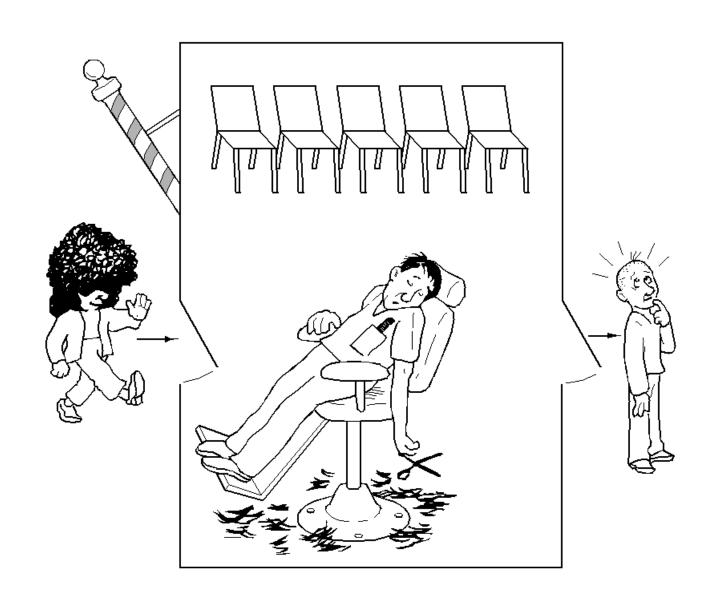
Tutorials

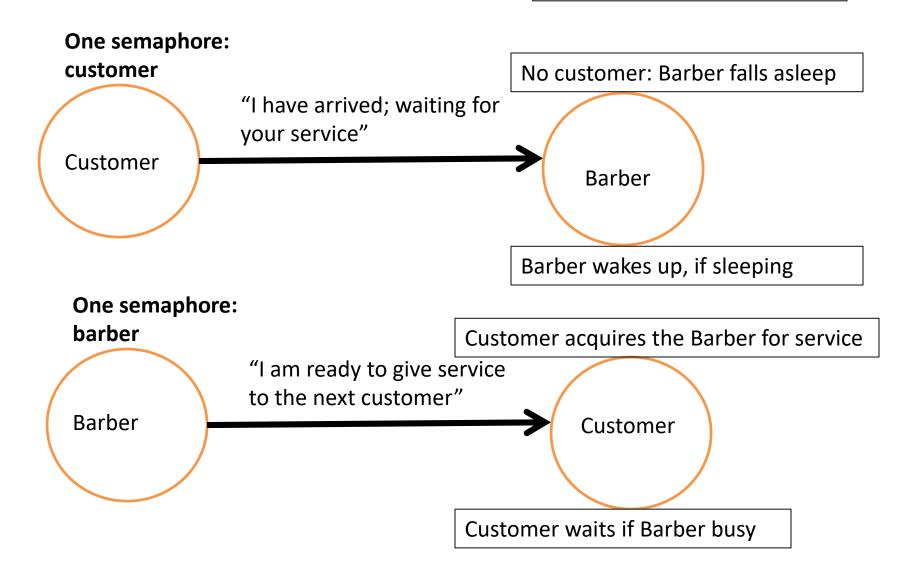
The Sleeping Barber Problem



Challenges

- Actions taken by barber and customer takes unknown amount of time (checking waiting room, entering shop, taking waiting room chair)
- Scenario 1
 - Customer arrives, observe that barber busy
 - Goes to waiting room
 - While he is on the way, barber finishes the haircut
 - Barber checks the waiting room
 - Since no one there, Barber sleeps
 - The customer reaches the waiting room and waits forever
- Scenario 2
 - Two customer arrives at the same time
 - Barber is busy
 - Both customers try to occupy the same chair!

