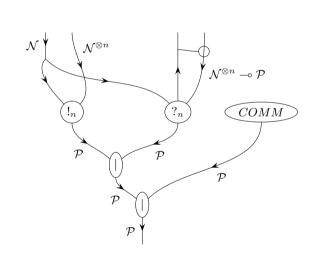
# Casper Formalized Pt I

Applying  $\pi$ -calculus

to modeling the Casper protocol





Vlad Zamfir, L.G. Meredith

# Aims and goals

Formal specification of Casper

Specification mapped to reference implementation

Specification mapped to simulation



# Methodology

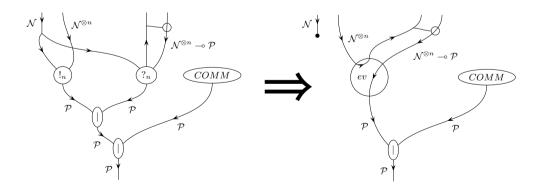
Bootstrap Casper spec using interaction diagrams

Map interaction diagrams to initial  $\pi$ -calculus specification

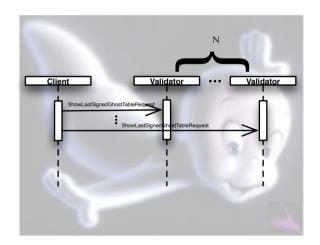
Refine specification

Map refined specification to SpecialK

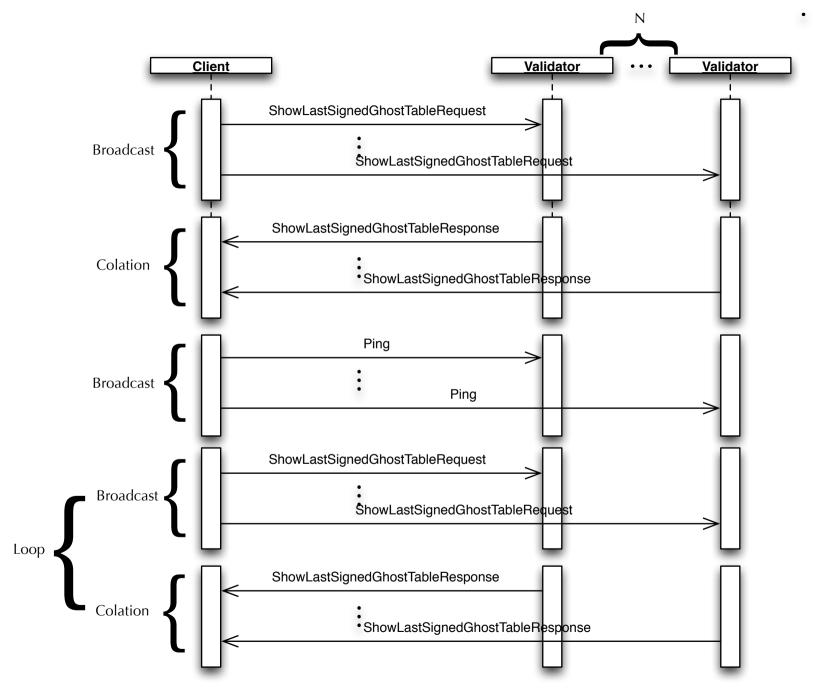
Map refined specification to Stochastic  $\pi$ -machine



