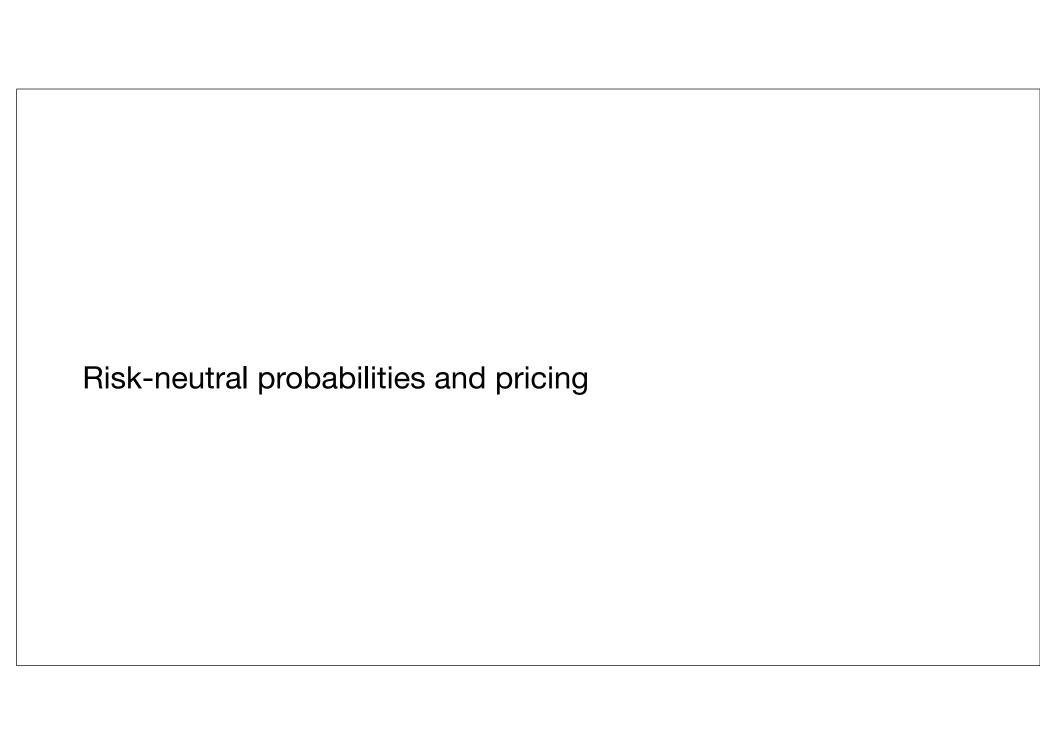
# 15.456 Financial Engineering MIT Sloan School of Management Paul F. Mende

Fundamental theorem of asset pricing, approximate replication, and risk-neutral pricing September 18, 2020

# Agenda

- Announcements
  - Problem Set 2 due Thursday, September 24 @ 11:59pm
  - Quiz alert
- Risk-neutral probabilities and asset pricing
- Multi-period dynamics and the binomial tree
- Measures and martingales
- Dynamic arbitrage theorem



## An improbable trick

- Whenever there is a bilinear sum (or integral), and all the coefficients are positive, we can interpret it **as if** probabilities were involved.
- Define these fictitious probabilities by dividing each coefficient by their sum

$$s(\mathbf{y}) = \sum_{i} c_i y_i$$
, define  $q_i \equiv \frac{c_i}{C}$ , where  $C = \sum_{i} c_i$ 

• Then,

$$s(\mathbf{y}) = C \sum_{i} q_i y_i = C \operatorname{E}[\mathbf{y}] = \operatorname{E}[C\mathbf{y}]$$

where the (fictitious) expectation is taken with respect to these "probabilities."

## Risk-neutral probabilities

There is an interesting interpretation of the state price vector: if we multiply by a
constant so that the sum of the components is unity, those components can be
interpreted as if they were probabilities for the occurrence of each state.

In components, write  $\mathbf{S} = A^* \psi$  as  $S_i = \sum_{\nu=1}^s A_{\nu i} \psi_{\nu}$ , where  $\nu = 1, 2, \dots, s$  labels the states, and  $i = 1, 2, \dots, n$  labels the assets.