Barber sleeps on "Customer" Customer sleeps on "Barber"



The Sleeping Barber Problem

```
#define CHAIRS 5
                                     /* # chairs for waiting customers */
typedef int semaphore;
                                     /* use your imagination */
                                     /* # of customers waiting for service */
semaphore customers = 0;
                                     /* # of barbers waiting for customers */
semaphore barbers = 0;
semaphore mutex = 1;
                                     /* for mutual exclusion */
int waiting = 0;
                                     /* customers are waiting (not being cut) */
void barber(void)
    while (TRUE) {
         down(&customers);
                                     /* go to sleep if # of customers is 0 */
         down(&mutex);
                                     /* acquire access to 'waiting' */
         waiting = waiting -1;
                                     /* decrement count of waiting customers */
         up(&barbers);
                                     /* one barber is now ready to cut hair */
         up(&mutex);
                                     /* release 'waiting' */
                                     /* cut hair (outside critical region) */
         cut_hair();
void customer(void)
     down(&mutex);
                                     /* enter critical region */
     if (waiting < CHAIRS) {
                                     /* if there are no free chairs, leave */
         waiting = waiting + 1;
                                     /* increment count of waiting customers */
         up(&customers);
                                     /* wake up barber if necessary */
         up(&mutex);
                                     /* release access to 'waiting' */
         down(&barbers);
                                     /* go to sleep if # of free barbers is 0 */
         get_haircut();
                                     /* be seated and be serviced */
    } else {
         up(&mutex);
                                     /* shop is full; do not wait */
```

Semaphore Barber: Used to call a waiting customer.

Barber=1: Barber is ready to cut hair and a customer is ready (to get service) too!

Barber=0: customer occupies barber or waits

Semaphore customer:

Customer informs barber that "I have arrived; waiting for your service"

Mutex: Ensures that only one of the participants can change state at once

The Sleeping Barber Problem

```
#define CHAIRS 5
                                     /* # chairs for waiting customers */
typedef int semaphore;
                                     /* use your imagination */
                                     /* # of customers waiting for service */
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         down(&barbers);
                                     /* go to sleep if # of free barbers is 0 */
         get_haircut();
                                     /* be seated and be serviced */
    } else {
         up(&mutex);
                                     /* shop is full; do not wait */
```

Barber sleeps on "Customer" Customer sleeps on "Barber"

For Barber: Checking the waiting room and calling the customer makes the critical section

For customer:

checking the waiting room and informing the barber makes its critical section

We want to use semaphores to implement a shared critical section (CS) among three processes T1, T2, and T3. We want to enforce the execution in the CS in this order: First T2 must execute in the CS. When it finishes, T1 will then be allowed to enter the CS; and when it finishes T3 will then be allowed to enter the CS; when T3 finishes then T2 will be allowed to enter the CS, and so on, (T2, T1, T3, T2, T1, T3,...).

Write the synchronization solution using a minimum number of binary semaphores and you are allowed to assume the initial value for semaphore variables.

T1	T2	T3
While(true) {	While(true) {	While(true) {
Wait(S3);	Wait(S1);	Wait(S2);
Print("C");	Print("B");	Print("A");
Signal (S2); }	Signal (S3); }	Signal (S1); }

Three concurrent processes X, Y, and Z execute three different code segments that access and update certain shared variables.

Process X executes the P operation (i.e., wait) on semaphores a, b and c;

process Y executes the P operation on semaphores b, c and d;

process Z executes the P operation on semaphores c, d, and a before entering the respective code segments.

After completing the execution of its code segment, each process invokes the V operation (i.e., signal) on its three semaphores.

All semaphores are binary semaphores initialized to one.

Which one of the following represents a deadlock-free order of invoking the P operations by the processes?

- (A) X: P(a)P(b)P(c) Y: P(b)P(c)P(d) Z: P(c)P(d)P(a)
- **(B)** X: P(b)P(a)P(c) Y: P(b)P(c)P(d) Z: P(a)P(c)P(d)
- (C) X: P(b)P(a)P(c) Y: P(c)P(b)P(d) Z: P(a)P(c)P(d)
- **(D)** X: P(a)P(b)P(c) Y: P(c)P(b)P(d) Z: P(c)P(d)P(a)

 The following two functions P1 and P2 that share a variable B with an initial value of 2 execute concurrently.

```
P1()
{
    C = B - 1;
    B = 2*C;
}

P2()
{
    D = 2 * B;
    B = D - 1;
}
```

