Problems with use of semaphores

- 1. Dead Lock
- 2. Time dependent errors
 - a. Timing
 - b. Programmer error

Problems with use of semaphores: Dead Lock

S-Q-1		
P0	P1	
Wait(S)	Wait(Q)	
Wait(Q)	Wait(S)	
	•	
•	•	
Signal(S)	Signal(Q)	
Signal(Q)	Signal(S)	

Consider following order of execution: Wait(S) in P0

Wait(Q) in P1 Wait(Q) in P0

Wait(S) in Pi

Problems with use of semaphores: Timing

Timing Error refers to those errors that happen only if a particular execution order takes place.

Solution

Locking

Problems with use of semaphores: **Programmer Errors**

Suppose we have the semaphore mutex = 1 for a group of cooperating processes as follows:

Repeat P(mutex)

Critical section

V(mutex) Remainder

Until false;

One process at a time will be in its critical section

Problems with use of semaphores: **Programmer Errors**

Let us assume that programmer is sleepy and made a mistake in coding as follows:

Case 1	Case 2	Case 3
V(mutex)	P(mutex)	V(mutex)
-	e •	
Critical section	Critical section	Critical section
P(mutex)	P(mutex)	V(mutex)
All processes are in their C. sections	Only one process gets into its C. Section	All processes are in their C. sections

Problems with use of semaphores: Programmer Errors

Solution

Use of Critical Region Construct

We need to use a sharable variable of type T with the C.R.C. which is declared as follows:

Var u: shared T;

Examples

var u : shared integer

var u : shared array[1..n] of boolean

Critical Region Construct

Var u: shared T; Region u do A.

(i.e., while task A is being executed, no other processes can use the variable u.)

Critical Region Construct

How is programmer miscoding prevented?

Programmer codes:

Region u do A;

Compiler generates:

P(u)

A;

V(u)

Abstract Data Type: skeleton

Variable declarations Procedure entry Proc1(...) Begin . . . End; Procedure entry Proc2(. . .) Begin . . . End;

Procedure entry Proce(. . .) Begin . . . End;

Begin

Initialization code

Integration of C.R.C. and ADT

Type frames = class

var free: shared array[1..n] of boolean

Procedure entry acquire (var index: integer);

Begin

region free

do for index = 1 to n

do if free[index] then Begin free[index] = false; exit;

End;

index =-1;
End;
Procedure entry release(index: integer)
Begin

region free do free[index] = true;

Begin

region free do for index = 1 to n do free[index] = true

End;

Nested Critical Region Constructs

Region x do region y do s1;

Problem:

Nested Critical Region Constructs may cause deadlock.

Nested Critical Region Constructs

Example:

Process Q: region x do region y do s1;

Process R: region y do region x do s2;

x = y = 1;

P(x) **p**(y) S1;

V(y) V(x)

P(y) p(x) S2; V(x)

V(y)

Nested Critical Region Constructs

Solution:

Establishing a priority among shared variables.

Example: x > y

That is, if shared variable x is in use by process Q, then the shared variable y will not be used by any other process until x is released.

Nested Critical Region Constructs

Example:

Process Q: region x do region y do s1; Process R: region y do region x do s2;

x = y = 1; x > y;

P(x) p(y) S1; V(y) P(y) p(x) S2; V(x) V(y)

Conditional Critical Region Construct

Region u when B do A; u is a shared variable B is a boolean expression

If B is true and u is not in use then A is executed.

Conditional Critical Region Construct

Example: Producer and Consumer

buffer: shared record pool:array[0..n-1] of item; count, in, out: integer;

Region buffer when count <n
do begin
pool[in] = nextp
in = in +1 mod n;

Region buffer when count >0 do begin nextc =pool[out]; out = out +1 mod n; count = count -1;

count = count +1;

PRODUCER

CONSUMMER

New language constructs

Both

Critical Region Construct and
Conditional Critical Region Construct

Delay multiple processes to enter their critical sections at the Entry section.

.. They are not 100% successful in synchronization of processes

New language constructs

Solution:

There is a need for a construct that can delay the execution of a process in two places:

at the entry section and inside the critical section.

New language constructs

To do so.

Conditional Critical Region Construct is modified.

Old CCRC Region a when B do A



New language constructs

For use of the modified Conditional Critical Region Construct We need to define Condition variable Manitor

New language constructs

1-Condition variable

var x: condition;

A condition variable is an object of a class defined by an abstract data type with two methods of Wait and Signal.

If process P1 invokes x. Wait then P1 is suspended until another process, like P2 invokes x. Signal.

If process P2 invokes x. Signal then

r.2 invokes x.Signal then
A suspended process, say PI, on x resumes its process.
If there is no suspended process on x, then
no action takes place. It looks like that x.Signal was
never executed.

New language constructs

2-Monitor follows the syntax of an abstract data type.

We use the integration of condition variable and monitor to solve the problem of dining philosopher using

Monitor

Type dining-philosophers = monitor

Var state: array[0..4] of (thinking, hungry, eating);

Var self: array[0..4] of condition;

edure entry pickup(i: 0.4) begin state[i] = hungry;

test(i); if state[i] != Eating { self[i].wait};

re entry putdown(i: 0.4)

begin state[i] =thinking; test(i-1 mod 5); test(i+1 mod 5);

ure entry test(k: 0...4)

Begin

for i =0 to 4 (state(ij = thinking)

Monitor

What is the difference between a monitor and a class? The difference is in use of:

Critical Region Construct (C.R.C) by class and Modified Conditional C.R.C by monitor.

C.R.C. provides the mutual exclusion on procedures M.C.C.R.C provides the mutual exclusion on procedures and

In the previous example, a philosopher is a resource. A resource can self.wait