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MATHEMATICS SPECIALIST UNIT 3

Semester One

2019

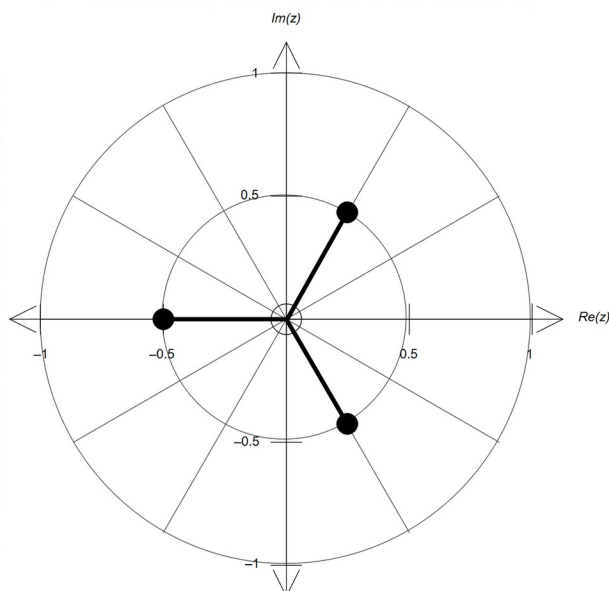
SOLUTIONS

Calculator-free Solutions

1. $w = iz - \bar{z} = i(x + yi) - (x - yi)$
 $i x - y - x + yi = -(x + y) + (x + y)i$ ✓✓
 $\therefore |w| = \sqrt{(x + y)^2 + (x + y)^2} = (x + y)\sqrt{2}$ units ✓
 and $\arg(w) = \tan^{-1}\left(\frac{-x + y}{x + y}\right) = \frac{3\pi}{4}$ only solution ✓ [4]

2. (a) (i) $f(-\sqrt{3}i) = 2(-\sqrt{3}i)^3 - (-\sqrt{3}i)^2 + 6(-\sqrt{3}i) - 3$
 $i 2(3\sqrt{3}i) - (-3) - 6\sqrt{3}i - 3 = 0 + 0i$ ✓✓
 (ii) $\bar{z} = \sqrt{3}i \rightarrow (z - \sqrt{3}i)$ is another factor ✓
 (iii) $2z^3 - 2z^2 + z - 3 = 0$
 $\therefore (z + \sqrt{3}i)(z - \sqrt{3}i)(az + b) = 0$ ✓
 Leading term: $az^3 = 2z^3 \rightarrow a = 2$ ✓
 Constant: $(\sqrt{3}i)(-\sqrt{3}i)(b) = 3b = -3 \rightarrow b = -1$ ✓
 $\therefore 2z - 1 = 0 \rightarrow z = \frac{1}{2}$ ✓
 Solutions $z = \pm\sqrt{3}i, \frac{1}{2}$

(b) $z^3 = -2^{-3} = 2^{-3} \text{cis}(\pi + 2k\pi) \quad k = 0, \pm 1$
 $\therefore z = 2^{-1} \text{cis}\left(\frac{\pi + 2k\pi}{3}\right) \quad k = 0, \pm 1$ ✓
 $k = 0 \rightarrow z = \frac{1}{2} \text{cis}\left(\frac{\pi}{3}\right) = \frac{1}{2}\left(\frac{1}{2} + \frac{\sqrt{3}}{2}i\right) = \frac{1}{4} + \frac{\sqrt{3}}{4}i$ ✓
 $k = 1 \rightarrow z = \frac{1}{2} \text{cis}(\pi) = -\frac{1}{2}$ ✓
 $k = -1 \rightarrow z = \frac{1}{2} \text{cis}\left(\frac{-\pi}{3}\right) = \frac{1}{2}\left(\frac{1}{2} - \frac{\sqrt{3}}{2}i\right) = \frac{1}{4} - \frac{\sqrt{3}}{4}i$ ✓