• Define  $R_{\nu i} = A_{\nu i}/S_i = \text{return of asset } i \text{ in state } \nu,$   $R_f = A_{\nu 1}/S_1 = \text{risk-free rate, independent of state } \nu,$   $q_{\nu} = R_f \psi_{\nu} = \text{risk-neutral probability of state } \nu.$ 

• Then 
$$\sum_{\nu} q_{\nu} = \sum_{\nu} R_{f} \psi_{\nu} = \frac{\sum A_{\nu 1} \psi_{\nu}}{S_{1}} = 1$$

## Risk-neutral pricing

Now re-express the pricing equation to get two interesting forms.

$$S_i = \sum A_{\nu i} \psi_{\nu} = \sum \frac{A_{\nu i}}{R_f} q_{\nu} = E\left[\frac{A_{\nu i}}{R_f}\right]$$

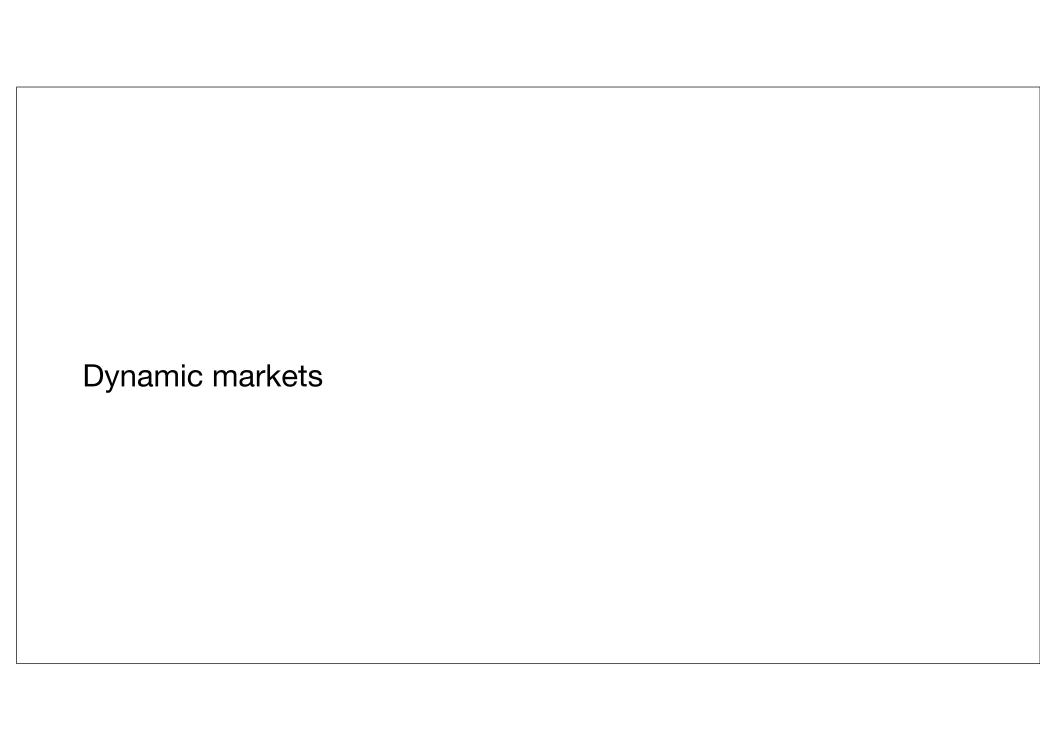
 This says that the security price of risky assets is the expectation of the discounted present value of the payoff under the risk-neutral measure. Divide by price and multiply by the risk-free rate to get

$$\sum R_{\nu i} q_{\nu} = \mathbf{E} \left[ R_{\nu i} \right] = R_f$$

 This says that the expected return of every risky asset is just the risk-free rate under the risk-neutral measure

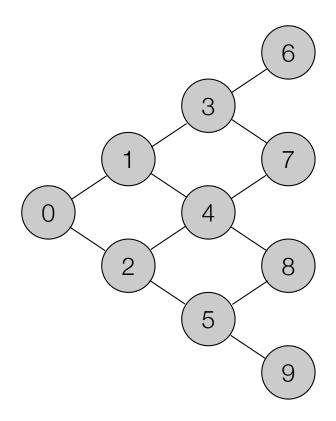
## Risk-neutral pricing

- Are risk-neutral probabilities really fictitious?
- Inferred from prices, sentiment in market
- Compare the questions
  - ▶ How likely is this event?
  - ▶ How much does it **cost** to insure against this event?
- Does a disagreement between objective and risk-neutral probabilities imply arbitrage?
- No. On the contrary, arbitrage is absent as long as risk-neutral probabilities exist.



