

Workshop 2

COMP90051 Statistical Machine Learning Semester 1, 2023

About your tutor

Agenda

- 1. Icebreaker
- 2. Python ecosystem for ML
- 3. Refresher: Bayes' theorem
- 4. Worksheet on Bayesian inference

Icebreaker

Learning outcomes

At the end of this workshop you should:

- be familiar with the Python ecosystem for machine learning
- develop intuition about the role of prior and posterior in Bayesian inference

Is your system ready to go?

- You should have installed Anaconda on your system before today's workshop. If not, please install it now.
- Anaconda is a Python distribution tailored for scientific computing
- Most of the packages we need are installed by default
- Worksheets will be distributed as Jupyter Notebooks





Top 5 libraries for beginners to master



- Library for working with large multidimensional arrays
- High-level functions for arrays



- Machine learning library
- Includes implementations of most models covered in this course (exception: neural nets)





matpletlib

Library for analysis and

manipulation of tabular data

to DataFrames and dplyr in R

Provides similar functionality

2D plotting library

pandas

 $y_{it} = \beta' x_{it} + \mu_i + \epsilon_{it}$

 Provides similar interface to **MATLAB**



- Scientific computing library
- Functionality includes: statistics/random number generation, linear algebra, optimisation, special functions, integration

We'll see some of these libraries later...









Deep learning frameworks

Probabilistic programming frameworks







Bayesian inference

Recall from Lecture 2

COMP90051 Statistical Machine Learning

Tools of probabilistic inference in The Cuta cutput: Bayesian probabilistic inference

- - Start with prior $P(\theta)$ and likelihood $P(X|\theta)$
 - * Observe data X = x
 - * Update prior to posterior $P(\theta|X=x)$
- Primary tools to obtain the posterior
 - Bayes Rule: reverses order of conditioning

$$P(\theta | X = x) = \frac{P(X = x | \theta)P(\theta)}{P(X = x)}$$

* Marginalisation: eliminates unwanted variables

$$P(X = x) = \sum_{t} P(X = x, \theta = t)$$

This quantity is called the evidence



- The likelihood $P(X = x | \theta)$ is the conditional probability of the data X = x as a function of θ .
- The prior $P(\theta)$ represents information we have that is not part of the collected data X = x.
- The evidence P(X = x) is the average over all possible values of theta.
- $P(\theta|X=x)$ is the posterior distribution, which represents our updated beliefs under our prior $P(\theta)$ now we have observed the data X = x.

prior:
$$P(D) = \frac{1}{13(a \cdot b)} = \frac{1}{13(a \cdot b)$$

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133 John or concentrated > more dutu-protes nove confident to estimation infor need updatu - posterior

$$7^{2}(8) = \frac{1}{\text{Reta(a.b)}}$$

$$P(x_{1}|\theta) = \theta^{x_{1}}(1-\theta)^{1-x_{1}}$$

$$P(x_{2}|\theta) = \theta^{x_{2}}(1-\theta)^{1-x_{2}}$$

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$$= \theta^{x_{1}+x_{2}+\theta+1}(1-\theta)^{2-x_{1}-x_{2}+1}$$

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$$= \theta^{x_{1}+x_{2}+\theta+1}(1-\theta)^{2-x_{1}-x_{2}+1}$$

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$$\frac{\pi}{|I|} p(xi|B) p(B)$$

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derivation for MP:
$$\widehat{\theta}_{MAP} = \underset{\theta}{\operatorname{arg max}} P(\theta|X_1,...,X_n)$$

$$= \frac{n_0 + 44 + 1}{n + 47 + 1}$$

$$|MAP| = P(\theta|X_1,...,X_n) = 0 = \sum_{i=1}^{N} \frac{1}{n}$$

$$|derivative: \frac{\partial L}{\partial \theta} = \sum_{i=1}^{N} \frac{1}{n} \frac{1}{n} \frac{\partial L}{\partial \theta} = 0$$

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