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**SEMESTER TWO**

**MATHEMATICS  
SPECIALIST  
UNITS 3 & 4**

**2019**

**SOLUTIONS**

**Calculator-Free Solutions**

$$1. \quad \bar{z} + \frac{z}{i} = (a-bi) + \frac{a+bi}{i} = (a+b) - (a+b)i \quad \checkmark \checkmark$$

$$\text{i.e. } \Re\left(\bar{z} + \frac{z}{i}\right) = -\Im\left(\bar{z} + \frac{z}{i}\right)$$

i.e. the complex number lies on the line  $y = -x$   $\checkmark$

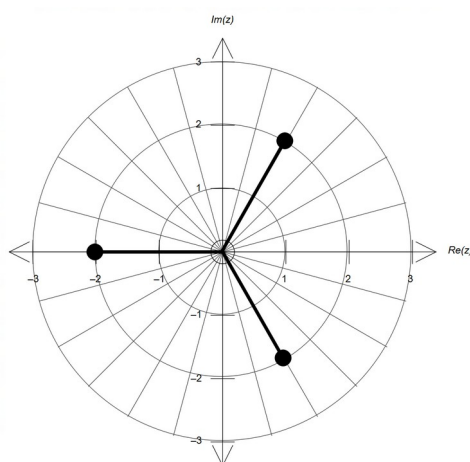
$$\therefore \arg\left(\bar{z} + \frac{z}{i}\right) = \frac{-\pi}{4} \vee \frac{3\pi}{4} \quad \checkmark \checkmark \quad [5]$$

$$2. \quad (\text{a}) \quad z^3 = -8 = 8 \operatorname{cis}(\pi + 2k\pi)$$

$$\therefore z = 2 \operatorname{cis}\left(\frac{\pi + 2k\pi}{3}\right) \text{ for } k = 0, \pm 1 \quad \checkmark$$

$$z_0 = 2 \operatorname{cis}\left(\frac{\pi}{3}\right), z_1 = 2 \operatorname{cis}(\pi), z_3 = 2 \operatorname{cis}\left(\frac{-\pi}{3}\right) \quad \checkmark \checkmark$$

(b)



$\checkmark$  magnitude = 2

$\checkmark$   $\frac{2\pi}{3}$  radians

$$(\text{c}) \quad P(z) = (z^3 + 8)(z^2 + bz + c) = z^5 - z^4 - 2z^3 + 8z^2 - 8z - 16$$

$$\therefore 8c = -16 \rightarrow c = -2$$

expanding with  $c = -2$  gives:

$$P(z) = z^5 + bz^4 - 2z^3 + 8z^2 + 8bz - 16$$

and therefore  $b = -1$  and  $c = -2$   $\checkmark$

(division of polynomials is also possible)

$$\text{Hence, } Q(z) = z^2 - z - 2 = (z - 2)(z + 1) \quad \checkmark$$

$$(\text{d}) \quad \therefore P(z) = (z^3 + 8)(z - 2)(z + 1) \quad \checkmark$$

$$\therefore z = -1, \pm 2 \wedge 1 \pm \sqrt{3}i$$

✓✓

[10]

3. (a)  $x = 2 \tan(\theta) \rightarrow \frac{dx}{d\theta} = \frac{2}{\cos^2 \theta} \rightarrow dx = \frac{2d\theta}{\cos^2 \theta} \quad \checkmark$

$$\theta(x) = \tan^{-1}\left(\frac{x}{2}\right) \rightarrow \theta(0) = 0 \wedge \theta(2) = \frac{\pi}{4}$$

$$\therefore a = 0 \wedge b = \frac{\pi}{4} \quad \checkmark$$

$$\sqrt{x^2 + 4} = \sqrt{4 \tan^2 \theta + 4} = \sqrt{4(\tan^2 \theta + 1)} = \sqrt{\frac{4}{\cos^2 \theta}}$$

$$\therefore \sqrt{x^2 + 4} = \frac{2}{\cos \theta} \quad \checkmark$$

$$\therefore \int_0^2 \frac{x}{\sqrt{x^2 + 4}} dx = \int_0^{\frac{\pi}{4}} \frac{2 \tan \theta}{\left(\frac{2}{\cos \theta}\right)} \times \frac{2 d\theta}{\cos^2 \theta} = \int_0^{\frac{\pi}{4}} \frac{2 \tan \theta}{\cos \theta} d\theta$$