The number of distinct values that B can possibly take after the execution

Consider the reader-writer problem with designated readers. There are n reader processes, where n is known beforehand. There are one or more writer processes. Items are stored in a buffer. Every item is written by a writer and is designated for a particular reader.

```
semaphore rw mutex = 1;
semaphore r_{mutex}[n] = \{0, 0, \dots, 0\};
reader (i)
        wait(r mutex[i]);
        while (true) {
                wait(rw_mutex);
                Read and remove one item from buffer, that is meant for the i-th reader;
                signal(rw_mutex);
                wait(r_mutex[i]);
writer ()
        while (true) {
                Generate item for reader i;
                wait(rw mutex);
                Write (item, i) to buffer;
                signal(rw_mutex);
                signal(r_mutex[i]);
```

Deadlock Detection

Allow system to enter deadlock state

Detection algorithm

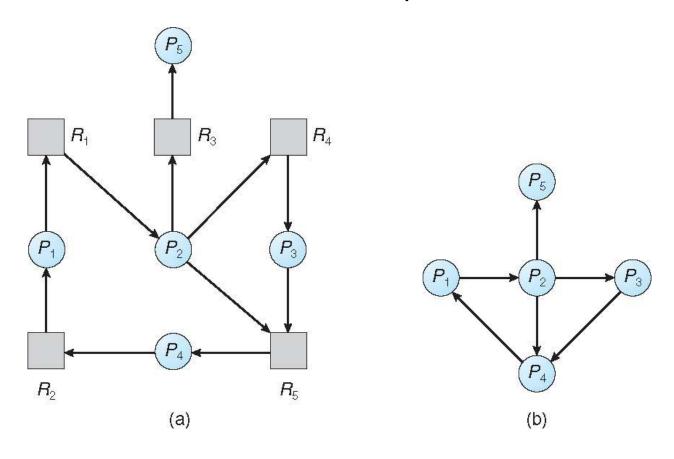
Recovery scheme

Single Instance of Each Resource Type

- In resource graph
 - $-P_i \rightarrow R \text{ and } R \rightarrow P_i$
- Maintain wait-for graph
 - Nodes are processes
 - $-P_i \rightarrow P_j$ if P_i is waiting for P_j

- Periodically invoke an algorithm that searches for a cycle in the graph.
- If there is a cycle, there exists a deadlock

Resource-Allocation Graph and Wait-for Graph



Resource-Allocation Graph

Corresponding wait-for graph

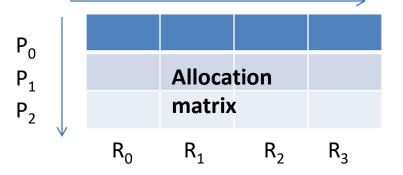
Several Instances of a Resource Type

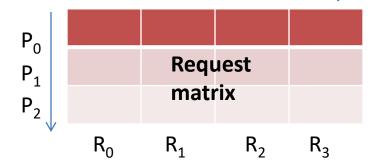
Let n = number of processes, and m = number of resources types.

• **Available**: A vector of length *m* indicates the number of available resources of each type.



 Allocation: An n x m matrix defines the number of resources of each type currently allocated to each process.





• Request: An $n \times m$ matrix indicates the current request of each process. If Request[i][j] = k, then process P_i is requesting k more instances of resource type R_i .

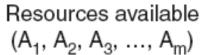
Several Instances of a Resource Type

Let n = number of processes, and m = number of resources types.