- ✓ magnitude = 0.5
- ✓ $\frac{2\pi}{3}$ radians apart

[13]

$$\begin{aligned}
 & x+y+z=1 \quad \dots \textcircled{1} \\
 3. \quad (a) \quad & 2x+2y+z=2 \quad \dots \textcircled{2} \\
 & x-2y-z=1 \quad \dots \textcircled{3}
 \end{aligned}$$

$$\textcircled{2} - \textcircled{1}: x+y=1 \dots \textcircled{4}$$

$$\textcircled{1} + \textcircled{3}: 2x-y=2 \dots \textcircled{5}$$

$$\textcircled{4} + \textcircled{5}: 3x=3 \rightarrow x=1 \quad \checkmark$$

$$x=1 \rightarrow \textcircled{4}: y=0 \quad \checkmark$$

$$x=1, y=0 \rightarrow \textcircled{1}: z=0 \quad \checkmark$$

(b) Entering equation into a matrix gives:

$$\begin{bmatrix} 1 & 1 & 1 & m \\ 2 & 2 & n & 2 \\ 1 & -2 & 1 & 1 \end{bmatrix}$$

Using row-reduction in one step gives:

$$\begin{bmatrix} 1 & 1 & 1 & m \\ 0 & 3 & 0 & (m-1) \\ 0 & 0 & (2-n) & (2m-2) \end{bmatrix}$$

From the last row: $2-n \neq 0 \rightarrow \therefore n \neq 2$ \checkmark

and $m \in R$. \checkmark

$$(c) \quad (i) \quad 2x-y+z=4 \rightarrow r \cdot \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} = 4$$

the normal to the plane is parallel to direction vector of the line,

$$\therefore \begin{pmatrix} a \\ b \\ c \end{pmatrix} = k \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} \quad k \in R \quad \checkmark$$

hence, accept values that are multiples of k as follows:

$$a=2k, b=-k, c=k \quad k \in R \quad \checkmark$$

$$(ii) \quad \text{Using } k=1, \text{ the line becomes } r = \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix} + \lambda \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}$$

$$\therefore \begin{pmatrix} 2+2\lambda \\ -2-\lambda \\ 1+\lambda \end{pmatrix} \cdot \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} = 4 \quad \checkmark$$

$$\rightarrow 7+6\lambda=4 \rightarrow \lambda = \frac{-1}{2} \quad \checkmark$$

$$\therefore r = \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -\frac{3}{2} \\ \frac{1}{2} \end{pmatrix}$$

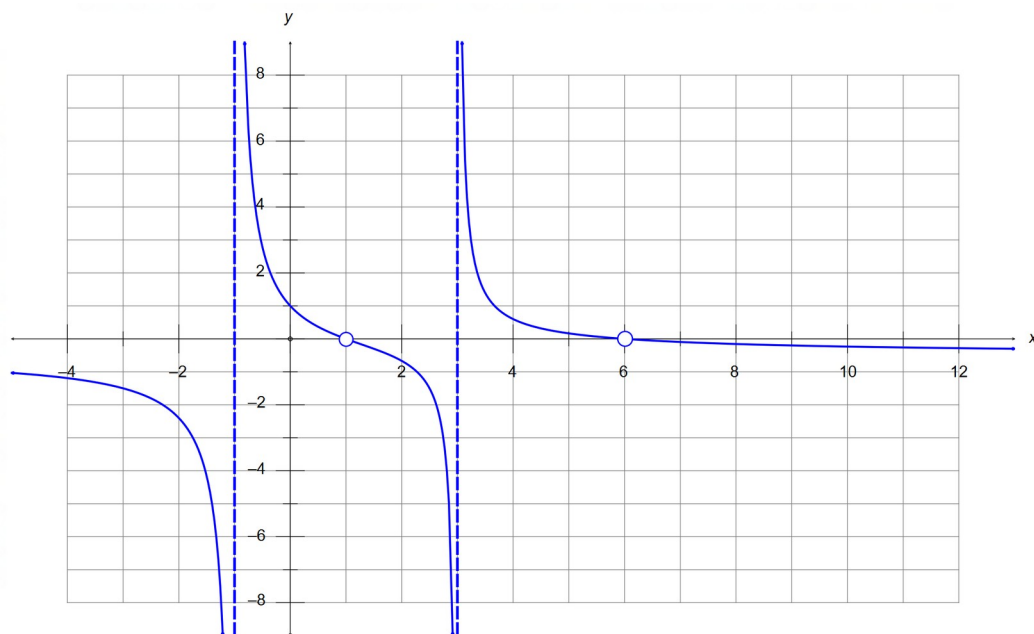
Coordinates of POI are $\left(1, -\frac{3}{2}, \frac{1}{2}\right)$

✓

[11]