(b) Using the substitution recommended in (a):

$$\int_0^{\frac{\pi}{4}} \frac{2 \tan \theta}{\cos \theta} d\theta = 2 \int_0^{\frac{\pi}{4}} \frac{\sin \theta}{\cos^2 \theta} d\theta = 2 \int_0^{\frac{\pi}{4}} \sin \theta \cos^{-2} \theta d\theta$$

$$\hookrightarrow 2 \left[ \frac{-\cos^{-1} \theta}{-1} \right]_0^{\frac{\pi}{4}} = 2 \left[ \frac{1}{\cos \theta} \right]_0^{\frac{\pi}{4}} = 2 \left[ \frac{1}{\frac{1}{\sqrt{2}}} - \frac{1}{1} \right] = 2(\sqrt{2} - 1) \quad \checkmark \checkmark$$

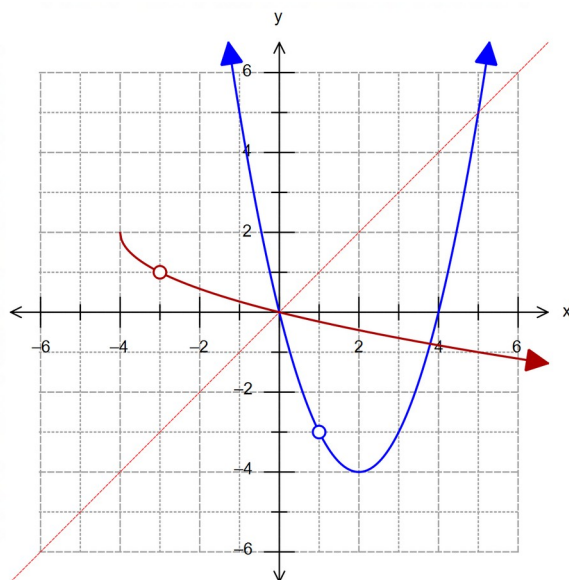
(other method is possible by setting  $u = x^2$ )

4. (a)  $f(x) = \frac{x(x^2 - 5x + 4)}{(x-1)} = \frac{x(x-4)(x-1)}{(x-1)} = x(x-4)$  provided  $x \neq 1 \quad \checkmark$

$$\therefore D_x = \{x \in \mathbb{R} : x \neq 1\} \quad \checkmark$$

$$R_y = \{y \in \mathbb{R} : y \geq -4 \wedge y \neq -3\} \quad \checkmark \checkmark$$

(b)



(b)

✓ parabola with roots at  $x=0$  and  $4$ , with tp at  $(2, -4)$

(d)

✓ square root function with tp at  $(-4, 2)$

✓ discontinuity at  $(-3, 1)$

4. (c) Turning point at  $(2, -4) \rightarrow \therefore x \leq 2 \rightarrow k=2$  ✓

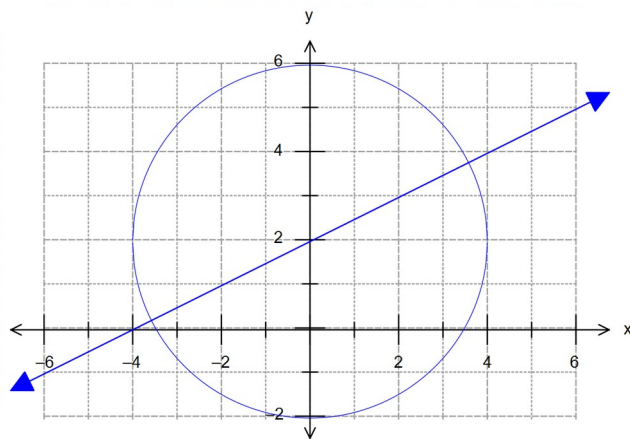
Algebraically by rearranging to make  $x$  the subject

gives  $f^{-1}(x) = 2 - \sqrt{x+4}$  ✓

- (d) Shown on the graph in (b). ✓✓ [10]

5. (a)  $|r - 2j| = 4$  ✓

- (b) The line can be obtained from two points, by choosing any two different values of  $\lambda$ .