Resources in existence
$$(E_1, E_2, E_3, ..., E_m)$$

Current allocation matrix

Row n is current allocation to process n



Request matrix

$$\begin{bmatrix} R_{11} & R_{12} & R_{13} & \cdots & R_{1m} \\ R_{21} & R_{22} & R_{23} & \cdots & R_{2m} \\ \vdots & \vdots & \vdots & & \vdots \\ R_{n1} & R_{n2} & R_{n3} & \cdots & R_{nm} \end{bmatrix}$$

Row 2 is what process 2 needs

Detection Algorithm

Define a relation ≤ over two vectors

X and Y are two vectors of length n

We say X ≤ Y
 Iff X[i] ≤Y[i] for all i=1, 2, ..., n

Detection Algorithm

1. Let *Work* and *Finish* be vectors of length *m* and *n*, respectively

Initialize:

- (a) Work = Available
- (b) For i = 1,2, ..., n, if $Allocation_i \neq 0$, then Finish[i] = false; otherwise, Finish[i] = true
- 2. Find an index i such that both:
 - (a) Finish[i] == false
 - (b) $Request_i \leq Work$

If no such i exists, go to step 4

Detection Algorithm (Cont.)

- 3. Work = Work + Allocation; Finish[i] = true go to step 2
- 4. If Finish[i] == false, for some i, $1 \le i \le n$, then the system is in deadlock state. Moreover, if Finish[i] == false, then P_i is deadlocked

Example of Detection Algorithm

- Five processes P_0 through P_4 ;
- three resource types
 A (7 instances), B (2 instances), and C (6 instances)
- Snapshot at time T_0 :

	<u> Allocation</u>	<u>Request</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	000	000
P_1	200	202	
P_2	303	000	
P_3	211	100	
P_4	002	002	

• Sequence $\langle P_0, P_2, P_3, P_1, P_4 \rangle$ will result in Finish[i] = true for all i

Example (Cont.)

P₂ requests an additional instance of type C

```
\frac{Request}{ABC}
P_0 = 0.00
P_1 = 2.02
P_2 = 0.01
P_3 = 1.00
P_4 = 0.02
```

- State of system?
 - Can reclaim resources held by process P_0 , but insufficient resources to fulfill other processes; requests
 - Deadlock exists, consisting of processes P_1 , P_2 , P_3 , and P_4

Home work

Tape drives
$$A = (2 \quad 1 \quad 0 \quad 0)$$

Available

Current allocation matrix

$$C = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 2 & 0 & 0 & 1 \\ 0 & 1 & 2 & 0 \end{bmatrix}$$

Request matrix

$$C = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 2 & 0 & 0 & 1 \\ 0 & 1 & 2 & 0 \end{bmatrix} \qquad \qquad R = \begin{bmatrix} 2 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 2 & 1 & 0 & 0 \end{bmatrix}$$

Detection-Algorithm Usage

- When, and how often, to invoke depends on:
 - How often a deadlock is likely to occur?
 - How many processes will be affected by deadlock?
- If deadlock frequent
 - Invoke detection algo frequently
- Invoke after each (waiting) resource request
 - Huge overhead
- CPU utilization drops

Recovery from Deadlock: Process Termination

- Abort all deadlocked processes
 - Expensive
- Abort one process at a time until the deadlock cycle is eliminated
 - Overhead=> invoke detection algo
- In which order should we choose to abort?
 - Priority of the process
 - How long process has computed
 - Resources the process has used
 - Resources process needs to complete
 - How many processes will need to be terminated
 - Is process interactive or batch?

Recovery from Deadlock: Resource Preemption

- Selecting a victim minimize cost
 - (# of resources holding, duration)
- Rollback return to some safe state, restart process from that state

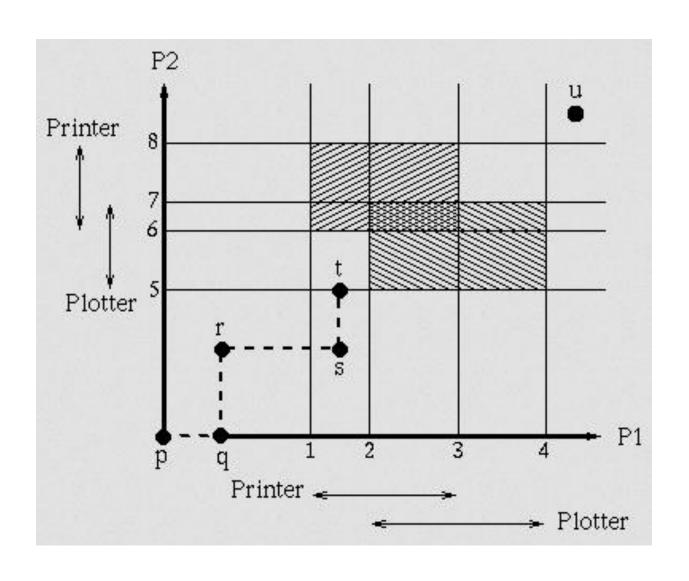
 Starvation – same process may always be picked as victim, include number of rollback in cost factor

