

## Cambridge Raspberry Jam

Name

Age

Parent

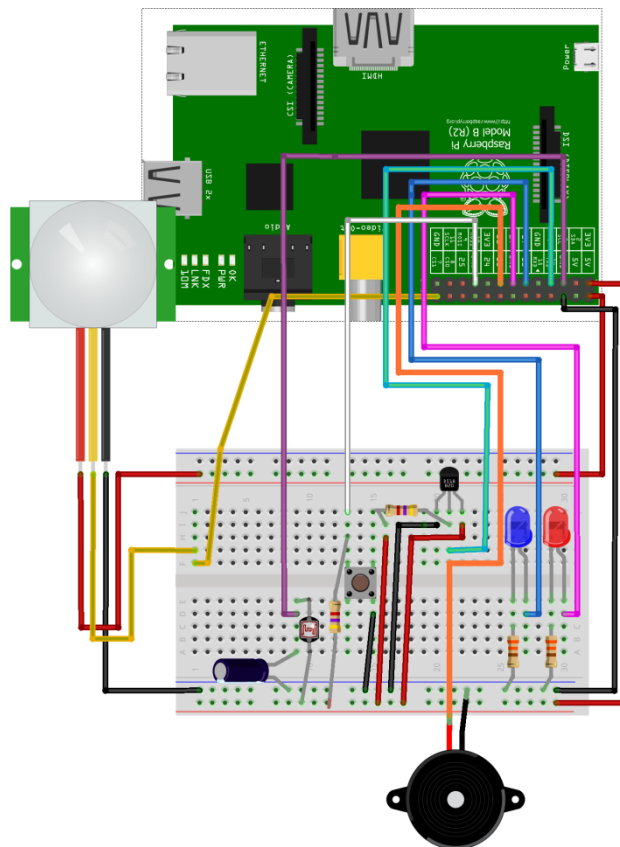
## Beginners worksheet #9

Project Passive Inferred Sensor

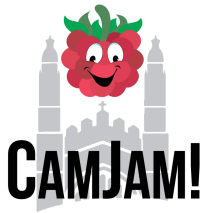
Description In this project you will learn how to wire and program a passive inferred sensor

### Tools required

- |   |   |   |
|---|---|---|
| <input type="checkbox"/> Raspberry Pi SD card | <input type="checkbox"/> 1 X Blue LED               | <input type="checkbox"/> 13 x m/f jumper wires        |
| <input type="checkbox"/> Keyboard             | <input type="checkbox"/> 2 x 330 $\Omega$ resistors | <input type="checkbox"/> 5 m/m jumper wire            |
| <input type="checkbox"/> Monitor + Cable      | <input type="checkbox"/> 2 4.7k $\Omega$ resistors  | <input type="checkbox"/> Temperature sensor (DS18B20) |
| <input type="checkbox"/> Power supply         | <input type="checkbox"/> Buzzer                     | <input type="checkbox"/> LDR Light Dependent resistor |
| <input type="checkbox"/> Breadboard           | <input type="checkbox"/> 1uf resistor               | <input type="checkbox"/> Passive Infrared Sensor      |
| <input type="checkbox"/> 1 X Red LED          | <input type="checkbox"/> Push button                |   |



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## Code

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### TURN ON THE LEDS "9\_pir.py"

```
#!/usr/bin/python
import RPi.GPIO as GPIO
import time
GPIO.setmode(GPIO.BCM)
GPIO.setwarnings(False)
GPIO.setup(27,GPIO.OUT)

GPIO_PIR = 7

print "PIR Module Test (CTRL-C to exit)"

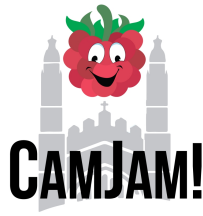
# Set pin as input
GPIO.setup(GPIO_PIR,GPIO.IN)          # Echo

Current_State = 0
Previous_State = 0

try:
    print "Waiting for PIR to settle ..."
    # Loop until PIR output is 0
    while GPIO.input(GPIO_PIR)==1:
        Current_State = 0
    print "  Ready"
    # Loop until users quits with CTRL-C
    while True :
        # Read PIR state
        Current_State = GPIO.input(GPIO_PIR)
        if Current_State==1 and Previous_State==0:
            # PIR is triggered
            print "  Motion detected!"
            # Record previous state
            GPIO.output(27,GPIO.HIGH)
            time.sleep(1)
            GPIO.output(27,GPIO.LOW)
            Previous_State=1
        elif Current_State==0 and Previous_State==1:
            # PIR has returned to ready state
            print "  Ready"
            Previous_State=0
            # Wait for 10 milliseconds
            time.sleep(0.01)

except KeyboardInterrupt:
    print "  Quit"
    # Reset GPIO settings
    GPIO.cleanup()
```

1. Change directory "cd Desktop/gpio\_python\_code/"
2. Create file "touch python 9\_pir.py"



3. Enter the code above code

Once complete "Ctrl + x" then "y" then "enter"

4. To run the python code "`sudo python 9_pir.py`" << Move in front of the PIR to activate it.