

Continual Learning for Image Classification and Object Detection

Eden Belouadah

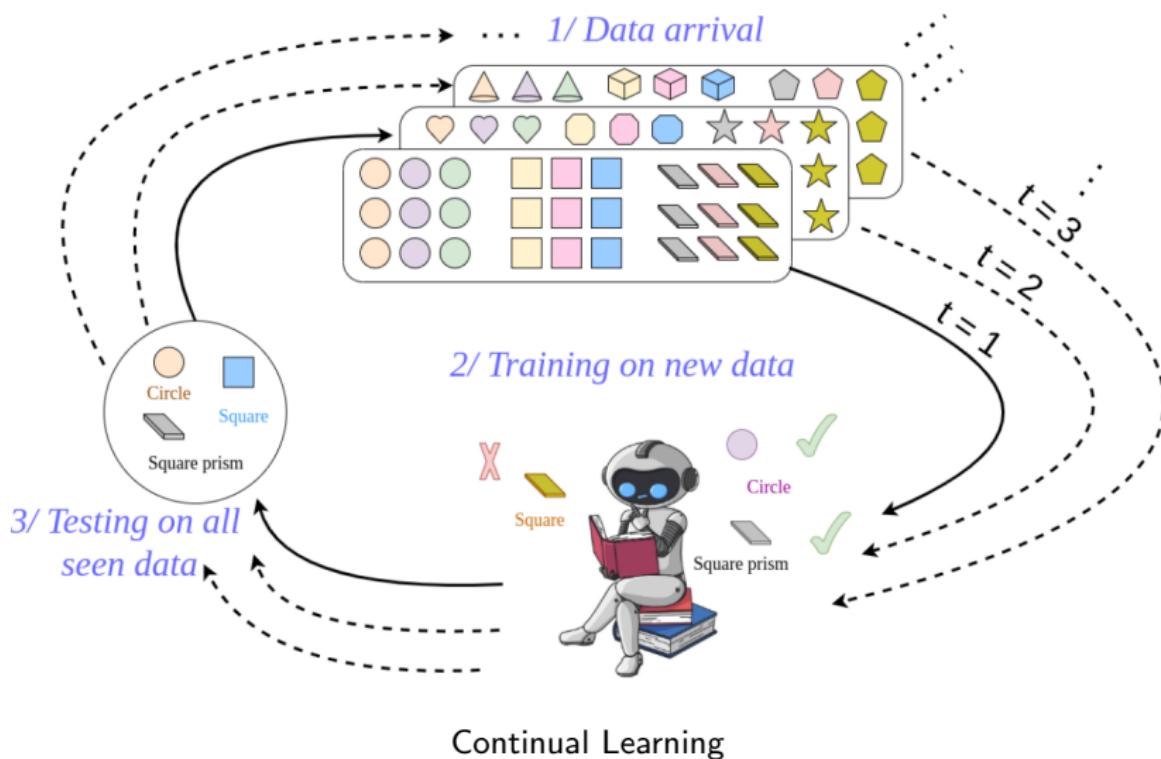
eb@datakalab.com



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Introduction

Continual Learning



Introduction

Applications of Continual Learning

Application examples of continual learning



Robotics



Autonomous cars



Face Recognition



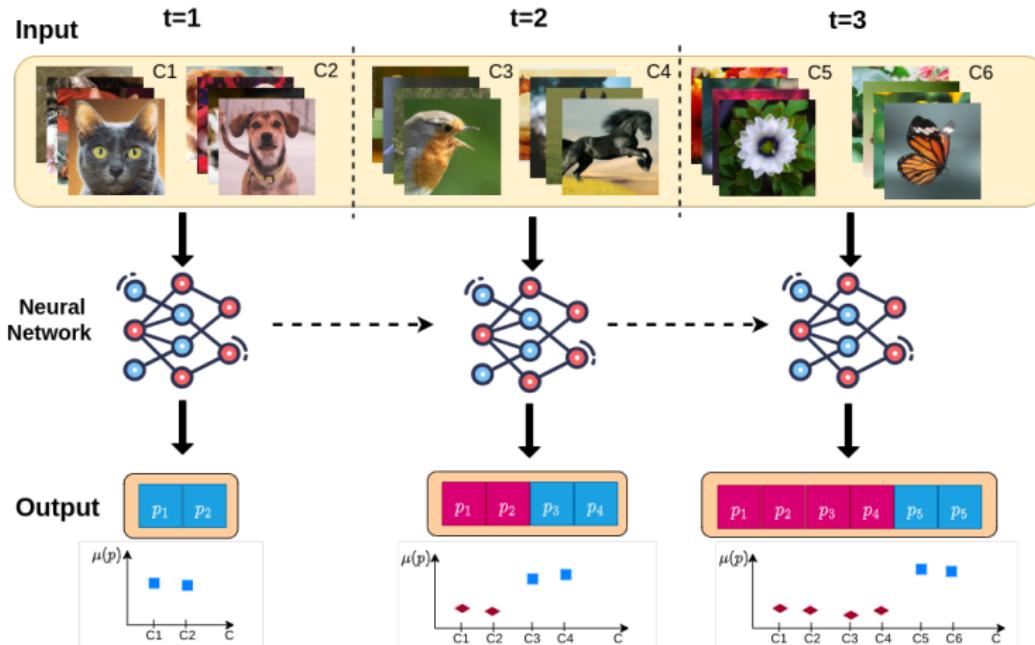
Health

Introduction

Challenges of Continual Learning

Catastrophic forgetting

- Tendency of neural networks to underfit past data when new one is ingested



Introduction