Deadlock Avoidance

Requires that the system has some additional *a priori* information available

- Simplest and most useful model requires that each process declare the maximum number of resources of each type that it may need
- The deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there can never be a circular-wait condition
- Resource-allocation state is defined by the number of available and allocated resources, and the maximum demands of the processes

Safe State



Safe State

- When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state
- System is in safe state if there exists a sequence $\langle P_1, P_2, ..., P_n \rangle$ of ALL the processes in the systems
 - such that for each P_i , the resources that P_i can still request can be satisfied by currently available resources + resources held by all the P_i , with j < i

That is:

- If P_i resource needs are not immediately available, then P_i can wait until all P_i have finished
- When P_j is finished, P_i can obtain needed resources, execute, return allocated resources, and terminate
- When P_i terminates, P_{i+1} can obtain its needed resources, and so on

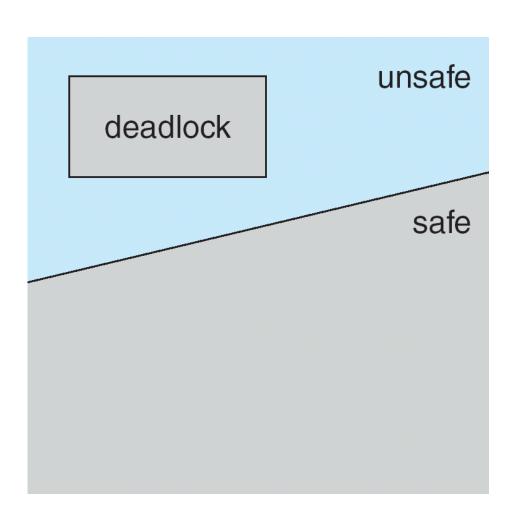
Basic Facts

If a system is in safe state ⇒ no deadlocks

 If a system is in unsafe state ⇒ possibility of deadlock

 Avoidance ⇒ ensure that a system will never enter an unsafe state.

Safe, Unsafe, Deadlock State



Three processes P0, P1, P2

Resource R=12 State at time t_0

	Maximum need	Current allocation
PO	10	5
P1	4	2
P2	9	2

Free resource = 3

Safe sequence <P1, P0, P2>

Safe state

State at time t₁
Allocate one resource to P2

Avoidance algorithms

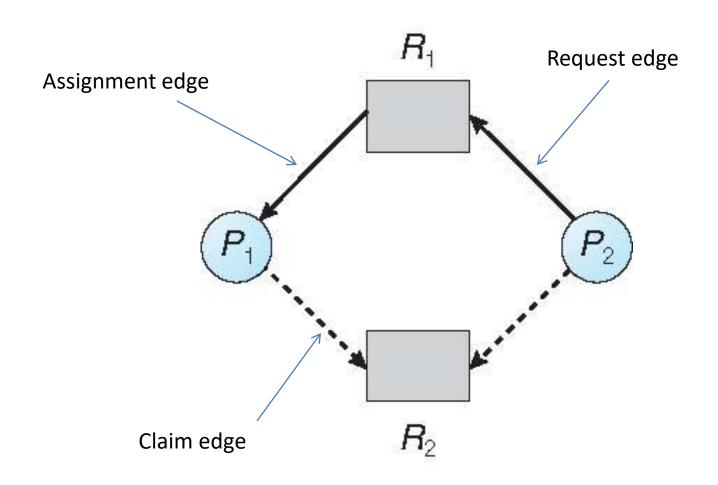
- Single instance of a resource type
 - Use a resource-allocation graph