# Next-to-simplest model

- Let's go from one period to many.
- Discrete time: 0,1,2,...,*T*,....
- Discrete states, distinct at each time step.
- Start with two basis assets
  - ▶ Bond same payoff, regardless of state, between any two fixed times
  - ▶ Stock uncertain payoff
    - ◆ State-dependence
    - → Path-dependence



# Static replication

- Example: *T*=3, stock moves only up or down.
- Suppose there is an option with strike price K

$$A = \begin{pmatrix} R_f^3 & S_0 R_u^3 \\ R_f^3 & S_0 R_u^2 R_d \\ R_f^3 & S_0 R_u R_d^2 \\ R_f^3 & S_0 R_d^3 \end{pmatrix}$$

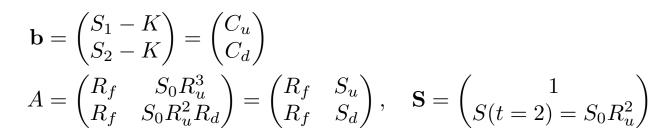
$$S_1 > S_2 > K > S_3 > S_4$$

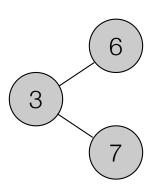
Payoff on a call or a put is (in terms of terminal prices)

$$C = \begin{pmatrix} S_1 - K \\ S_2 - K \\ 0 \\ 0 \end{pmatrix}, \quad P = \begin{pmatrix} 0 \\ 0 \\ K - S_3 \\ K - S_4 \end{pmatrix}$$

Cannot replicate either with stock and bond – an incomplete market.

- Instead, let's consider replication one time-step at a time
- Focus on each node and the possible conditional outcomes
- Example: payoff at *t*=3, given that one is already in a specific state at *t*=2

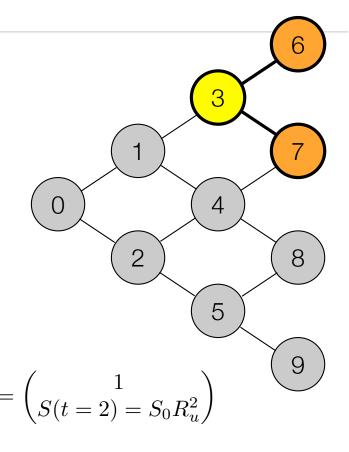




- Instead, let's consider replication one time-step at a time
- Focus on each node and the possible conditional outcomes
- Example: payoff at *t*=3, given that one is already in a specific state at *t*=2

$$\mathbf{b} = \begin{pmatrix} S_1 - K \\ S_2 - K \end{pmatrix} = \begin{pmatrix} C_u \\ C_d \end{pmatrix}$$

$$A = \begin{pmatrix} R_f & S_0 R_u^3 \\ R_f & S_0 R_u^2 R_d \end{pmatrix} = \begin{pmatrix} R_f & S_u \\ R_f & S_d \end{pmatrix}, \quad \mathbf{S} = \begin{pmatrix} 1 \\ S(t=2) = S_0 R_u^2 \end{pmatrix}$$



Solve for the replicating portfolio for the node:

$$A\mathbf{x} = \mathbf{b} \implies \mathbf{x} = A^{-1}\mathbf{b}$$

$$A = \begin{pmatrix} R_f & S_u \\ R_f & S_d \end{pmatrix}, \quad A^{-1} = \frac{1}{R_f(S_d - S_u)} \begin{pmatrix} S_d & -S_u \\ -R_f & R_f \end{pmatrix}$$

$$\mathbf{x} = \begin{pmatrix} B \\ \Delta \end{pmatrix} = A^{-1} \begin{pmatrix} C_u \\ C_d \end{pmatrix} = \frac{1}{R_f(S_d - S_u)} \begin{pmatrix} S_d C_u - S_u C_d \\ -R_f C_u + R_f C_d \end{pmatrix} = \begin{pmatrix} \frac{S_u C_d - S_d C_u}{R_f (S_u - S_d)} \\ \frac{C_u - C_d}{S_u - S_d} \end{pmatrix}$$

