



Douter de tout ou tout croire sont deux solutions également commodes, qui nous dispensent de réfléchir.
–Henri Poincaré

Introduction to Model Comparison

Why compare models?

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- All models are imperfect
- How good is our model given the modelling goals?

Comparing models

Before beginning, evaluate the goals of the comparison

- Predictive performance
- Hypothesis testing
- Reduction of overfitting

If you are asking yourself, "should I use A/B/DIC?"

Remember Betteridge's law...

Comparing models

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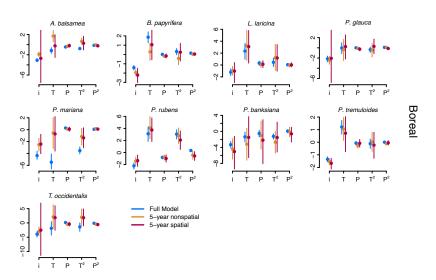
- Predictive performance
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Remember Betteridge's law...

Any headline that ends in a question mark can be answered with the word "NO"

Informal model comparison



Matthew Talluto - Model Comparison

Comparison through evaluation

If the goal is predictive performance, evaluate directly.

- Cross-validation
- k-fold cross validation

Cost: can be computationally intensive (especially for Bayesian). But you are already paying this cost (you ARE evaluating your models, right?)

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Requires selecting an evaluation score

- ROC/TSS (classification)
- RMSE (continuous)
- Goodness of fit
- •

Consider a regression model

$$\begin{aligned} \text{pr}(\boldsymbol{\theta}|\boldsymbol{y},\boldsymbol{x}) &\propto \text{pr}(\boldsymbol{y},\boldsymbol{x},|\boldsymbol{\theta}) \text{pr}(\boldsymbol{\theta}) \\ \boldsymbol{y} &\sim \mathcal{N}(\boldsymbol{\alpha} + \boldsymbol{\beta}\boldsymbol{x},\boldsymbol{\sigma}) \end{aligned}$$

From a new value \hat{x} we can compute a posterior prediction $\hat{y} = \alpha + \beta x$

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Ippd =
$$pr(\hat{y}|\theta)$$

Where is the prior?

We want to summarize lppd taking into account:

- an entire set of prediction points $\hat{x} = \{x_1, x_2, \dots x_n\}$
- the entire posterior distribution of θ
 - (or, realistically, a set of S draws from the posterior distribution)

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$$lppd = \sum_{i=1}^{n} log \left(\frac{1}{S} \sum_{s=1}^{S} pr(\hat{y} | \theta^{s}) \right)$$

To compare two competing models θ_1 and θ_2 , simply compute $lppd_{\theta_1}$ and $lppd_{\theta_2}$, the "better" model (for prediction) is the one with a larger lppd.

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Considering the lpd (using the calibration data), it can be proven, when θ_2 is *strictly nested* within θ_1 , that $lpd_{\theta_1}>lpd_{\theta_2}.$

Thus, we require a method for penalizing the larger (or more generally, more flexible) model to avoid simply overfitting, especially when validation data are unavailable.

AIC =
$$2k - 2 \log pr(x|\theta)$$

- $pr(x|\theta) = max(pr(x|\theta))$ and k is the number of parameters.
- AIC increases as the model gets worse or the number of parameters gets larger
- = $-2 \log pr(x|\hat{\theta})$ is sometimes referred to as *deviance*

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What is the number of parameters in a hierarchical model?

DIC

$$D(\theta) = -2\log(pr(x|\theta))$$

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We still penalize the model based on complexity, but we must estimate how many *effective* parameters there are:

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$$\mathsf{p}_\mathsf{D} = \mathbb{E}[\mathsf{D}(\theta)] - \mathsf{D}(\mathbb{E}[\theta])$$

$$DIC = D(\mathbb{E}[\theta]) + 2p_D$$

Pros:

- Easy to estimate
- Widely used and understood
- Effective for a variety of models regardless of nestedness or model size

Cons

- Not Bayesian
- Assume $\theta \sim \mathcal{M} \mathcal{N}$
- Modest computational cost

Consider two competing models θ_1 and θ_2

In classical likelihood statistics, we can compute the likelihood ratio:

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A fully Bayesian approach is to take into account the entire posterior distribution of both models:

$$K = \frac{pr(\theta_1|X)}{pr(\theta_2|X)}$$

For a single posterior estimate of each model:

$$\begin{split} \mathsf{K} &= \frac{\mathsf{pr}(\theta_1 \big| \mathsf{X})}{\mathsf{pr}(\theta_2 \big| \mathsf{X})} \\ &= \frac{\mathsf{pr}(\mathsf{X} \big| \theta_1) \mathsf{pr}(\theta_1)}{\mathsf{pr}(\mathsf{X} \big| \theta_2) \mathsf{pr}(\theta_2)} \end{split}$$

To account for the entire distribution:

$$\begin{split} \mathsf{K} &= \frac{\int \mathsf{pr}(\theta_1|\mathsf{X}) \mathsf{d}\theta_1}{\int \mathsf{pr}(\theta_2|\mathsf{X}) \mathsf{d}\theta_2} \\ &= \frac{\int \mathsf{pr}(\mathsf{X}|\theta_1) \mathsf{pr}(\theta_1) \mathsf{d}\theta_1}{\int \mathsf{pr}(\mathsf{X}|\theta_2) \mathsf{pr}(\theta_2) \mathsf{d}\theta_2} \end{split}$$

And others

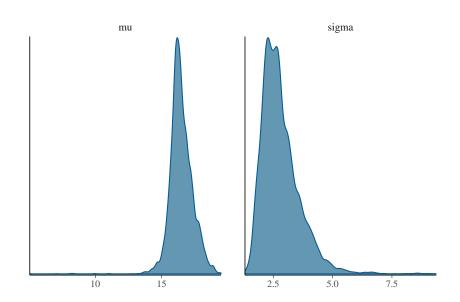
- Bayesian model averaging
- Reversible jump MCMC

```
library(mcmc)
suppressMessages(library(bayesplot))
logposterior <- function(params, dat)</pre>
  if(params[2] \le 0)
    return(-Inf)
  mu <- params[1]
  sig <- params[2]</pre>
  lp <- sum(dnorm(dat, mu, sig, log=TRUE)) +</pre>
      dnorm(mu, 16, 0.4) + dgamma(sig, 1, 0.1)
  return(lp)
```

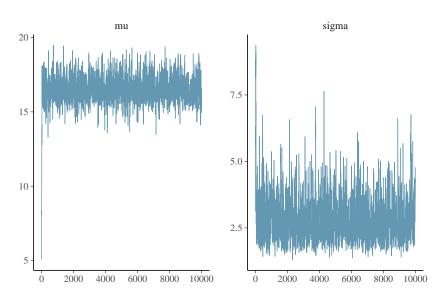
Software

[1] 0.4035

Software



Software



Other software

- mcmc
- LaplacesDemon
- JAGS
- Stan