

1. [Properties of LU factorization, 1+2pt] We study basic properties of the LU-factorization.

- (a) Give an example of an invertible 3×3 matrix that does not have any zero entries, for which the LU decomposition without pivoting fails.

(a) Example:

Let $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 5 \\ 1 & 3 & 4 \end{bmatrix}$ We claim A is a Matrix desired.

Suppose

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 5 \\ 1 & 3 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ l_{21} & 1 & 0 \\ l_{31} & l_{32} & 1 \end{bmatrix} \begin{bmatrix} U_{11} & U_{12} & U_{13} \\ 0 & U_{22} & U_{23} \\ 0 & 0 & U_{33} \end{bmatrix}$$

Process the Computation.

$$U_{11}=1$$

$$U_{11} \cdot l_{21} = 2 \Rightarrow l_{21} = 2$$

$$U_{11} \cdot l_{31} = 1 \Rightarrow l_{31} = 1$$

$$U_{12}=2$$

$$l_{21} \cdot U_{12} + U_{22} = 4 \Rightarrow U_{22} = 0 \quad \text{which cause a problem}$$

$$U_{13}=3$$

$$U_{13} \cdot l_{21} + U_{23} = 4$$

$$\Rightarrow U_{23} = -2$$

$$U_{12} \cdot l_{31} + U_{22} \cdot l_{31} = 3$$

$$2 + 0 = 3 \quad \text{which is not possible}$$

Therefore, A is not LU decomposible.

(b) Show that the LU factorization of an invertible matrix $A \in \mathbb{R}^{n \times n}$ is unique. That is, if

$$A = LU = L_1 U_1$$

with upper triangular matrices U, U_1 and unit lower triangular matrices L, L_1 , then necessarily $L = L_1$ and $U = U_1$. You can use the results we discussed in class about products of lower/upper triangular matrices, and their inverses.

proof.

If $LU = L_1 U_1$, As A is invertible, which induce L, U, L_1, U_1 invertible.

$$\text{then } L_1^{-1} L = U_1 \cdot U^{-1}$$

$$\begin{aligned} & (\text{as otherwise } \det(A) = \det(L) \det(U) \\ & = \det(L_1) \det(U_1) \\ & \text{would be } 0) \end{aligned}$$

$$\text{We claim } L_1^{-1} L = U_1 U^{-1} = I$$

As: \circ L_1^{-1} is a unit lower matrix as it is an inverse of L_1 ,
which is a lower unit matrix.

\circ $L_1^{-1} \cdot L$ is a unit lower matrix as it is a product of 2
lower unit matrix.

Similarly. $U_1 U^{-1}$ is upper triangle as U^{-1} is upper as U is,
and then the property of product makes $U_1 U^{-1}$ upper triangle.

However, as $L_1^{-1} \cdot L = U_1 U^{-1}$, where LHS is lower Δ and RHS is Upper Δ
 $L_1^{-1} \cdot L = U_1 U^{-1}$ is diagonal. Further more, as $L_1^{-1} \cdot L$ is unit.
we have $L_1^{-1} \cdot L = U_1 U^{-1} = I$

$$\text{As } L_1^{-1} \cdot L = I = U_1 U^{-1}$$

We have $L_1 = L$ and $U_1 = U$, where uniqueness follows.

2. [LU for transposed matrix, 2+2pt] Let $n \geq 2$. Consider a matrix $A \in \mathbb{R}^{n \times n}$ for which every leading principal submatrix of order less than n is non-singular.

- (a) Show that A can be factored in the form $A = LDU$, where $L \in \mathbb{R}^{n \times n}$ is unit lower triangular, $D \in \mathbb{R}^{n \times n}$ is diagonal and $U \in \mathbb{R}^{n \times n}$ is unit upper triangular.

Proof.

Given all leading principal submatrices of order $< n$ is invertible

We have $A = LU'$

Here U' is not necessarily unit, however, by the nature of factorization.
 $U'_{ij} \neq 0$ unless $j=n$

It suffices to show that U' admits a decomposition s.t. $U' = DU$
 where D diagonal, U unit upper.

We construct it in this way

Consider U^T , which is a Lower Triangle

Apply LU decomposition on U^T , as all leading ^{sub} matrix of A is invertible. only the last entry of U^T can be 0. \Rightarrow LU decompos. is possible.

$$U^T = L_2 U_2$$

$$\Rightarrow U = (L_2 U_2)^T = U_2^T \cdot L_2^T$$

Notice that L_2^T here is unit Upper triangle.