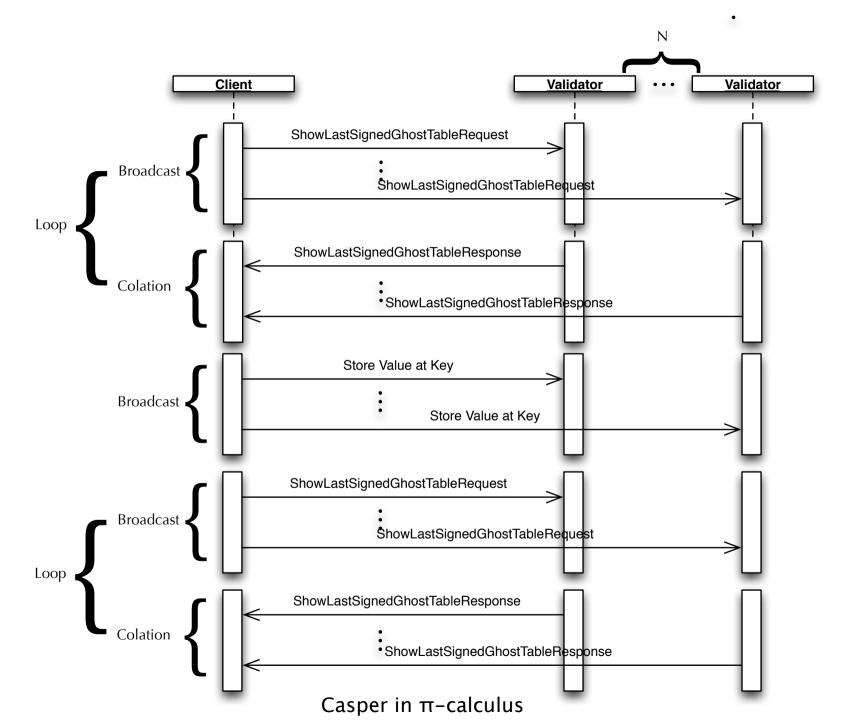
# Casper in interaction diagrams



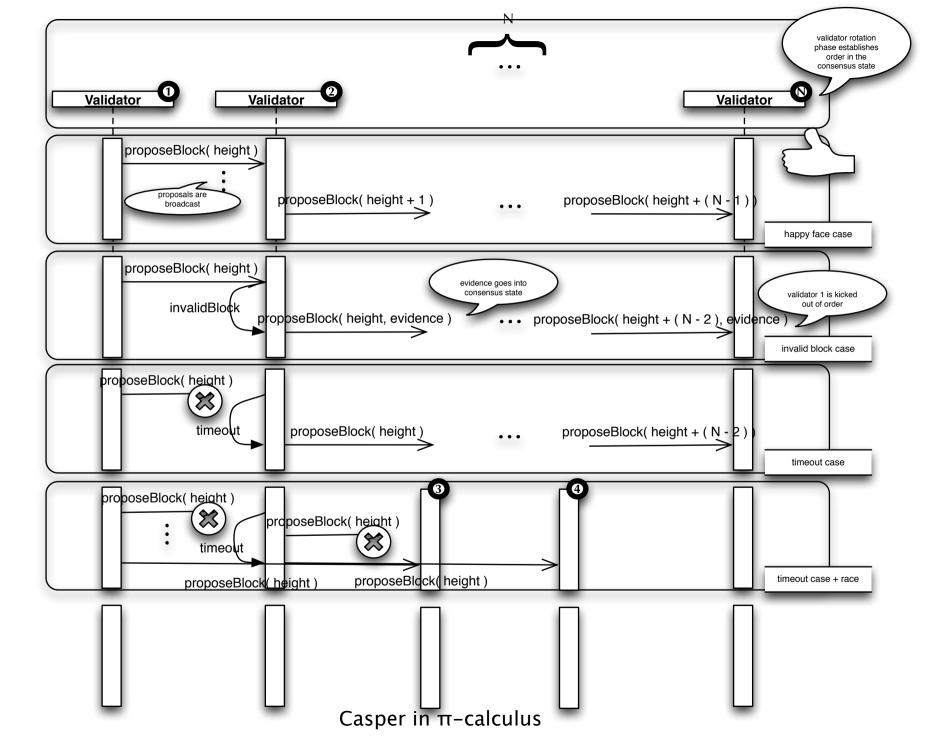


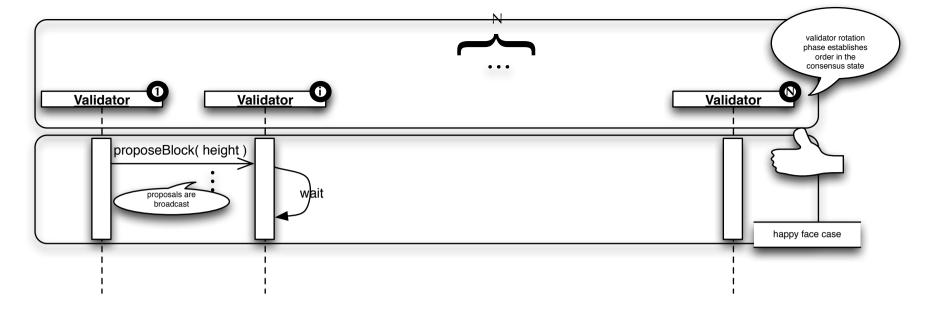


Casper in  $\pi$ -calculus



# Consensus: Validator <-> Validator interactions



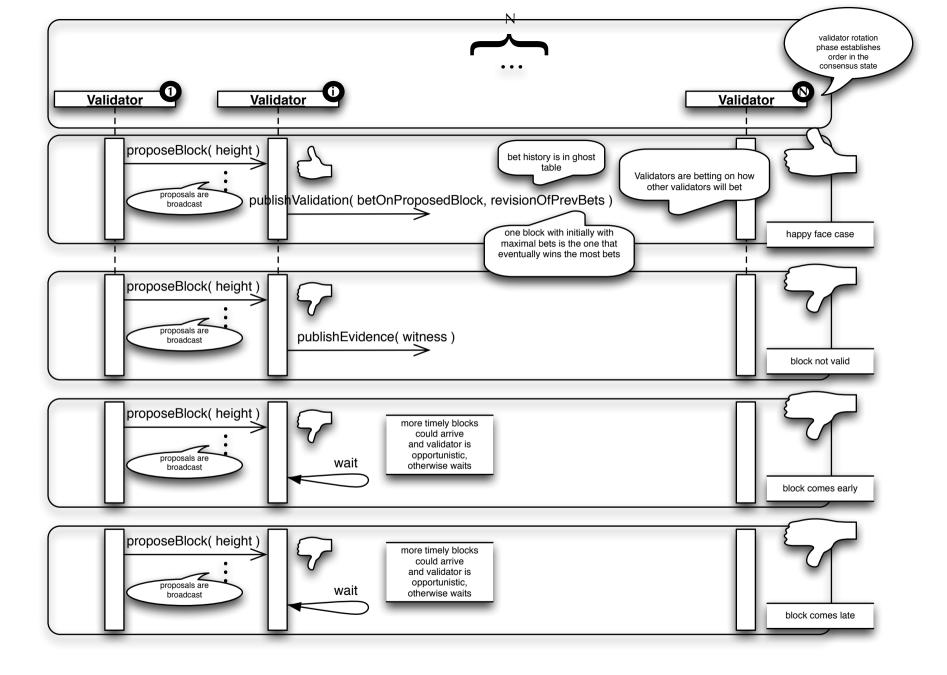


For validator i, v(i), if the proposal is from v(current), then v(i) can publish validation straightaway, otherwise wait for the proposer ==v(current), then publish validation.

Blocks contain validations of other blocks.

Publishing a validation is placing a bet that the validated block is the block that will be finalized at that height.

Validations also contain new bets on non-finalized previous blocks.



Casper in  $\pi$ -calculus

### To do list

State transition function

Bonding/unbonding

Rejection of validators based on evaluation of evidence

Distribution of transaction fees and bonds

Execution, re-ordering, and finalizing of txns

Assume fn, current: time -> Z[N] where N is the number of validators. At end / beginning of bonding period current is recalculated.

current = current\_1 || current\_2 || ... || current\_M

to get parallelism speed up opportunities

### To do list

```
Block consists of
* ghost entries ( prev hash, next hash )
* reorg transitions
* new txns

valid( block ) ==
   stateX( block.ghostEntries._1 ) == block.ghostEntries._2
&& stateX( block.reorgX._1 ) == block.reorgX._2
```

# Blocks and ghost table structure

```
block ::= ( entry*, signature )
entry ::= ghost | reorg | txn
ghost ::= ( prev, ( block | validation | evidence ), post )
evidence ::= ( address, bet* )
reorg ::= ( prev, txn*, post )
txn ::= ( prev, ( receiver, data, signature ), post )
validation ::= ( ( hash( block ), bet )*, signature )
state ::= ( cmgrState, appState )
cmgrState ::= ( ghostTable, validator*, evidenceChecker, txnFees )
```

