

## Splay trees outline

- Splay tree concept
- Splaying operation: double-rotations
- Splay insertion
- Splay search
- Splay deletion
- Running time of splay tree operations

## Splay trees

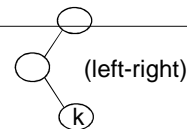
- A splay tree is a balanced BST built using an **amortization** approach –
  - that is, do more work after every insertion or search to save subsequent search time.
- “More work”:
  - What: Bring the accessed (i.e., inserted or searched) node **to the root**.
  - Why: It pays off if the accessed node is accessed again soon.
  - How: **Double-rotate** – called “**splaying**.”

## Splaying operation

- **Splay(k)**: move a node k to the root through **double** rotation operations.
  - Single rotation is not used in the splay tree.
- As a result, halve the depth of most nodes (excluding the root) encountered on the path from the root to the accessed node.
- Splaying *tends to* -- not always -- keep the splay tree more balanced than the BST.

## Splay double-rotations

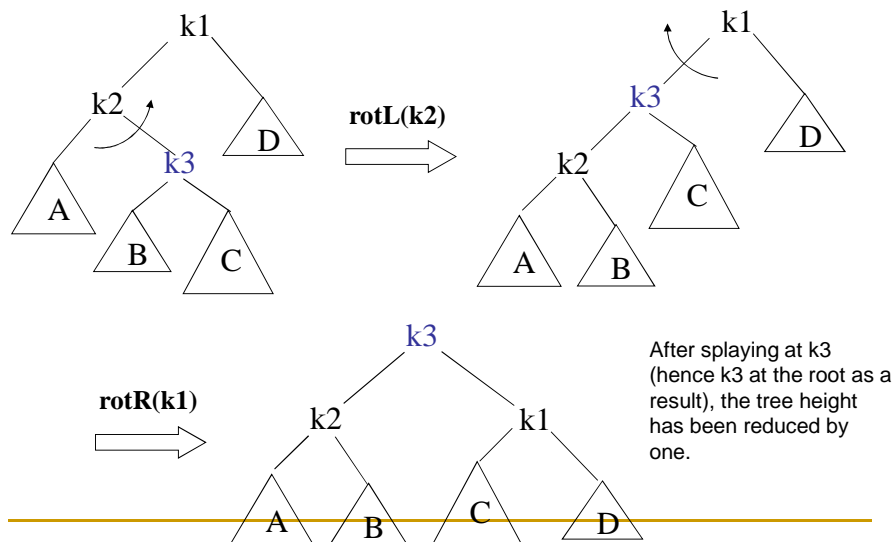
- Two cases for splay(k):
  - Zig-zag: left-right or right-left
    - The order of rotations is **bottom-up**.
    - It reduces the tree height by one.
    - This case is the same as the AVL tree.
  - Zig-zig: left-left or right-right
    - The order of rotations is **top-down**.
    - It tends to reduce the distances to most nodes encountered (except the root) to about half.
    - This case is different from the AVL tree, and brings the positive effect of splaying.