Here we prove that U_2^T is diagonal.

As L_2^T is unit, it is invertible.

$\Rightarrow U_2^T = U \cdot (L_2^T)^{-1}$ which is a product of 2 upper matrix

$\Rightarrow U_2^T$ is upper

but it is also lower as U_2 is upper.

$\Rightarrow U_2^T$ is diagonal.

Therefore, we see. $A = L' \cdot U_2^T \cdot L_2^T$

$$\begin{matrix} & \downarrow & \downarrow & \downarrow \\ \text{where.} & L & D & U \end{matrix}$$

- (b) If the factorization $A = LU$ is known, where L is unit lower triangular and U is upper triangular, show how to find the LU-factors of the transpose A^T . Note that our requirement for an LU-factorization is that L is unit lower triangular, and U is upper triangular.

proof.

As $A = LU$ is known.

Then we may use A to get

$$A = L D U'$$

$$\Rightarrow A^T = U'^T D L^T$$

$$\Rightarrow A^T = U^T (D L^T)$$

here U^T is lower unit triangle

and $D L^T$ is upper triangle.

3. [Cholesky factorization, 3+2pt]

- (a) A matrix A is called symmetric if $A = A^T$. If we compute $A = LDU$ for a symmetric matrix A , and find that each diagonal entry of $D > 0$, argue that A can be factored as $A = RR^T$ and find R in terms of L, D, U . Note that the factorization $A = RR^T$ can only be done for some types of symmetric matrices (specifically symmetric-positive-definite (spd) matrices), and is referred to as a Cholesky factorization.

proof.

First, we claim A is invertible. Indeed, as $A = LDU$

$$\det(A) = \det(L) \det(D) \det(U)$$

As L and U are both unit matrix. $\det(U) > 0$ $\det(L) > 0$.

Also, as D has diagonal entry > 0 . $\det(D) > 0$

$\Rightarrow \det(A) \neq 0$ i.e. A invertible.

As $A = LDU$,

$$A^T = U^T D^T L^T = U^T D L^T = LDU = A$$

Here We can write $A = L(DU)$
and $A = U^T(DL^T)$

Notice. L and U^T are lower unit Triangle.
 DU and DL^T are Upper Triangle.

Given the conclusion of Question 1. the LU decomposition of A invertible is unique.

We have: $\begin{cases} L = U^T \\ DL^T = DU \end{cases} \Rightarrow L = U^T$

(Note that as D invertible. the second equation
deduce $L = U^T$ as well)

Therefore,

$$A = L D L^T$$

As the entry of D is positive.

We can construct $E = \text{diag}(\sqrt{D_{ii}})$ s.t. $E^2 = D$

$$A = L E \cdot E L^T$$

Therefore. $A = (L E) \cdot (L E)^T$

$$\text{where } E = \text{diag}(\sqrt{D_{ii}})$$

(b) The algorithm to find the Cholesky factorization of an $n \times n$ matrix A is as follows:
for $j = 1, \dots, n$

$$\text{i. } r_{jj} = \sqrt{a_{jj} - \sum_{k=1}^{j-1} r_{jk}^2}$$

$$\text{ii. for } i > j: r_{ij} = \frac{1}{r_{jj}} \left(a_{ij} - \sum_{k=1}^{j-1} r_{ik} r_{jk} \right)$$

Use this to compute the Cholesky factorization of

$$A = \begin{bmatrix} 2 & 1 & 1/2 & 1/4 \\ 1 & 4 & 1 & 1/2 \\ 1/2 & 1 & 4 & 1 \\ 1/4 & 1/2 & 1 & 2 \end{bmatrix}.$$

To avoid computing the square root of a negative number (which happens for matrices that are not spd), check at each step that the quantity under the square root in the computation of r_{jj} is positive. If it is not, display an error message¹ and stop the code. Please hand in your commented code.