✓✓ line  $y = \frac{x}{2} + 2$

$$\left| \begin{pmatrix} 2\lambda - 2 \\ \lambda + 1 \end{pmatrix} - \begin{pmatrix} 0 \\ 2 \end{pmatrix} \right| = \left| \begin{pmatrix} 2(\lambda - 1) \\ \lambda - 1 \end{pmatrix} \right| = 4 \quad \checkmark$$

$$\therefore 4(\lambda - 1)^2 + (\lambda - 1)^2 = 16$$

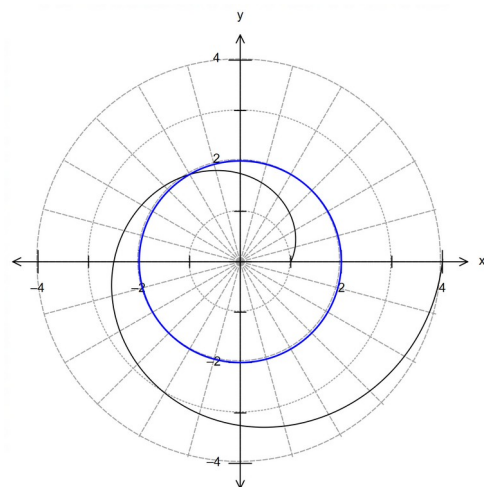
$$5(\lambda - 1)^2 = 16 \rightarrow \lambda = 1 \pm \frac{4}{\sqrt{5}} \quad \checkmark$$

$$\therefore r \left( 1 \pm \frac{4}{\sqrt{5}} \right) = \begin{pmatrix} 2 \left( 1 \pm \frac{4}{\sqrt{5}} \right) - 2 \\ 1 \pm \frac{4}{\sqrt{5}} + 1 \end{pmatrix} = \begin{pmatrix} \pm \frac{8}{\sqrt{5}} \\ 2 \pm \frac{4}{\sqrt{5}} \end{pmatrix} \quad \checkmark \quad [6]$$

6. (a) Choosing the polar point  $(4, 2\pi)^P$ :

$$\arg(z) = 2\pi \rightarrow |z| = k(2\pi) + 1 = 4 \therefore k = \frac{3}{2\pi} \checkmark$$

(b)



✓ circle centred at O  
with radius 2

- (c) Using  $|z| = 2$ :

$$2 = \frac{3}{2\pi} \arg(z) + 1 \rightarrow \arg(z) = \frac{2\pi}{3} \quad \checkmark \checkmark$$

$$\therefore w = 2 \operatorname{cis}\left(\frac{2\pi}{3}\right) = 2 \cos\left(\frac{2\pi}{3}\right) + 2i \sin\left(\frac{2\pi}{3}\right) = -1 + \sqrt{3}i \quad \checkmark \checkmark \quad [6]$$

7. (a) Area of a segment:  $A = \frac{r^2}{2}(\theta - \sin \theta)$

$$\therefore A = \frac{\left(\frac{1}{2}\right)^2}{2}(2\theta - \sin(2\theta)) = \frac{1}{8}(2\theta - \sin 2\theta)$$

$$\therefore V = A \times l = \frac{1}{8}(2\theta - \sin 2\theta) \times 8 = 2\theta - \sin 2\theta \quad \checkmark$$

(b)  $\frac{dV}{d\theta} = 2 - 2 \cos 2\theta \quad \checkmark$

(c)  $\cos \theta = \frac{\frac{1}{2} - x}{\frac{1}{2}} = 1 - 2x \quad \checkmark$

$$\therefore x = \frac{1}{2} - \frac{1}{2} \cos \theta \quad \checkmark$$

$$\frac{dx}{dt} = 0 - \frac{1}{2} \times -\sin \theta \times \frac{d\theta}{dt} = \frac{1}{2} \frac{\sin \theta d\theta}{dt} \quad \checkmark$$

(d)  $\frac{d\theta}{dt} = \frac{d\theta}{dV} \times \frac{dV}{dt} = \frac{0.1}{2 - 2 \cos 2\theta}$

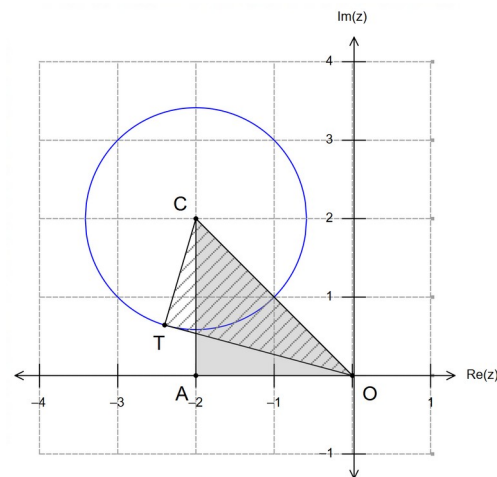
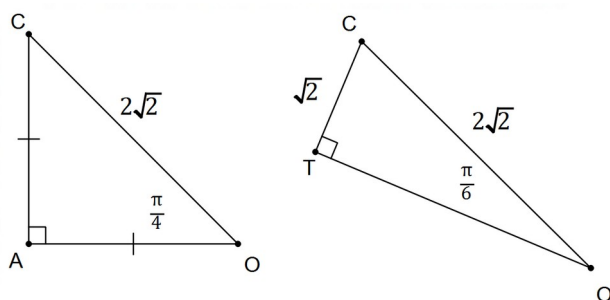
$$\therefore \frac{dx}{dt} = \frac{1}{2} \sin \theta \times \frac{0.1}{2 - 2 \cos 2\theta} = \frac{\sin \theta}{40(1 - \cos 2\theta)} \quad \checkmark$$

