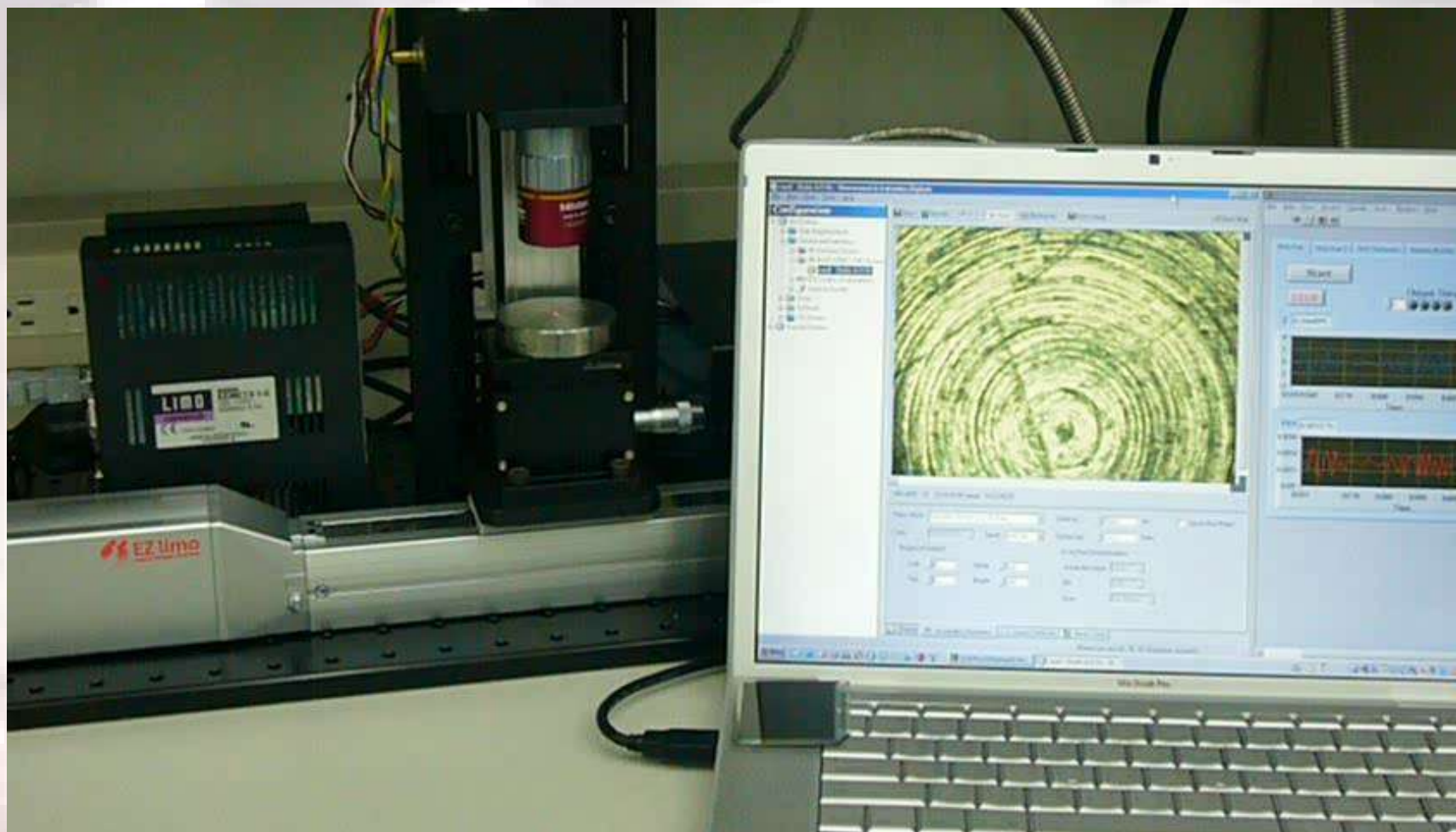
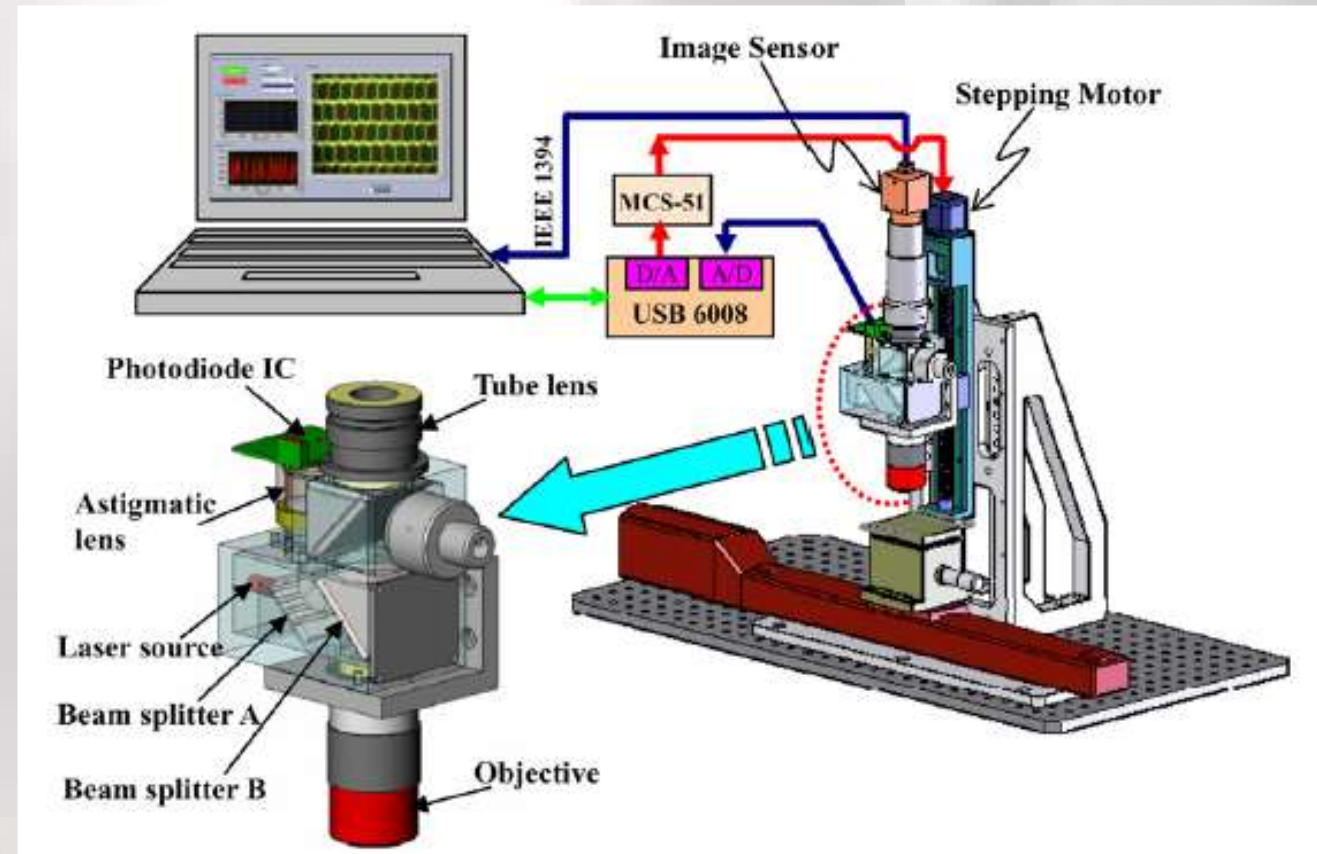
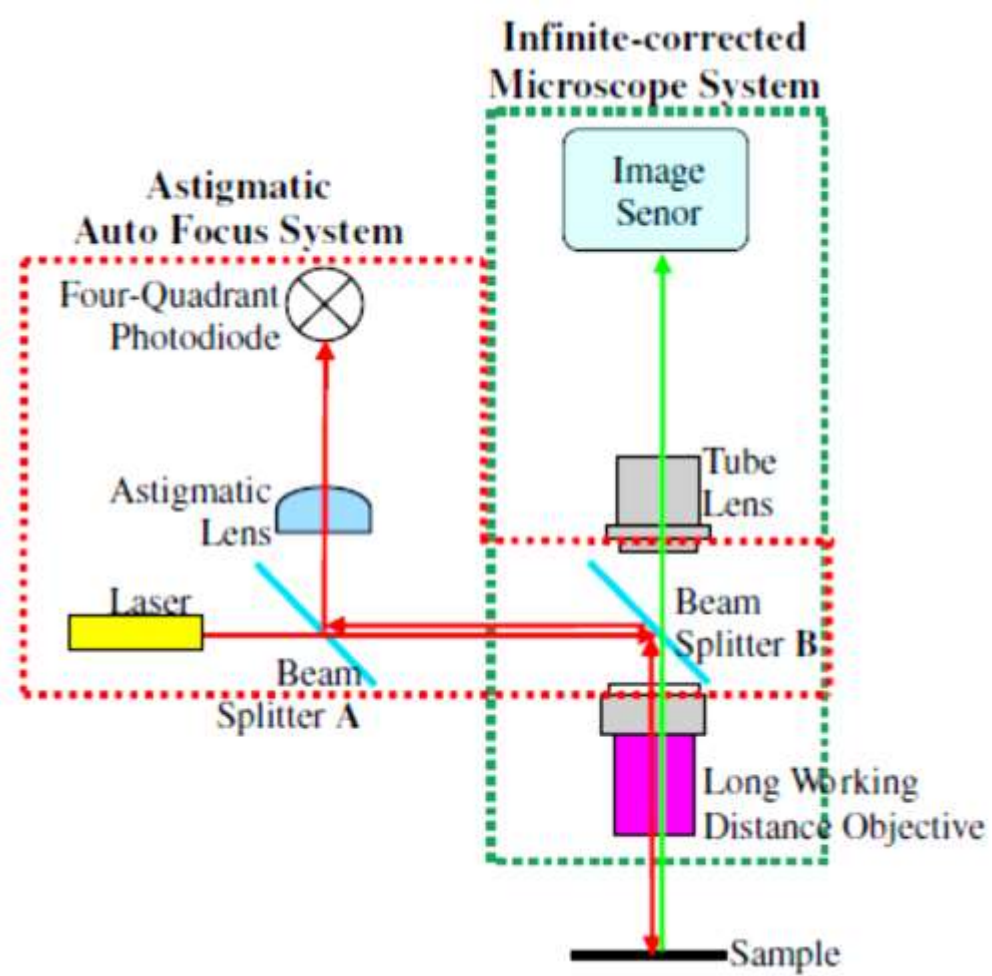