# Blocks and ghost table structure

```
appState ::= state of a deterministic automaton
   history : ghostTable -> txn*
   stateFn: (appState, txn) -> appState
appState
((initialState) \ history)((txn, state) => stateFn(txn, state))
stateHash ::= hash( ( hash( cmgr ), hash( appState ) )
prev ::= stateHash
post ::= stateHash
ghostTable ::= height -> ( block ->( bet, validator )* )*
```

## Blocks and ghost table structure

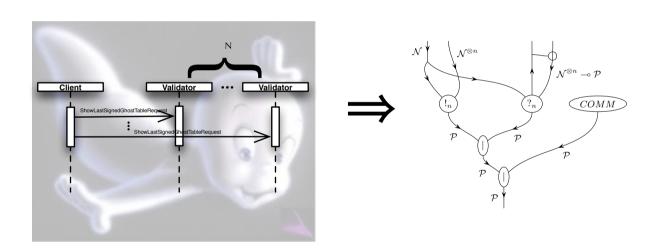
### To do list

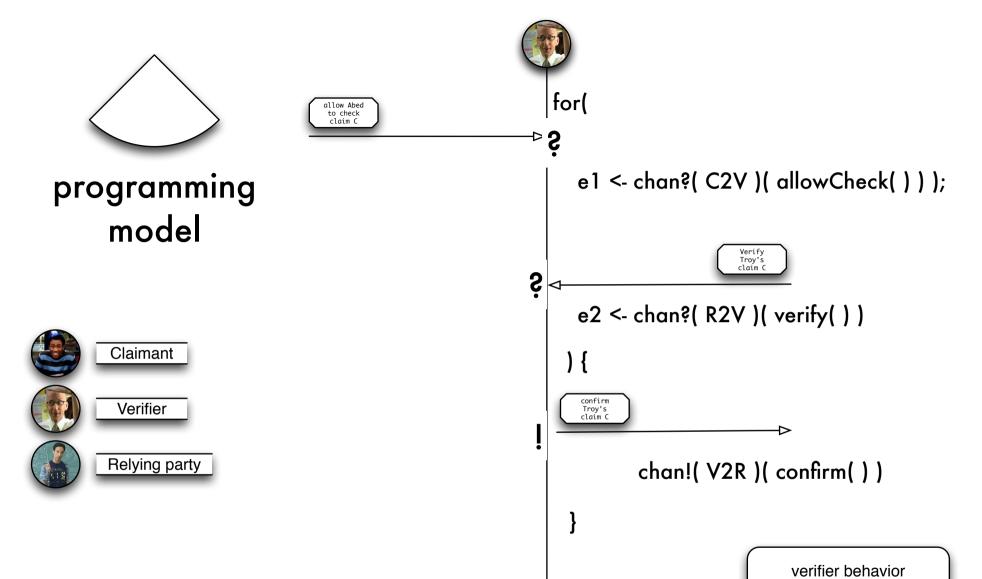
Assume fn, current: time -> Z[N] where N is the number of validators. At end / beginning of bonding period current is recalculated.

current = current\_1 || current\_2 || ... || current\_M

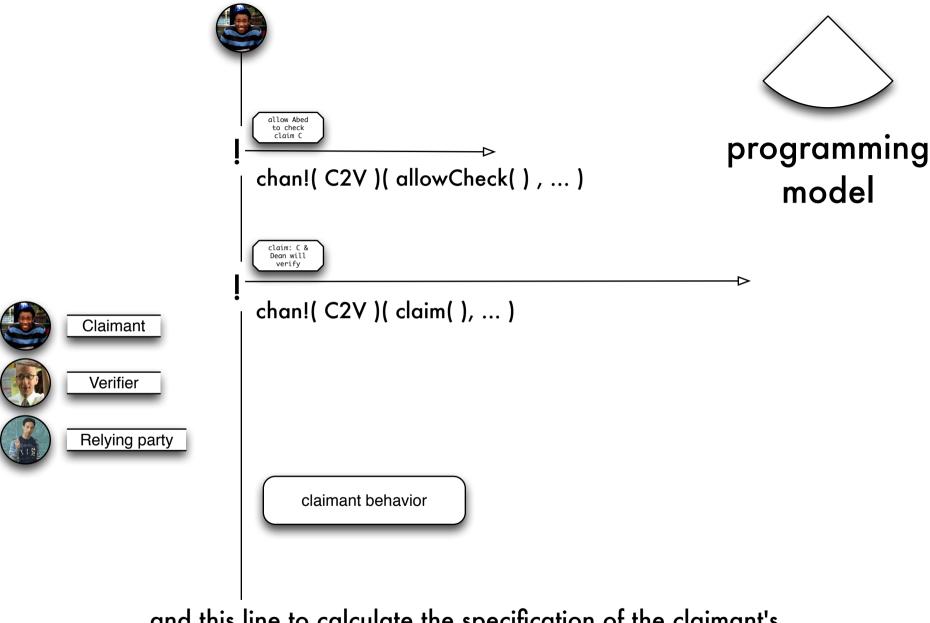
to get parallelism speed up opportunities

