpassiir', ...
    'PassbandFrequency',500,'PassbandRipple',0.9, ...
    'StopbandFrequency',2e3,'StopbandAttenuation',50,'SampleRate',8e3);

figure(1);
fvtool(lpFilt_IIR,'magnitude')
title("IIR Filter")
```



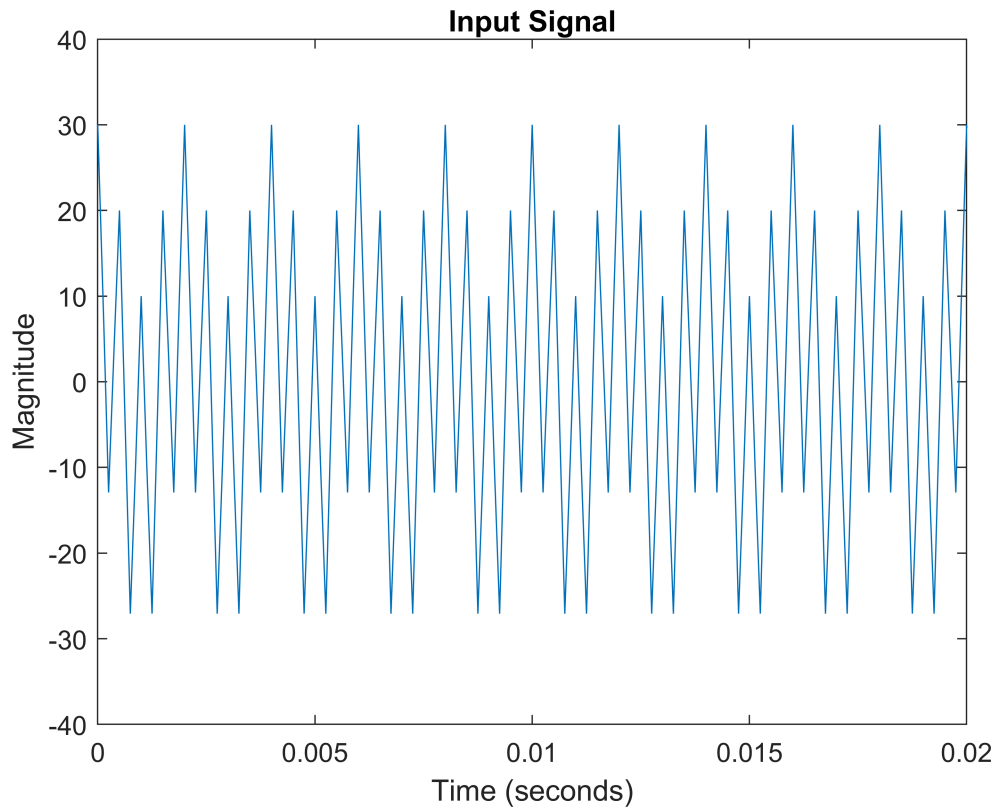
(b) Process the signal $x(t)$ through the effective analog system. Generate sufficient samples so the output response $y(t)$ goes into steady state. Plot the steady state $y(t)$ and comment on the filtering result.

```
Fs = 8e3;
t = 0:1/Fs:1-1/Fs;

