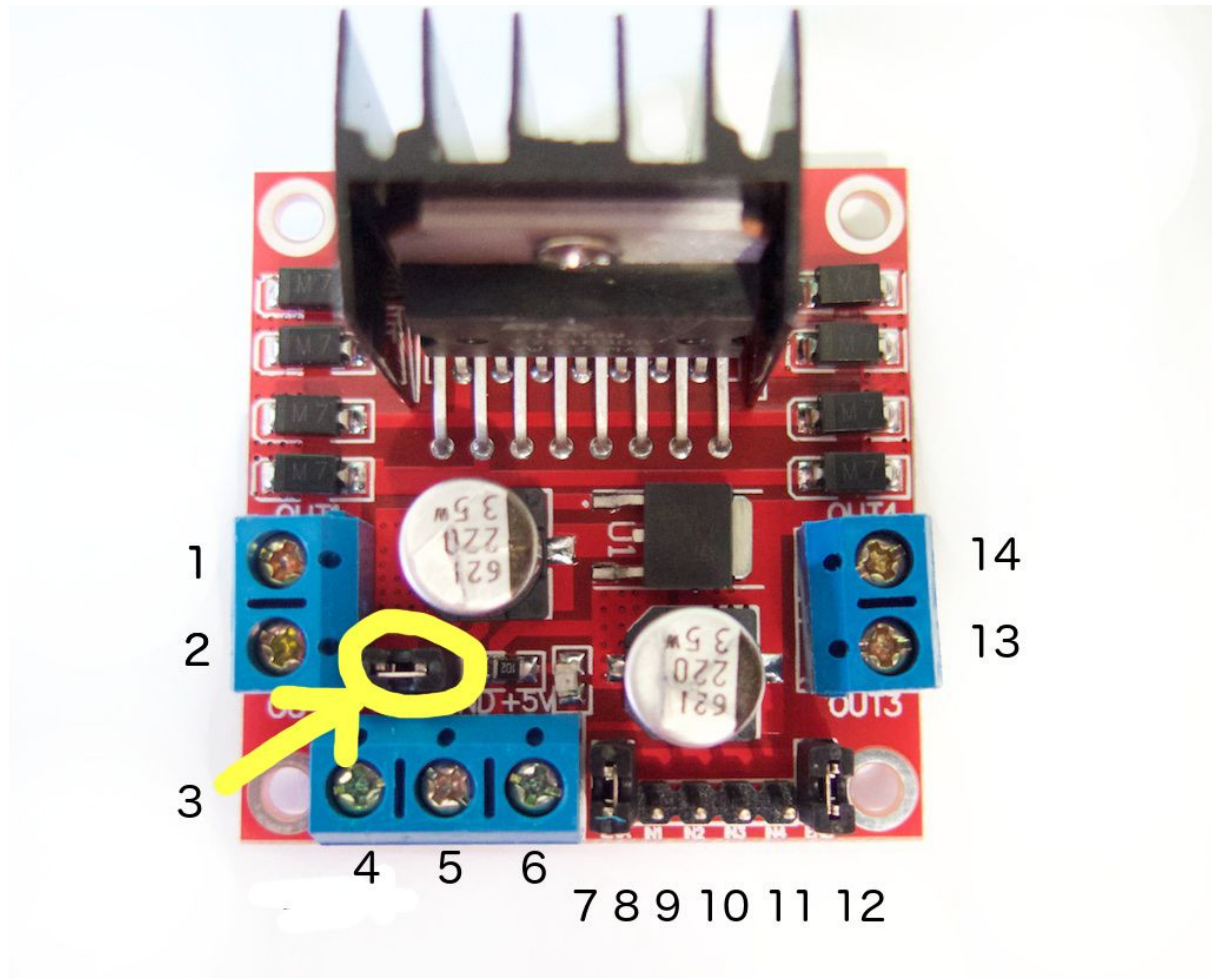


Nematode wiring

Motordriver

Jumper 3 => external 12V DC



## Arduino Pins

Pin Arduino			Motor driver	Ultrason	
0	RX serial				
1	TX serial				
2					
3					
4					
5	IN		==>	==>	Button
6	OUT		==>	==>	Speaker
7	OUT		==>	==>	Speaker

[illegible]