Note that

$$\Delta = \frac{C_u - C_d}{S_u - S_d} = \begin{cases} 1 & \text{if both states in the money since } C = S - K, \\ 0 & \text{if both states out of the money, } C_u = C_d = 0 \end{cases}$$

Now that we have a replicating portfolio for this node (and any node),

$$\mathbf{S}^*\mathbf{x} = B + S\Delta$$

State prices are coefficients of the payoff, or more directly,

$$\psi = (A^*)^{-1} \mathbf{S} = (A^{-1})^* \mathbf{S}$$

$$= \frac{-1}{R_f(S_u - S_d)} \begin{pmatrix} S_d & -R_f \\ -S_u & R_f \end{pmatrix} \begin{pmatrix} 1 \\ S \end{pmatrix} = \frac{-1}{R_f(S_u - S_d)} \begin{pmatrix} S_d - R_f S \\ -S_u + R_f S \end{pmatrix}$$

$$= \frac{+1}{R_f(R_u - R_d)} \begin{pmatrix} R_f - R_d \\ R_u - R_f \end{pmatrix} = \frac{1}{R_f} \mathbf{q}$$

• No arbitrage requires  $R_u > R_f > R_d$ 

The state prices and risk-neutral probabilities depend only on the return parameters

$$\mathbf{q} = \begin{pmatrix} \frac{R_f - R_d}{R_u - R_d} \\ \frac{R_u - R_f}{R_u - R_d} \end{pmatrix}$$

• Therefore at any node, call value given in terms of **next period** state values as

$$C = \psi^* \mathbf{b} = (\psi_1 \quad \psi_2) \begin{pmatrix} C_u \\ C_d \end{pmatrix}$$
$$= q_u \frac{C_u}{R_f} + q_d \frac{C_d}{R_f}$$

• This is the expected discounted payoff, under the risk-neutral measure, at the node.

# Pricing: work backward from terminal values

· Omitting time subscripts for clarity,

$$t = 2: C_3 = \frac{1}{R_f} (q_u C_6 + q_d C_7)$$

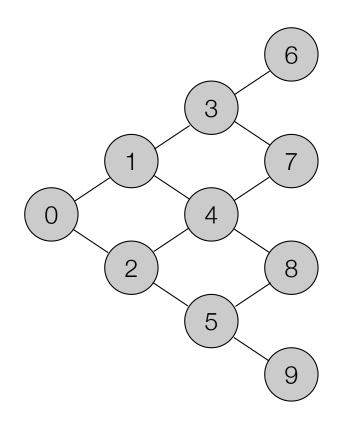
$$C_4 = \frac{1}{R_f} (q_u C_7 + q_d C_8)$$

$$C_5 = \frac{1}{R_f} (q_u C_8 + q_d C_9)$$

$$t = 1: C_1 = \frac{1}{R_f} (q_u C_3 + q_d C_4)$$

$$C_2 = \frac{1}{R_f} (q_u C_4 + q_d C_5)$$

$$t = 0: C_0 = \frac{1}{R_f} (q_u C_1 + q_d C_2)$$



# Pricing: work backward from terminal values

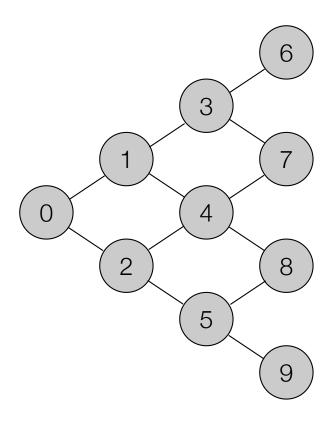
- Each step of recursion is an expectation
- In general, write at each node

$$C_t = \mathcal{E}_t \left[ \frac{C_{t+1}}{R_f} \right]$$

where the expectation is conditional on the given time. For example, for t=2 at node 5, the only states that enter on the right-hand side are the t=3 states:  $\{8,9\}$ 