# Astigmatic Method and Applications

# Astigmatic Method and Applications



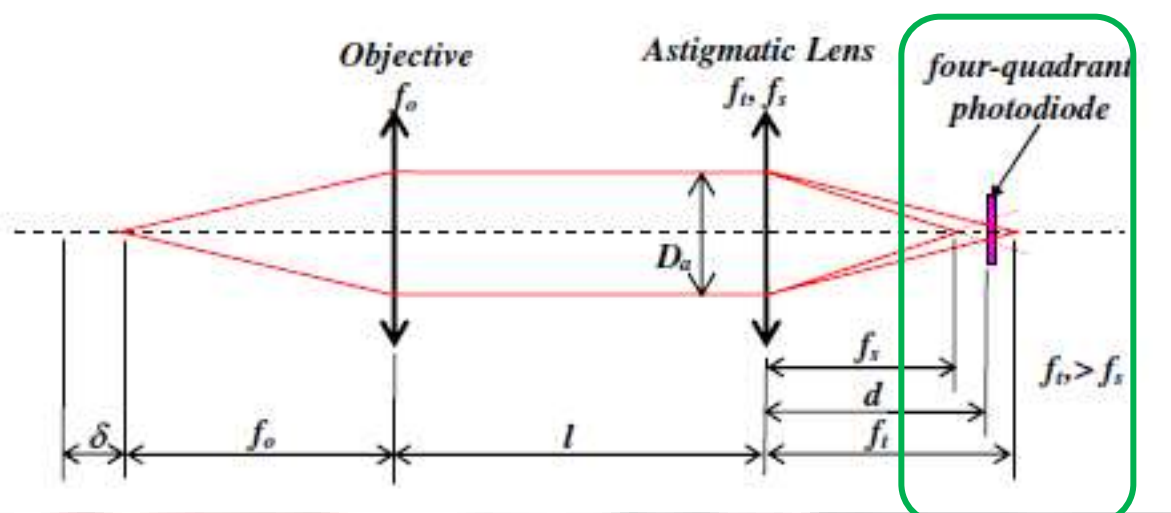
# Optical Layout



Microscopy with Astigmatic optical system enables autofocusing

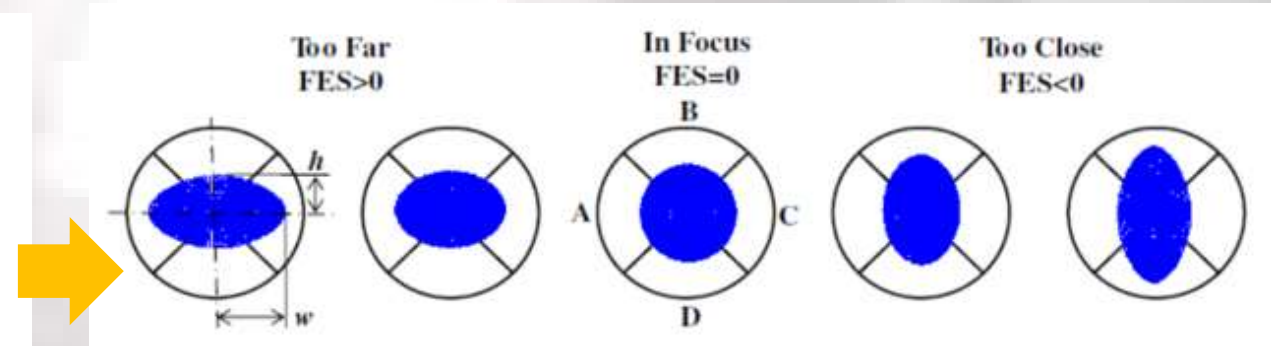
# Modeling based on Geometrical Optics

(No Gaussian Beam Considered)



The scheme of equivalent optical layout for an astigmatic automatic focus system

$f_o$ : objective's focal length,  
 $l$ : distance between the objective & the astigmatic lens,  
 $f_t$ : tangential focal length of the astigmatic lens,  
 $f_s$ : sagittal focal length of the astigmatic lens ( $f_t > f_s$ ),  
 $D_a$ : the diameter of the collimated laser beam  
 $d$ : the distance between the astigmatic lens and the four quadrant photodiode.