Class-Incremental Learning

Training

Task boundaries



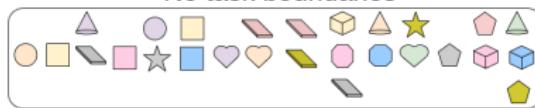
Task-IL

State 1 State 2 State 3



Class-IL

No task boundaries

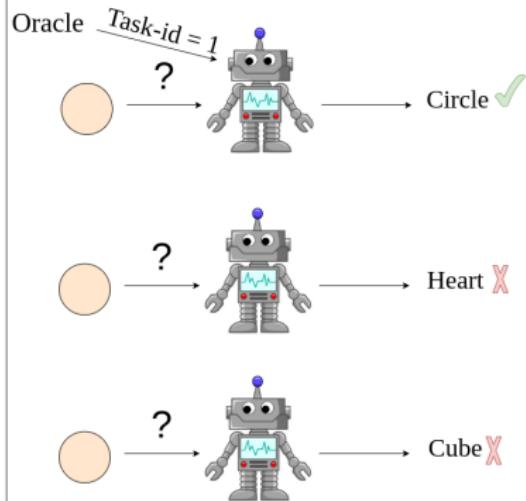


Domain-IL

Time

Testing

Oracle

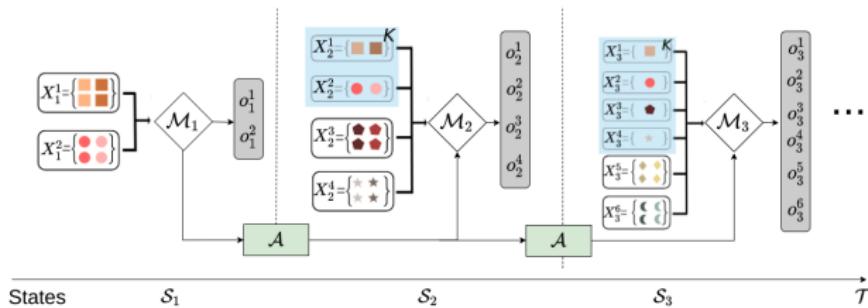


Three Scenarios of Continual Learning

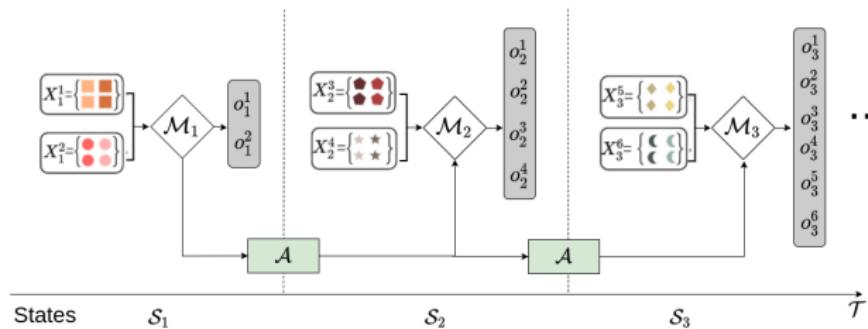
Introduction

Two scenarios of Class-Incremental Learning

► Incremental Learning with memory



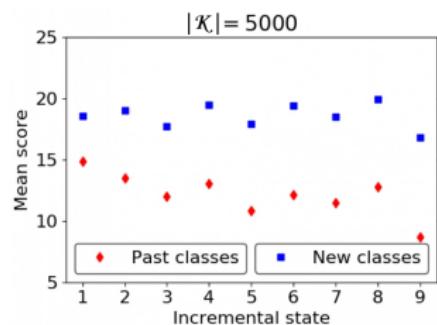
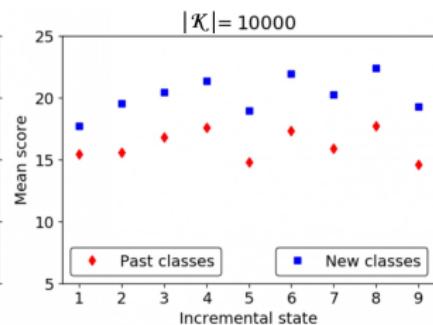
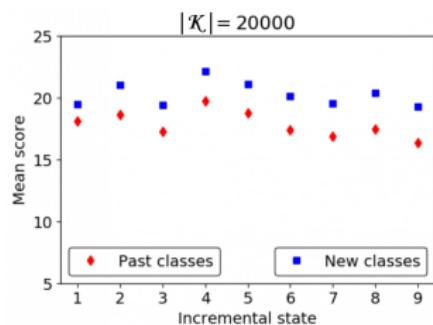
► Incremental Learning without memory