4. (a) Roots: $a=1, b=-3$ or $a=-3, b=1$ ✓✓
 Poles: $c=-1, d=-6$ or $c=-6, d=-1$ ✓✓
 y-intercept: $f(0) = \frac{k(1)(-3)}{(-1)(-6)} = \frac{-k}{2} = 1 \rightarrow k = -2$ ✓

(b)



- (c) $x = \pm 3$ from symmetry over the y-axis ✓ [11]

5. (a) From the graphs:
 $f(x) = 0$ for $x = \pm 2$, hence need $g(x) = \pm 2$ ✓
 but $0 < g(x) < 3 \rightarrow g(x) = 2$ only
 and $g(x) = 2$ for $x = -1$, and hence $k = -1$ ✓
- (b) $f(x) = 4 - x^2$ and $g(x) = \sqrt{x+5}$ ✓
 $gf(x) = g(f) = \sqrt{f+5} = \sqrt{9-x^2}$ ✓
- (c) Need $f(x) \neq -5$ and $f(x) \neq 4$ ✓
 Hence, $x \neq 3$ and $x \neq 0$
 \therefore Domain $\{ -3 < x < 3 \wedge x \neq 0 \}$ ✓✓
 Range stays the same $\{ 0 < y < 3 \}$ ✓ [8]

6. (a) Centre is midpoint between P and $Q = \begin{pmatrix} 5 \\ 0 \\ 1 \end{pmatrix}$ ✓

Radius $\frac{1}{2}|PQ| = \frac{1}{2} \begin{vmatrix} 4 \\ 2 \\ -2 \end{vmatrix} = \begin{vmatrix} 2 \\ 1 \\ -1 \end{vmatrix} = \sqrt{6}$ ✓

$\therefore \left| r - \begin{pmatrix} 5 \\ 0 \\ 1 \end{pmatrix} \right| = \sqrt{6}$ ✓

(b) \overrightarrow{PQ} is normal to the plane, hence $n = \overrightarrow{PQ} = \begin{pmatrix} 4 \\ 2 \\ -2 \end{pmatrix}$ ✓

$n \cdot PQ = \begin{pmatrix} 4 \\ 2 \\ -2 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ -1 \\ 2 \end{pmatrix} = 12 - 2 - 4 = 6$ ✓

$\therefore r \cdot \begin{pmatrix} 4 \\ 2 \\ -2 \end{pmatrix} = 6 \rightarrow 2x + y - z = 3$ (simplified) ✓

[6]

Calculator-Assumed Solutions

7. Let $z = a + bi$ with $\sqrt{a^2 + b^2} = 4$

$$|z + 2i|^2 + |z - 2i|^2$$

$$\checkmark \sqrt{a^2 + (b+2)^2} + \sqrt{a^2 + (b-2)^2} \quad \checkmark$$

$$\checkmark (a^2 + b^2 + 4b + 4) + (a^2 + b^2 - 4b + 4) \quad \checkmark$$

$$\checkmark 2(a^2 + b^2) + 8 \quad \checkmark$$

$$\checkmark 2 \times 4^2 + 8 = 40 \quad \checkmark \quad [4]$$

8. (a) (i) $\vec{OA} + 3\vec{OC} \checkmark \begin{pmatrix} 5+3x \\ y+9 \\ -1 \end{pmatrix}$

since the z-coordinate is already of magnitude 1, then the x and y coordinates must be zero. Hence,

$$x = -\frac{5}{3} \quad \text{and} \quad y = -9 \quad \checkmark \checkmark$$

(ii) $\frac{3}{2}\vec{AB} = \vec{BC} \quad \checkmark$

$$\therefore 3(\vec{OB} - \vec{OA}) = 2(\vec{OC} - \vec{OB})$$

$$3\vec{OB} - 3\vec{OA} = 2\vec{OC} - 2\vec{OB}$$

$$5\vec{OB} = 3\vec{OA} + 2\vec{OC}$$

$$5 \begin{pmatrix} 9 \\ 0 \\ -2 \end{pmatrix} = 3 \begin{pmatrix} 5 \\ y \\ -4 \end{pmatrix} + 2 \begin{pmatrix} x \\ 3 \\ 1 \end{pmatrix} \quad \checkmark$$

$$\begin{pmatrix} 45 \\ 0 \\ -10 \end{pmatrix} = \begin{pmatrix} 15 + 2x \\ 3y + 6 \\ -10 \end{pmatrix}$$

$$\therefore x = 15 \quad \text{and} \quad y = -2 \quad \checkmark \checkmark$$

(b) $|\vec{AB}| = \begin{vmatrix} 0 \\ 6 \\ 0 \end{vmatrix} = 6 \quad \checkmark$

$$|\vec{AC}| = \begin{vmatrix} -4 \\ 3 \\ \alpha - 1 \end{vmatrix} \quad \text{and} \quad |\vec{BC}| = \begin{vmatrix} -4 \\ -3 \\ \alpha - 1 \end{vmatrix} \quad \checkmark$$