See Code page below

4. [Backward substitution implementation, 5pt] Write a code for backward substitution to solve systems of the form $Ux = b$, i.e., write a function $x = \text{backward}(A, b)$, which expects as inputs an upper triangular matrix $U \in \mathbb{R}^{n \times n}$, and a right hand side vector $b \in \mathbb{R}^n$, which returns the solution vector $x \in \mathbb{R}^n$. The function should find the size n from the vector b and also check if the matrix and the vector sizes are compatible before it starts to solve the system. [Please hand in your commented code](#). Apply your program for the computation of for $x \in \mathbb{R}^4$, with

$$U = \begin{bmatrix} 1 & 2 & 6 & -1 \\ 0 & 3 & 1 & 0 \\ 0 & 0 & 4 & -1 \\ 0 & 0 & 0 & 2 \end{bmatrix}, \quad b = \begin{bmatrix} -1 \\ -3 \\ -2 \\ 4 \end{bmatrix}.$$

See Code page below

HW_2_code

February 27, 2022

```
[1]: import numpy as np
```

0.1 Question 3b

```
[2]: def choleskyfact(A):
    """
    Input: A: n*n matrix, 2d array
    Output: R n*n matrix, 2d array
    """

    # Check if the input is valid

    if A.shape[0] != A.shape[1]:
        raise ValueError("Input should be square.")

    if not np.allclose(A, A.T):
        raise ValueError("Input should be symmetric.")

    # Initialize the output R matrix

    n = A.shape[0]
    R = np.zeros((n, n))

    # Implement the iteration accordingly as the given instruction

    for j in range(n):
        temp = A[j][j] - sum([(R[j][k])**2 for k in range(0, j)])
        if temp <= 0:
            raise ValueError("The quantity under the square root is negative")

        R[j][j] = temp**(1/2)

        for i in range(j+1, n):
            R[i][j] = (1/R[j][j])*(A[i][j] - sum([R[i][k]*R[j][k] for k in
                                         range(0, j)]))
```

```
    return R
```

[3]: # Apply the code to the matrix given

```
A = np.array([
    [2, 1, 1/2, 1/4],
    [1, 4, 1, 1/2],
    [1/2, 1, 4, 1],
    [1/4, 1/2, 1, 2]
])

print("The R solved by the self-defined function is: \n", choleskyfact(A))
print("\nCompared with the solution generated by numpy method: \n", np.linalg.
    ~cholesky(A))
```

The R solved by the self-defined function is:

```
[[1.41421356 0.          0.          0.        ]
 [0.70710678 1.87082869 0.          0.        ]
 [0.35355339 0.40089186 1.92724822 0.        ]
 [0.1767767  0.20044593 0.44474959 1.31558703]]
```

Compared with the solution generated by numpy method:

```
[[1.41421356 0.          0.          0.        ]
 [0.70710678 1.87082869 0.          0.        ]
 [0.35355339 0.40089186 1.92724822 0.        ]
 [0.1767767  0.20044593 0.44474959 1.31558703]]
```

0.2 Question 4

```
[4]: def backward(U, b):
    """
    Input: U, n*n upper matrix, 2Darray, b: n*1 array
    Output: x, n*1 array
    """
    b = b.squeeze() # in case input is an column vactor

    # Check if the input is valid

    if U.shape[0] != U.shape[1]:
        raise ValueError("U should be square.")

    if not np.allclose(U, np.triu(U)):
        raise ValueError("U should be upper triangular.")

    if b.shape[0] != U.shape[0]:
```

```

    raise ValueError("Input dimension not compatible.")

n = U.shape[0]

# Initialize the output array
x = np.zeros(n)

# Implement the iteration according to the instructions given
for i in range(1, n+1):
    x[-i] = (1 / U[-i][-i])*(b[-i] - sum([U[-i][-j]*x[-j] for j in range(1, -i)]))

return x

```

[5]: # Apply the program on the matrix given.

```

U = np.array([
    [1, 2, 6, -1],
    [0, 3, 1, 0],
    [0, 0, 4, -1],
    [0, 0, 0, 2],
])

b = np.array([-1, -3, -2, 4])

print("The result is: \n", backward(U, b))
print("\nCompare with the result from taking inverse: \n", np.linalg.inv(U)@b.T)

```

The result is:

[3. -1. 0. 2.]

Compare with the result from taking inverse:

[3. -1. 0. 2.]

5. [Right hand sides with many zeros, 4pt] For a given dimension n , fix some k with $1 \leq k \leq n$. Now let $L \in \mathbb{R}^{n \times n}$ be a non-singular lower triangular matrix and let the vector $b \in \mathbb{R}^n$ be such that $b_i = 0$ for $i = 1, 2, \dots, k$.