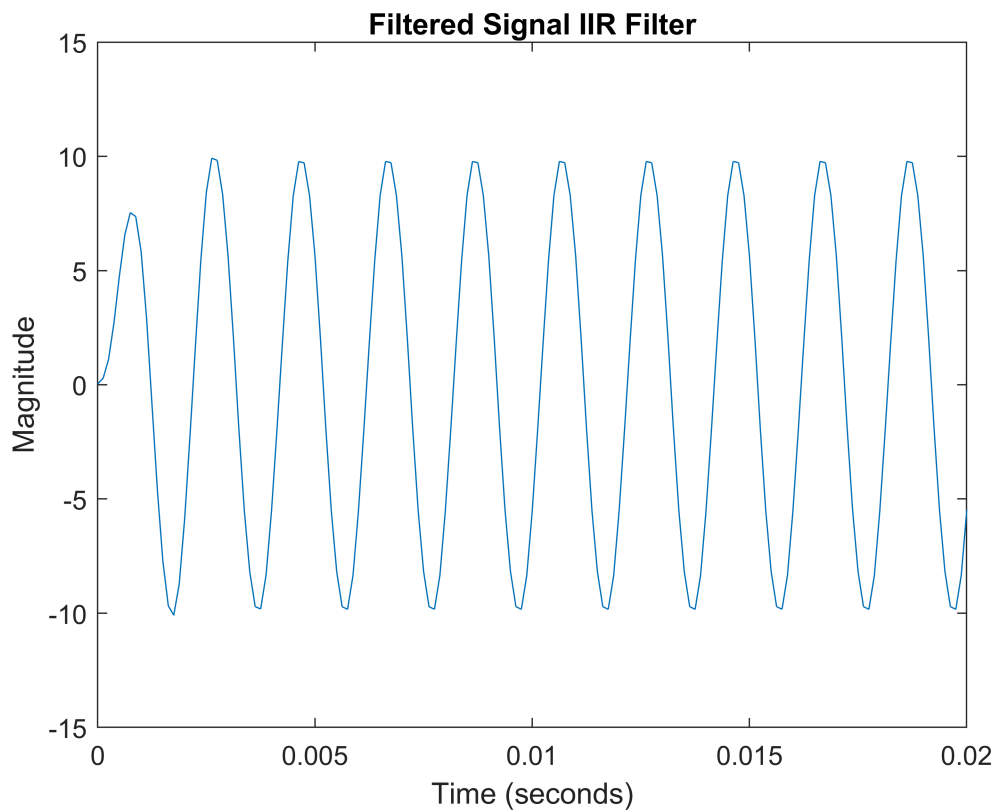
xc = 10*cos(1000*pi*t) + 20*cos(4000*pi*t);
figure(2);
plot(t,xc)

xlim([0 0.02])
ylim([-40.0 40.0])
title("Input Signal")
```

```
xlabel("Time (seconds)")  
ylabel("Magnitude")
```



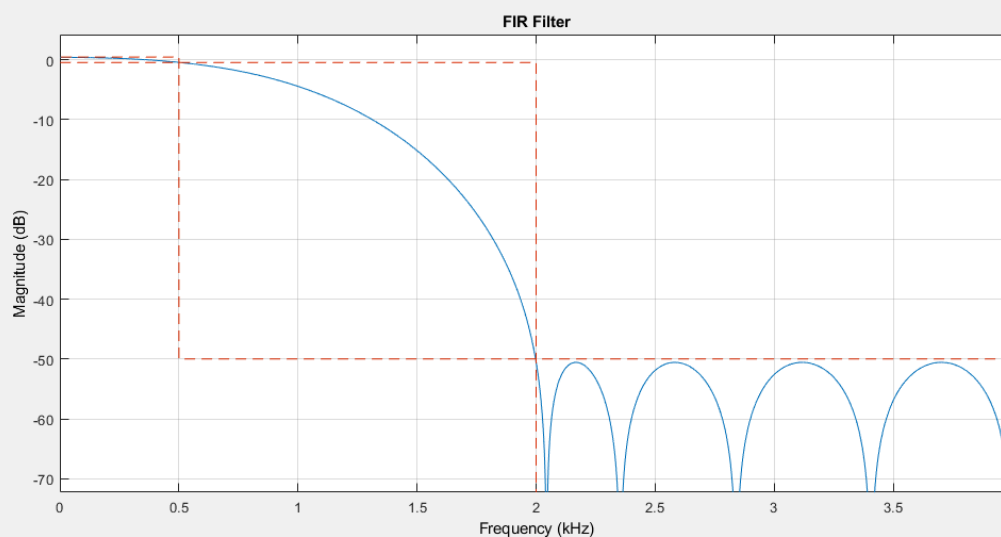
```
filtered_data_IIR = filter(lpFilt_IIR,xc);  
  
figure(3);  
plot(t,filtered_data_IIR)  
xlim([0 0.02])  
ylim([-15.0 15.0])  
title("Filtered Signal IIR Filter")  
xlabel("Time (seconds)")  
ylabel("Magnitude")
```



(c) Repeat parts (a) and (b) by designing an equiripple FIR filter. Compare the orders of the two filters and their filtering results.