- Multiple instances of a resource type
 - Use the banker's algorithm

Resource-Allocation Graph Scheme

- Claim edge $P_i \rightarrow R_j$ indicated that process P_j may request resource R_i ; represented by a dashed line
- Claim edge converts to request edge when a process requests a resource
- Request edge converted to an assignment edge when the resource is allocated to the process
- When a resource is released by a process, assignment edge reconverts to a claim edge
- Resources must be claimed a priori in the system

Resource-Allocation Graph

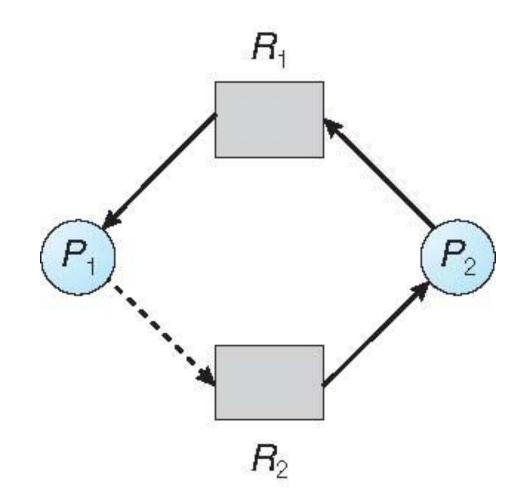


Resource-Allocation Graph Algorithm

- Suppose that process P_i requests a resource R_j
- The request can be granted only if converting the request edge to an assignment edge does not result in the formation of a cycle in the resource allocation graph

- If no cycle
 - Safe state

Unsafe State In Resource-Allocation Graph



Suppose that process P_2 requests a resource R_2

Banker's Algorithm

- Multiple instances
- Each process must a priori claim maximum use
- When a process requests a set of resources
 - System decides whether the allocation is safe
- When a process requests a resource not safe?
 - it may have to wait
- When a process gets all its resources it must return them in a finite amount of time

Data Structures for the Banker's Algorithm

Let n = number of processes, and m = number of resources types.

- Available: Vector of length m. If available [j] = k, there are k instances of resource type R_i available
- Max: $n \times m$ matrix. If Max[i,j] = k, then process P_i may request at most k instances of resource type R_i
- Allocation: $n \times m$ matrix. If Allocation[i,j] = k then P_i is currently allocated k instances of R_i
- Need: $n \times m$ matrix. If Need[i,j] = k, then P_i may need k more instances of R_i to complete its task

Need[i,j] = Max[i,j] - Allocation[i,j]

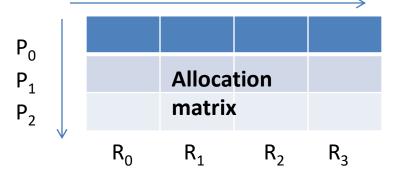
Several Instances of a Resource Type

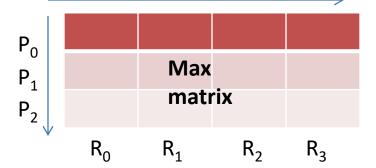
Let n = number of processes, and m = number of resources types.

• **Available**: A vector of length *m* indicates the number of available resources of each type.

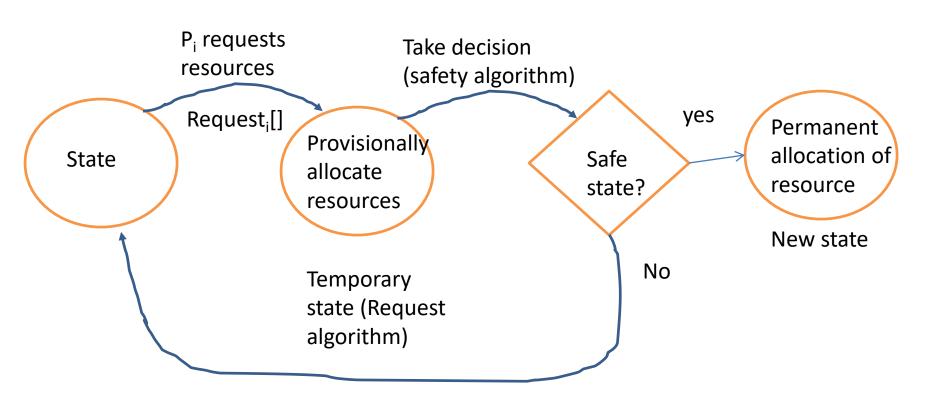


 Allocation: An n x m matrix defines the number of resources of each type currently allocated to each process.





