PISO-P16R16 PEX-P8R8/P16R16

Digital I/O Card

Linux Software Manual

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1. Linux Software Installation

The PIO-D48 can be used in Linux kernel 2.4.X to 4.15.X. For Linux O.S, the recommended installation and uninstall steps are given in Sec $1.1 \sim 1.2$

1.1 Linux Driver Installing Procedure

- Step 1: Copy the Linux driver "ixpio.tar.gz" in the directory "NAPDOS\Linux" of the companion CD or download the latest driver from our website to the Linux host.
- Step 2: You must use the '**root**' identity to compile and install PIO/PISO Linux driver.
- Step 3: Decompress the tarball "ixpio.tar.gz".
- Step 4: Type 'cd' to the directory containing the package's source code and 'type './configure' to configure the package for your linux system.
- Step 5: Type 'make' to compile the package.
- Step 6: You can type './ixpio.inst' to install the PIO/PISO driver module and build the device file "ixpioX" in the device directory "/dev" automatically.

1.2 Linux Driver Uninstalling Procedure

- Step 1: Type `cd' to the directory containing the package's source code.
- Step 2: Type `./ixpio.remove' to remove the PIO/PISO driver module.

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2. Static Library Function Description

The static library is the collection of function calls of the PIO-DIO cards for linux kernel 2.4.x and 2.6.x to 4.15.x system. The application structure is presented as following figure. The user application program developed by C (C++) language can call library "libpio.a" in user mode. And then static library will call the module ixpio to access the hardware system.

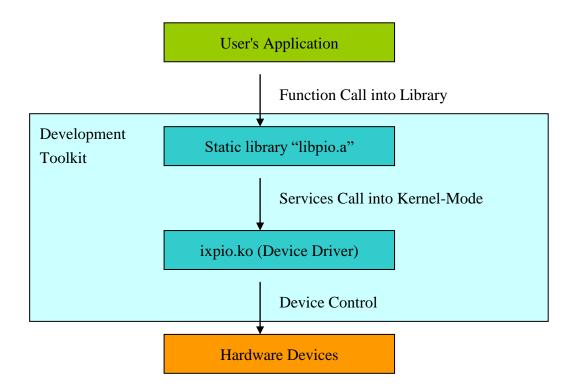


Figure 2.1

2.1 Table of ErrorCode and ErrorString

Table 2.1

Error Code	Error ID	Error String	
0	PIODA_NOERROR	OK (No error!)	
1	PIODA_MODULE_NAME_GET_ERROR	Module name can't get from file /proc/ixpio/ixpio	
4	PIODA_PORT_DEFINED_ERROR	Port number out of range	
5	PIODA_DIGITAL_OUTPUT_ERROR	Digital output error	
6	PIODA_DIGITAL_INPUT_ERROR	Digital input error	
23	PIODA_CARD_ID_ERROR	Read Card ID error	

2.2 Function Descriptions

Table 2.2

Function Definition				
char * PIODA_GetDriverVersion(void);				
char * PIODA_GetLibraryVersion(void);				
int PIODA_Open(char *dev_file);				
WORD PIODA_Close(WORD fd);				
WORD PIODA_DriverInit(WORD);				
WORD PIODA_Digital_Output(WORD, WORD, byte);				
WORD PIODA_Digital_Input(WORD, WORD, WORD *);				
WORD PIODA_CARD_ID(WORD fd, byte *id);				

2.3 PISO-P16R16/PEX-P8R8/P16R16 FUNCTIONS

2.3.1 PIODA_GetDriverVersion

Description:

To show the version number of PIO/PISO linux driver.

Syntax:

char * PIODIO_GetDriverVersion(Void)

Parameter:

None

Return:

The version of PIO/PISO linux driver version.

2.3.2 PIODA_GetLibraryVersion

Description:

To show the version number of PIO/PISO linux static library.

Syntax:

char * PIODIO_GetLibraryVersion(void)

Parameter:

None

• Return:

PIO/PISO linux static library version.

2.3.3 PIODA_Open

Description:

To open device file.

Syntax:

int PIODIO_Open(char *dev_file)

Parameter:

dev_file: The path of device file

• Return:

The file descriptor of device file. If the file descriptor < 0, it means that open device file failure.

2.3.4 PIODA Close

• Description:

To close device file.

Syntax :

Word PIODIO_Close(WORD fd)

Parameter :

fd: The file descriptor of device file that get from function PIODIO_Open

Return:

```
"PIODA_NOERROR"
(Please refer to "Section 2.1 Error Code")
```

2.3.5 PIODA DriverInit

• Description:

To allocates the computer resource for the device. This function must be called once before applying other PIODA functions.

• Syntax:

WORD PIODA_DriverInit(WORD fd)

• Parameter:

fd: The file descriptor of device file that get from function PIODIO_Open

• Return:

```
"PIODA_MODULE_NAME_GET_ERROR"
"PIODA_NOERROR"
(Please refer to "Section 2.1 Error Code")
```

2.3.6 PIODA_Digital_Output

Description :

This subroutine sends the 8 bits data to the specified I/O port.

Syntax:

WORD PIODA_Digital_Output(WORD fd, WORD port, byte data);

Parameter :

fd: The file descriptor of device file that get from function PIODIO Open.

port: The output port number.

PISOP16R16_DIOA: DO0~DO7 PISOP16R16_DIOA: DO8~DO15 PISOP16R16_DIO_ALL: DO0~DO15 data: 8 bits data.