when  $x = \frac{1}{4}$  m we obtain  $\theta = \frac{\pi}{3}$   $\checkmark$

$$\therefore \left. \frac{dx}{dt} \right|_{\theta = \frac{\pi}{3}} = \frac{\sin\left(\frac{\pi}{3}\right)}{40\left(1 - \cos\left(\frac{2\pi}{3}\right)\right)} = \frac{\frac{\sqrt{3}}{2}}{40\left(1 + \frac{1}{2}\right)} = \frac{\sqrt{3}}{120} \left[ \frac{m^3}{min} \right] \quad \checkmark \quad [8]$$

**Calculator-assumed Solutions**

8. From the diagram we obtain two right angled triangles:



And therefore we have:

$$|z|_{\min} = 2\sqrt{2} - \sqrt{2} = \sqrt{2} \quad \checkmark$$

$$|z|_{\max} = 2\sqrt{2} + \sqrt{2} = 3\sqrt{2} \quad \checkmark$$

$$\arg(z)_{\min} = \frac{3\pi}{4} - \frac{\pi}{6} = \frac{7\pi}{12} \quad \checkmark\checkmark$$

$$\arg(z)_{\max} = \frac{3\pi}{4} + \frac{\pi}{6} = \frac{11\pi}{12} \quad \checkmark$$

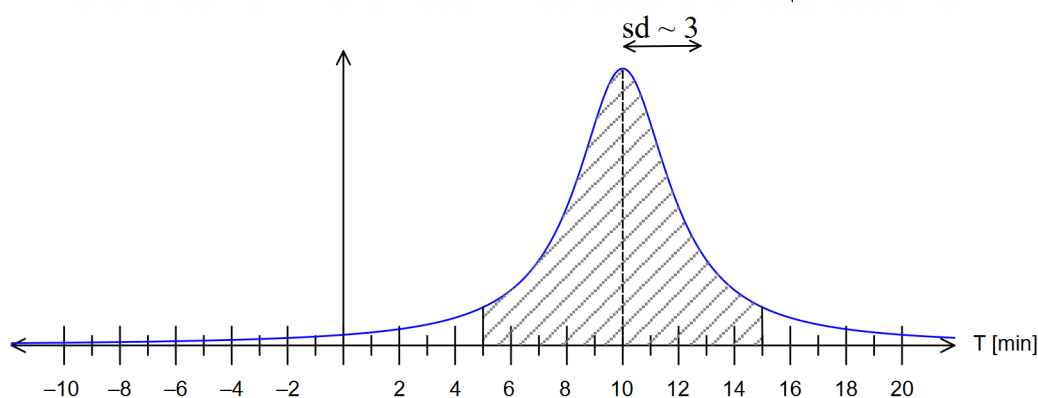
[5]

9. (a)  $\bar{T} \sim N\left(15, \frac{300}{30}\right)$  ✓

$$\therefore \sigma^2(\bar{T}) = 10 \rightarrow \sigma(\bar{T}) = \sqrt{10} \approx 3.16 \quad \checkmark$$

$$\therefore P(5 \leq \bar{T} \leq 15) = 0.8862 \approx 0.89 \text{ (2dp.)} \quad \checkmark$$

(b)



✓ Normal distribution  
centred at  $\mu(\bar{T}) = 10$

standard  
approx. 3 min  
with area

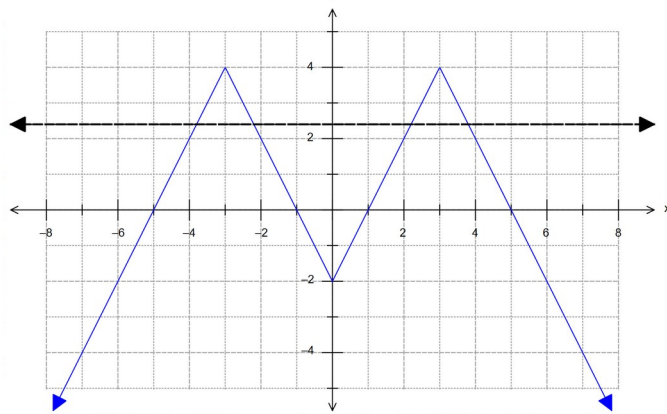
[6]



10. (a)  $y = -2|x+3|+4$   
 $\therefore a = -2, b = 3, c = 4$

✓✓✓

(b) The diagram below shows  $f(-|x|)$ :



Therefore, a horizontal line  $y = d$  would intersect the graph for  $-2 < d < 4$ .