# How to turn interaction diagrams into $\pi$ -calculus specs

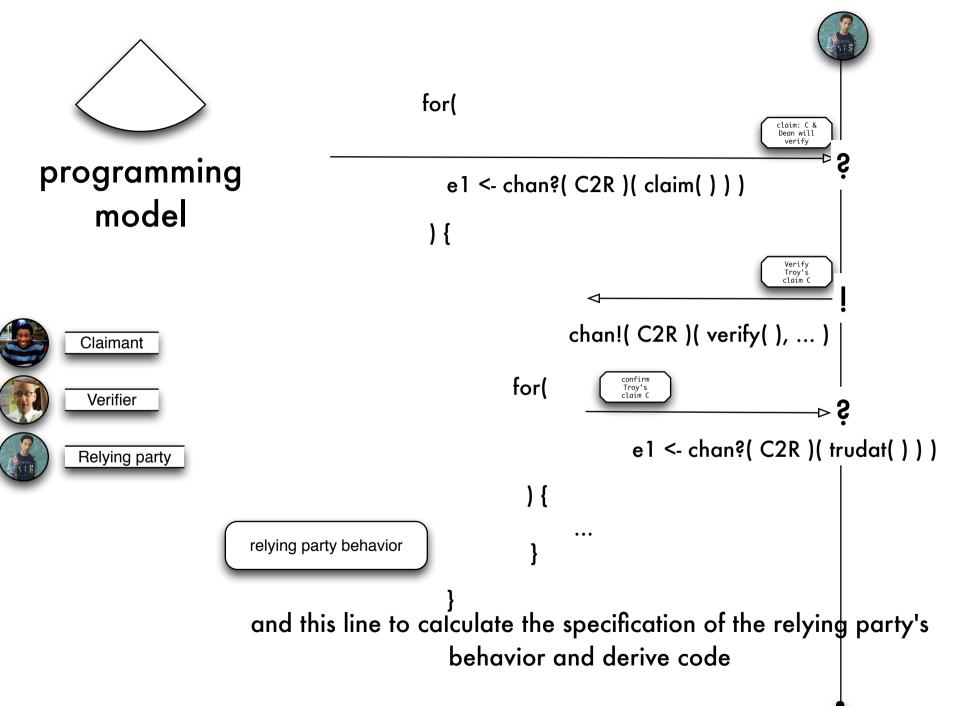




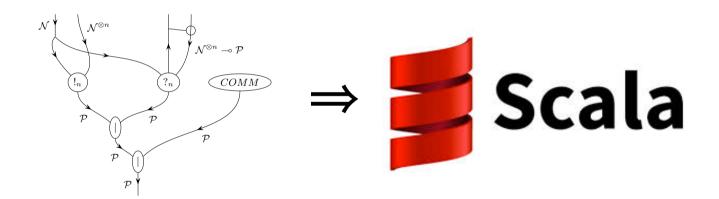
Just walk this line to calculate the specification of the verifier's behavior and derive code



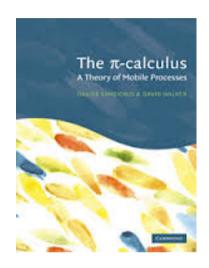
and this line to calculate the specification of the claimant's behavior and derive code