If $\triangle ABC$ equilateral, then $|\vec{AB}| = |\vec{AC}| = |\vec{BC}| = 6$

$$\therefore \begin{vmatrix} -4 \\ 3 \\ \alpha - 1 \end{vmatrix} = \begin{vmatrix} -4 \\ -3 \\ \alpha - 1 \end{vmatrix} = 6$$

$$4^2 + 3^2 + (\alpha - 1)^2 = 6^2$$

✓

$$(\alpha - 1)^2 = 11 \rightarrow \therefore \alpha = 1 \pm \sqrt{11}$$

✓

[10]

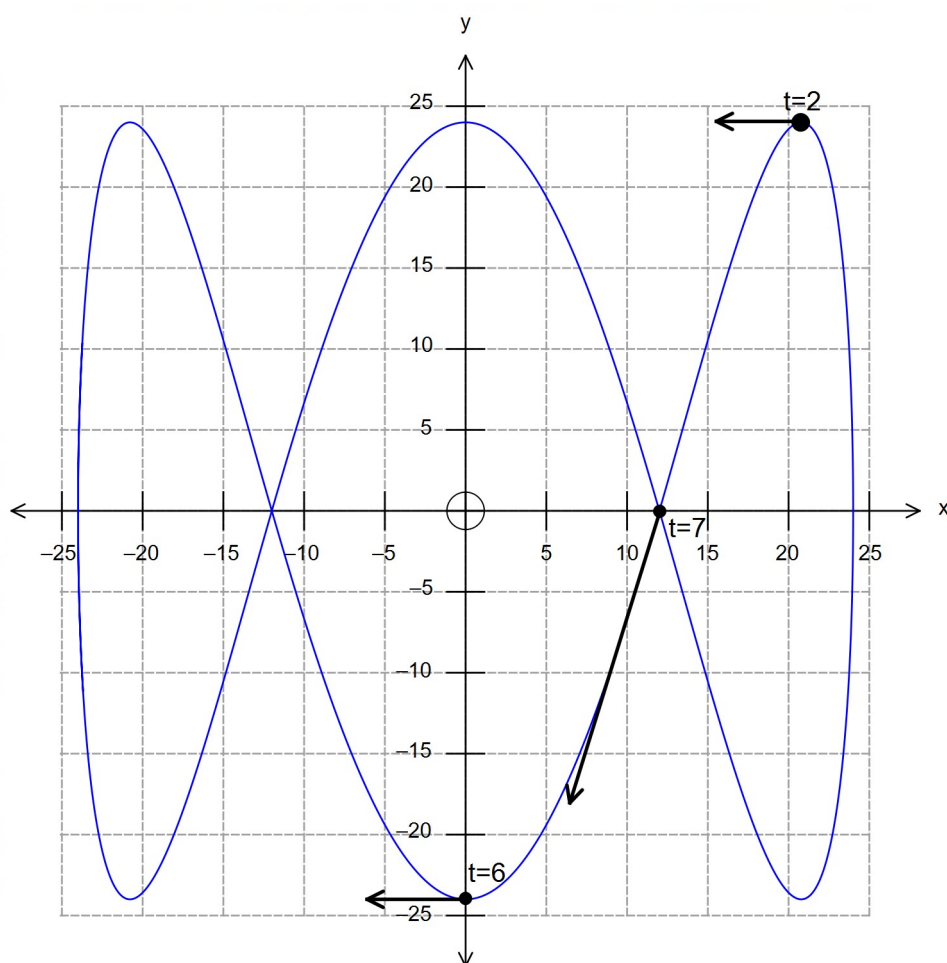
10. (a) $v = -2\pi \sin\left(\frac{\pi t}{12}\right)i + 6\pi \cos\left(\frac{\pi t}{4}\right)j$ ✓✓