✓✓✓

[6]

(graphical explanation can be accepted)

11. (a)  $\vec{OM} = \begin{pmatrix} 120 \\ -80 \\ 40 \end{pmatrix} + t \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} x \\ y \\ 0 \end{pmatrix} = \text{location of ground collision}$  ✓

$\therefore 40 - t = 0 \rightarrow t = 40$  seconds

✓

$\therefore \vec{OM}(40) = \begin{pmatrix} 120 \\ -80 \\ 40 \end{pmatrix} + 40 \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 200 \\ -40 \\ 0 \end{pmatrix}$

✓

and  $|\vec{OM}(40)| = \begin{vmatrix} 200 \\ -40 \\ 0 \end{vmatrix} = 40 \begin{vmatrix} 5 \\ -1 \\ 0 \end{vmatrix} = 40\sqrt{26} \approx 203.96 \text{ km from O}$  ✓

(b)  $\vec{OM} = \begin{pmatrix} 120 \\ -80 \\ 40 \end{pmatrix} + t \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} x \\ y \\ 10 \end{pmatrix} = \text{point 10 km above ground}$

$\therefore 40 - t = 10 \rightarrow t = 30$  sec from detection time

✓

$\therefore \vec{OM}(30) = \begin{pmatrix} 120 \\ -80 \\ 40 \end{pmatrix} + 30 \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 180 \\ -50 \\ 10 \end{pmatrix}$

✓

$\begin{pmatrix} 180 \\ -50 \\ 10 \end{pmatrix} - \begin{pmatrix} 20 \\ 160 \\ 0 \end{pmatrix} = \begin{pmatrix} 160 \\ -210 \\ 10 \end{pmatrix}$  displacement vector for ABM

✓

$$\therefore speed = \frac{1}{30} \left| \frac{160}{-210} \right| = \frac{\sqrt{698}}{3} \approx 8.81 \text{ km/s} \quad \checkmark$$

11. (c) (Using the conditions for collision will show that they do not collide. If no other work is shown then award two marks for this attempt)

Using closest-approach method with CAS:  $f_{\min}$

$$\overrightarrow{OM} = \begin{pmatrix} 2t+120 \\ t-80 \\ 40-t \end{pmatrix} \quad \text{and} \quad \overrightarrow{ABM} = \begin{pmatrix} 20+4.6t \\ 160-5.25t \\ 0+0.042t \end{pmatrix}$$

$$\therefore {}_{ABM}r_{OM} = \overrightarrow{ABM} - \overrightarrow{OM} = \begin{pmatrix} 2.6t-100 \\ 240-6.25t \\ 1.042t-40 \end{pmatrix} \quad \checkmark\checkmark$$

$$\therefore |{}_{ABM}r_{OM}| = \sqrt{(2.6t-100)^2 + (240-6.25t)^2 + (0.042t-40)^2} \quad \checkmark$$

$$\text{CAS: } f_{\min} \rightarrow |{}_{ABM}r_{OM}|_{\min} \approx 0.15 \text{ km} \quad \text{for } t = 38.41 \text{ s} \quad \checkmark\checkmark \quad [13]$$

12. (a)  $\left. \frac{dy}{dx} \right|_{(0,2)} = \frac{1}{2(0)+2} = \frac{1}{2} \quad \checkmark\checkmark$