Return:

"PIODA_PORT_DEFINED_ERROR"

"PIODA_DIGITAL_OUTPUT_ERROR"

"PIODA_NOERROR"

(Please refer to "Section 2.1 Error Code")

2.3.7 PIODA_Digital_Input

Description :

This subroutine reads the 8 bits data from the specified I/O port.

Syntax :

WORD PIODA_Digital_Input(WORD fd, WORD port, WORD *di_data);

Parameter :

fd: The file descriptor of device file that get from function PIODIO_Open.

port: The input port number.

PISOP16R16_DIOA: DI0~DI7 PISOP16R16_DIOA: DI8~DI15 PISOP16R16_DIO_ALL: DI0~DI15

di_data: A variable address used to storage the 8 bits input data.

Return:

"PIODA_PORT_DEFINED_ERROR"

"PIODA_DIGITAL_INPUT_ERROR"

"PIODA_NOERROR"

(Please refer to "Section 2.1 Error Code")

2.3.8 PIODA CARD ID

Description :

This subroutine can get Card ID.

The Card ID can be set using the SW1 dip switch, so it is easy to set the correct connections between cards and devices. So, by reading the Card ID users can check whether their program is accessing the correct card.

Syntax :

WORD PISOP16R16_Card_ID(WORD fd, byte *id)

Parameter :

fd: The file descriptor of device file that get from function PIODIO_Open.

id: The number of Card ID.

• Return:

"PIODA_CARD_ID_ERROR",
"PIODA_NOERROR".
(Please refer to "Section 2.1 Error Code")

3. PISO-P16R16/PEX-P8R8/P16R16 Linux Demo

All of demo programs will not work normally if PIO/PISO linux driver would not be installed correctly. During the installation process of PIO/PISO linux driver, the install-scripts "ixpio.inst" will setup the correct kernel driver. After driver (version 0.23.1 or the later driver version) compiled and installation, the related demo programs, development library and declaration header files for different development environments are presented as follows.

Table 3.1

Driver Name	Directory Path	File Name	Description	
	Include	piodio.h	PIO/PISO library header	
	lib	libpio.a	PIO/PISO static	
		libpio_64.a	library	
	examples/ pisop16r16_pexp8r8_p16r1 6	port.c	DI and DO demo	
ixpio			(ch0~ch15)	
		port2.c	DI and DO demo	
			(ch8~ch15)	
		port_a.c	DI and DO demo	
			with library	
		card_id.c	Read Card ID	
		card_id_a.c	Read Card ID with	
			library	

3.1 Demo code "port.c"

This demo program is used to output data to DO0~DO15 and read data from DI0~DI15

In Figure 3.1, use DI0 to test. When DI0 read value, then present 0x1, else is 0.

```
root@winson-G41M-ES2L:~/ixpio/examples/pisop16r16_pexp8r8_p16r16# ./port
Enter to continue, ESC to exit.
DO[0:15]=0x0000
DI[0:15]=0x0000
DO[0:15]=0xffff
DI[0:15]=0x0001
DO[0:15]=0xfffe
DI[0:15]=0x0000
DO[0:15]=0xfffd
DI[0:15]=0x0001
DO[0:15]=0xfffc
DI[0:15]=0x0000
DO[0:15]=0xfffb
DI[0:15]=0x0001
DO[0:15]=0xfffa
DI[0:15]=0x0000
DO[0:15]=0xfff9
DI[0:15]=0x0001
root@winson-G41M-ES2L:~/ixpio/examples/pisop16r16_pexp8r8_p16r16#
```

Figure 3.1

3.2 Demo code "port2.c"

This demo program is used to output data to DO8~DO15 and read data from DI8~DI15

In Figure 3.2, use DI0 to test. When DI0 read value, then present 0x1, else is 0

Figure 3.2

3.3 Demo code "port_a.c"

This demo is using the static library. Output data to DO0~DO15 and read data from DI0~DI15

In Figure 3.3 use DI0 to test. When DI0 read value, then present 0x1, else is 0.

```
root@winson-G41M-ES2L:~/ixpio/examples/pisop16r16_pexp8r8_p16r16# ./porta
Enter to continue, ESC to exit.

D0[0:15]=0x0000
DI[0:15]=0x0000

D0[0:15]=0x0001
D0[0:15]=0x0002
D1[0:15]=0x0000

D0[0:15]=0x0000

D0[0:15]=0x00001

D0[0:15]=0x00001

D0[0:15]=0x00001

D0[0:15]=0x00001

D0[0:15]=0x00001

D0[0:15]=0x00001

D0[0:15]=0x00000

D0[0:15]=0x00000

D0[0:15]=0x00005
D1[0:15]=0x00001
^[
root@winson-G41M-ES2L:~/ixpio/examples/pisop16r16_pexp8r8_p16r16#
```

Figure 3.3

3.4 Demo code "card_id.c"

Read Card ID.

root@winson-G41M-ES2L:~/ixpio/examples/pisop16r16_pexp8r8_p16r16# ./card_id CARD ID is 0x01

3.5 Demo code "card_id_a.c"

This demo is using the static library. Read Card ID.

root@winson-G41M-ES2L:~/ixpio/examples/pisop16r16_pexp8r8_p16r16# ./card_ida CARD ID is 1 root@winson-G41M-ES2L:~/ixpio/examples/pisop16r16_pexp8r8_p16r16#