• Then combining steps, the *t*=0 price is

$$C_{t=0} = \frac{1}{R_f^3} \text{E} \left[ \text{E}_1 \left[ \text{E}_2 \left[ C_3 \right] \right] \right] = \frac{1}{R_f^3} \text{E} \left[ C_3 \right]$$



## Conditional and iterated expectations

- Basic result on iterated expectations: the expectation of an expectation is an expectation!
  - ▶ Important because hedging and pricing are conditioned on information at a given time.
  - ▶ Filtrations: information revealed over time
- Conditional probability and expectation:

$$\operatorname{Prob}(A=a,B=b) = \operatorname{Prob}(A=a|B=b) \operatorname{Prob}(B=b)$$
 
$$\operatorname{E}\left[A|B=b\right] = \sum_{a} a \operatorname{Prob}(A=a|B=b) = f(b)$$

• The expectation of A conditional on B = b is a function of b. Taking **its** expectation...

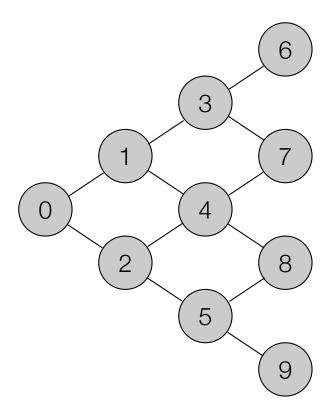
## Conditional and iterated expectations

• The expectation of A conditional on B = b is a function of b. Taking **its** expectation...

$$\begin{split} \operatorname{E}\left[\operatorname{E}\left[A|B\right]\right] &= \operatorname{E}\left[f(b)\right] = \sum_{b} \operatorname{Prob}(B=b)f(b) \\ &= \sum_{b} \operatorname{Prob}(B=b) \left[\sum_{a} a \operatorname{Prob}(A=a|B=b)\right] \\ &= \sum_{a,b} a \left[\operatorname{Prob}(A=a|B=b) \operatorname{Prob}(B=b)\right] \\ &= \sum_{a,b} a \operatorname{Prob}(A=a,B=b) \\ &= \sum_{a} a \operatorname{Prob}(A=a) \\ &= \operatorname{E}\left[A\right] \end{split}$$

# Pricing: work backward from terminal values

- This works for any function of the stock price on the terminal nodes
  - ▶ Calls of any strike
  - ▶ Puts of any strike
  - ▶ Forwards
  - Etc.
- Key ingredients
  - ▶ Bond: captures time value of money
  - ▶ Stock: captures uncertainty over time
  - ▶ Delta: solves for unique dynamic hedging ratio
  - ▶ Risk-neutral probabilities: consistently assigned



#### Calibration

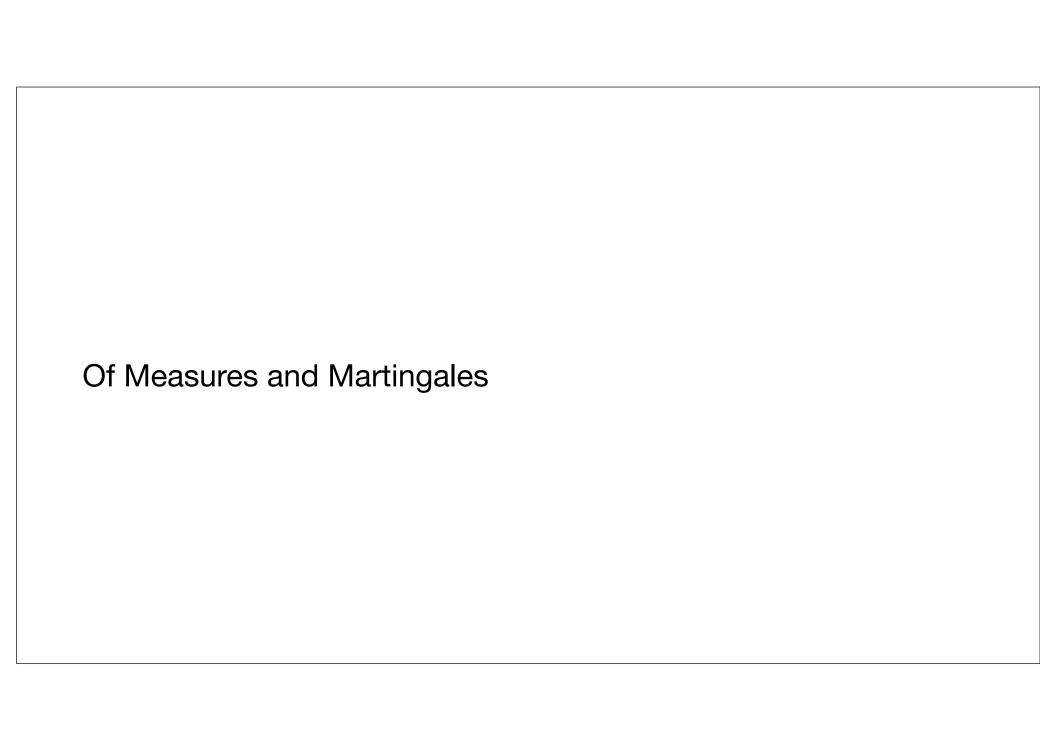
- Identification of binomial model parameters
  - ▶ Returns (up, down)
  - ▶ Probabilities (up, down)
  - Average return per period
  - ▶ Volatility of return
- Example:

$$\overline{R} = 1.009 = 1 + 0.9\%$$
 $\sigma = 4.4\%$ 
 $p = 1/2$ 
 $R_u = 1.053$ 
 $R_d = 0.965$ 

$$\overline{R} = E[R] = pR_u + (1 - p)R_d 
= R_d + p(R_u - R_d) 
\sigma^2 = E[(R - \overline{R})^2] = E[R^2] - \overline{R}^2 
= [pR_u^2 + (1 - p)R_d^2] - [pR_u + (1 - p)R_d]^2 
= p(1 - p)(R_u - R_d)^2$$

$$R_{u} = \overline{R} + \sigma \sqrt{\frac{1-p}{p}},$$

$$R_{d} = \overline{R} - \sigma \sqrt{\frac{p}{1-p}},$$



## Measuring up

- We've explored two kinds of measure and their application
  - Risk neutral: no-arbitrage pricing
  - ▶ Objective: expected utility, portfolio optimization
- We can bridge the two by relating two different ways to compute expectations. For instance, a risk-neutral expectation can also be written as an objective expectation, though of a different random variable

$$\mathbb{E}^{Q}[X] = \sum_{i} q_{i} X_{i} = \sum_{i} p_{i} \left(\frac{q_{i}}{p_{i}}\right) X_{i} = \mathbb{E}[mX]$$

• The original RV gets multiplied times a correction factor known as the **change of** measure  $q_i$ 

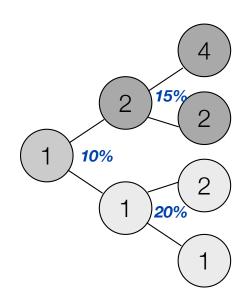
$$m_i = \frac{q_i}{p_i}$$

## Conditional change

- Let's generalize and let probabilities change along different paths.
- Example: (very special numerical choice!)  $R_u = 2$   $\Rightarrow q_u = \frac{R_f R_d}{R_u R_d} = R_f 1$
- Time-varying conditional risk-free rates

$$R_{f,0} = 1.1, \quad R_{f,1} = \begin{cases} 1.15 & \text{if stock goes up,} \\ 1.20 & \text{if stock goes down.} \end{cases}$$

- Note:
  - ▶ Objective probabilities are constant
  - ▶ Risk-neutral probabilities are path-dependent



## Martingales

 A martingale is a stochastic process for which the expectation at any point in time of its future value is equal to the current value

$$\mathbb{E}_t[X_{t'}] = X_t, \quad t < t'$$

 Martingales will be the natural way that our single-period results extend to a dynamic, multiperiod world. In one period, we had the pricing relation for any risky asset

$$\mathbb{E}^Q[R_i] = R_f$$

• For a single asset, this gives  $\mathbb{E}_t^Q[R_t] = R_{ft} = \mathbb{E}_t^Q\left[\frac{S_{t+1}}{S_t}\right] = \frac{1}{S_t}\mathbb{E}_t^Q[S_{t+1}]$   $S_t = \frac{1}{R_{ft}}\mathbb{E}_t^Q[S_{t+1}]$ 

