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### Instructions

- This assignment is based on a total of 12.5 points.
- Submit through Gradescope.
- Due on August 28, 11.59pm AEST.

### Problem I

Recall that for scalar  $\lambda > 0$ , the probability density function of an "exponential" random variable with parameter  $\lambda$ , is  $P(x; \lambda) = \lambda \exp(-\lambda x)$ . We have n independent samples  $x_1, \ldots, x_n$ . Each  $x_1, \ldots, x_n$  is a scalar. Each  $x_i$  is an "exponential" random variable with parameter  $\lambda$ .

1) [2 points] We define the dataset  $D = \{x_1, \dots, x_n\}$ . Give a short expression for the log-likelihood function  $l(D; \lambda) = \sum_{i=1}^{n} \log P(x_i; \lambda)$ . Show all the steps in your derivation.

The log-likelihood function is the logarithm of the product of the individual probabilities since the samples are independent. 
$$|(D;\lambda)| = \sum_{i=1}^{n} \log P(X_i;\lambda)$$
$$= \sum_{i=1}^{n} \log (N \exp(-\pi X_i))$$
$$= \sum_{i=1}^{n} (\log(N) + \log(e \times P(-\pi X_i)))$$
$$= \sum_{i=1}^{n} (\log(N) - \pi X_i)$$
$$= n(\log(N) - \pi X_i)$$

2) [2 points] What is the maximum likelihood estimator? In other words, what is the value of  $\lambda$  for which the derivative of  $l(D; \lambda)$  with respect to  $\lambda$  is zero? Show all the steps in your derivation.

Now we have 
$$(CD_{j}\Pi) = nlog(\Pi) - \Pi_{ij}^{Z}X_{i}$$

$$\frac{\partial L(D_{j}\Pi)}{\partial \Pi} = \frac{\partial (nlog(\Pi) - \Pi_{ij}^{Z}X_{i})}{\partial \Pi} = \frac{n}{n} - \sum_{i=1}^{n}X_{i}$$
So that we can confirm that this critical point is a maximum.
$$\frac{n}{n} - \sum_{i=1}^{n}X_{i} = 0$$
Thus the MLE for  $\Pi$  is  $\hat{\Pi} = \frac{1}{n}$ , where  $\hat{X} = \frac{1}{n}$ 

COMP90051 Jean Honorio (jean.honorio@unimelb.edu.au) 2024-2, Assignment 1, Page 2/4 Student ID: Name: Muhar Guan

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### Problem II

3) [2 points] Assume we use classifiers from a countably finite model class  $\mathcal{F}$  of 1000000 classifiers. On a dataset of 20 i.i.d. samples, we obtain an empirical risk (i.e., training error) of 0.35.

Would you recommend using this classifier or not? Assume we want to be certain with probability at least 0.99. Please answer "Yes" or "No", and clearly explain why.

Now we have R[REI] - Roll >2 for some \$ = F] = G, where S=|F|e^2ne^2 . Then we take compliment of this event using Pr(A)=|-Pr[not A] Pr[REI]-BCI] = E for all \$t \in F \text{21-8. Therefore, with the \$probability at least 1-6, the true risk of any classifiers in F can be upper bounded by RIJE, where Roll is its empirical risk and \$E = \frac{1091F1+\text{121/62}}{2n} \frac{1}{1620} = \frac{1}{200} on unseen data crestly dates , so I will not recommend using this classifier.

4) [2 points] Assume we use classifiers from a countably finite model class  $\mathcal{F}$  of 2000000 classifiers. On a dataset of 1000 i.i.d. samples, we obtain an empirical risk (i.e., training error) of 0.1.

Would you recommend using this classifier or not? Assume we want to be certain with probability at least 0.99. Please answer "Yes" or "No", and clearly explain why.

We still use the same formula in C37, A[7] { orly legiciand 20,198 The bound is tight.

with high probability org, the true rish of this classifier will lower than 0.198 when me deploy it on unseen data. Therefore, such bound can provide performance guarantee for our model and the the classifier is robust for future data. Conclusion. Yes, be cause the generalization bound suggests that the true error of this classified is likely to be bow, and the classifier can still perform well on unseen data. Crecommend using this classifier)

5) [0.5 points] On another dataset with  $p \ge 100$  features, assume we run 3 classification algorithms and obtain the following empirical risks (i.e., training errors). We also include the VC dimension of the 3 algorithms.

Algorithm	Empirical risk	VC dimension
A1	0.15	p
A2	0.15	$p^2$
A3	0.15	$p^3$

Which algorithm should we prefer? Write "A1" or "A2" or "A3", and clearly explain your answer.