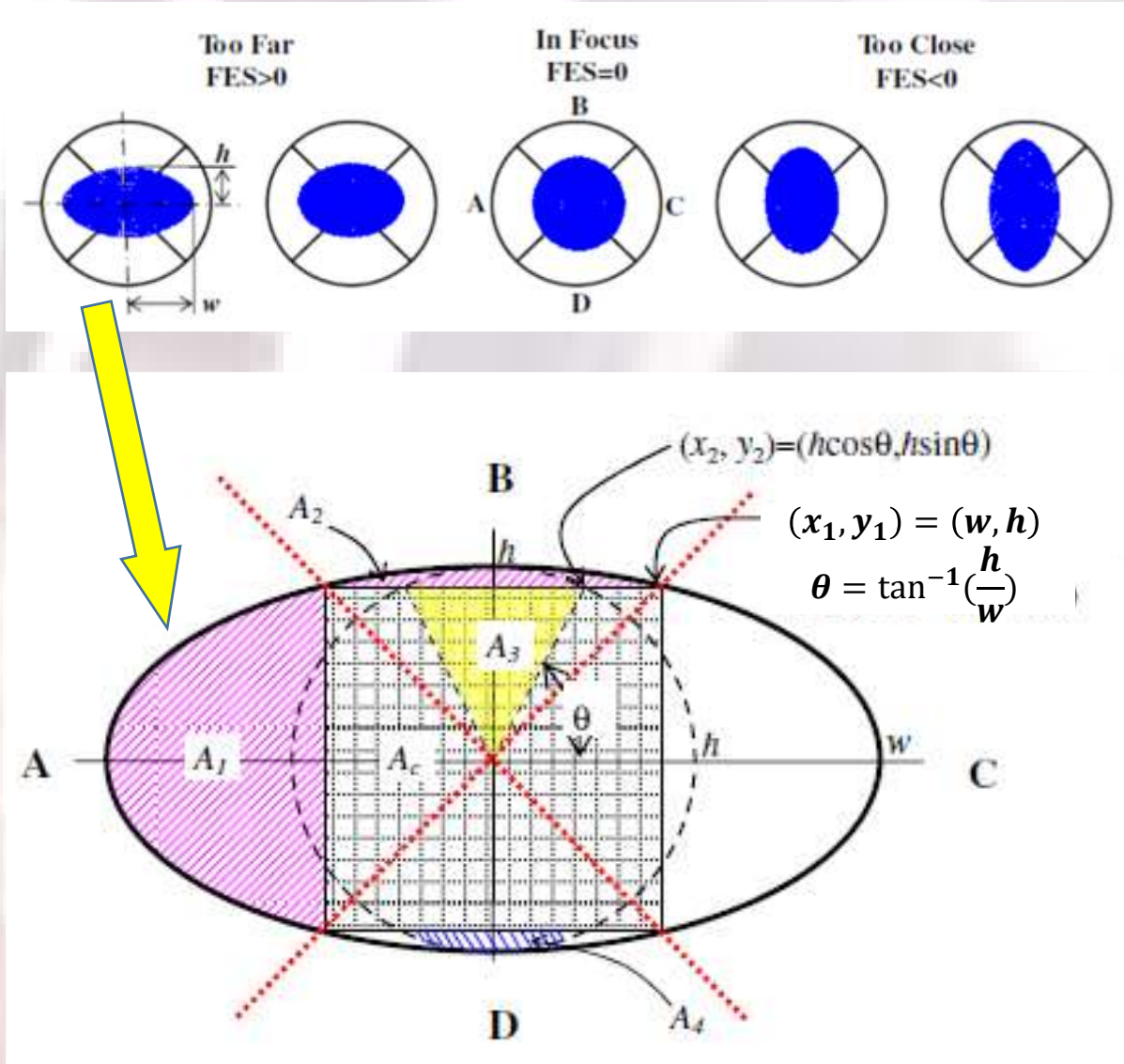
FES(focus error signal) determined by using signal of Quadrant Photodiode

$$FES = \frac{(Q_A + Q_C) - (Q_B + Q_D)}{Q_A + Q_B + Q_C + Q_D}$$

$$FES = \begin{cases} < 0, \text{ Too close} \\ = 0, \text{ In Focus} \\ > 0, \text{ Too Far} \end{cases}$$



# Spot Analysis



FES(focus error signal) is defined to be

$$FES = \frac{(Q_A + Q_C) - (Q_B + Q_D)}{Q_A + Q_B + Q_C + Q_D}$$

$$\Rightarrow FES = \frac{2(A_1 - A_2)}{\pi w h} \quad \begin{array}{l} \text{Area difference} \\ \text{Area of Ellipse} \end{array}$$

$$\Rightarrow FES = \frac{4}{\pi} \tan^{-1} \frac{h}{w} - 1$$

Case 1.  $h = 0 \Rightarrow FES = -1$

$\Rightarrow$  Ellipse become a horizontal line

Case 2.  $w = 0 \Rightarrow FES = 1$ ,

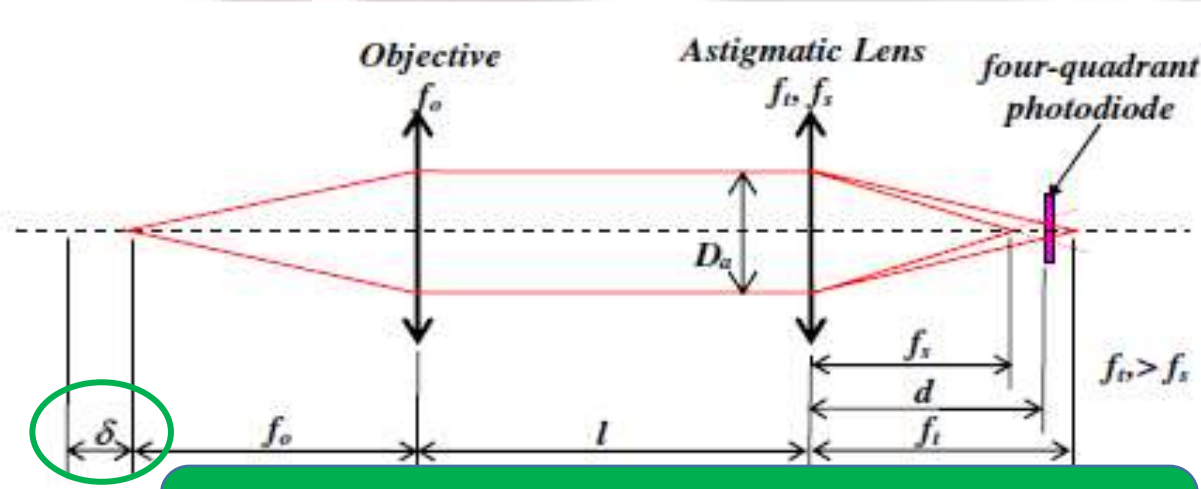
$\Rightarrow$  Ellipse become a vertical line

Case 3.  $h = w \Rightarrow FES = 0$

$\Rightarrow$  Ellipse become a circle

spot area relationship on the fourquadrant photodiode plane

# Geometrical Optics Modeling



The sample defocus distance  $\Delta z$  is half of the point light source distance  $\delta$