Introduction

Usefulness of a bounded memory

Memory reduces prediction bias towards new classes



Mean prediction scores of past and new classes with vanilla fine tuning

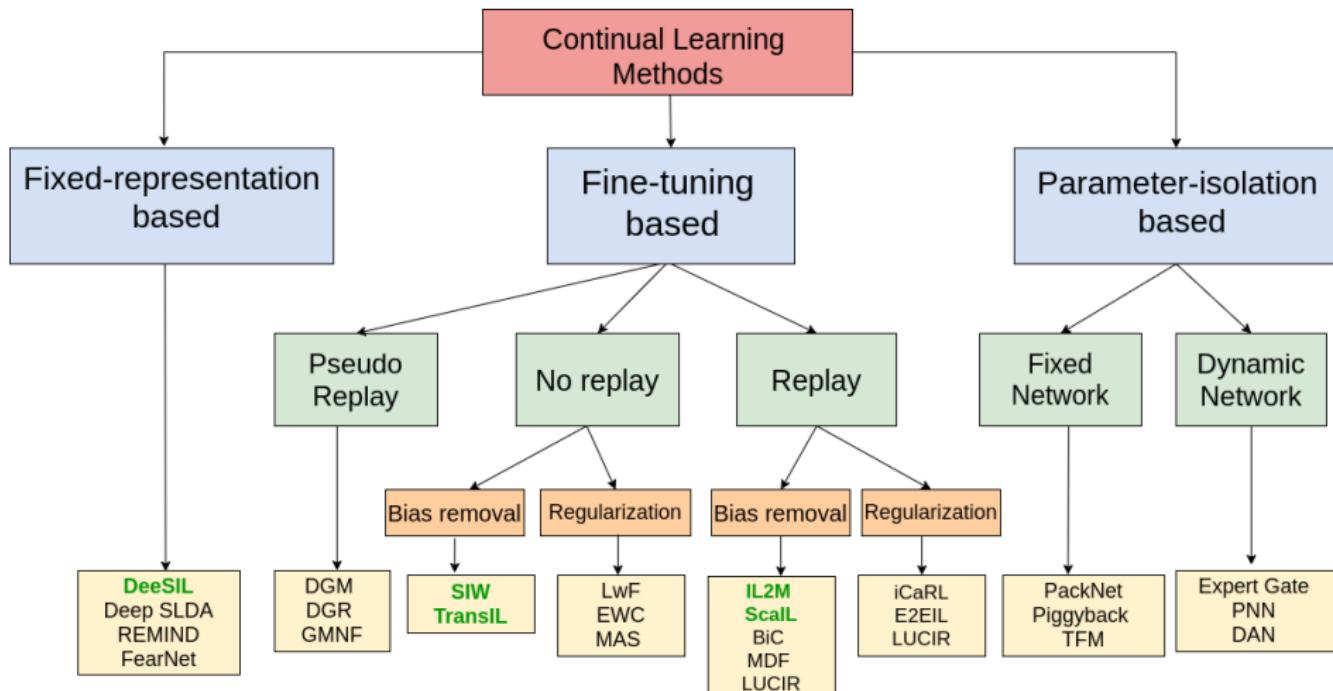
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1. State of the art

State of the art

Three main categories

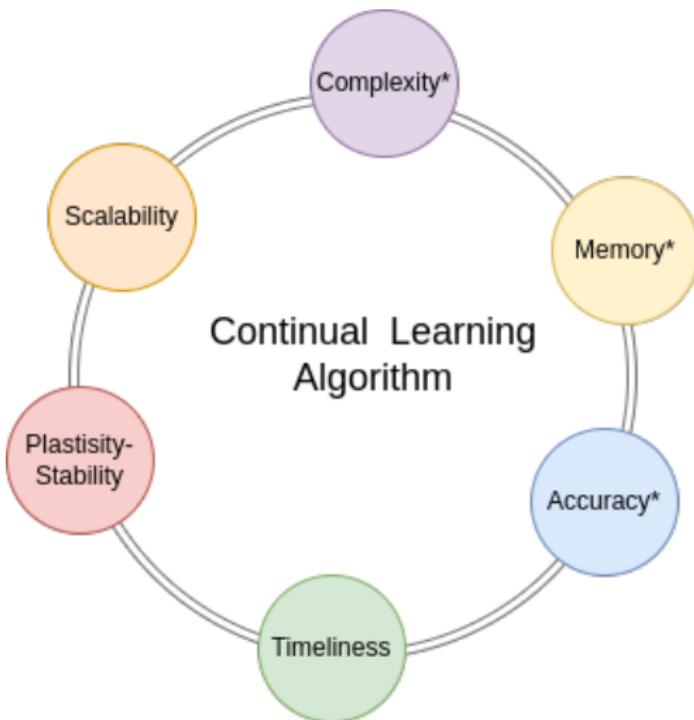


[Schema inspired by Lange et al., 2019]