```
lpFilt_FIR = designfilt('lowpassfir', ...
    'PassbandFrequency',500,'PassbandRipple',0.9, ...
    'StopbandFrequency',2e3,'StopbandAttenuation',50,'SampleRate',8e3);

figure(4);
fvtool(lpFilt_FIR,'magnitude')
title("FIR Filter")
```

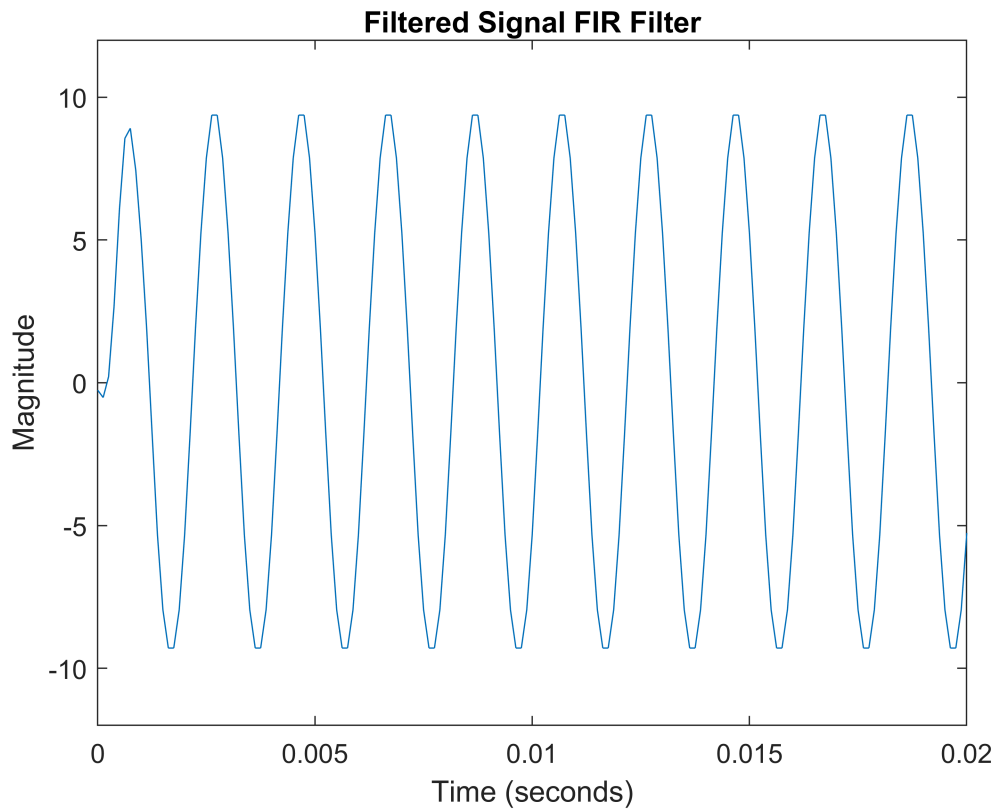


```

filtered_data_FIR = filter(lpFilt_FIR,xc);

figure(5);
plot(t,filtered_data_FIR)
xlim([0 0.02])
ylim([-12.0 12.0])
title("Filtered Signal FIR Filter")
xlabel("Time (seconds)")
ylabel("Magnitude")

```



```

filtord(lpFilt_FIR)

```

```

ans = 11

```

```

filtord(lpFilt_IIR)

```

```

ans = 5

```

Order of IIR Filter is 5 and Order of FIR Filter is 11.

Also, we can see that IIR Filter in the beginning takes time to adjust to the achieve steady state.