## Mapping Light Source to imaging Plan

$$S_s = \frac{f_s(l - f_o)\delta - f_o^2 f_s}{(l - f_o - f_s)\delta - f_o^2}$$



$$S_t = \frac{f_t(l - f_o)\delta - f_o^2 f_t}{(l - f_o - f_t)\delta - f_o^2}$$

$$w = \left| \frac{S_s - d}{S_s} \right| \frac{D_a}{2}$$

$$h = \left| \frac{S_t - d}{S_t} \right| \frac{D_a}{2}$$

To form a circular spot on the four-quadrant photodiode with a point light source located at the objective's focal point ( $\delta = 0$ ), the position of the photodiode is defined to be

$$d = \frac{2f_t f_s}{f_t + f_s}$$

Considering  $S_t = S_s = d$

$$\Rightarrow \delta_t = \frac{f_0^2(f_t - f_s)}{(1 - f_0)(f_t - f_s) + 2f_tf_s} = \frac{f_0^2}{(1 - f_0) + e}$$

$$\delta_s = \frac{f_0^2(f_t - f_s)}{(1 - f_0)(f_t - f_s) - 2f_tf_s} = \frac{f_0^2}{(1 - f_0) - e}$$

## Where

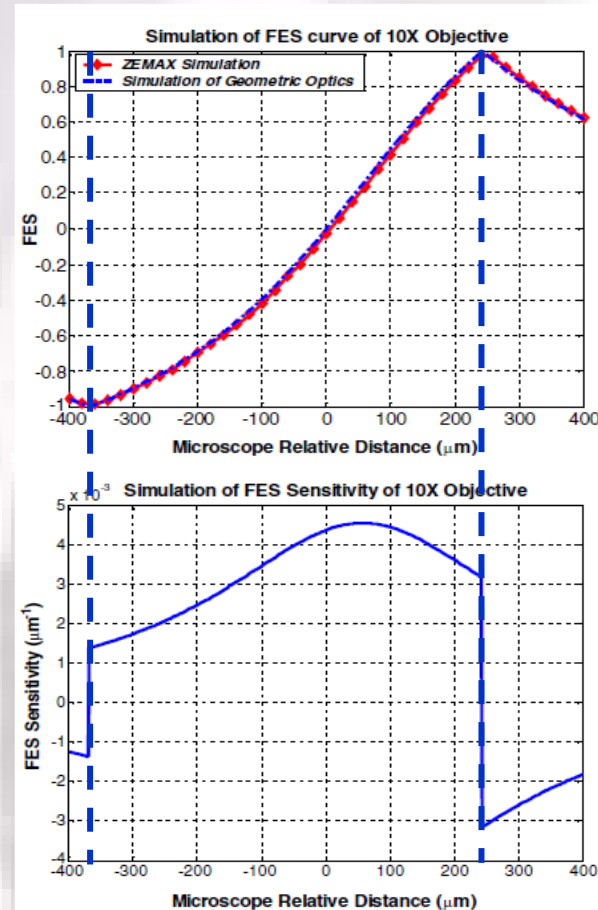
$$e = \frac{2f_t f_s}{f_t - f_s}$$

$$f_t = \frac{ed}{e - d}; f_s = \frac{ed}{e + d}$$

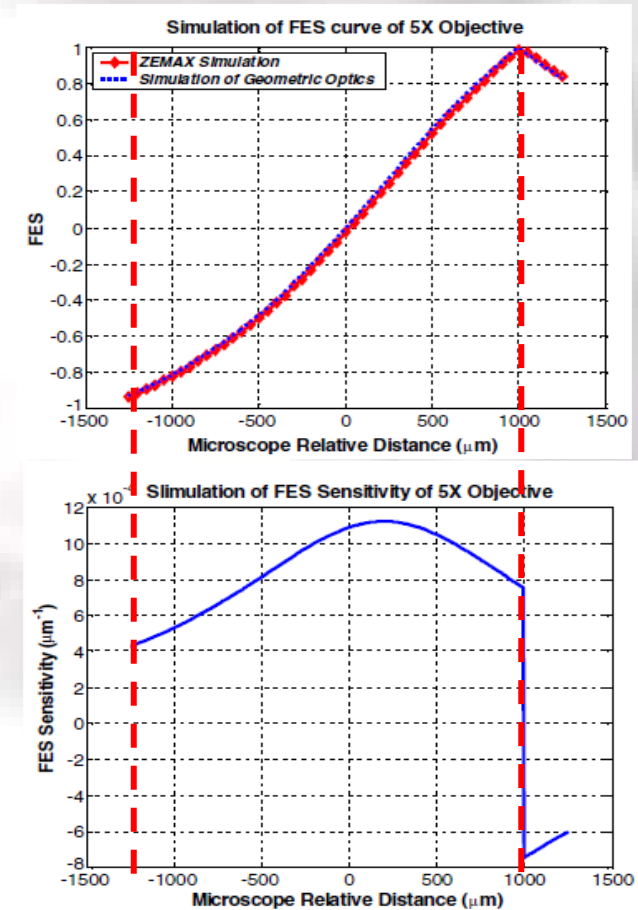
# Simulation of FES



Mitutoyo, MPlan Apo NIR 20X  
 NA=0.4, WD=20.0 mm  
 Wavelength range 480, 1800 nm



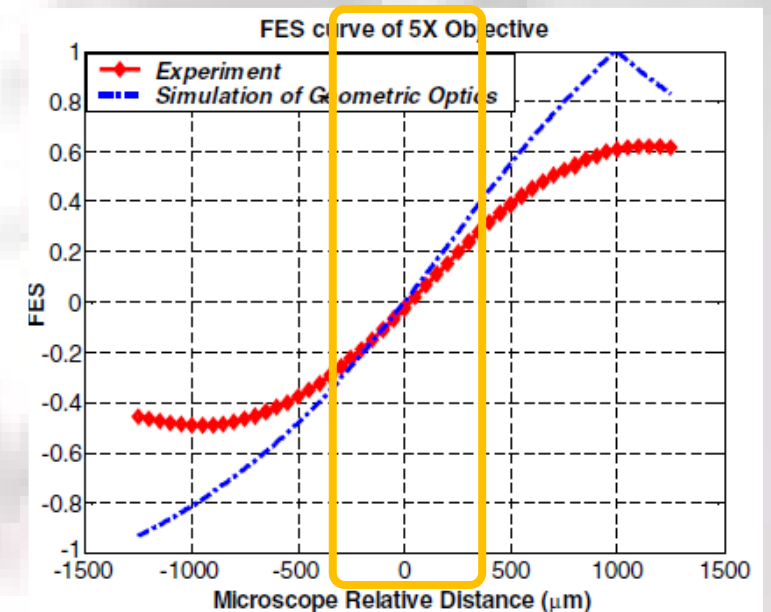
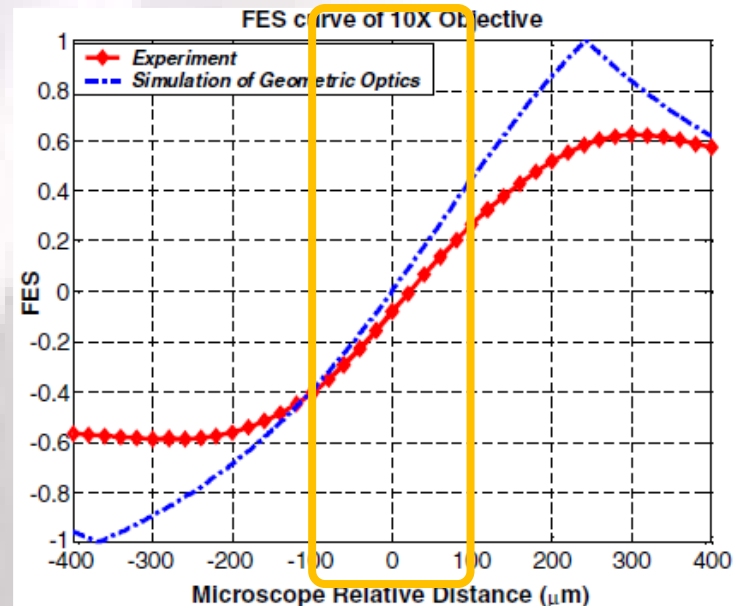
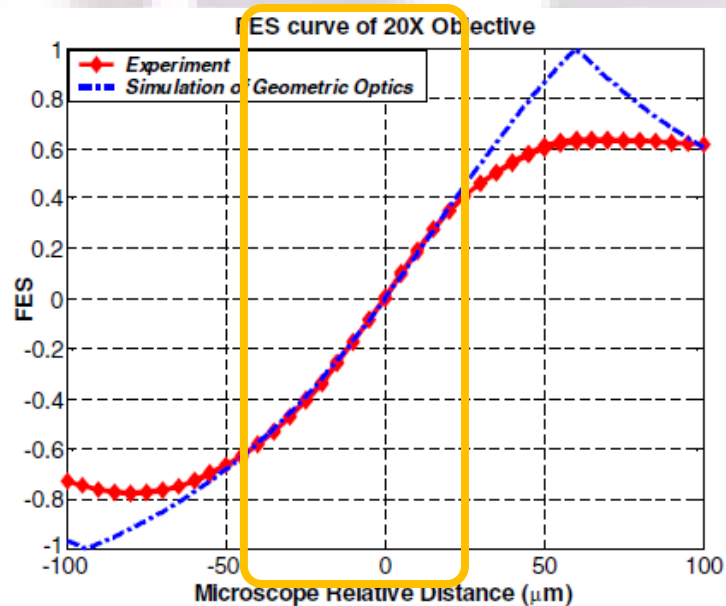
10X