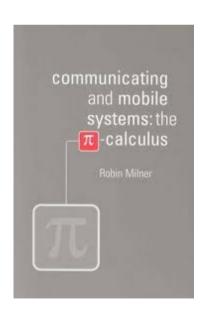
# How to turn $\pi$ -calculus specs into scala code



```
{ }
P,Q ::= 0
                                         [| a |](m) ![ [| v1 |](m), ..., [| vn |](m) ]
     a![ v1, ..., vn ]
                                         for([x1, ..., xn] \leftarrow [|a|](m)){
     a?( x1, ..., xn )P
                                             [|P|](m)(x1, ..., xn)
     P | Q
                                          spawn{ [| P |](m) }; spawn{ [| Q |](m) }
                                         { val q = \text{new Queue}(); [| P |](m[a <- q])}
     (new a)P
     ( def X( x1, ..., xn ) = P )[v1, ..., vn]
                                         object X {
                                             def apply(x1, ..., xn) = {
                                                [|P|](m) (x1, ..., xn)
     X[v1, ..., vn]
                                         X([| v1 |](m), ..., [| vn |](m))
            [|-|](-): (\pi-calculus, Map[Symbol, Queue]) -> Scala
```

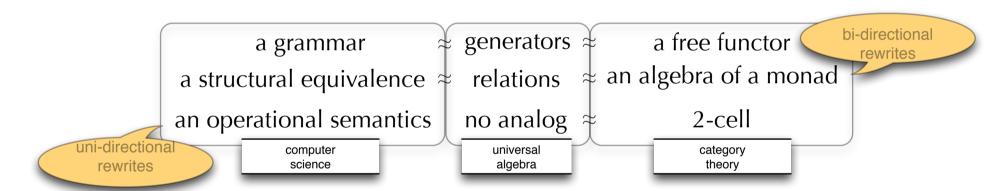


# applied $\pi$ -calculus



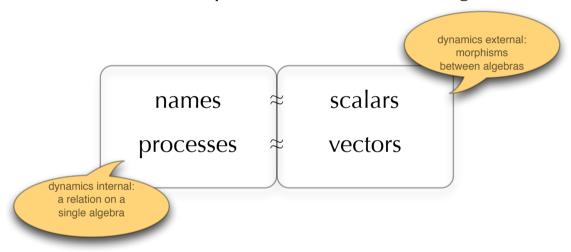
# How to specify a computational calculus

Modern presentations of computational calculi generalize generators and relations style presentations of universal algebra They are typically given in terms of



# How to specify a computational calculus

Process calculi, like vector spaces, are two sorted algebraic structures



A morphism from one process calculus to another *preserves* computational dynamics

A morphism from one vector space to another *is* computational dynamics

### **Syntax**

```
P,Q ::= 0

a![t]Q

a?(t)P

P | Q

(new a)P

(def X(t) = P)[u]

X[t]
```

```
t,u ::= val | var | fn(t1, ..., tN)
val ::= bool | int | string | double | ...
var ::= _ | X | Y | Z | ...
fn ::= x | y | z | ...
```

### Structural congruence

The structural congruence of processes, noted  $\equiv$ , is the least congruence containing  $\alpha$ -equivalence,  $\equiv_{\alpha}$ , making (P, |, 0) into commutative monoids and satisfying

$$(\operatorname{new} x)(\operatorname{new} x)P \equiv (\operatorname{new} x)P$$
 
$$(\operatorname{new} x)(\operatorname{new} y)P \equiv (\operatorname{new} y)(\operatorname{new} x)P$$
 
$$((\operatorname{new} x)P) \mid Q \equiv (\operatorname{new} x)(P \mid Q)$$

#### Reduction rules

unify(t, u, s)
$$a?(t)P \mid a![u]Q \rightarrow Ps \mid Qs$$

$$P \rightarrow P'$$

$$P \mid Q \rightarrow P' \mid Q$$

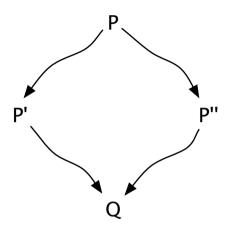
$$P \rightarrow P'$$

$$(new a)P \rightarrow (new a)P'$$

$$P \equiv P' \quad P' \rightarrow Q' \quad Q' \equiv Q$$

$$P \rightarrow Q$$

# Important properties of computational calculi



Confluence

lambda calculus is confluent

 $\pi$ -calculus is **not** confluent

a![ u1 ]Q1 | a?( t )P | a![ u2 ]Q2 typical race condition