(b) The slope is undefined at  $x = -1$   $\checkmark$

(c)  $\frac{dy}{dx} = \frac{1}{2(x+1)} \rightarrow 2dy = \frac{dx}{x+1}$

$$\therefore \int 2dy = \int \frac{dx}{x+1}$$

$$\therefore 2y = \ln|x+1| + C_1 \quad \checkmark$$

$$y = \frac{1}{2} \ln|x+1| + C_2 = \ln \sqrt{x+1} + C_2$$

$$(0,2) \rightarrow 2 = \ln \sqrt{1} + C_2 \rightarrow C_2 = 2 \quad \checkmark$$

$$\therefore y = \ln \sqrt{x+1} + 2 = \ln e^2 \sqrt{x+1} \quad \checkmark$$

13. (a)  $\bar{X}$  is approximately normally distributed as the sample size  $n=40 > 30$

$$\therefore \bar{X} \sim N\left(8, \frac{8^2}{40}\right) = N(8, 1.6) \quad \checkmark\checkmark$$

$$\text{i.e. } \sigma(\bar{X}) = \sqrt{1.6} \approx 1.2649 \quad \checkmark$$

(b)  $P(5 < \bar{X} < 11) = 0.9823 \quad \checkmark\checkmark$

(c) No, there is no change.  $\checkmark$

Because the sample size ( $40 > 30$ ) provides a normal distribution for the sample means, despite the shape of the parent distribution.

✓

13. (d)  $P(\bar{X} > 10) = 0.05 \checkmark$

and  $\bar{X} \sim N\left(8, \frac{8^2}{n}\right)$ , i.e.  $\sigma(\bar{X}) = \frac{8}{\sqrt{n}}$

If  $P(z > k) = 0.05 \rightarrow k = 1.6448 \checkmark$

$\therefore \frac{10-8}{\left(\frac{8}{\sqrt{n}}\right)} = 1.6448 \rightarrow n = 43.29 \approx 44 \checkmark \checkmark$

14. (a) (i)  $\frac{d(x \cos x)}{dx} = \cos x - x \sin x \checkmark$

(ii)  $d(x \cos x) = \cos x dx - x \sin x dx$

$\therefore \int_0^{\pi} d(x \cos x) = \int_0^{\pi} \cos x dx - \int_0^{\pi} x \sin x dx$

$\int_0^{\pi} x \sin x dx = \int_0^{\pi} \cos x dx - \int_0^{\pi} d(x \cos x)$

$\int_0^{\pi} \sin x dx - [x \cos x]_0^{\pi} \checkmark$

$\int_0^{\pi} \sin x dx - [\pi \cos \pi - 0] \checkmark$

$\int_0^{\pi} \sin x dx - [-\pi] = \pi$

(b)  $x^2 - x - 2 = (x-2)(x+1)$

Let  $\frac{3}{x^2 - x - 2} = \frac{A}{x-2} + \frac{B}{x+1}$

then:  $3 = A(x+1) + B(x-2)$

for  $x=2 \rightarrow 3 = 3A + 0 \rightarrow A=1 \checkmark$

for  $x=-1 \rightarrow 3 = 0 - 3B \rightarrow B=-1 \checkmark$

$\int \frac{3}{x^2 - x - 2} dx = \int \frac{dx}{x-2} - \int \frac{dx}{x+1}$

$\int \ln|x-2| - \ln|x+1| + C \checkmark$

$\int \ln\left|\frac{x-2}{x+1}\right| + C$

15. (a)  $\frac{dQ}{dt} = k(100-Q) = -k(Q-100)$

$\therefore \int \frac{dQ}{Q-100} = -\int k dt$

$\ln|Q-100| = -kt + C \checkmark$

$$Q - 100 = e^{-kt+C} = e^C \times e^{-kt} = A e^{-kt}$$

✓

$$\therefore Q(t) = A e^{-kt} + 100$$

15. (b)  $Q(0) = A + 100 = 900 \rightarrow A = 800$  ✓

$2.5 \text{ hrs} = 150 \text{ min}$

$\therefore Q(150) = 800e^{-150k} + 100 = 450$

$\rightarrow e^{-150k} = \frac{350}{800} \rightarrow k = \frac{\ln\left(\frac{7}{16}\right)}{-150} \approx 0.0055$  ✓

$\therefore Q(t) = 800e^{-0.0055t} + 100$

Since exponential decay never crosses the x-axis, we must choose the first value that would round to zero.

i.e.  $Q(t) = 100.49$  (other values less than 100.5 are acceptable)

$Q(t) = 800e^{-0.0055t} + 100 = 100.49$  ✓

$e^{-0.0055t} = \frac{0.49}{800} \rightarrow t = \frac{\ln\left(\frac{0.49}{800}\right)}{-0.0055} \approx 1345.08 \approx 1345 \text{ min}$  ✓

16. (a)  $\frac{dB}{dt} = rB(k - B)$  from formula sheet ✓

(b)  $B(t) = \frac{5000}{1 + Ae^{-kt}}$  from formula sheet, with 5000 as limit ✓✓

