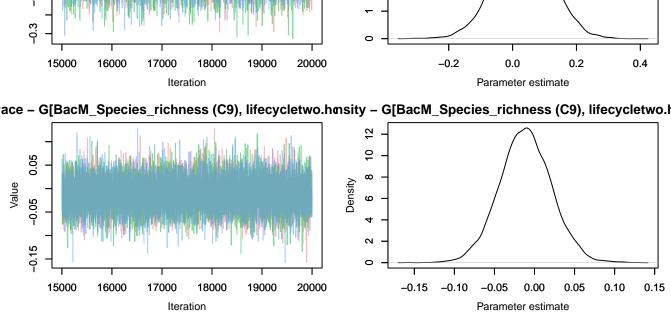
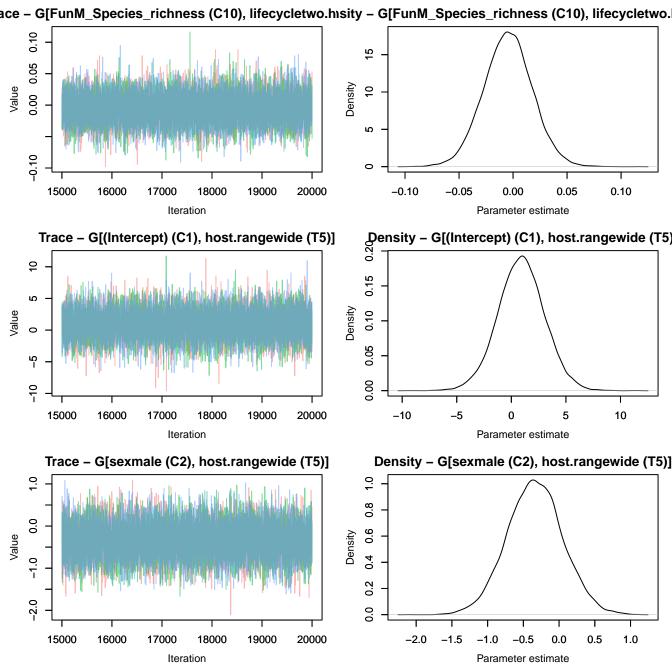
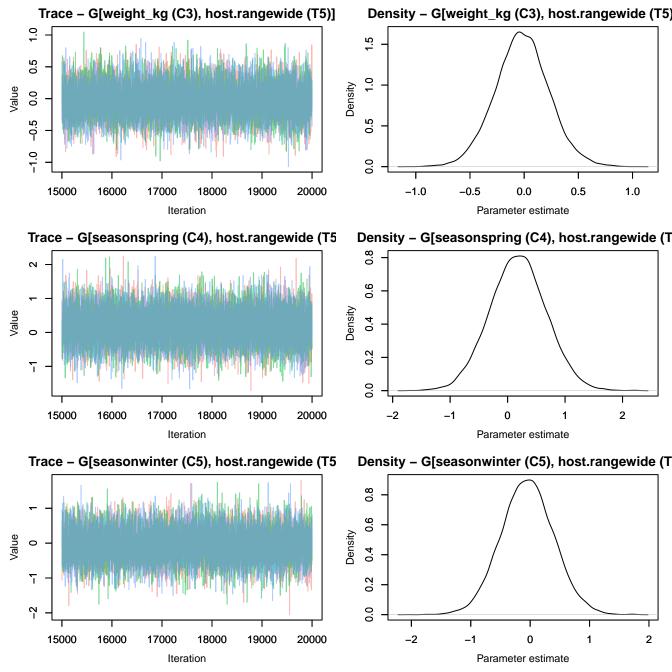


Trace - G[tree_cover_1000m (C7), lifecycletwo.host Density - G[tree_cover_1000m (C7), lifecycletwo.hos 25 0.05 2 Density 5 Value 0.00 9 -0.05 S 15000 -0.05 0.00 0.05 16000 17000 18000 19000 20000 Parameter estimate Iteration race - G[Diet_Species_richness (C8), lifecycletwo.hoensity - G[Diet_Species_richness (C8), lifecycletwo.h 0.3 9. Density Value 9







Trace - G[human_fpi_1000m (C6), host.rangewide (Density - G[human_fpi_1000m (C6), host.rangewide 0.05 9 Density Value -0.05 -0.15 2 -0.15 15000 16000 17000 18000 19000 20000 -0.20 -0.10 0.00 0.05 0.10 -0.05Parameter estimate Iteration Trace - G[tree_cover_1000m (C7), host.rangewide (Density - G[tree_cover_1000m (C7), host.rangewide 23 2 0.05 5 Density Value 0.00 -0.05 S 15000 16000 19000 20000 -0.05 0.00 0.05 0.10 18000 17000 Iteration Parameter estimate Trace - G[Diet_Species_richness (C8), host.rangewid/ensity - G[Diet_Species_richness (C8), host.rangewi