5X

Objective Lens: Magnificent  
 Possible Working Range

# Astigmatic Lens Method for Autofocusing System



Microscope objective	FES sensitivity at focus position	FES at focus position	Depth of focus	Focusing window
20×	$18.40 \times 10^{-3} \mu\text{m}^{-1}$	0.004	$1.7 \mu\text{m}$	$0.004 \pm 0.016$
10×	$3.58 \times 10^{-3} \mu\text{m}^{-1}$	-0.082	$4.1 \mu\text{m}$	$-0.082 \pm 0.08$
5×	$0.87 \times 10^{-3} \mu\text{m}^{-1}$	-0.023	$14.0 \mu\text{m}$	$-0.023 \pm 0.06$

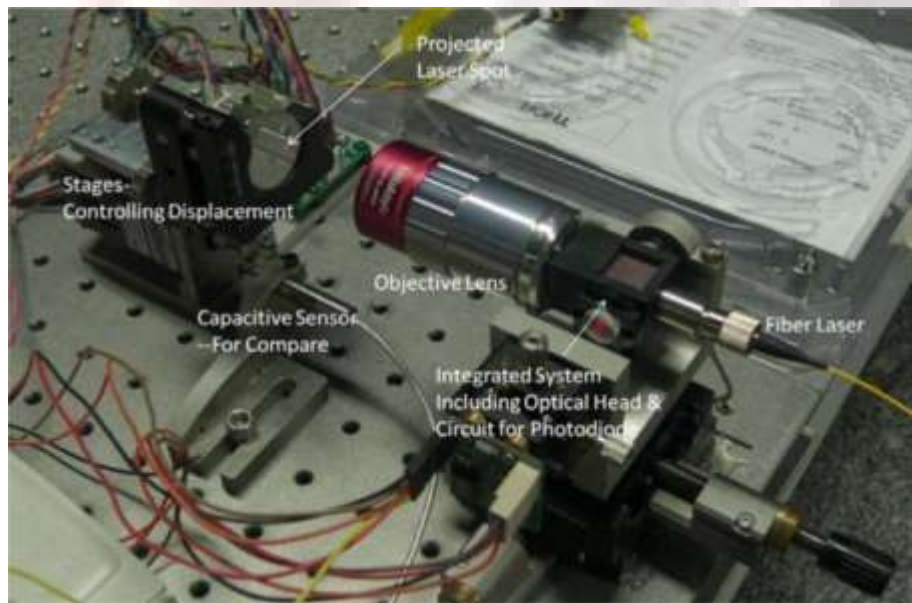
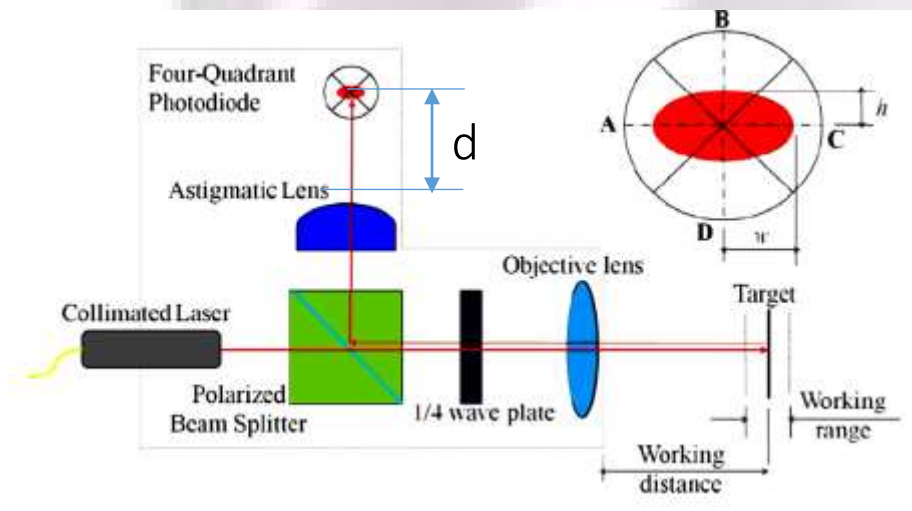
Center of Spot Size  
Determined by FES

Objective Lens

Laser Spot Size



# For Displacement Measurement



Objective Lens:

Mitutoyo, MPlan Apo NIR 5X

Focal Length: 40 mm

WD: 35 mm

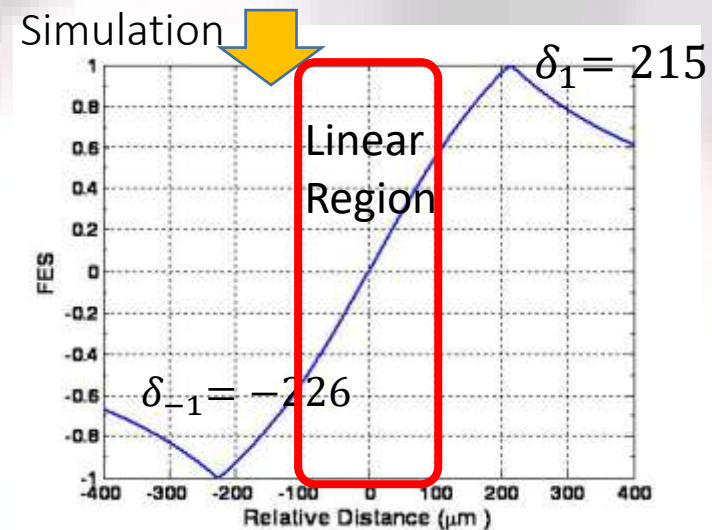
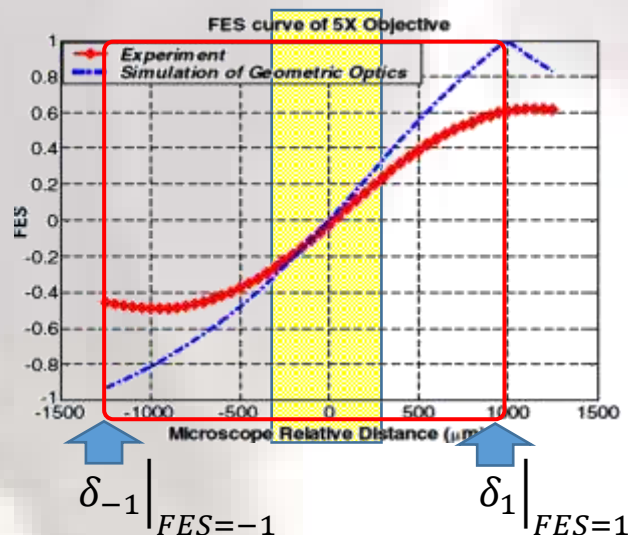
$d = 50 \text{ mm}$

Define  $\delta_i = \delta @ FES = i, FES \in [-1, 1]$

Working Range:  $200 \mu\text{m}$  (FES- $\delta$  curve is Linear)

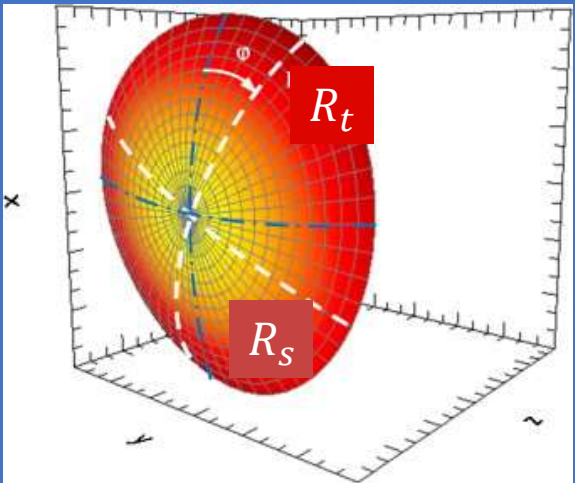
$\Rightarrow \delta_1 = 215 \mu\text{m}$  for design

$\Rightarrow (f_s, f_t) = (49.321 \text{ mm}, 50.699 \text{ mm})$



# System Development

Bi-conic Lens



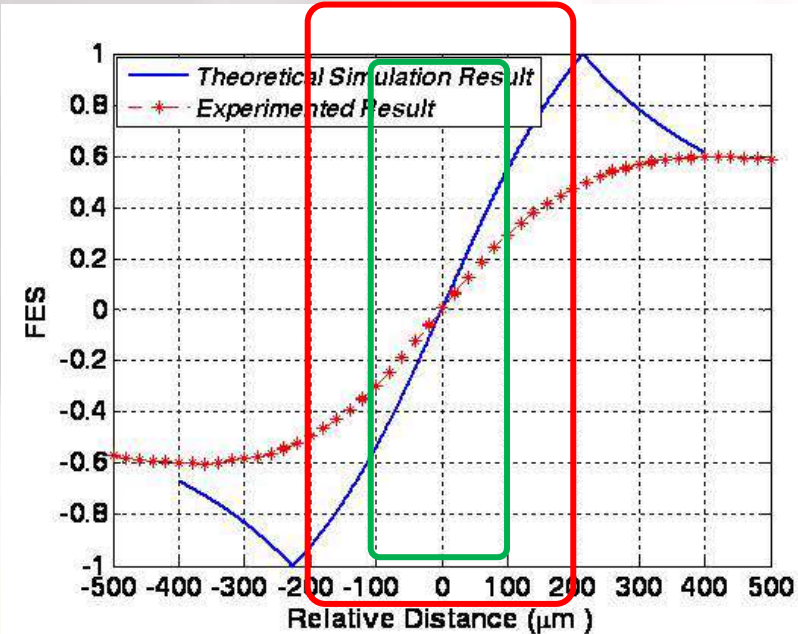
Methodical Model for Optical Surface

$$z = \frac{x^2/R_s + y^2/R_t}{1 + \sqrt{1 - (x/R_s)^2 - (y/R_t)^2}}$$

Design Analysis Results  
 $(f_s, f_t) = (49.321 \text{ mm}, 50.699 \text{ mm})$



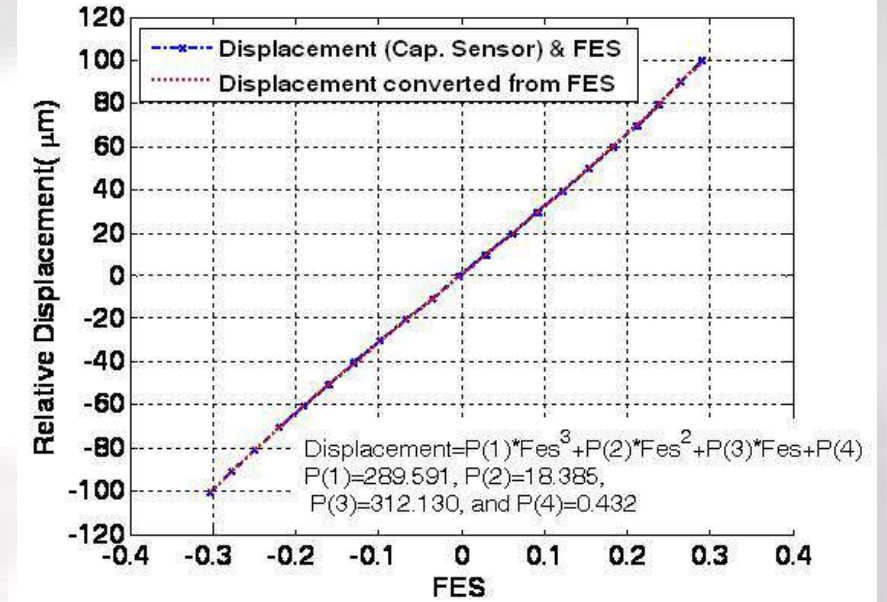
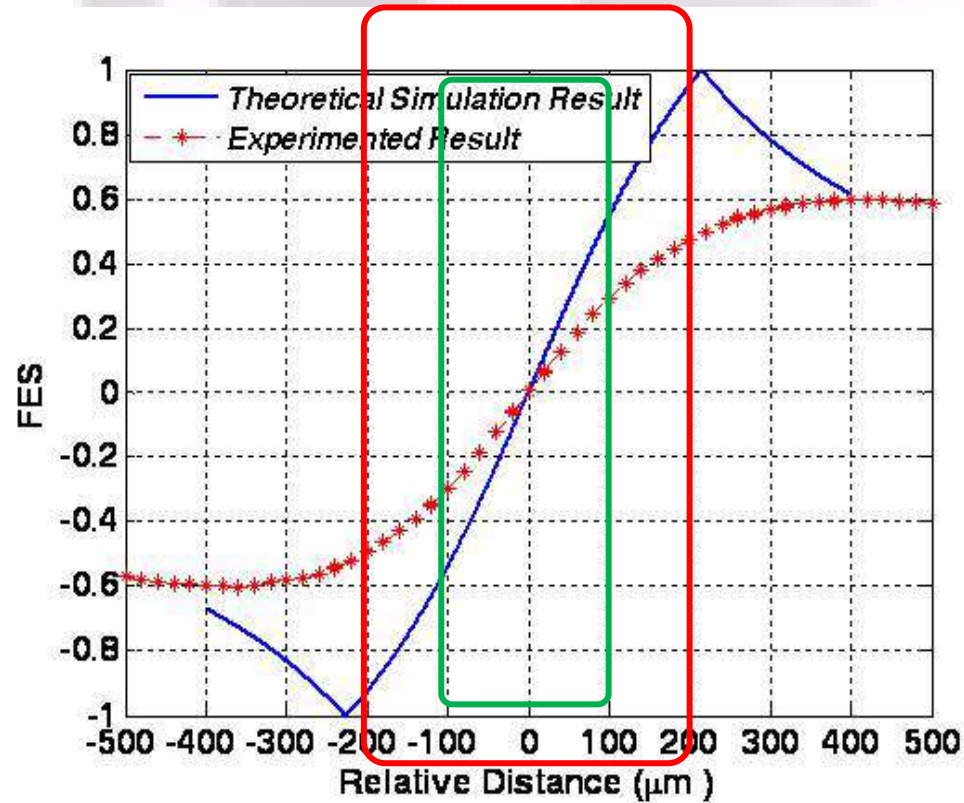
By using PMMA,  $n=1.49$   
 $\Rightarrow R_s = 24.167 \text{ mm}; R_t = 24.842 \text{ mm}$