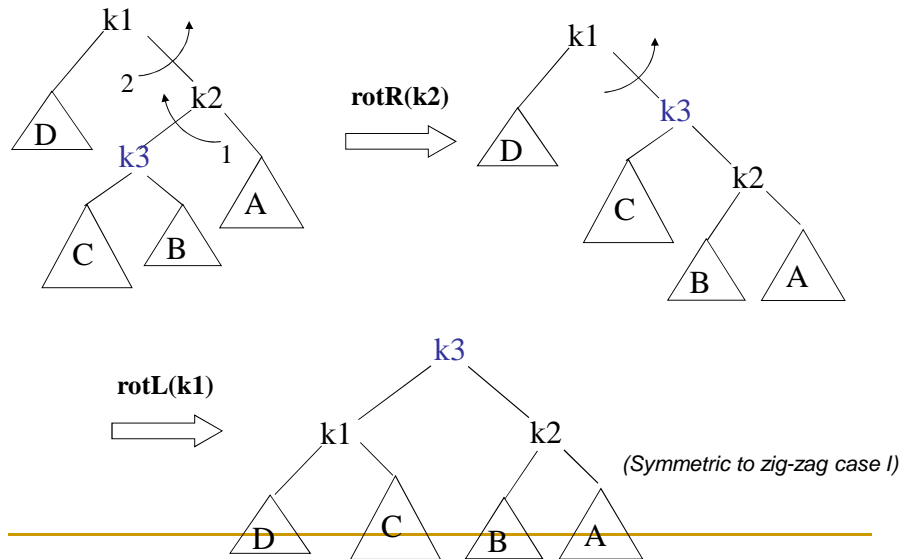
## Summary: rotations in AVL and splay

Tree type Case	AVL tree	Splay tree
zig-zig	single rotation	top-down double rotation
zig-zag	bottom-up double rotation	bottom-up double rotation

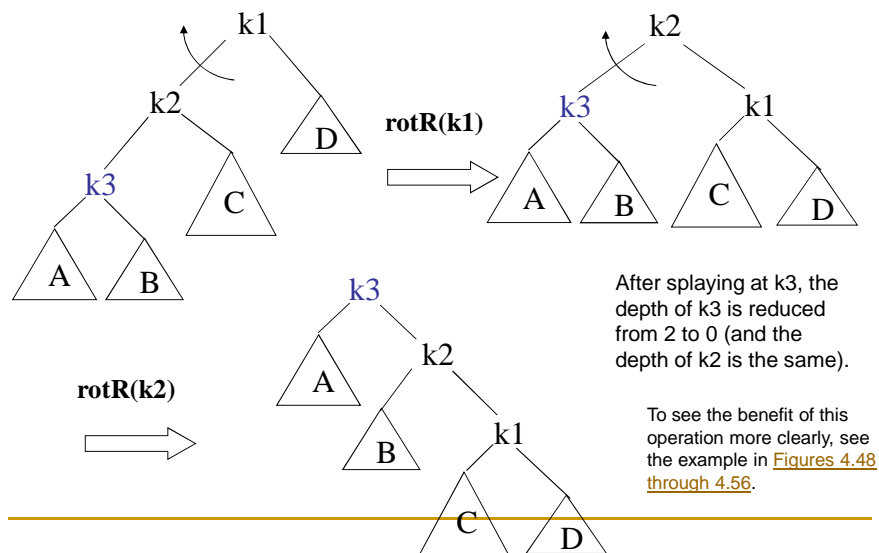
### Splay(k3): zig-zag case I



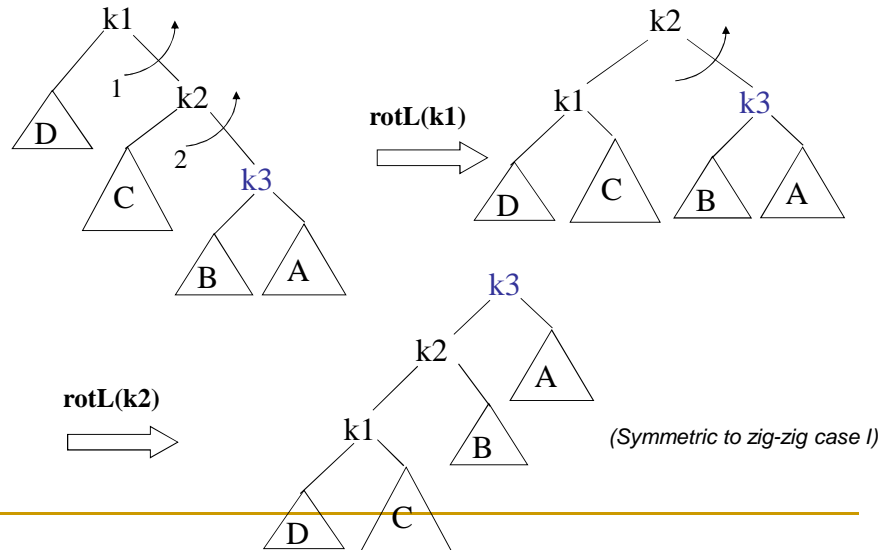
## Splay(k3): zig-zag case II



## Splay(k3): zig-zig case I

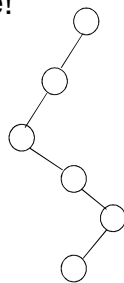


## Splay(k3): zig-zig case II



## What if the access path length is an odd number?

- One rotation must be a single rotation.
- Do it either at the bottom or at the top.
  - The resulting tree structures may be different. Both are fine!



