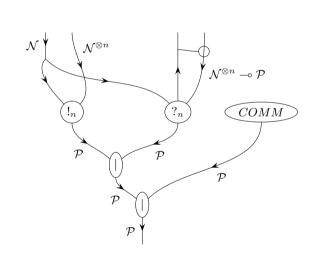
Casper Formalized Pt I

Applying π -calculus

to modeling the Casper protocol





Vlad Zamfir, L.G. Meredith

Aims and goals

Formal specification of Casper

Specification mapped to reference implementation

Specification mapped to simulation



Methodology

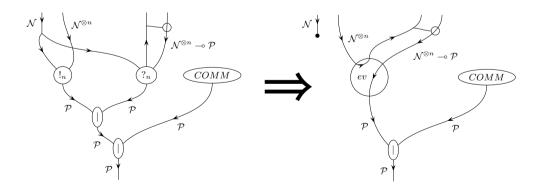
Bootstrap Casper spec using interaction diagrams

Map interaction diagrams to initial π -calculus specification

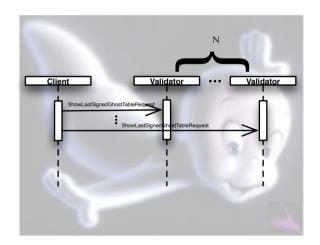
Refine specification

Map refined specification to SpecialK

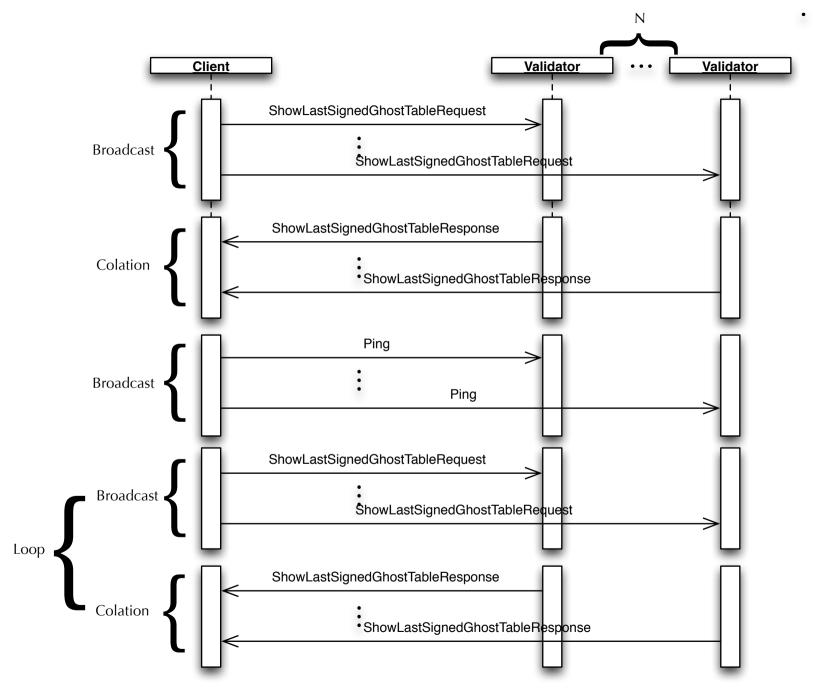
Map refined specification to Stochastic π -machine