Parameters	Spec.
Displ. Range	$\pm 100 \mu\text{m}$
Meas. Sensitivity	$3.35 \times 10^{-3}$ (a. u./ $\mu\text{m}$ )
Accuracy	$\leq 0.6 \mu\text{m}$
Working Range	37.5 mm



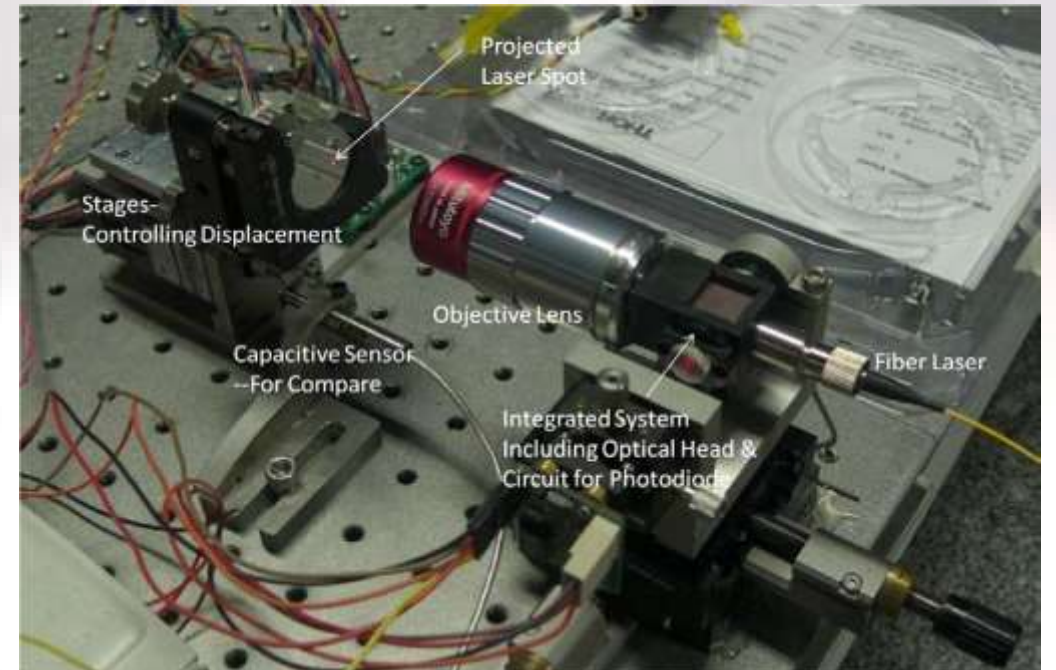
# Calibration



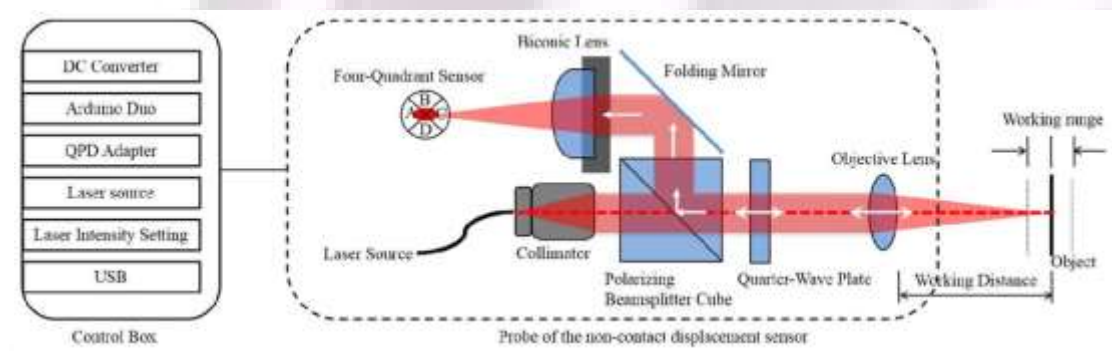
Fitting Displacement with FES by

$$\text{Disp} = \sum_{i=0}^3 a_i \times \text{FES}^i$$

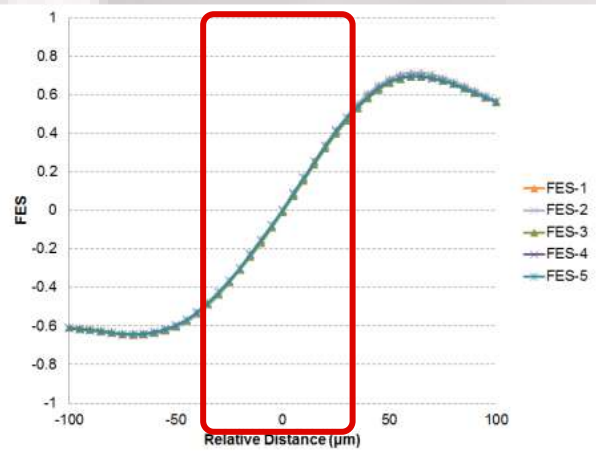
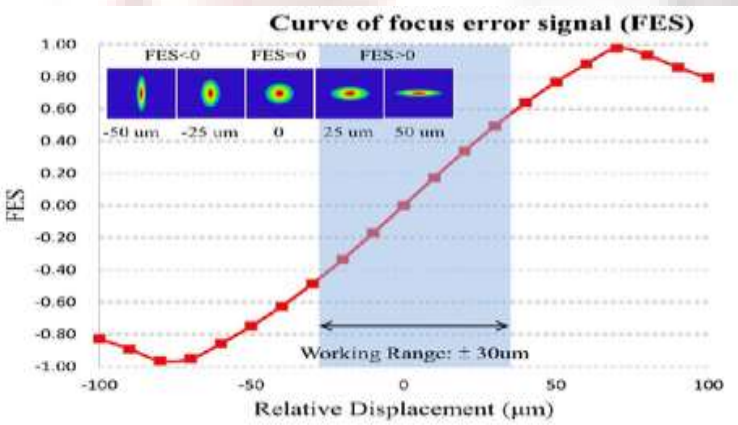
$$\Rightarrow [a_i] = [0.43, 312.13, 18.39, 289.60]$$