[References are in appendix slides]

State of the art

Challenges



* [Inspired by Rebuffi et al., 2017]

State of the art

Pros and Cons

	Complexity	Memory	Accuracy	Timeliness	Plasticity-Stability	Scalability
Fine tuning based	Increases slowly	The bigger the memory, the better the model	Best SoTA results with memory	Retraining is needed at each state	Depends on the availability of the memory	Depends on the size of the memory
Fixed representation based	Increases slowly	Low dependency	Good if the initial model is trained on large dataset	Fast	Bad if incremental classes are different from the initial ones	Heavily depends on the fixed representation
Parameter isolation based	Depends if fixed or dynamic network	Non compulsory	Depends on how much the model architecture can increase	Retraining is needed at each state	Good	Scale well if resources are available

LwF: Learning without Forgetting (Li and Hoiem, 2016)

- Fine Tuning with distillation loss

$$\mathcal{L}_t^d(x) = \sum_{(x,y) \in \mathcal{D}_t} \sum_{j=1}^{N_{t-1}} -\hat{\sigma}_{t-1}^j(x) \log[\hat{\sigma}_t^j(x)] \quad (1)$$

where $\hat{\sigma}$ is the softened softmax

- ▶ (+) No memory of the past is needed
- ▶ (−) The gap with a *Joint* training is large

iCaRL: Incremental Classifier and Representation Learning (Rebuffi et al., 2017)

- LwF with memory
- Herding to select exemplars

$$e \leftarrow \arg \min_{x \in X} \|\mu - \frac{1}{k}[f(x) + \sum_{j=1}^{k-1} f(e_j)]\| \quad (2)$$

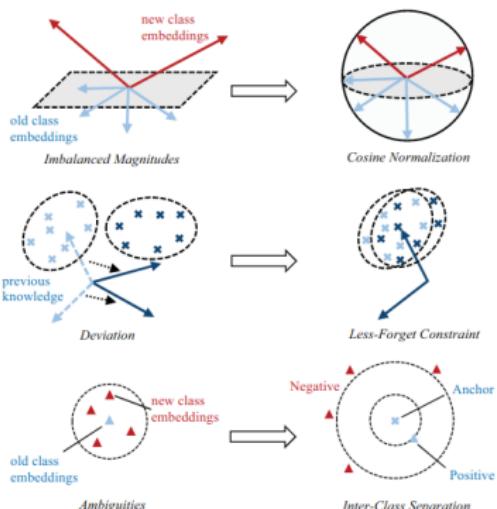
- Nearest Exemplars Mean (NEM)

$$y^* = \arg \min_{y \in [1, N_t]} \|f(x) - \mu_y\| \quad (3)$$

- ▶ (+) Combination of powerful components
- ▶ (-) Unfair comparison with baselines

LUCIR: Learning a Unified Classifier Incrementally via Rebalancing (Hou et al., 2019)

- Cosine normalization
 - Less-forget constraint
 - Inter-class separation
 - ▶ (+) Powerful objective
 - ▶ (-) Important execution time



BiC: Bias Correction (Wu et al., 2019)

- Distillation loss
- Bias-removal layer

$$BiC(\mathbf{o}_t^k) = \begin{cases} \mathbf{o}_t^k & \text{if } k \in [1, t-1] \\ \alpha_t \mathbf{o}_t^k + \beta_t \cdot \mathbf{1} & \text{if } k = t \end{cases} \quad (4)$$

- ▶ (+) Simple, fast, and accurate
- ▶ (-) Uses a validation set (memory required)

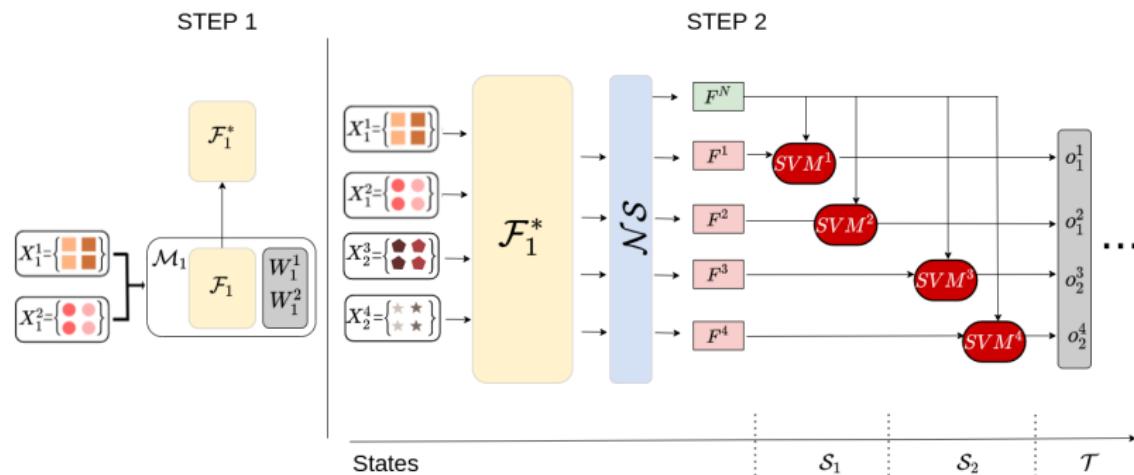
2. Class-incremental learning with memory