We have with high probability 1-8, R[fo] < Rolfal ty 8 YCLF) leg (1911) + leg (19/5)

Since all algorithms have the control of the state of the stat vive nave with night proceedings 1-8, RL to ] < Rollad TN

Since all algorithms have the same empirical risk Rollad TN

Since all algorithms have the same empirical risk Rollad, and they used the same traing dataset soith the same number of Samples n, and they are compared under the same confidence level 1-5. So the algorithm with the lowest VC dimension will have the tightest bound, indicating better performance on unseen data and making it the most preferable choice. Now we have VC(A) < In conclusion, VC dimension is a measure of complexity of model. A model with prigher complexity always has stronger ability to fit wider variety of functions, but also has higher risk of overfitting, leading to poover performance on the prediction of unseen data.

# COMP90051 Jean Honorio (jean.honorio@unimelb.edu.au) 2024-2, Assignment 1, Page 3/4

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## Problem III

**6)** [2 points] Suppose we only have 4 training samples in two dimensions: two positive samples  $\underline{x}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ ,  $\underline{x}_2 = \begin{bmatrix} 5 \\ 5 \end{bmatrix}$  and two negative samples  $\underline{x}_3 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$ ,  $\underline{x}_4 = \begin{bmatrix} 1 \\ 5 \end{bmatrix}$ .

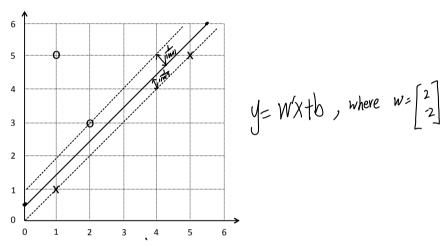
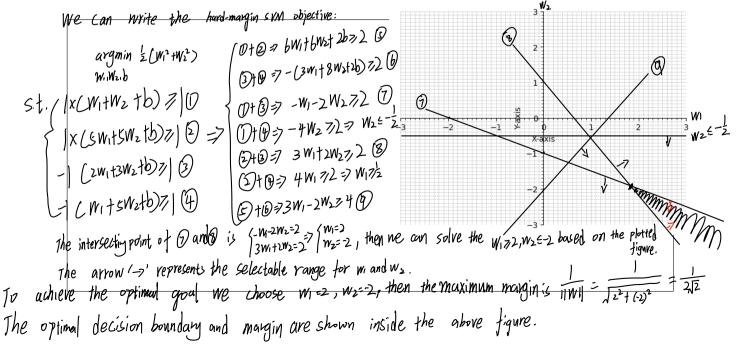


Figure 1: Training set (positive points shown as X, negative points shown as O)

What is the margin (distance from the separating/decision boundary to a sample) achieved by the maximum margin linear classifier?

*Important:* We do not require the separating/decision boundary to pass through the origin.

Show all the steps in your derivation. You can draw inside the figure, or use the space below.



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#### Problem IV

7) [2 points] Consider the following dataset with 12 samples.

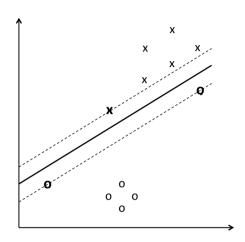


Figure 2: Training set (positive points shown as X, negative points shown as O), maximum margin linear classifier, and the 3 support vectors (in bold)

Imagine we remove some points from the above training set and learn a support vector machine with the remaining points. How many points can we remove (at most) from the above training set so that the separating/decision boundary remains exactly the same as in the above chart?

Write the number of points (for instance:  $0, 1, 2, 3, \ldots$ , or 12) and clearly explain your answer. You can draw inside the figure, or use the space below.

We can remove at most 9 points from above trainy set notile remain the decision boundary exactly the same as in the above chart.

Support vertors are the point that lie on the margin lines and directly influence the position of the decision boundary. When we solve this using lagrangian, the not = = \frac{2}{7}\tau\_1\text{i/xi} and b\* can be recovered boundary. When we solve this using lagrangian, the not = \frac{2}{7}\tau\_1\text{i/xi} and b\* can be recovered toom dual solution yicb\*+\frac{1}{7}\text{i/xi}xi/xi)=1. We can note that the not and b\* are only decided by the training points noith corresponding \text{7i-70, those training points are support vectors and we discard all the other points with corresponding \text{7i-70, those training points are support vectors and \text{3 points} are \text{1 is oblious that there are 9 points are non-support vectors (\text{7j-0}) and 3 points are support vectors(\text{7j-0}) the non-support vectors do not influence the decision boundary, hence remove them does not change the position.