

HACKATHON Chapter III - 2025



BERLIN 2025





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PITCHING SESSION

Porto Motive



The Plan

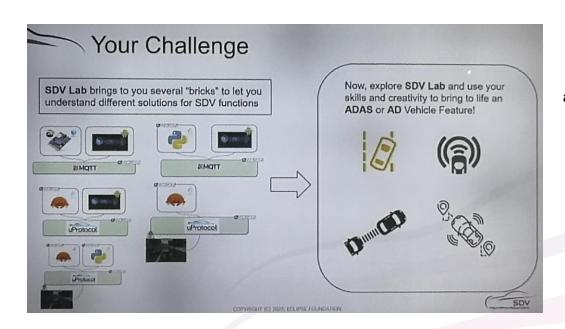
We chose the SDV Lab.

Initial Situation

At the Hackathon
Eclipse SDV Chapter Three, we
were challenged to
choose between
two different
tracks:

1.Software-Defined Vehicle (SDV) Lab

2.Mission: Update Possible



Why?

Because, having **no prior experience** in the **automotive** field, it seemed:

- 1. **more intuitive** for us to start with this challenge.
- 2. From a learning perspective, it also felt more logical to first understand how to implement car features before moving on to the update challenge (i.e., learn first, update later).



The Plan



Main Idea

- **1.Prevent rear-end collisions** by enabling the first car in a traffic jam queue to deviate when a vehicle approaches at high speed (in cases where the collision would not otherwise cause a massive chain reaction).
- **2.Reduce the effects of collisions** (especially in traffic jams) by redistributing the impact across the queue of vehicles similar to Newton's cradle ultimately **saving lives**, which is our primary goal.

Plan

- 1. We will implement an adaptive Rear Collision Evasion System (RCES) as a proof of concept, which we name it as Backward Automotive Life-Saving System (or B.A.L.S.).
- 2. To achieve this, we will use **CARLA** (the open-source driving simulator) and design an **algorithm** that **leverages RADAR** to **detect vehicles approaching from behind/rear**. The system will then **automatically trigger an evasive maneuver**, deviating the car to the left or right (depending on available space).

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∖ Team and Structure



| Name | Role(s) |
|---------------------|-----------|
| Bruno Miguel | developer |
| Rui Almeida | developer |
| Miguel Biltes | developer |
| João Silva | developer |
| Bernardo Esteves | developer |



The Product / Service / Added Value

Rear Collision Evasion System (RCES)

The problem

- In traffic jams, the risk of rear-end collisions is high.
- Most current systems only prepare occupants (tensioning seat belts, headrests, hazard lights)
- Active technology to evade the vehicle and prevent or mitigate the impact does not exist

Benefits

- Increased safety in traffic jams and highways
- Real innovation: from passive to active protection against rear-end collisions
- Potential for patent and competitive differentiation
- Scalable for future autonomous vehicles and cooperative driving ystems

Our solution

RCES - Rear Collision Evasion System

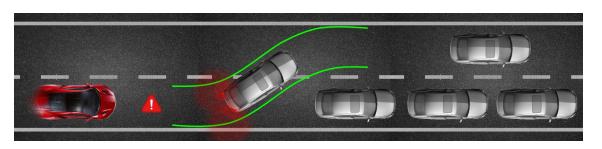
- Intelligent detection of rapidly approaching vehicles from the rear (cameras, radar, lidar)
- Real-time assessment of lateral and forward space
- Automatic microevasions to the left/ right (when safe) to reduce or avoid impact
- Integration with V2V (Vehicle-to-Vehicle Communication): surrounding vehicles collaborate to open soace for evasive maneuver

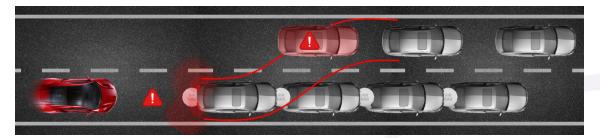
If you can't avoid the traffic jam, avoid the impact.

The most important goal and main purpose and improvement of this solution (namely comparing with market benchmark) is that this solution doesn't exist.... ... And effectivelly this system can save lifes.



How it works - scheme





How it works

- 1. If there are vehicles in front of the car, the system will attempt to steer the car into an adjacent lane (either to the right or left), depending on whether the car is currently in the leftmost or rightmost lane, and only if a lane is available for the maneuver.
- 2. If no adjacent lane is available, the car will prepare for the collision by unlocking the brakes (of our car and the other cars) and attempting to distribute the force of the impact across all involved vehicles, minimizing the damage.





How it works – Video 1





How it works – Video 2



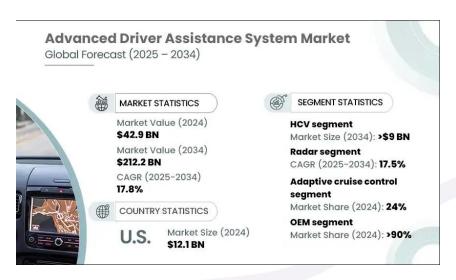


The Market & The Competition

1. Market & Market Size

Market Opportunity

- Automotive Safety Systems Market (ADAS & Active Safety)
 - Global market size (2024): \$42B+
 - Expected growth: CAGR ~10% until 2030
 - Driven by regulation (EU NCAP, NHTSA, UN ECE standards) and consumer demand for safer vehicles.