Let's do it at the bottom in this class.

## Splay insertion algorithm

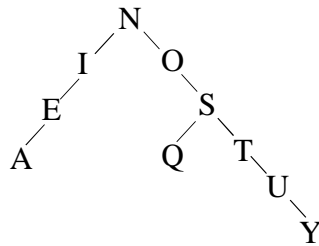
```
insert(node) {  
  1. Insert the new node.  
  2. Let  $n$  be the length of the path traversed for the  
     insertion.  
     Then,  
     a. If  $n = 2m$  (i.e., even number)  
        then perform  $m$  double rotations.  
     b. If  $n = 2m+1$  (i.e., odd number)  
        then perform one single rotation followed by  
            $m$  double rotations.  
}
```

## Exercise: splay tree insertion

- Construct a splay tree by inserting B, Y, U, A, G in sequence.
- Q. *What if the node already exists?*
- A. *Splay from the existing node.*
- (See the [answer key](#).)

## Exercise: splay tree search

- Search the tree below with the following keys in sequence: E, A, S, Y, Q, U, T, I, O, and N.



See the [answer key](#).

- *Q. What if a node is not found?*
- *A. Splay from the last node visited.*

## Splay deletion: remove(node)

1. Splay-search the node. (That is, find the node and rotate it up to the root.)
2. Find the largest node in the left subtree of the root (or find the smallest node in the right subtree) and rotate it up to replace the root.

## Splay deletion: remove(node) – side note

- **Q.** What is the point of bringing the node to the root after finding it, only to remove it?
  - The rationale for splaying is that a node accessed now is likely to be accessed again soon.
  - But, in the case of remove(node), the node is removed (so never accessed again) after all the work done to splay it up to the root.
- **A.** Splaying tends to shorten the access path to every node encountered while finding the node.
  - Recall the demo of Figures 4.47 to 4.56 in the textbook and see how the depth of each node is reduced at each splaying, especially in the beginning with a bunch of zig-zig cases. Of course, this depth reduction does not happen all the time, but overall we see the trend.

## Top-down splay tree

- Bottom-up splay tree walks the access path twice – once for searching and once for splaying.
- Top-down splay tree does the splaying while walking down the access path.
  - Section 12.1



## Top-down splay tree -- side note

- The splay tree has been shown to be faster than the AVL tree in benchmark experiments performed using "real" applications.
  - All balanced BSTs we are studying are main-memory data structures and, thus, the run-time is very sensitive to the code implementation. Splay tree operations can be coded more efficiently (I mean, the top-down splay tree) than the AVL tree operations. This could be one reason for the benchmark results being in favor of the splay tree.

## Running time of splay tree operations

- A single operation:  $O(\log N)$  average,  $O(N)$  worst. But, the worst case occurs less frequently than the BST.
- Searching for  $M$  nodes:  $O(M \cdot \log N)$  for both average and worst.
- Inserting  $N$  nodes:  $O(N \cdot \log N)$  for both average and worst.
- So, the **amortized** running time of a single operation is  $O(\log N)$ .
- **Note.** Compare with the BST case, where searching for  $M$  nodes and inserting  $N$  nodes take  $O(M \cdot N)$  and  $O(N^2)$ , respectively.

## Running time of splay tree operations (cont.)

- Analyzing the running time of splay operations involves **amortized algorithm analysis**. This analysis appears in Section 11.5, but is beyond our scope here.
- What's in Section 11.5?
  - Consider the *potential function*  $\Phi$  of a splay tree  $T$  as:  $\Phi(T) = \sum_{x \in T} R(x)$ , where the rank of a node  $x$ ,  $R(x)$ , is defined as  $\log S(x)$  where  $S(x)$  is the number of descendants of a node  $x$  (including  $x$  itself) in  $T$ . Then, the amortized running time to splay a tree at node  $x$  is at most  $3(R(T) - R(x)) + 1 = 3(\log N - R(x)) + 1 = O(\log N)$ , where  $R(T)$  is the rank of the root of  $T$ .
    - Proof of this claim appears in page 533.