# Martingales: examples and counterexamples

- Examples
- Random walk  $X_t = X_{t-1} + \epsilon_t, \quad e.g., \epsilon_t \sim \mathcal{N}(0, \sigma^2)$ 
  - ▶ Require zero-mean increments
  - ▶ Re-write for applications by shifting time ahead (forecasted) instead of behind (recursion)

$$X_{t+1} = X_t + \epsilon_{t+1}, \quad \mathbb{E}_t[\epsilon_{t+1}] = 0$$
  
$$\mathbb{E}_t[X_{t+1}] = X_t$$

Random walk with drift

$$X_{t+1} = X_t + \mu + \epsilon_{t+1}, \quad \mathbb{E}_t[\epsilon_{t+1}] = 0$$
  
 $\mathbb{E}_t[X_{t+1}] = X_t + \mu \neq X_t$   
 $r_{t+1} = X_{t+1} - X_t$ 

#### Time to iterate

- Allow risk-free rate to be time-varying. Can be moved in or out of expectations with respect to which it is (conditionally) constant.
  - ▶ Conventions: time index of risk-free rate identifies start of period for which rate applies

$$S_{T-1} = \frac{1}{R_{f,T-1}} \mathbb{E}_{T-1}^{Q} [S_T]$$

$$S_{T-2} = \frac{1}{R_{f,T-2}} \mathbb{E}_{T-2}^{Q} \left[ \frac{1}{R_{f,T-1}} \mathbb{E}_{T-1}^{Q} [S_T] \right]$$

$$= \mathbb{E}_{T-2}^{Q} \left[ \mathbb{E}_{T-1}^{Q} \left[ \frac{S_T}{R_{f,T-2}R_{f,T-1}} \right] \right]$$

#### Time to iterate

Continuing backward in time to any earlier time,

$$S_t = \mathbb{E}_t^Q \left[ \mathbb{E}_{t+1}^Q \left[ \cdots \mathbb{E}_{T-1}^Q \left[ \frac{S_T}{R_{f,t} R_{f,t+1} \cdots R_{f,T-1}} \right] \right] \right]$$

· Denominator is compound return over period. Simplify by defining

$$\beta_t \equiv R_{f,0} R_{f,1} \cdots R_{f,t-1}, \quad \beta_0 \equiv 1$$

$$\prod_{\tau=t}^{T-1} R_{f\tau} = \frac{\prod_{\tau=0}^{T-1} R_{f\tau}}{\prod_{\tau=0}^{t-1} R_{f\tau}} = \frac{\beta_T}{\beta_t}$$

$$S_t = \mathbb{E}_t^Q \left[ \frac{S_T}{\beta_T / \beta_t} \right] = \beta_t \mathbb{E}_t^Q \left[ \frac{S_T}{\beta_T} \right]$$

## Discounted price process

 Grouping factors by their time references, the discounted price process is a martingale:

$$\frac{S_t}{\beta_t} = \mathbb{E}_t^Q \left[ \frac{S_T}{\beta_T} \right]$$

Nothing special about terminal point

If 
$$X_t = \frac{S_t}{\beta_t}$$
, then  $\mathbb{E}_{t_1}^Q \left[ X_{t_2} \right] = \mathbb{E}_{t_1}^Q \left[ \mathbb{E}_{t_2}^Q \left[ X_T \right] \right]$ 
$$= \mathbb{E}_{t_1}^Q \left[ X_T \right]$$
$$= X_{t_1}$$

## Martingale propositions

• If a process equals its expectation one time-step ahead, then it is a martingale

Suppose 
$$X_t = \mathbb{E}_t[X_{t+1}]$$
, for  $t = 0, 1, ..., T - 1$ .  
 $X_t = \mathbb{E}_t[X_{t+1}] = \mathbb{E}_t [\mathbb{E}_{t+1}[X_{t+2}]] = \mathbb{E}_t[X_{t+2}]$ ,  
 $X_t = \mathbb{E}_t[X_{t+1}] = \mathbb{E}_t [\mathbb{E}_{t+1} [\mathbb{E}_{t+2}[X_{t+3}]]] = \mathbb{E}_t[X_{t+3}]$ , etc.

