

My Title is Long

Master Thesis in Intelligente Industrieroboter of

My Name

At the Department of Informatics Institute for Anthropomatics and Robotics (IAR) -Intelligent Process Control and Robotics (IPR)

First reviewer: Prof. Dr.-Ing. habil. Björn Hein

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xx. Month 20XX - xx. Month 20XX

Karlsruher Institut für Technologie Fakultät für Informatik Postfach 6980 76128 Karlsruhe

Todo list

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I declare that I have developed and written the enclosed thesis completely by myself, and have not used sources or means without declaration in the text.
Karlsruhe, August 18, 2017
(My Name)



Abstract

English abstract.

Keywords: Keywords, of, my, Thesis

Zusammenfassung

Mein Titel ist lang

Deutsche Zusammenfassung

Stichwörter: Die, Stichwörter, für, meine, Arbeit

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	and Inner UR for upper radius. The real value of inner lower radius for
	object Pitcher is very hard to be determined precisely, therefore the real
	value is marked with n/a

1. Introduction

As an useful aid in all scientific work following book is recommended: [1]

... Hello, here is some text without a meaning. This text should show what a printed text will look like at this place. If you read this text, you will get no information. Really? Is there no information? Is there a difference between this text and some nonsense like "Huardest gefburn"? Kjift – not at all! A blind text like this gives you information about the selected font, how the letters are written and an impression of the look. This text should contain all letters of the alphabet and it should be written in of the original language. There is no need for special content, but the length of words should match the language.

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1.0.1. Introduction Sub

Stuff

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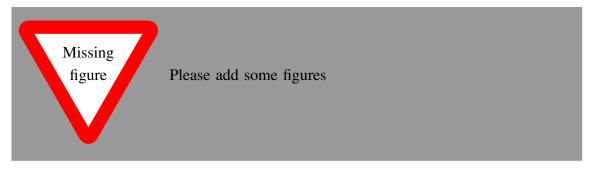
2. State of the art

3. Methods

4. Concept

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5. Implementation



6. Results

Object	Speed [cm/s]	Inner LR [cm]	Inner UR [cm]
	real	n/a	5.65
Pitcher	4.60	3.71 ± 0.67	5.09 ± 2.23
	10.64	3.55 ± 0.57	6.14 ± 0.69
	real	7.55	7.55
Cookie O	4.60	6.98 ± 0.27	6.98 ± 0.27
	10.64	6.77 ± 0.26	6.77 ± 0.26

Table 6.1.: Estimated objects inner parameters on different speeds compared to real sizes of the object. Inner LR stands for lower inner radius of the object and Inner UR for upper radius. The real value of inner lower radius for object *Pitcher* is very hard to be determined precisely, therefore the real value is marked with n/a.

7. Discussion

8. Conclusion

. .

Bibliography

[1] M. Deininger, H. Lichter, J. Ludewig, and K. Schneider. (1992) Studienarbeiten ein leitfaden zur vorbereitung, durchführung und betreuung von studien, diplom- und doktorarbeiten am beispiel informatik. Wiesbaden. [Online]. Available: http://link.springer.com/book/10.1007/978-3-322-99375-5

Appendix

A. First Appendix Section

ein Bild

Figure A.1.: A figure