(b) $r(2) = 24 \cos\left(\frac{\pi}{6}\right)i + 24 \sin\left(\frac{\pi}{2}\right)j$
 $\hookrightarrow 12\sqrt{3}i + 24j \approx \langle 20.78, 24 \rangle \text{ cm}$ ✓

$v(2) = -2\pi \sin\left(\frac{\pi}{6}\right)i + 6\pi \cos\left(\frac{\pi}{2}\right)j$
 $\hookrightarrow -\pi i + 0j = \langle -\pi, 0 \rangle \text{ cm/s}$ ✓

$r(6) = 24 \cos\left(\frac{\pi}{2}\right)i + 24 \sin\left(\frac{3\pi}{2}\right)j$
 $\hookrightarrow 0i - 24j = \langle 0, -24 \rangle \text{ cm}$ ✓

$v(6) = -2\pi \sin\left(\frac{\pi}{2}\right)i + 6\pi \cos\left(\frac{3\pi}{2}\right)j$
 $\hookrightarrow -2\pi i + 0j = \langle -2\pi, 0 \rangle \text{ cm/s}$ ✓



(c) $\omega_{\min} = \frac{\pi}{12} \rightarrow T_{\max} = \frac{2\pi}{\omega_{\min}} = \frac{2\pi}{\pi/12} = 24 \text{ sec}$ ✓

$$(d) \quad a = \frac{-\pi^2}{6} \cos\left(\frac{\pi t}{12}\right) i - \frac{3\pi^2}{2} \sin\left(\frac{\pi t}{4}\right) j \quad \checkmark$$

$$\therefore a(8) = \frac{-\pi^2}{6} \cos\left(\frac{8\pi}{12}\right) i - \frac{3\pi^2}{2} \sin\left(\frac{8\pi}{4}\right) j = \frac{-\pi^2}{12} i \quad \checkmark$$

$$\therefore |v| = 2\pi \sqrt{\sin^2\left(\frac{\pi t}{12}\right) + 9\cos^2\left(\frac{\pi t}{4}\right)}$$

✓✓

✓✓

✓

[17]

✓✓

✓✓

✓✓

✓✓

[8]

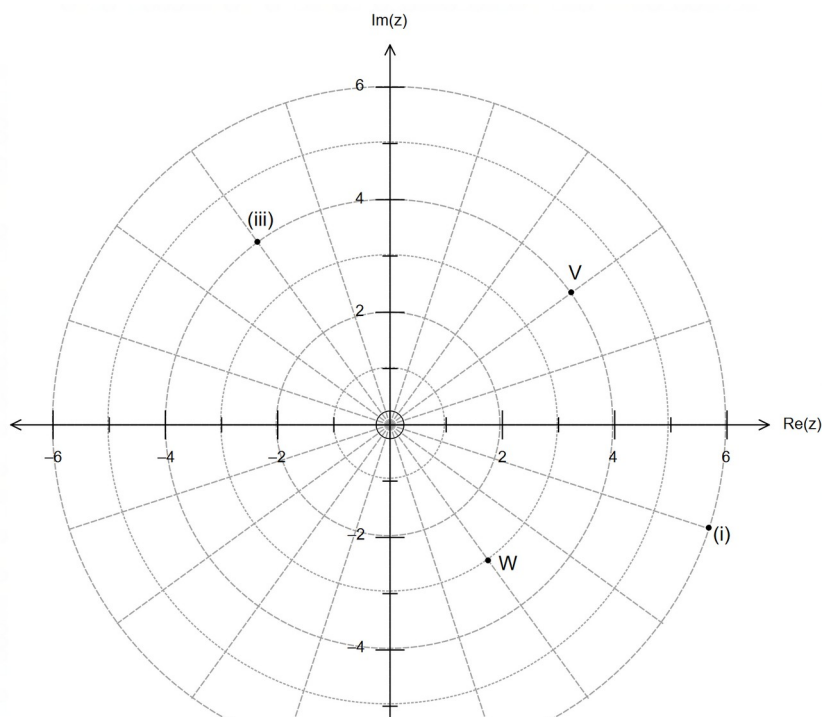
$$(i) \quad \frac{1}{2} \mathbf{v} \times \mathbf{w} = \frac{1}{2} \times 12 \operatorname{cis}\left(\frac{\pi}{5} - \frac{3\pi}{10}\right) = 6 \operatorname{cis}\left(\frac{-\pi}{10}\right)$$