Deadlock avoidance: Flow chart for P_i



Restore the old state

Safety Algorithm

1. Let *Work* and *Finish* be vectors of length *m* and *n*, respectively. Initialize:

```
Work = Available
Finish [i] = false for i = 0, 1, ..., n- 1
```

- 2. Find an *i* such that both:
 - (a) Finish[i] = false
 - (b) $Need_i \leq Work$ If no such *i* exists, go to step 4
- 3. Work = Work + Allocation; Finish[i] = true go to step 2
- 4. If *Finish* [*i*] == true for all *i*, then the system is in a safe state

Resource-Request Algorithm for Process P_i

Request = request vector for process P_i .

- If $Request_i[j] = k$ then process P_i wants k instances of resource type R_i
 - 1. If *Request_i* ≤ *Néed_i* go to step 2. Otherwise, raise error condition, since process has exceeded its maximum claim
 - 2. If $Request_i \le Available$, go to step 3. Otherwise P_i must wait, since resources are not available
 - 3. Pretend to allocate requested resources to P_i by modifying the state as follows:

```
Available = Available - Request;;
Allocation; = Allocation; + Request;;
Need; = Need; - Request;;
```

- \square If safe \Rightarrow the resources are allocated to Pi
- □ If unsafe ⇒ Pi must wait, and the old resource-allocation state is restored

Example of Banker's Algorithm

5 processes P₀ through P₄;
 3 resource types:

A (10 instances), B (5instances), and C (7 instances)

Snapshot at time T_0 :

	<u>Allocation</u>	<u>Max</u> <u>Available</u>
	ABC	ABC ABC
P_0	010	753 332
P	200	3 2 2
P	302	902
P	3 211	222
P	002	4 3 3

Example (Cont.)

• The content of the matrix *Need* is defined to be *Max – Allocation*

	<u>Need</u>
	ABC
P_0	743
P_1	122
P_2	600
P_3	011
P_4	431

	Allocation	Max	Available
	ABC	ABC	ABC
P_0	010	753	3 3 2
P_1	200	322	
P_2	302	902	
P_3	211	222	
P_4	002	433	

• The system is in a safe state since the sequence $\langle P_1, P_3, P_4, P_2, P_0 \rangle$ satisfies safety criteria

Example (Cont.)

The content of the matrix Need is defined to be Max – Allocation

• The system is in a safe state since the sequence $\langle P_1, P_3, P_4, P_2, P_0 \rangle$ satisfies safety criteria

Example: P_1 Request (1,0,2)

Check that Request ≤ Available (that is, (1,0,2) ≤ (3,3,2)
 ⇒ true

<u> </u>	<u> Allocation</u>	<u>Need</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	743	230
P_1	302	02	0
P_2	302	600	
P_3	2 1 1	011	
P_4	002	431	

- Executing safety algorithm shows that sequence $< P_1$, P_3 , P_4 , P_0 , P_2 satisfies safety requirement
- Can request for (3,3,0) by P_4 be granted?
- Can request for (0,2,0) by P₀ be granted?

Deadlock Handling

Strategies for dealing with deadlocks:

- 1. Detection and recovery. Let deadlocks occur, detect them, take action.
- 2. Dynamic avoidance by careful resource allocation.
- 3. Prevention, by structurally negating one of the four required conditions.
- 4. Just ignore the problem.

Deadlock Prevention

Restrain the ways request can be made

- Mutual Exclusion not required for sharable resources; must hold for nonsharable resources
 - Read only file
- Hold and Wait must guarantee that whenever a process requests a resource, it does not hold any other resources
 - Require process to request and be allocated all its resources before it begins execution,
 - Allow process to request resources only when the process has none
 - Release all the current resource and then try to acquire
 - Low resource utilization; starvation possible

Deadlock Prevention (Cont.)