- (a) Let the vector $y \in \mathbb{R}^n$ be the solution of $Ly = b$. Show, by partitioning L into blocks, that $y_j = 0$ for $j = 1, 2, \dots, k$.
- (b) Use this to give an alternative proof of Theorem 2.1 (iv), i.e., that the inverse of a non-singular lower triangular matrix is itself lower triangular.

$$(a) Ly = b$$

Partition L and correspondingly y and b into the following way.

$$\begin{bmatrix} L_{(k \times k)} & 0_{(k \times (n-k))} \\ L_{(n-k \times k)} & L_{(n-k \times n-k)} \end{bmatrix} \begin{bmatrix} y_1 \\ \vdots \\ y_k \\ y_{k+1} \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} b_1 \\ \vdots \\ b_k \\ b_{k+1} \\ \vdots \\ b_n \end{bmatrix}$$

Here we can see

$$\begin{bmatrix} b_1 \\ \vdots \\ b_k \\ b_{k+1} \\ \vdots \\ b_n \end{bmatrix} = L_{(n-k \times k)} \begin{bmatrix} y_1 \\ \vdots \\ y_k \\ y_{k+1} \\ \vdots \\ y_n \end{bmatrix} + 0_{(n-k \times k)} \cdot \begin{bmatrix} y_{k+1} \\ \vdots \\ y_n \end{bmatrix} \Rightarrow \begin{array}{l} L_{(n-k \times k)} \text{ is invertible} \end{array}$$

$$\Rightarrow \begin{bmatrix} b_1 \\ \vdots \\ b_k \\ b_{k+1} \\ \vdots \\ b_n \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} = L_{(n-k \times k)} \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \\ y_{k+1} \\ \vdots \\ y_n \end{bmatrix} \begin{array}{l} \text{as } L \text{ is invertible} \\ (\text{as non singularity of } L \text{ guarantees non zero diagonal}) \end{array} \Rightarrow L_{(n-k \times k)} \text{ has trivial kernel.}$$

As $b_{k+1} = 0 \Rightarrow y_{i=0} \forall i \in \{k+1, \dots, n\}$

(b)

Let $I = \begin{bmatrix} 1 & & & \\ e_1 & \cdots & e_n \end{bmatrix}$ where $e_i = \begin{bmatrix} 0 \\ \vdots \\ i \\ \vdots \\ 0 \end{bmatrix}$ i th entry.

Let L be an invertible lower triangle matrix.

$$L \cdot L^T = I$$

$$L \begin{bmatrix} 1 & & & \\ l_1 & \cdots & l_n & \\ | & & | & \\ \vdots & & \vdots & \\ 1 & & & \end{bmatrix} = \begin{bmatrix} 1 & & & \\ e_1 & \cdots & e_n & \\ | & & | & \\ \vdots & & \vdots & \\ 1 & & & \end{bmatrix}$$

here we can see $L f_i = e_i$.

as e_i has 0 entry from 1 to $i-1$.

its solution, by as has 0 entry from 1 to $i-1$

$$\text{As } L^{-1} = \begin{bmatrix} l_1 & \cdots & l_n \\ | & & | \\ \vdots & & \vdots \end{bmatrix}$$

and for each f_i , it has 0 entry from 1 to $i-1$

it follows L^{-1} is lower triangular as well.

6. [Inverse matrix computation, 1+1+2pt] Let us use the LU -decomposition to compute the inverse of a matrix².

- (a) Describe the algorithm (we discussed it in class) that uses the LU -decomposition of an $n \times n$ matrix A for computing A^{-1} by solving n systems of equations (one for each unit vector).
- (b) Give the floating point operation count of this algorithm.
- (c) Improve the algorithm by taking advantage of the structure (i.e., the zero entries—see previous problem) of the right-hand side. What is the new algorithm's floating point operation count?

(a) 1° Solve L - U decomposition of A .