 If a process is defined as a sequence of expectations of a fixed random variable, then it is a martingale

Suppose 
$$X_t = \mathbb{E}_t[Y]$$
, for  $t = 0, 1, \dots, T - 1$ .  
Then  $\mathbb{E}_t[X_{t'}] = \mathbb{E}_t[\mathbb{E}_{t'}[Y]] = \mathbb{E}_t[Y] = X_t$ .

## Self-financing trading strategies

- What is the cost of all the re-hedging in the binomial tree model? Zero.
  - Portfolio is risk-free at each time step
  - ▶ Can liquidate to cash and re-establish new re-hedged position.
- Example: suppose you buy a **mispriced** call option and hedge; this is equivalent to selling (the payoff of) a correctly-priced option and buying an underpriced one.
  - ▶ P/L on initial trade date equals mispricing minus (or plus) half-spread
  - ▶ Mark-to-market vs. mark-to-model
  - ▶ P/L on subsequent days expected to be zero for each day

# Self-financing trading strategies

- More generally, suppose a **dynamic, self-financing trading strategy** has portfolio value, share price, and share quantity equal to  $V_t, S_t, \theta_t$
- Recursive value equation
  - ▶ Cash decreased by purchase price of shares
  - ▶ Over one day, cash grows at risk-free rate
  - Over one day, stock changed price while quantity is constant

$$V_{t+1} = R_{f,t}V_t + \theta_t S_t (R_{t+1} - R_{f,t}), \quad R_{t+1} = S_{t+1}/S_t$$
  
=  $R_{f,t}(V_t - \theta_t S_t) + \theta_t S_{t+1}$ 

Cash minus purchase price

Market value of shares one day later

# Self-financing trading strategies

Taking the risk-neutral expectation,

$$\mathbb{E}_{t}^{Q} [V_{t+1}] = R_{f,t}(V_{t} - \theta_{t}S_{t}) + \theta_{t}\mathbb{E}_{t}^{Q}[S_{t+1}]$$
$$= R_{f,t}(V_{t} - \theta_{t}S_{t}) + \theta_{t}(R_{f,t}S_{t}) = R_{f,t}V_{t}$$

• Therefore the discounted price process of the self-financing **strategy** is a martingale:

$$V_t = \mathbb{E}_t^Q \left[ \frac{V_{t+1}}{R_{f,t}} \right] \implies \frac{V_t}{\beta_t} = \mathbb{E}_t^Q \left[ \frac{V_T}{\beta_T} \right], \quad \text{for } t \le T$$

# Dynamic arbitrage

- Define two types of **dynamic arbitrage**, analogous to Type I and II static arbitrage
- Type I: there exists a (no-lose) self-financing strategy with

$$V_0 \le 0$$
,  $V_T \ge 0$ , and  $Prob(V_T > 0) \ne 0$ 

• Type II: there exists a (riskless) self-financing strategy with

$$V_0 < 0, \quad V_T = 0$$

# Dynamic arbitrage theorem

- There is no dynamic arbitrage if and only if
  - ▶ There exists a positive measure Q
  - ▶ Discounted price process of strategies are martingales
- Multiperiod model has no arbitrage if and only if each 1-period model is arbitrage-free.
  - ▶ The "if" direction is true by construction since multiperiod model is built up using 1-period models.
- Key idea: martingale rule formalizes notion of one-period no-arbitrage implying

$$\mathbb{E}^Q[R] = R_f$$

# Dynamic arbitrage theorem

- The unconditional measure is the product of positive conditional measures.
- Given a set of martingale price processes, show there is a contradiction if dynamic arbitrage exists.
- Type I:  $\mathbb{E}_t^Q \left[ \frac{V_T}{\beta_T} \right] > 0 \text{ since } Q \text{ is positive and } V_T > 0.$  But this also equals

$$\mathbb{E}_{t}^{Q}\left[\frac{V_{T}}{\beta_{T}}\right] = \frac{V_{0}}{\beta_{0}} = V_{0} \leq 0$$
, which is a contradiction.

• Type II:

$$0 = \mathbb{E}_t^Q \left[ \frac{V_T}{\beta_T} \right] = \frac{V_0}{\beta_0} = V_0 < 0$$
, which is a contradiction.