✓✓

$$\textcolor{red}{\mathfrak{I}}6\text{cis}\left(\frac{-\pi}{2}\right)$$

✓✓

✓✓



12. (b) (i) $|z|_{max}$ and $|z|_{min}$ occur along the line connecting the centre of the circle with the origin.

$$\begin{vmatrix} 2 \\ 1 \end{vmatrix} = \sqrt{5}$$

$$\therefore |z|_{max} = 4 + \sqrt{5} \text{ and } |z|_{min} = 4 - \sqrt{5} \quad \checkmark \checkmark$$

(ii) $(x-2)^2 + (y-1)^2 = 16$ and $\Re(z) = x = 4$

$$\therefore 4 + (y-1)^2 = 16 \rightarrow y = 1 \pm \sqrt{12} \quad \checkmark \checkmark$$

$$\therefore \arg(z) = \tan^{-1}\left(\frac{1 \pm \sqrt{12}}{4}\right) = 0.8402^R \vee -0.5521^R \quad \checkmark \checkmark \quad [12]$$

13. (a) Speed $\checkmark \begin{vmatrix} 25 \\ -12 \\ 2 \end{vmatrix} = \sqrt{773} \approx 27.80 \text{ m/s} \quad \checkmark$

$$\begin{pmatrix} 25 \\ -12 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} 25 \\ -12 \\ 0 \end{pmatrix} = \begin{vmatrix} 25 \\ -12 \\ 2 \end{vmatrix} \times \begin{vmatrix} 25 \\ -12 \\ 0 \end{vmatrix} \times \cos \theta \quad \checkmark$$

$$\therefore \cos \theta = \frac{769}{\sqrt{769 \times 773}} \rightarrow \theta = 4.13^\circ \quad \checkmark$$

(b) $15 \text{ min } \checkmark 900 \text{ s}$

$$\vec{OB}(900) = 900 \begin{pmatrix} 25 \\ -12 \\ 2 \end{pmatrix} = \begin{pmatrix} 22500 \\ -10800 \\ 1800 \end{pmatrix} \quad \checkmark$$

$$\vec{RB} = \vec{OB} - \checkmark = \begin{pmatrix} 22500 \\ -10800 \\ 1800 \end{pmatrix} - \begin{pmatrix} 6400 \\ -12500 \\ 300 \end{pmatrix} = \begin{pmatrix} 16100 \\ 1700 \\ 1500 \end{pmatrix} \quad \checkmark$$

$$\text{Distance } \checkmark \begin{vmatrix} 16100 \\ 1700 \\ 1500 \end{vmatrix} = 100 \begin{vmatrix} 161 \\ 17 \\ 15 \end{vmatrix} = 100 \sqrt{26435} \approx 16258.84 \text{ m} \quad \checkmark$$

(c) $\vec{OB}(960) = 960 \begin{pmatrix} 25 \\ -12 \\ 2 \end{pmatrix} = \begin{pmatrix} 24000 \\ -11520 \\ 1920 \end{pmatrix} \quad \checkmark$

$$\checkmark (960) = \begin{pmatrix} 6400 \\ -12500 \\ 300 \end{pmatrix} + 960 \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 24000 \\ -11500 \\ 1920 \end{pmatrix} \quad \checkmark$$

$$\therefore \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \frac{1}{60} \begin{pmatrix} 24000 - 6400 \\ -11520 + 12500 \\ 1920 - 300 \end{pmatrix} = \begin{pmatrix} 293.\bar{3} \\ 16.\bar{3} \\ 27 \end{pmatrix} \text{ m/s} \quad \checkmark$$

at 1,920 m above level ground.

✓

(d) distance $\left| \begin{array}{c} 24000 \\ -11520 \\ 1920 \end{array} \right| \approx 26\,690.76\text{ m}, \therefore v = \frac{26690.76}{343} = 77.82\text{ s}$ ✓✓ [12]

14. (a) $\frac{1}{z} = \frac{1}{\cos \theta + i \sin \theta} \times \frac{\cos \theta - i \sin \theta}{\cos \theta - i \sin \theta} = \frac{\cos \theta - i \sin \theta}{\cos^2 \theta + \sin^2 \theta} = \cos \theta - i \sin \theta \quad \checkmark \checkmark$

(b) $z^n + z^{-n} = 2 \cos(n\theta) \rightarrow \cos(n\theta) = \frac{z^n + z^{-n}}{2} \quad \checkmark$