2° Solve $A y_i = \begin{bmatrix} 0 \\ i \\ 0 \end{bmatrix}$ for $i \in \{1, \dots, n\}$
 i-th entry

In the following way: 1° Solve $L b_i = \begin{bmatrix} 0 \\ i \\ b_i \end{bmatrix}$ i-th entry
 2° Solve $U y_i = b_i$

3° Put y_i together into a matrix. namely: $A^{-1} = \begin{bmatrix} y_1 & \dots & y_n \end{bmatrix}$

(b) FLOP: Solving L - U -Decompose: $\frac{2}{3}n^3$

Solving y_i n times: $2n^2 \times n = 2n^3$ } $\frac{2}{3}n^3 + 2n^3$

(c) LU decomposition cannot be simplified. ($\frac{2}{3}n^3$)

Since know L is lower triangle and $\begin{bmatrix} 0 \\ i \\ 0 \end{bmatrix}$ i-th column has 0...0 if i is not

when solving $L b_i = e_i$ we only need to calculate the lower part
 (from $i+1$ to n)

Nandy

$$\left[\begin{array}{c|c} L_{(k \times k)} & O_{(k \times (n-k))} \\ \hline \text{---} & \text{---} \\ \text{---} & \text{---} \end{array} \right] = \left[\begin{array}{c|c} b_1 & e_1 \\ \vdots & \vdots \\ b_{k-1} & e_{k-1} \\ \hline \cancel{b_k} & \cancel{e_k} \\ \cancel{b_n} & \cancel{e_n} \end{array} \right]$$

L b_i e_i

only the  part.

Therefore, the flop for backward sub for L b_i e_i is $\sum_{i=1}^n i^2$

has only $\sum_{i=1}^{n-1} i^2$

The product of $Oy = b$ cannot be simplified

So we reduce the flop to: $\sum_{i=1}^{n-1} i^2 + n + \frac{2}{3}n^3 = 2n^3$

7. [Stability of the Gaussian elimination, 2+1+2+1pt]

Consider the system

$$Ax = b, \quad (1)$$

3 of 3

where $A, L, E \in \mathbb{R}^{n \times n}$, $x, b \in \mathbb{R}^n$, with $A = L + E$. L is unit lower triangular, where all the subdiagonal elements are -1 , i.e., $l_{i,j} = -1$ for $i < j$, $l_{i,i} = 1$ for $i = 1, \dots, n$, and $l_{i,j} = 0$ otherwise. Additionally, E is a matrix such that $e_{i,n} = 1$ for $i = 1, \dots, n-1$ and $e_{i,j} = 0$ otherwise. For example, when $n = 5$, we have

$$A = \begin{pmatrix} 1 & - & - & - & \\ -1 & 1 & 0 & 0 & 1 \\ -1 & -1 & 1 & 0 & 1 \\ -1 & -1 & -1 & 1 & 1 \\ -1 & -1 & -1 & -1 & 1 \end{pmatrix}.$$

(a) Prove that A is invertible for any n , by induction.

(a) Proof by induction.

(Base Step) $n=2$

$$A = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \quad \det(A) = 2 \neq 0$$

$\Rightarrow A$ invertible.

(Inductive Step)

Assume for $n-1$ and prove for n

$$A = \begin{bmatrix} 1 & 0 & \cdots & 0 & 1 \\ -1 & \boxed{\quad} & & & \\ \vdots & & & & \\ -1 & & & & \end{bmatrix}$$

Note that to calculate the determinant of A .
There're only 2 non-zero entry on the first row.

For the \square , the determinant is nonzero as is assumed.

for the \square part, we need to permute the column to let it become the $(n-1) \times (n-1)$ A-like matrix

$$\begin{array}{cccccc} -1 & 1 & & & & \\ -1 & -1 & 1 & -1 & & \\ -1 & -1 & -1 & -1 & 1 & \\ -1 & -1 & -1 & -1 & -1 & \\ 1 & -1 & -1 & -1 & -1 & \end{array}$$

we need to put the most left column to the right most.
so we need to switch $(n-2)$ times.
After doing so, we need to multiply (-1) to the last column.

Then $\det(\square) = (-1)^{n-2} \cdot (-1) \cdot \det(\square)$ the $(n-1) \times (n-1)$ A-like matrix.
 $\det(A) = \det(A^{(n-1) \times (n-1)}) + (-1)^{(n-1)} \cdot (-1)^{n-1} \cdot \det(A^{(n-1) \times (n-1)})$
 $= 2 \cdot \det(A^{(n-1) \times (n-1)})$

As is given in the assumption, $A^{(n-1) \times (n-1)}$ is invertible \Leftrightarrow non zero determinant.

$\Rightarrow \det(A)$ is non zero \Leftrightarrow invertible.

According to the (Base step) and (Inductive Step).

we have A is invertible $\forall n \in \mathbb{N}$.