Class-Incremental Learning with memory

DeeSIL: Deep-Shallow Incremental Learning (W-ECCV 2018)

DeeSIL: Deep-Shallow Incremental Learning (Belouadah and Popescu, 2018, W-ECCV)

- Fixed Representation based
- Inspired by transfer learning
- Works with and without memory



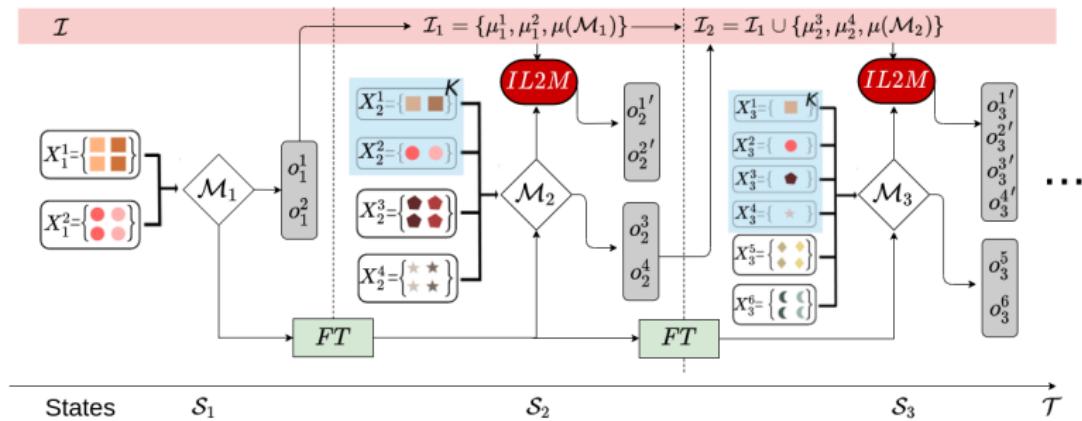
Overview of *DeeSIL*

Class-Incremental Learning with memory

IL2M: Incremental Learning with Dual memory (ICCV 2019)

IL2M: Incremental Learning with Dual memory (Belouadah and Popescu, 2019, ICCV)

- Fine Tuning based
- Leverages past class statistics



Overview of $IL2M$

Class-Incremental Learning with memory

IL2M: Incremental Learning with Dual memory (ICCV 2019)

- Past class score rectification

For all past classes ($j = 1, \dots, N_{t-1}$):

$$\sigma_t^{j'} = IL2M(\sigma_t^j) = \begin{cases} \sigma_t^j \times \frac{\mu_i^j}{\mu_t^j} \times \frac{\mu(\mathcal{M}_t)}{\mu(\mathcal{M}_i)}, & \text{if } pred = new \\ \sigma_t^j, & \text{otherwise} \end{cases} \quad (5)$$

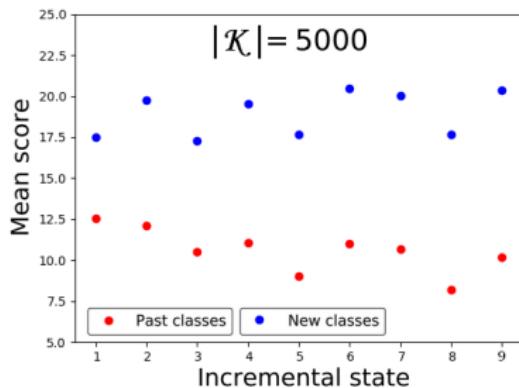
with:

- ▶ i - the initial state in which the j^{th} class was learned
- ▶ t - the current incremental state
- ▶ σ_t^j - the raw prediction the j^{th} class in the current state t
- ▶ μ_i^j and μ_t^j - the mean classification scores of the j^{th} class in states i and t
- ▶ $\mu(\mathcal{M}_t)$ and $\mu(\mathcal{M}_i)$ - the model mean score in states t and i

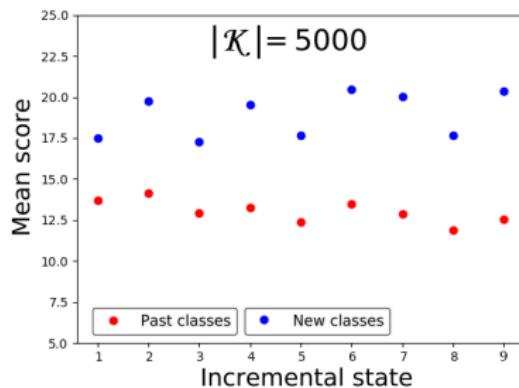
Class-Incremental Learning with memory

IL2M: Incremental Learning with Dual memory (ICCV 2019)

