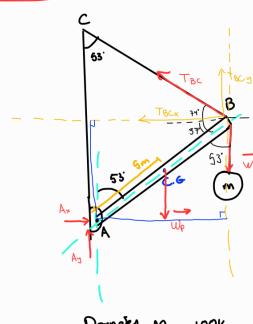
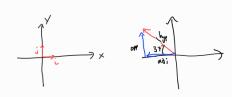
Exercices 11; 14 et 18 chapitre 3

#11



Hyp L est en équilibre

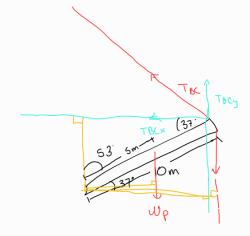
- 1) D.C.L
- 2) conditions equilibre



Donnels
$$Mp = 100 \text{Kg}$$

 $m = 50 \text{Kg}$

$$1 \leq F_{x} = A_{x} - T_{ec}(cos(37) = 0)$$



$$\leq M_A = \mathcal{M}_A^{\overrightarrow{TS}} + \mathcal{M}_A^{\overrightarrow{wp}} + \mathcal{M}_A^{\overrightarrow{w}} = \bigcirc$$

The Tocy
$$M_A \stackrel{\overrightarrow{\text{Toc}}}{=} + (T_{BC}, Cos(37)) \cdot (10 \cdot (cs(53)) + (T_{BC}, Sin(37)) \cdot (10 \cdot Cos(37))$$

$$M_A = -(W_P) \cdot (S \cdot Cos(37))$$

$$M_{A}^{\overrightarrow{w}} = -(w) \cdot (10 \cdot \cos(37))$$

$$\leq M_{A} = + \left(T_{BC} \cdot \left(\cos \left(37 \right) \right) \cdot \left(10 \cdot \left(\cos \left(53 \right) \right) + \left(T_{BC} \cdot \sin \left(37 \right) \right) \cdot \left(10 \cdot \cos \left(37 \right) \right) - \left(W_{p} \cdot y \right) \cdot \left(5 \cdot \cos \left(37 \right) \right) - \left(W \cdot y \right) \cdot \left(10 \cdot \cos \left(37 \right) \right) \right)$$

$$\leq F_{x} = A_{x} - \left(T \cdot \cos(24)\right) - \left(M_{0} \cdot g\right) \cdot \left(\cos(53)\right) - \left(\left(M \cdot g\right) \cdot \left(\cos(53)\right) = C\right)$$

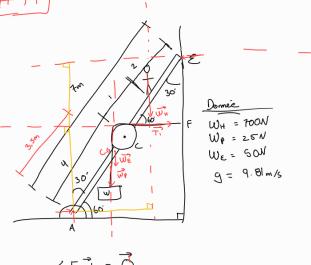
$$A_{H} = \left(A_{x} \cdot \sin(53)\right) - \left(A_{y} \cdot \cos(53)\right)$$

Direction

$$tan \Theta = \frac{Ay}{Ax}$$

$$\frac{\partial Hownow}{\partial Hownow}$$

14



$$\leq M_{A} = M_{A}^{\overrightarrow{wh}} + M_{A}^{\overrightarrow{we}} + M_{A}^{\overrightarrow{wh}} + M_{A}^{\overrightarrow{\tau,}} + M_{A}^{\overrightarrow{e}}$$

$$M_{\epsilon} = -(W_H) \cdot (5 \cdot \cos(60))$$

$$M_{\varepsilon}^{\widetilde{w}\widetilde{\varepsilon}} = -(W_{\varepsilon}) \cdot (\beta, 5 \cdot (\omega_{\varepsilon}(60)))$$

$$M_{\xi}^{\vec{w}\vec{p}} = -(w_{p}) \cdot (4 - \cos(60) - 0.1)$$

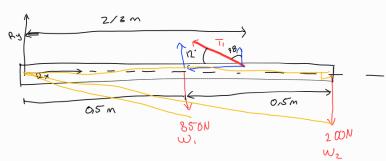
$$M_{\varepsilon}^{\tau} = -(\tau_{i}) \cdot (U \cdot Sin(60) + 0,1)$$

$$M_{\varepsilon}^{\vec{\epsilon}} = + (\varepsilon) \cdot (7 \cdot (\cos(30))$$

$$\leq M_{\varepsilon} = -(W_{H}) \cdot (5 \cdot \cos(60) - (W_{\varepsilon}) \cdot (3.5 \cdot \cos(60)) - (W_{\rho}) \cdot (3.9 \cdot \cos(60))$$

$$-(T_{i}) \cdot (4.1 \cdot \cos(30)) + (\varepsilon) \cdot (7 \cdot \cos(30)) = 0$$

 $W_{p}=T_{i}=25N$



$$\leq F_{\times} = R_{\times} - T \cdot Cos(12) = 0$$

$$\leq F_x = Nx -$$

$$\leq F_y = R_y + T. \sin(12) - W_1 - W_2 = 0$$

$$M_{R}^{\vec{T}} = + (T. Sin(12)) \cdot (2/3)$$

$$\mathcal{M}_{R}^{\overrightarrow{w_{i}}} = -(\omega_{i}) \cdot (0.5)$$

$$\left| \frac{\vec{w}_2}{\vec{k}} = -(w_2) \cdot (1) \right|$$

$$f_{\times} = 2646.35N$$

$$f_{x} = 2646.35N$$
 $f_{y} = -12.5N$ (mul orienter)