PISO-P8R8/P8SSR8AC/P8SSR8DC

Digital I/O Card

Linux Software Manual

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1. Linux Software Installation

The PISO-P8R8/P8SSR8AC/P8SSR8DC can be used in linux kernel 2.4.X and 2.6.X. For Linux O.S, the recommended installation and uninstall steps are given in Sec $1.1 \sim 1.2$

1.1 Linux Driver Installing Procedure

- Step 1: Copy the linux driver "ixpio-0.20.15.tar.gz" (or the later driver version) in the directory "NAPDOS\Linux" of the companion CD or download the latest driver from our website to the linux host.
- Step 2: You must use the '**root**' identity to compile and install PIO/PISO linux driver.
- Step 3: Decompress the tarball "ixpio.tar.gz".
- Step 4: Type 'cd' to the directory containing the package's source code and type './configure' to configure the package for your linux system.
- Step 5: Type 'make' to compile the package.
- Step 6: You can type './ixpio.inst' to install the PIO/PISO driver module and build the device file "ixpioX" in the device directory "/dev" automatically.

1.2 Linux Driver Uninstalling Procedure

- Step 1: Type `cd' to the directory containing the package's source code.
- Step 2: Type `./ixpio.remove' to remove the PIO/PISO driver module.

2. Static Library Function Description

The static library is the collection of function calls of the PIO-DIO cards for linux kernel 2.4.x and 2.6.x system. The application structure is presented as following figure. The user application program developed by C(C++) language can call library "libpio.a" in user mode. And then static library will call the module ixpio to access the hardware system.

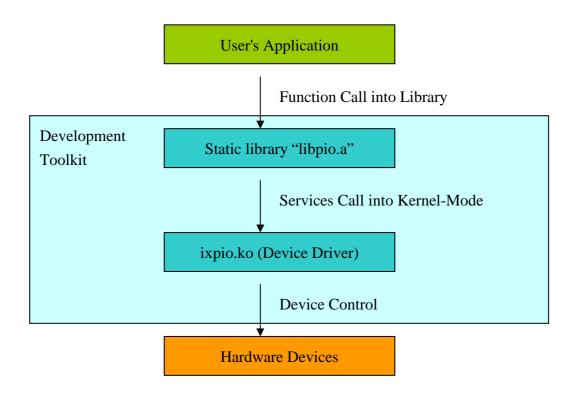


Figure 2.1

2.1 Table of ErrorCode and ErrorString

Table 2.1

Error Code	Error ID	Error String
0	PIODA_NOERROR	OK (No error!)
1	PIODA_MODULE_NAME_GET_ERROR	Module name can't get
		from file /proc/ixpio/ixpio
5	PIODA_DIGITAL_OUTPUT_ERROR	Digital output error
6	PIODA_DIGITAL_INPUT_ERROR	Digital input error

2.2 Function Descriptions

Table 2.2

Function Definition				
char * PIODA_GetDriverVersion(void);				
char * PIODA_GetLibraryVersion(void);				
int PIODA_Open(char *dev_file);				
WORD PIODA_Close(WORD fd);				
WORD PIODA_DriverInit(WORD);				
WORD PIODA_Digital_Output(WORD, WORD, byte);				
WORD PIODA_Digital_Input(WORD, WORD, WORD *);				

2.3 Digital I/O FUNCTIONS

2.3.1 PIODA_GetDriverVersion

• Description:

To show the version number of PIO/PISO linux driver.

• Syntax:

char * PIODIO_GetDriverVersion(Void)

• Parameter:

None

Return:

The version of PIO/PISO linux driver.

2.3.2 PIODA_GetLibraryVersion

Description:

To show the version number of PIO/PISO linux static library..

Syntax:

char * PIODIO_GetLibraryVersion(void)

Parameter:

None

Return:

The version of PIO/PISO linux static library.

2.3.3 PIODA_Open

Description:

To open device file.

Syntax:

int PIODIO_Open(char *dev_file)

Parameter:

dev_file: The path of device file

• Return:

The file descriptor of device file. If the file descriptor < 0, it means that open device file failure.

2.3.4 PIODA_Close

Description :

To close device file.

• Syntax:

Word PIODIO_Close(WORD fd)

Parameter :

fd: The file descriptor of device file that get from function PIODIO_Open

Return:

"PIODA_NOERROR"

(Please refer to "Section 2.1 Error Code")

2.3.5 PIODA_DriverInit

Description :

To allocates the computer resource for the device. This function must be

called once before applying other PIODA functions.

Syntax:

WORD PIODA_DriverInit(WORD fd)

Parameter :

fd: The file descriptor of device file that get from function PIODIO_Open

• Return:

```
"PIODA_MODULE_NAME_GET_ERROR"
"PIODA_NOERROR"
(Please refer to "Section 2.1 Error Code")
```

2.3.6 PIODA_Digital_Output

• Description:

This subroutine sends the 8 bits data to the specified I/O port.

• Syntax:

WORD PIODA_Digital_Output(WORD fd, WORD port, byte data);

Parameter :

fd: The file descriptor of device file that get from function PIODIO_Open.

port: PISO-P8R8 don't assign DO port, so user set value = 0.

data: 8 bits data.

Return:

```
"PIODA_DIGITAL_OUTPUT_ERROR"

"PIODA_NOERROR"

(Please refer to "Section 2.1 Error Code")
```

2.3.7 PIODA_Digital_Input

Description :

This subroutine reads the 8 bits data from the specified I/O port.

Syntax :

WORD PIODA_Digital_Input(WORD fd, WORD port, WORD *di_data);

• Parameter:

fd : The file descriptor of device file that get from function PIODIO_Open.

port : PISO-P8R8 don't assign DI port, so user set value = 0. di_data : A variable address used to storage the 8 bits input data.

• Return:

"PIODA_DIGITAL_INPUT_ERROR"

"PIODA_NOERROR"

(Please refer to "Section 2.1 Error Code")

3. PISO-P8R8/P8SSR8AC/P8SSR8DC Demo Programs

All of demo programs will not work normally if PIO/PISO linux driver would not be installed correctly. During the installation process of PIO/PISO linux driver, the install-scripts "ixpio.inst" will setup the correct kernel driver. After driver(version 0.20.15 or the later driver version) compiled and installation, the related demo programs, development library and declaration header files for different development environments are presented as follows.

Table 3.1

Driver Name	Directory Path	File Name	Description
	include	piodio.h	PIO/PISO library header
ixpio-0.20.15	Lib	libpio.a	PIO/PISO static library
	examples/pisop8r8	dio.c	Digital input and output demo
		dio_a.c	DI and DO demo with library

3.1 Demo code "dio.c"

This demo program is used to output digital from COM[0..7] and NO[0..7], input digital data from DIA[0..7] and DIB[0..7].

3.2 Demo code "dio_a.c"

This demo program coded by using the static library "libpio.a". It is used to output digital from COM[0..7] and NO[0..7], input digital data from DIA[0..7] and DIB[0..7].