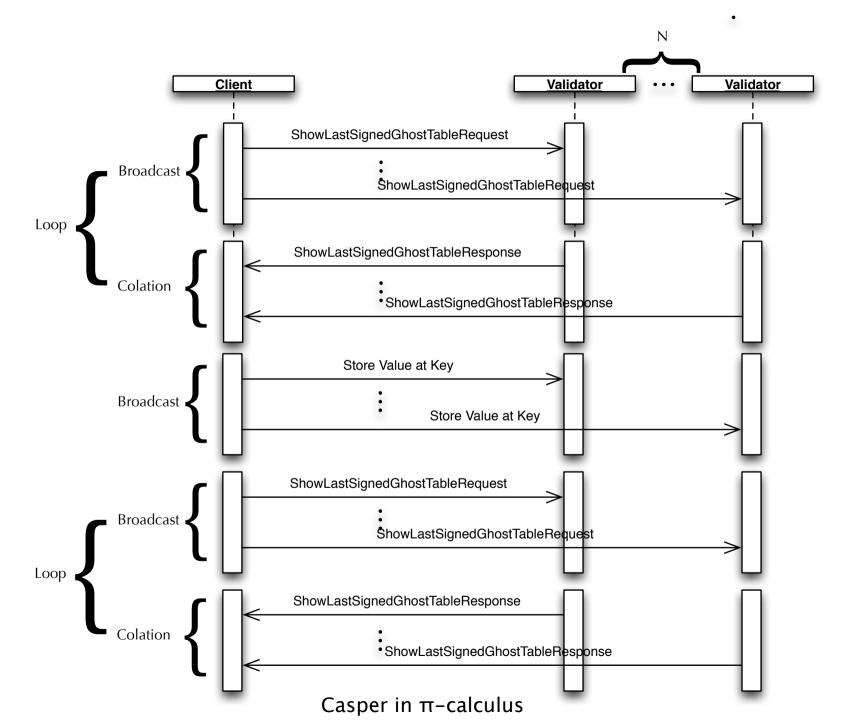
Casper in interaction diagrams



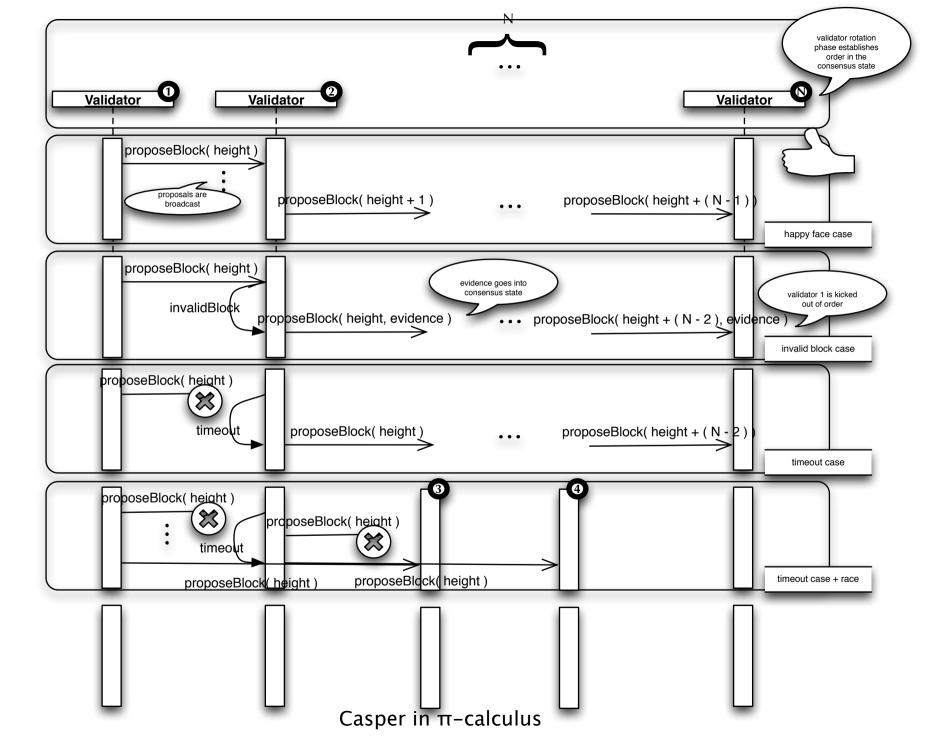




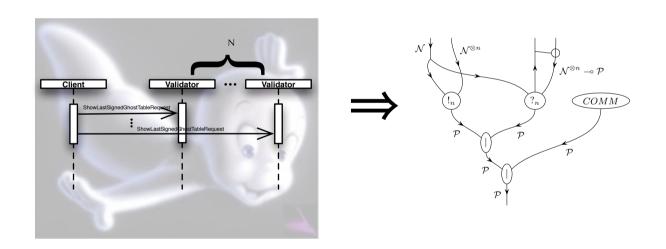
Casper in π -calculus

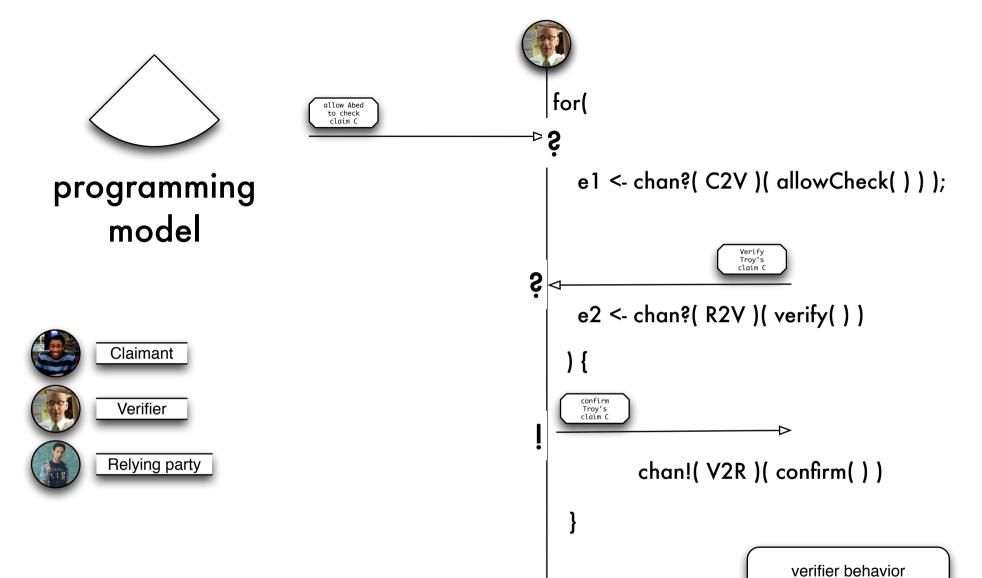


Consensus: Validator <-> Validator interactions

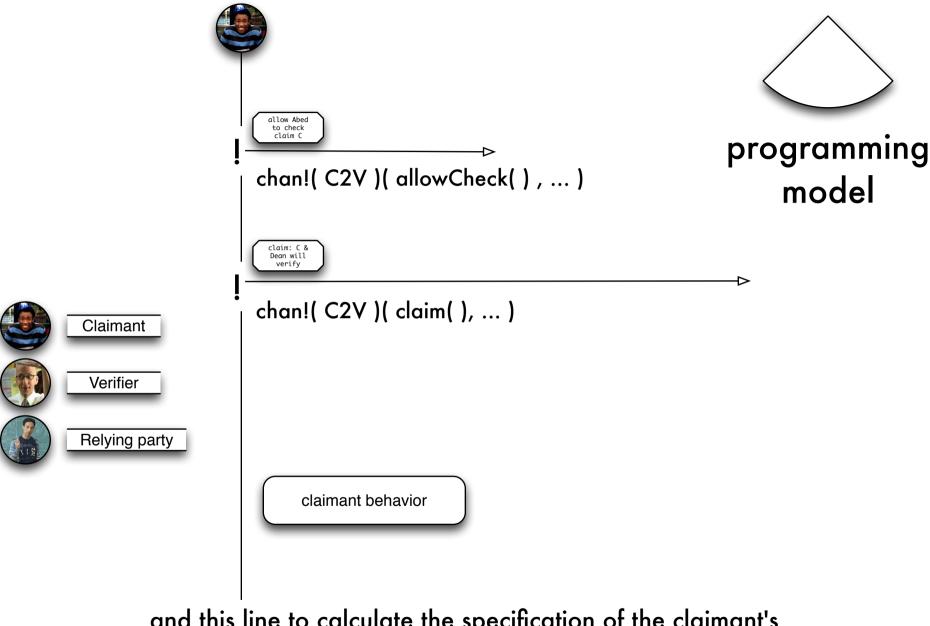


How to turn interaction diagrams into π -calculus specs

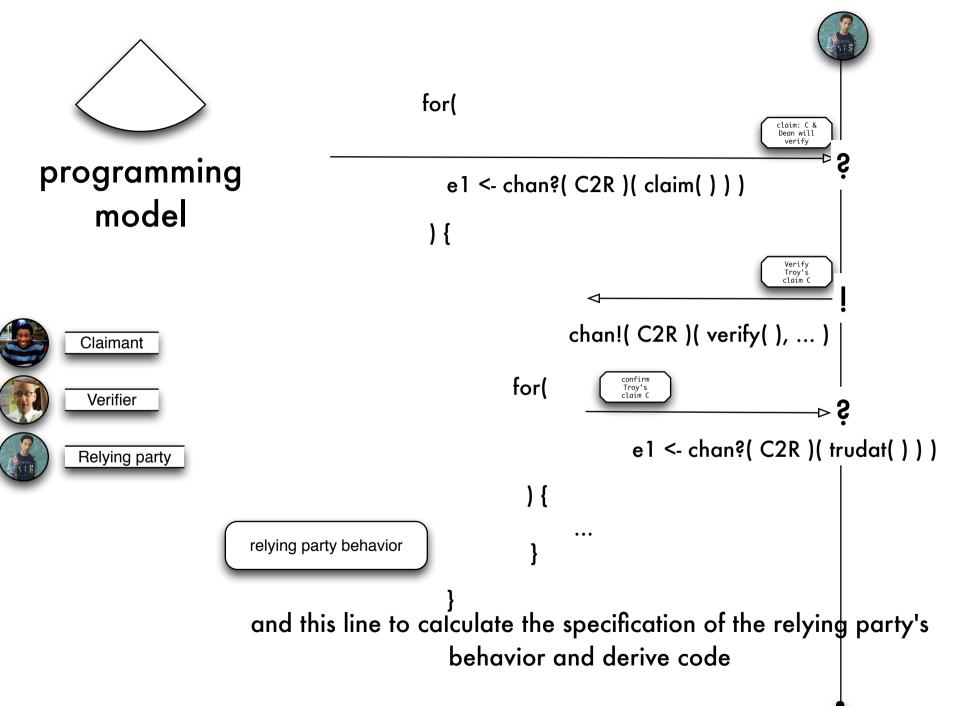




Just walk this line to calculate the specification of the verifier's behavior and derive code



and this line to calculate the specification of the claimant's behavior and derive code



How to turn π -calculus specs into scala code

```
{ }
P,Q ::= 0
                                         [| a |](m) ![ [| v1 |](m), ..., [| vn |](m) ]
     a![ v1, ..., vn ]
                                         for([x1, ..., xn] \leftarrow [|a|](m)){