$\therefore B(15) = \frac{5000}{1 + Ae^{-15k}} = 2278$  and  $B(25) = \frac{5000}{1 + Ae^{-25k}} = 4304$

solving simultaneously: CAS  $\rightarrow A = 24, k = 0.2$  ✓✓

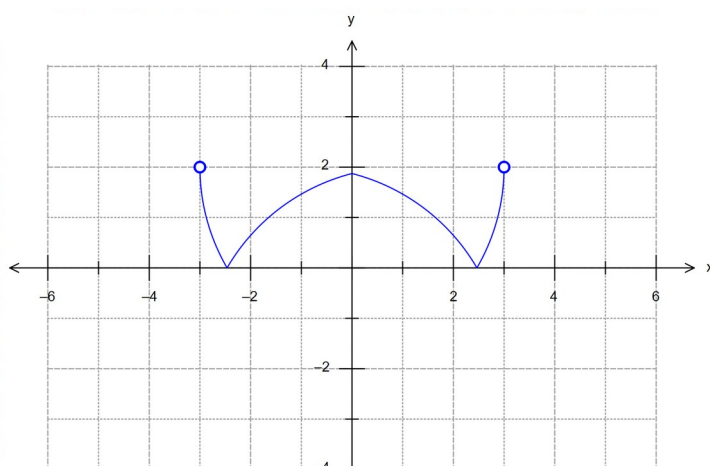
$\therefore B(t) = \frac{5000}{1 + 24e^{-0.2t}}$

(c) Since the line  $y = 5000$  is the upper asymptote, it will never actually reach 5000. Therefore we must choose the first value that would round to 5000:

$B(t) = \frac{5000}{1 + 24e^{-0.2t}} = 4999.5$  ✓

CAS  $\rightarrow t = 61.94 \text{ hrs} = 61:56 \text{ hrs}$  ✓

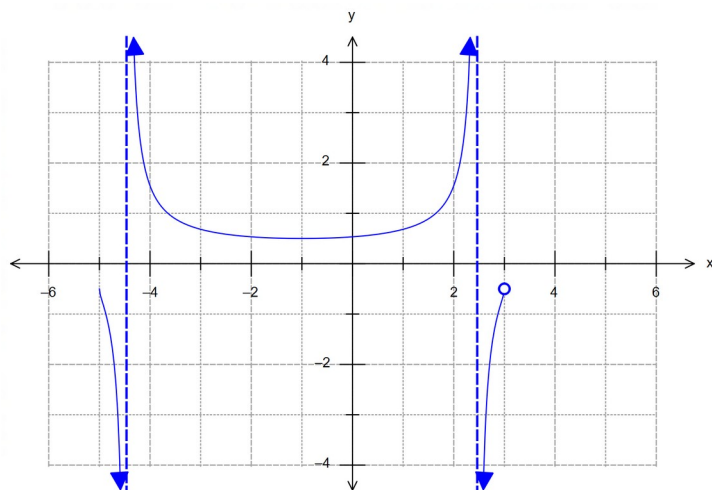
17. (a) (i)



✓ reflection over x axis

✓ reflection over y axis

17. (a) (ii)



- ✓ vertical asymptotes at the roots of the circle
- ✓ crosses the original function at points  $y = \pm 1$
- ✓ behaviour on either side of the asymptotes

$$(b) \quad (i) \quad h \circ f(x) = h(f) = \frac{1}{(4-f)^2} = \frac{1}{(4-4+4\sqrt{x-1})^2} = \frac{1}{16(x-1)} \quad \checkmark$$

$$(ii) \quad \text{For } h(x): \quad (4-x)^2 \neq 0$$

$$\therefore (4-f)^2 \neq 0 \quad \checkmark$$

$$4-f \neq 0 \rightarrow \sqrt{x-1} \neq 0 \rightarrow x \neq 1$$

$$\text{Domain of } f(x) = \{x \in \mathbb{R} : x > 1\} \quad \checkmark$$

$$\text{Range of } h \circ f(x) = \{y \in \mathbb{R} : y > 0\} \quad \checkmark$$