Competitors

- Indirect: Current ADAS providers (Bosch, Mobileye, Continental) focus on front/side collision avoidance and emergency braking, not rear collision evasion.
- **Direct**: None offering an **active rear collision avoidance maneuvering system** this is a **white space** opportunity.



The Market & The Competition

Target Customers

- OEMs (Original Equipment Manufacturers): Car makers like Mercedes, BMW, Tesla, Toyota, VW, Hyundai.
- Tier 1 Suppliers:

Bosch, Continental, ZF, Valeo — companies that integrate new safety tech into vehicles.

•Aftermarket & Fleet Operators:

Possibility of retrofitting fleet vehicles (taxis, logistics, ride-sharing).

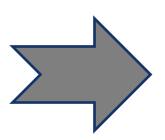




The Market & The Competition

Our Differentiation:

- Active evasion system → prevents or reduces the collision
- B.A.L.S. integrates communication for cooperative safety
- Adaptive real-time micromaneuvers (steering & brake release to maximize force distribution) Balls make your life safier.



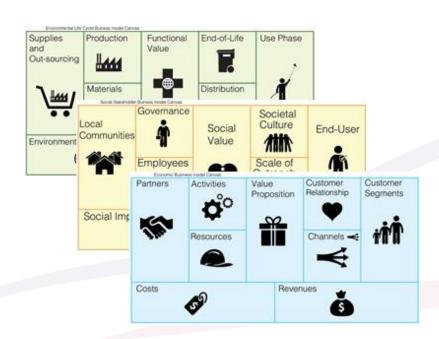
(Business) Opportunity

- Current solutions are passive → they only prepare occupants (seatbelts, headrests, hazard lights)
- Governments and insurers increasingly demand safety-first technology
- Global push for road safety and autonomous driving Technologies
- Increasing adoption of ADAS (Advanced Driver Assistance Systems) in all vehicle segments
- Potential integration into future autonomous cars and fleet management systems



2. Business Model

- Licensing to OEMs: License RCES software + hardware integration kits to car manufacturers.
- Partnerships with Tier 1 suppliers: Collaborate with Bosch, Continental, ZF, or Valeo to embed RCES into their existing ADAS platforms.
- **Retrofit Kits** (long-term): Hardware/software retrofit for fleet vehicles (logistics, taxis, ride-hailing, buses).
- Revenue Streams:
 - Licensing fees per vehicle
 - Long-term royalties (per unit sold with RCES)
 - Potential SaaS extension for V2V communication (subscription for fleet connectivity).





3. Implementation Plan

Phase 1 – Concept & Prototype (0–12 months)

- Simulation in CARLA + Al-based trajectory planning.
- Proof-of-concept with RADAR + camera + micro-evasive maneuvering algorithms.

Phase 2 – Pilot & Testing (12–24 months)

- Build partnerships with universities / automotive labs.
- Test on real vehicles (retrofit kit with RADAR + ECUs).
- Safety validation under EuroNCAP crash test protocols.

Phase 3 – Industrial Partnerships (24–36 months)

- Collaborate with **Tier 1 suppliers** for system integration.
- File patents on RCES algorithms and V2V integration.
- Begin pilot integration with 1-2 **OEMs**.

Phase 4 – Commercial Rollout (36+ months)

- Launch RCES as an embedded system in new vehicles.
- Retrofit kits for fleets in parallel.





4. Investment Needs

• 40% – Research & Development

• 30% – Pilot testing & certification with partners

· 20% - Business development & partnerships •

• 10% – Legal, patents & regulatory approvals



Seed Stage (Year 1-2): ~€2-3M

• R&D & Talent: Hire AI engineers, automotive software developers, safety experts.

• Hardware: RADAR, LIDAR, ECUs, testing vehicles.

• Simulation & Validation: CARLA infrastructure, real-world prototyping.

• IP Protection: Patent filing and legal costs.



Series A (Year 2-3): ~€10-15M

- Pilot Programs with OEMs and Tier 1 suppliers.
- **Regulatory Compliance** (EuroNCAP, NHTSA validation).
- Scaling R&D for V2V integration.



Series B (Year 3-5): ~€30M+

- Commercial Partnerships with OEMs.
- Mass production readiness.
- Retrofit solutions for fleet market.





- Market: €40B+ growing, with a white space (no active rear collision evasion tech today).
- Clients: OEMs, Tier 1 suppliers, fleets.
- Business Model: Licensing + partnerships + retrofit kits.
- Plan: Prototype → Pilot → Partnerships → Commercial launch.
- Investment: Initial €2-3M for R&D + IP, scaling to €30M+ for commercial rollout.

Sources:

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Thank You slide

Thank your audience and encourage them to get in touch afterwards.