- Effect of *IL2M*



Before



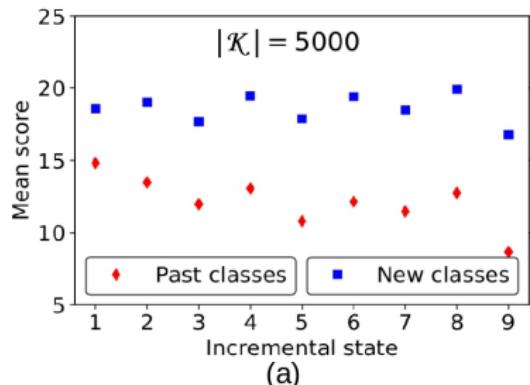
After

Class-Incremental Learning with memory

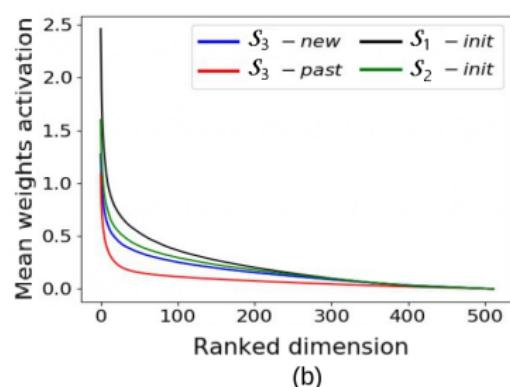
ScalL: Classifier weights Scaling for Class IL (WACV 2020)

ScalL: Classifier weights Scaling for Class IL (Belouadah and Popescu, 2020, WACV)

- Fine Tuning based
- Forgetting happens mainly in the final layer
- Features are usable across incremental states



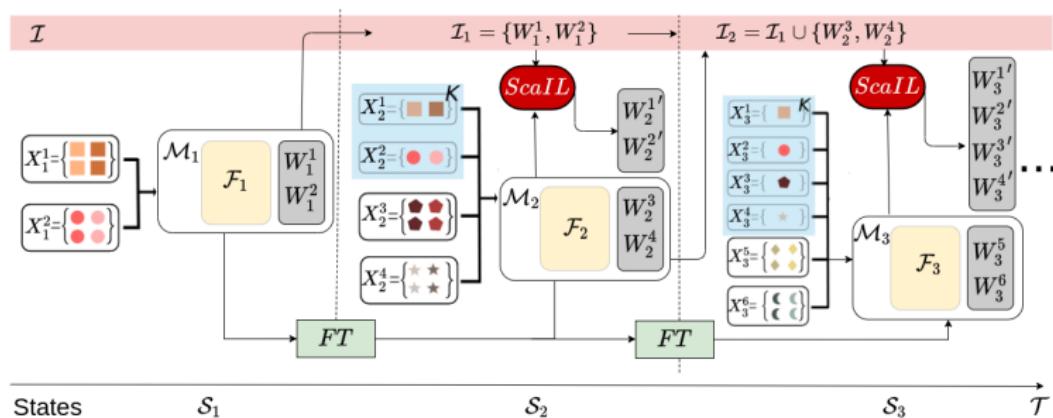
Mean prediction scores and weights magnitudes



Class-Incremental Learning with memory

ScalL: Classifier weights Scaling for Class IL (WACV 2020)

- Past class weights replay



Overview of *ScalL*

Class-Incremental Learning with memory

ScalL: Classifier weights Scaling for Class IL (WACV 2020)

- Sort class weights

$$\widehat{\mathbf{W}}_t^j = \text{sort}(|w_j^1|, |w_j^2|, \dots, |w_j^d|, \dots, |w_j^D|) ; j \in [N_{t-1}, N_t], d \in [1, D] \quad (6)$$

$\widehat{\mathbf{W}}_t^j$ is the sorted version of the initial weights vector of new class j .

- Compute state mean vector

$$\mu_t^d = \frac{1}{P_t} \times \sum_{j=N_{t-1}}^{N_t} \widehat{w}_j^d \quad d \in [1, D] \quad (7)$$

where μ_t (of dimension D) is the mean vector of the ranked new classes' weights in the state S_t , and d is a dimension in the feature vector.