(b) When $n = 5$ and $b = \left(1, \frac{1}{4}, \frac{1}{9}, \frac{1}{16}, \frac{1}{25}\right)^T$, solve for x in (1) using Gaussian elimination, then backward substitution.

$$\left[\begin{array}{ccccc|c} 1 & 0 & 0 & 0 & 1 & 1 \\ -1 & 1 & 0 & 0 & 1 & \frac{y_4}{4} \\ -1 & -1 & 1 & 0 & 1 & y_9 \\ -1 & -1 & -1 & 1 & 1 & y_{16} \\ -1 & -1 & -1 & -1 & 1 & y_{25} \end{array} \right] + R_1 \left[\begin{array}{ccccc|c} 1 & 0 & 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 & 2 & \frac{y_4}{4} \\ 0 & -1 & 1 & 0 & 2 & y_9 \\ 0 & -1 & -1 & 1 & 2 & y_{16} \\ 0 & -1 & -1 & -1 & 2 & y_{25} \end{array} \right] + R_2$$

$$\left[\begin{array}{ccccc|c} 1 & 0 & 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 & 2 & 1 + \frac{1}{4} \\ 0 & 0 & 1 & 0 & 4 & 1 + \frac{1}{4} \\ 0 & 0 & -1 & 1 & 4 & 1 + \frac{1}{4} \\ 0 & 0 & -1 & -1 & 4 & 1 + \frac{1}{4} \end{array} \right] \xrightarrow{\text{R3} \leftarrow R3 - R1, \text{R4} \leftarrow R4 - R1, \text{R5} \leftarrow R5 - R1}$$

$$\left[\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 2 \\ 0 & 0 & 1 & 0 & 4 \\ 0 & 0 & 0 & -1 & 8 \\ \hline 0 & 0 & 0 & -1 & 8 \end{array} \right] \xrightarrow{\begin{array}{l} +\frac{1}{4} \\ +Y_9 \\ +1+\frac{1}{4} \\ +Y_{10}+1+\frac{1}{4} \\ +1+Y_9+1+Y_4 \end{array}} \left[\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 2 \\ 0 & 0 & 1 & 0 & 4 \\ 0 & 0 & 0 & -1 & 8 \\ \hline 0 & 0 & 0 & -1 & 8 \end{array} \right] + R4$$

$$\left[\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 2 \\ 0 & 0 & 1 & 0 & 4 \\ 0 & 0 & 0 & 1 & 8 \\ 0 & 0 & 0 & 0 & 16 \end{array} \right] \xrightarrow{\begin{array}{l} I \\ II - 2I \\ III + 4I \\ IV + 8I \\ V + 16I \end{array}} \left[\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 2 \\ 0 & 0 & 1 & 0 & 4 \\ 0 & 0 & 0 & 1 & 8 \\ 0 & 0 & 0 & 0 & 16 \end{array} \right]$$

Do back prep.

$$b_5 = \frac{1}{11} \times \frac{33569}{3600} = \frac{33569}{57600}$$

$$b_4 = \frac{673}{124} - 8b_5 = \frac{9}{800}$$

$$b_3 = \frac{85}{36} - 4b_5 = \frac{431}{14400}$$

$$b_2 = \frac{5}{4} - 2b_5 = \frac{243}{28800}$$

$$b_1 = 1 - b_5 = \frac{24031}{57600}$$

- (c) Now consider $A, \mathbf{x}, \mathbf{b}$, where n is not specified. Put (1) into the form $U\mathbf{x} = \mathbf{c}$, where U is upper triangular using Gaussian elimination (you do not have write what \mathbf{c} is since \mathbf{b} is not given). What is $\max_{i,j} |u_{i,j}|$?

According to the Gauss Elimination Process above.

for i th step. we need to add i^{th} row to k^{th} row
 $k \in \{i+1, \dots, n\}$

Therefore, for the last column

$$U_{1:n} = 1 + 1 + 2 + 4 + \dots + 2^{i-2} \\ = 2^i - 1$$

As other entry is either 0 or 1

$$\text{We have } \max_{i,j} |U_{ij}| = U_{n,n} = 2^{n-1}$$

- (d) For large n , e.g., $n = 2000$, what problems can you envision if you try to solve (1) using Gaussian elimination on a computer? Explain.

1° Since the largest number of U is 2^{n-1} for $n \times n$ matrix.

this number is really hard to store in Computer as it is too large. Even if it can be stored, it will waste a great memory.

As other number are small.

2° The Condition Number of the eliminated matrix tends to be big. The matrix is highly unstable.