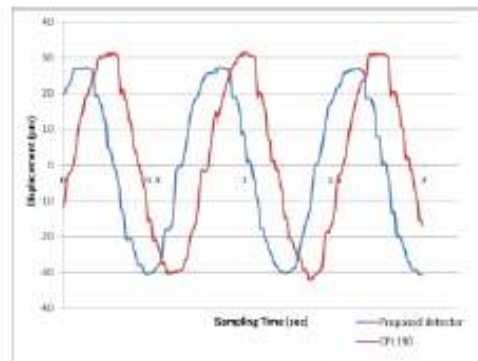
# Vibration measurement



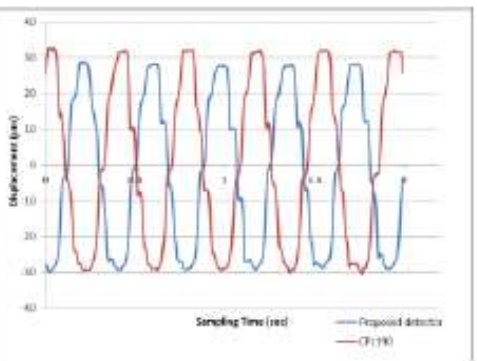
objective lens,  $f_o=10\text{mm}$   
Diode Laser, 637 nm  
 $f_t = 53.979 \text{ mm}$ ;  $f_s = 46.566 \text{ mm}$   
QPD is 49.7 mm away from astigmatic lens



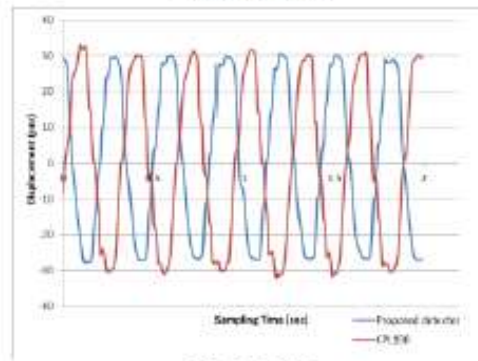
$$\text{FES}(d) = 0.0158d + 0.0152$$



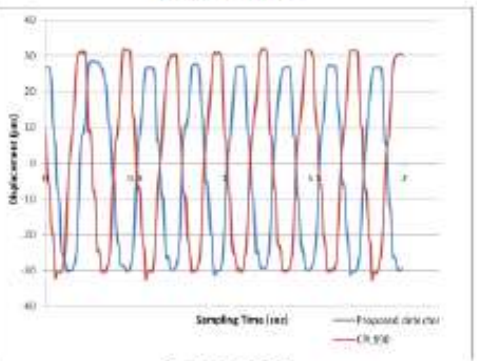
(A) 1.33Hz



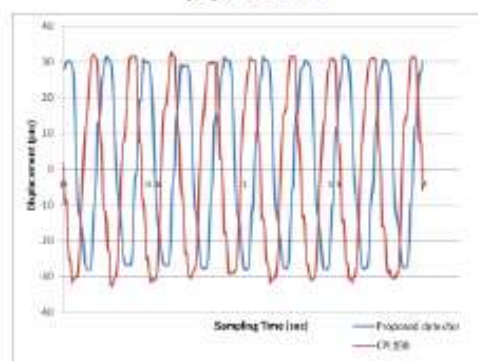
(B) 2.67Hz



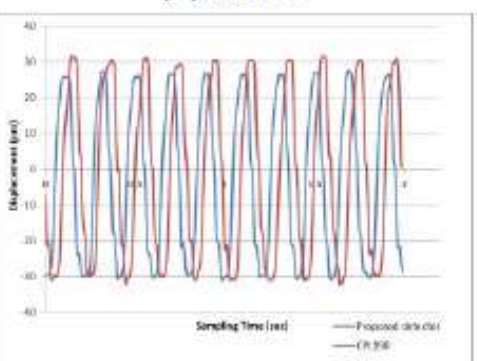
(C) 3.33Hz



(D) 4.00Hz



(E) 4.67Hz

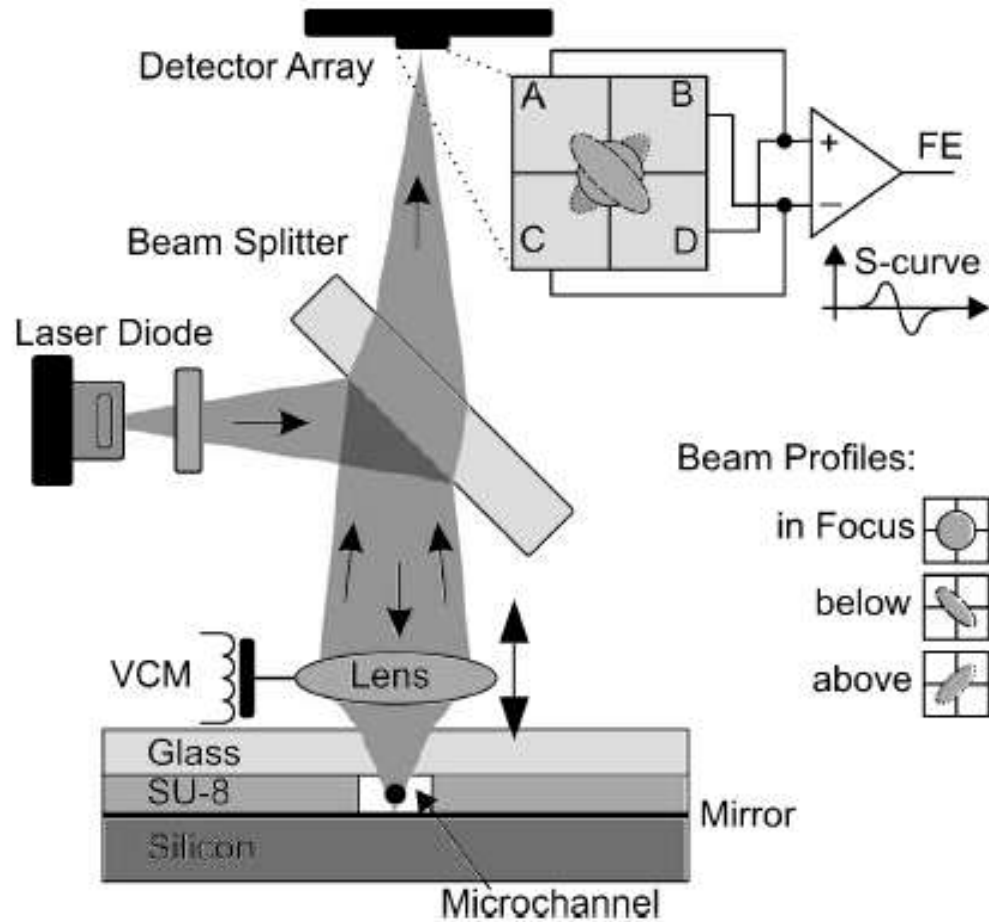


(F) 5.33Hz

Comparing with Capacitor Displacement Sensor



# Application of DVD pickup heads



Scanning Vertically in Constant Velocity