$z^n - z^{-n} = 2i \sin(n\theta) \rightarrow \sin(n\theta) = \frac{z^n - z^{-n}}{2i} \quad \checkmark$

(c) $\cos(2\theta) = \frac{z^2 + z^{-2}}{2} \quad \text{and} \quad \sin(4\theta) = \frac{z^4 - z^{-4}}{2i} \quad \checkmark \checkmark$

(d) $\cos(2\theta) \times \sin(4\theta) = \left(\frac{z^2 + z^{-2}}{2} \right) \times \left(\frac{z^4 - z^{-4}}{2i} \right)$

$\quad \quad \quad i \frac{1}{4i} (z^6 - z^{-2} + z^2 - z^{-6}) \quad \checkmark$

$\quad \quad \quad i \frac{1}{2} \left(\frac{z^6 - z^{-6}}{2i} \right) + \frac{1}{2} \left(\frac{z^2 - z^{-2}}{2i} \right) \quad \checkmark$

$\quad \quad \quad i \frac{1}{2} \sin(6\theta) + \frac{1}{2} \sin(2\theta) \quad \checkmark$

[9]

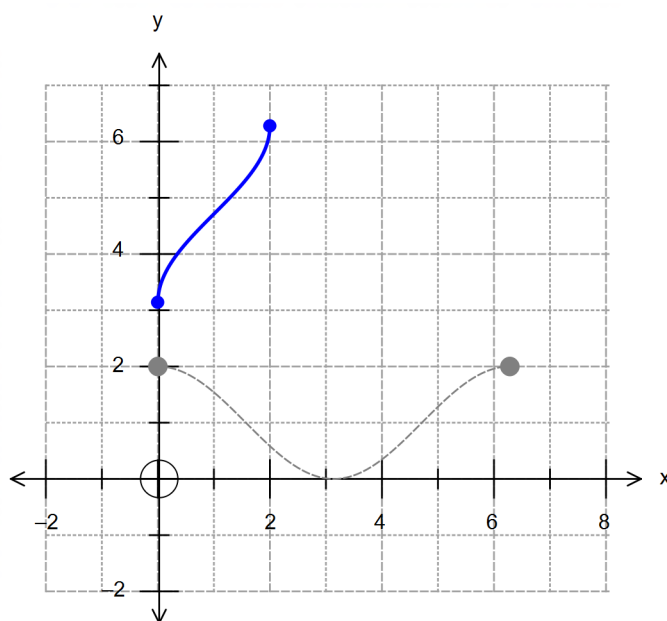
15. (a) $f^{-1}(x)$ does not exist because $f(x)$ is not a one-to-one function. \checkmark

(b) (i) Need $\pi \leq x \leq 2\pi$, hence $k = \pi \quad \checkmark$

Then, $f^{-1}(x) = \pi + \cos^{-1}(1-x) \quad \checkmark \checkmark$

(ii) Domain $i[0 \leq x \leq 2]$ and Range $i[\pi \leq y \leq 2\pi] \quad \checkmark \checkmark$

(c)



\checkmark sinusoidal and
symmetrical over the line
 $y=x$

\checkmark correct location and
boundaries (accuracy)

(d) $gf(f^{-1}) = g(x)$

$$\therefore g(x) = gf(f^{-1}) = f^{-1} + 1 = \pi + \cos^{-1}(x-1) + 1$$

✓✓

[10]

$$16. \quad x = \cos(2\theta) = \cos^2\theta - \sin^2\theta = 2\cos^2\theta - 1 \quad \checkmark$$

$$\therefore \cos^2\theta = \frac{x+1}{2} \quad \checkmark$$

Similarly,

$$x = \cos(2\theta) = \cos^2\theta - \sin^2\theta = 1 - 2\sin^2\theta$$

$$\therefore \sin^2\theta = \frac{1-x}{2} \quad \checkmark$$

and $y = \tan\theta$, and for domain to remain the same:

$$y^2 = \tan^2\theta = \frac{\sin^2\theta}{\cos^2\theta} = \frac{1-x}{2} \div \frac{x+1}{2} \quad \checkmark$$

$$\text{Hence, } y^2 = \frac{1-x}{x+1} \quad \checkmark$$

[5]

(Other methods are possible depending on their choice of trigonometric identity. Award marks accordingly).