     a?( x1, ..., xn )P
                                             [|P|](m)(x1, ..., xn)
     P | Q
                                          spawn{ [| P |](m) }; spawn{ [| Q |](m) }
                                         { val q = \text{new Queue}(); [| P |](m[a <- q])}
     (new a)P
     ( def X( x1, ..., xn ) = P )[v1, ..., vn]
                                         object X {
                                             def apply(x1, ..., xn) = {
                                                [|P|](m) (x1, ..., xn)
     X[v1, ..., vn]
                                         X([| v1 |](m), ..., [| vn |](m))
            [|-|](-): (\pi-calculus, Map[Symbol, Queue]) -> Scala
```

applied π -calculus

Syntax

```
P,Q ::= 0

a![t]Q

a?(t)P

P | Q

(new a)P

( def X(t) = P)[u]

X[t]
```

```
t,u ::= val | var | fn(t1, ..., tN)
val ::= bool | int | string | double | ...
var ::= _ | X | Y | Z | ...
fn ::= x | y | z | ...
```

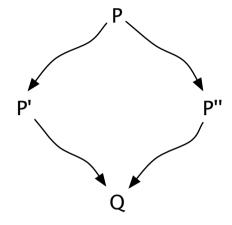
Structural congruence

The structural congruence of processes, noted \equiv , is the least congruence containing α -equivalence, \equiv_{α} , making (P, |, 0) into commutative monoids and satisfying

$$(\operatorname{new} x)(\operatorname{new} x)P \equiv (\operatorname{new} x)P$$

$$(\operatorname{new} x)(\operatorname{new} y)P \equiv (\operatorname{new} y)(\operatorname{new} x)P$$

$$((\operatorname{new} x)P) \mid Q \equiv (\operatorname{new} x)(P \mid Q)$$



Confluence

lambda calculus is confluent

 π -calculus is **not** confluent

a![u1]Q1 | a?(t)P | a![u2]Q2 typical race condition

Casper in $\pi\text{-calculus}$