[9]

$$18. \quad (a) \quad t = 2\pi \approx 6.28 \text{ seconds} \quad \checkmark$$

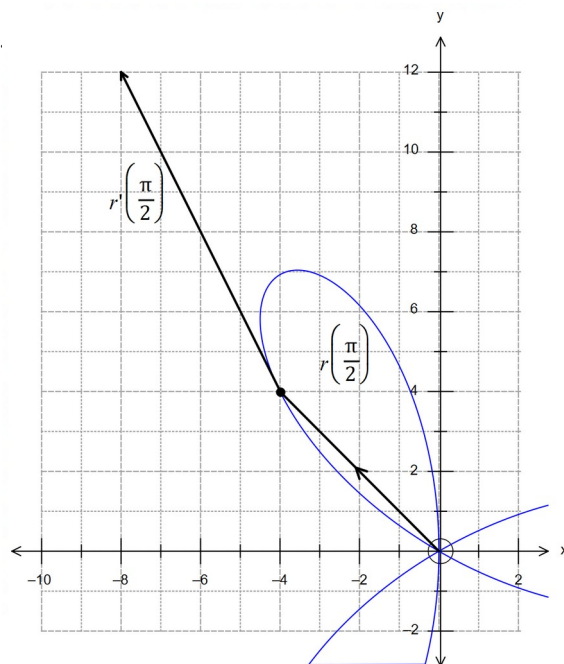
$$(b) \quad r\left(\frac{\pi}{2}\right) = 4 \begin{pmatrix} \cos\left(\frac{\pi}{2}\right) + \cos\pi \\ \sin\left(\frac{\pi}{2}\right) - \sin\pi \end{pmatrix} = 4 \begin{pmatrix} -1 \\ 1 \end{pmatrix} = -4i + 4j \text{ [m] from O} \quad \checkmark$$

$$\dot{r}(t) = 4 \begin{pmatrix} -\sin t - 2\sin(2t) \\ \cos t - 2\cos(2t) \end{pmatrix} \quad \checkmark$$

$$\dot{r}\left(\frac{\pi}{2}\right) = 4 \begin{pmatrix} -\sin\left(\frac{\pi}{2}\right) - 2\sin\pi \\ \cos\left(\frac{\pi}{2}\right) - 2\cos\pi \end{pmatrix} = 4 \begin{pmatrix} -1 \\ 2 \end{pmatrix} = -4i + 8j \text{ [m/s]} \quad \checkmark$$



18. (b) Continued.



- ✓ position vector  $(-4, 4)$  drawn from O.
- ✓ velocity vector  $(-4, 8)$  relative to  $(-4, 4)$  [i.e. drawn from  $(-4, 4)$ ]

$$(c) \quad |v|_{\max} = 4\sqrt{5+4 \times 1} = 12 \text{ m/s} \quad \checkmark$$

$$\text{for } \sin(3t) = 1 \rightarrow 3t = \frac{\pi}{2} \rightarrow t = \frac{\pi}{6} \quad \checkmark$$

$$r\left(\frac{\pi}{6}\right) = 4 \begin{pmatrix} \cos\left(\frac{\pi}{6}\right) + \cos\left(\frac{\pi}{3}\right) \\ \sin\left(\frac{\pi}{6}\right) - \sin\left(\frac{\pi}{3}\right) \end{pmatrix} = \begin{pmatrix} 2\sqrt{3} + 2 \\ 2 - 2\sqrt{3} \end{pmatrix} \approx \begin{pmatrix} 5.46 \\ -1.46 \end{pmatrix} \quad \checkmark \quad [9]$$

19. (a) the apparent “root” is in fact a discontinuity which

$$\text{occurs at } \tan\left(\frac{\pi}{2}\right) \rightarrow x + \frac{\pi}{6} = \frac{\pi}{2} \rightarrow x = \frac{\pi}{3} \quad \checkmark$$

$$\therefore \int_0^{\frac{\pi}{3}} \frac{1}{\tan\left(x + \frac{\pi}{6}\right)} dx = \int_0^{\frac{\pi}{3}} \frac{\cos\left(x + \frac{\pi}{6}\right)}{\sin\left(x + \frac{\pi}{6}\right)} dx$$

$$\therefore \left[ \ln \left| \sin \left( x + \frac{\pi}{6} \right) \right| \right]_0^{\frac{\pi}{3}} \quad \checkmark$$

$$\therefore \ln \left| \sin \left( \frac{\pi}{2} \right) \right| - \ln \left| \sin \left( \frac{\pi}{6} \right) \right|$$

$$\therefore \ln(1) - \ln\left(\frac{1}{2}\right) = \ln\left(\frac{1}{2}\right)^{-1} = \ln 2 \quad \checkmark$$

(b)

$$V = \pi \int_0^h \left( \frac{r}{h} x \right)^2 dx = \frac{\pi r^2}{h^2} \int_0^h x^2 dx$$

$$\frac{\pi r^2}{h^2} \left[ \frac{x^3}{3} \right]_0^h = \frac{\pi r^2}{h^2} \times \frac{h^3}{3} = \frac{\pi}{3} r^2 h$$

✓✓

[9]