No Preemption –

- If a process that is holding some resources,
- Requests another resource that cannot be immediately allocated to it
 - Resources were allocated to some waiting process
- Preempt the desired resource from waiting process
- Allocate to current process
- Cpu Registers
- Circular Wait Impose a total ordering of all resource types
 - Require that each process requests resources in an increasing order of enumeration

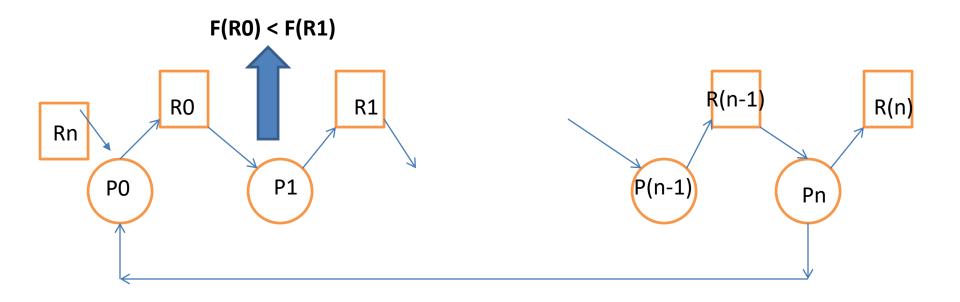
- Let R={R1, R2,....,Rm} set of resource type
- We assign unique integer with each type
- One to one function F:R→N

F(tape drive)=1

F(disk)=5

F(printer)=12

- Protocol: Each process can request resource only in an increasing order.
- Initially request R_i, after that, it can request R_j
 - If and only if $F(R_i)>F(R_i)$
- Currently holding R_i; Want to request R_i.
 - Must have released R_i



$$F(R0) < F(R1) < F(R2) < < F(Rn) < F(R0)$$

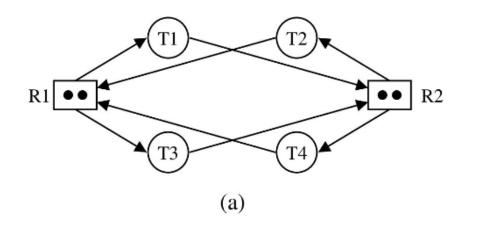
Problem 1

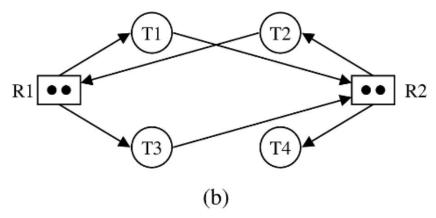
A system is having 3 user processes each requiring max 2 units of resource R.

What is the minimum number of units of R such that no deadlock will occur?

Problem 2

Deadlock or not? Justify.





Problem 3

Q1: A single processor system has three resource types X, Y, and Z, which are shared by three processes. There are 5 units of each resource type.

Allocation

	Х	Y	Z
PO	1	2	1
P1	2	0	1
P2	2	2	1

Request

	Х	Υ	Z
PO	1	0	3
P1	0	1	2
P2	1	2	0

(i) Is the system in a safe state? What is the safe sequence?

(ii) What will happen if process P₁ requests two additional instances of resource type C?

.

Answer:

- (i) According to the question-
- $Total = [XYZ] = [555], Total_Allocation = [XYZ] = [543]$

Now, Available = Total - Total $_{-}$ Allocation = [5 5 5] - [5 4 3] = [0 1 2]

• Step: With the instances available currently, only the requirement of process P1 can be satisfied. So, process P1 is allocated the requested resources. It completes its execution and then frees up the instances of resources held by it. (Then, Available = [0.12] + [2.01] = [2.13]

By repeating the above step, we will get the following

- \rightarrow P0, Available = [3 3 4]
- \rightarrow P2, Available = [5 5 5]
- -→ There exists a safe sequence P1, P0, P2 in which all the processes can be executed.

(ii)New_Request = P1 [0 0 2], so Now, available becomes [0 1 0],