Class-Incremental Learning with memory

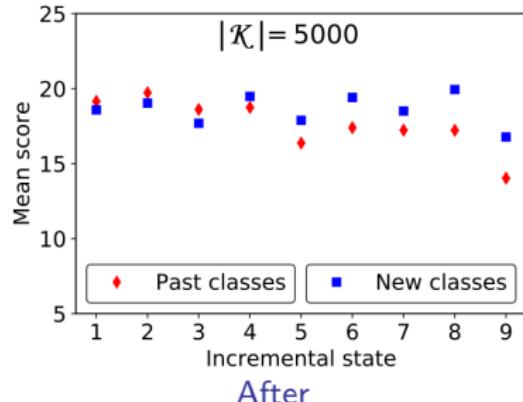
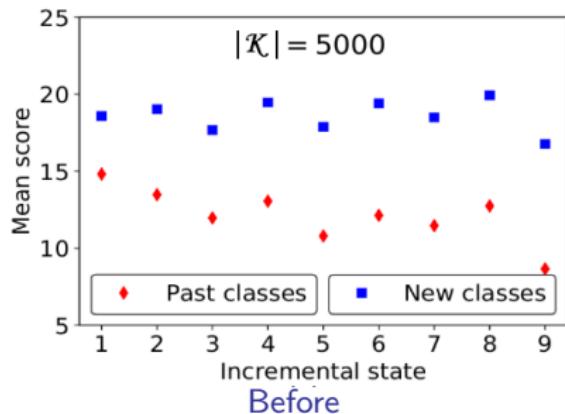
ScalL: Classifier weights Scaling for Class IL (WACV 2020)

- Normalize past class weights

$$w_j^{d'} = \frac{\mu_t^{R(d)}}{\mu_i^{R(d)}} \times w_j^d \quad (8)$$

$w_j^{d'}$ is the scaled version of w_j^d , the d^{th} dimension of the initial classifier W_i^j of the j^{th} past class.

- Effect of ScalL



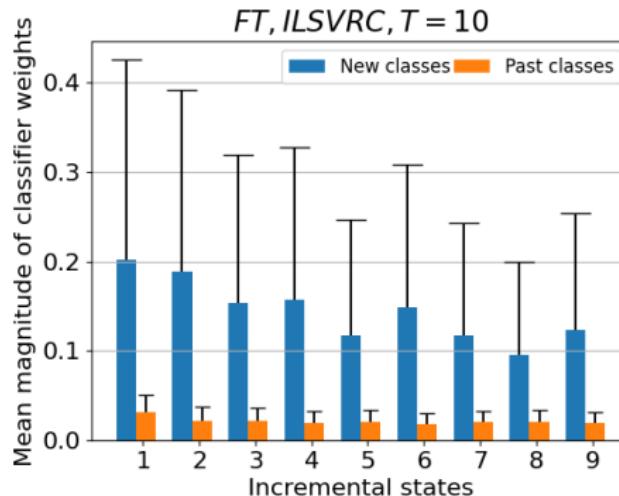
2. Class-incremental learning without memory

Class-Incremental Learning without memory

SIW: Standardization of Initial Weights for Class IL (BMVC 2020)

SIW: Standardization of Initial Weights for Class Incremental Learning (Belouadah et al., 2020, BMVC)

- Fine Tuning based
- Bias in the mean weights magnitudes

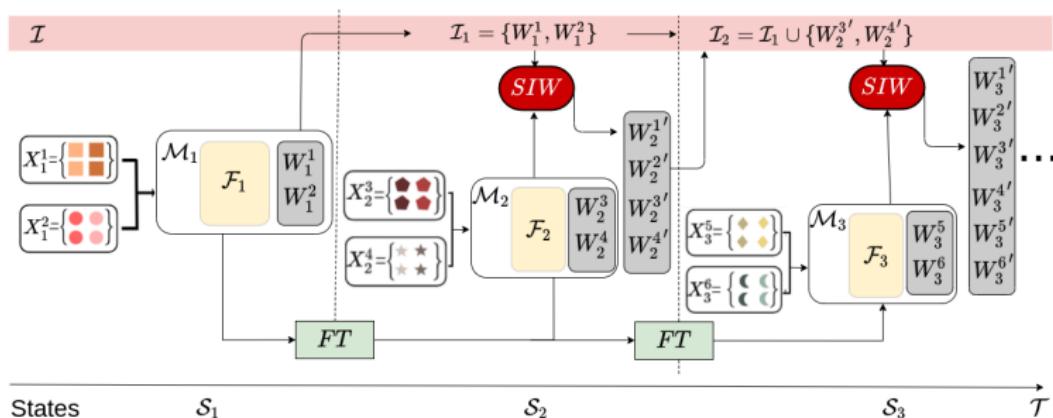


Mean weights magnitudes without memory

Class-Incremental Learning without memory

SIW: Standardization of Initial Weights for Class IL (BMVC 2020)

- Past class weights replay

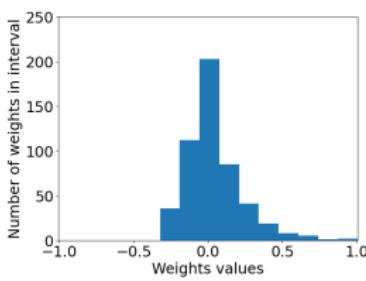
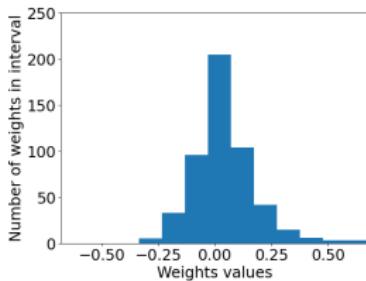
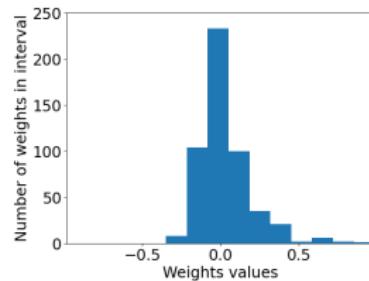
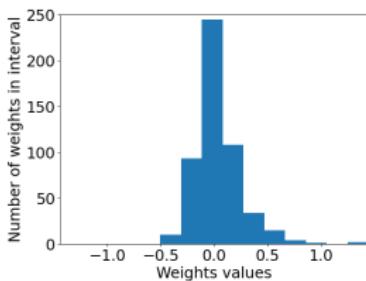
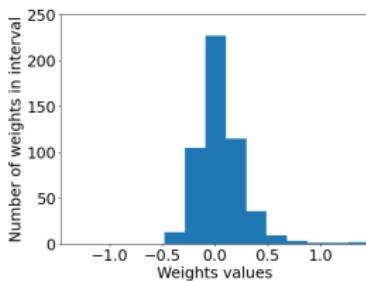
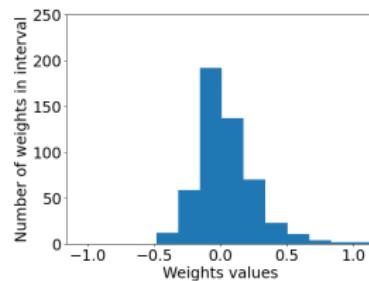


Overview of *SIW*

Class-Incremental Learning without memory

SIW: Standardization of Initial Weights for Class IL (BMVC 2020)

- Classifier weights distribution



Class-Incremental Learning without memory

SIW: Standardization of Initial Weights for Class IL (BMVC 2020)

- Standardization of Initial Weights

$$w'_d = \frac{w_d - \mu(\mathbf{W})}{\sigma(\mathbf{W})} \quad (9)$$

with:

w_d is the d^{th} dimension of an initial classifier \mathbf{W} , $\mu(\mathbf{W})$ and $\sigma(\mathbf{W})$ are the mean and standard deviation of \mathbf{W} .

- State-level calibration

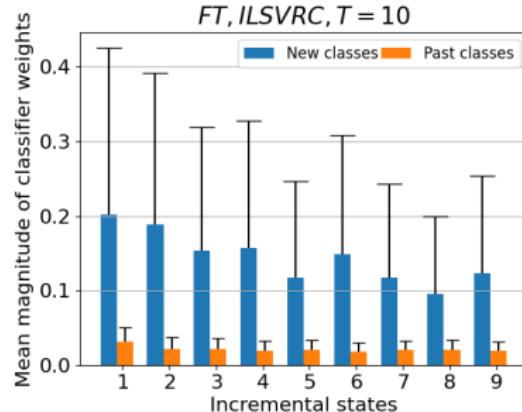
$$o_t^j(x) = (\mathbf{f}_t(x) \cdot \mathbf{W}_t^{j'} + b_j^i) \times \frac{\mu(\mathcal{M}_t)}{\mu(\mathcal{M}_i)} \quad (10)$$

$\mu(\mathcal{M}_t)$ and $\mu(\mathcal{M}_i)$ are means of top-1 predictions of models learned in the t^{th} and i^{th} states

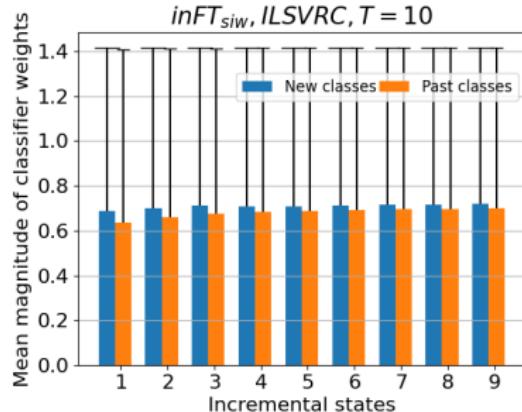
Class-Incremental Learning without memory

SIW: Standardization of Initial Weights for Class IL (BMVC 2020)

- Effect of SIW on weights magnitudes



Before



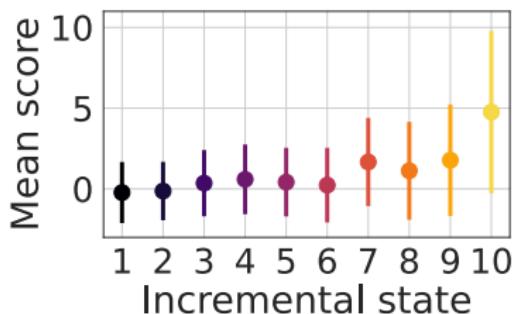
After

Class-Incremental Learning without memory

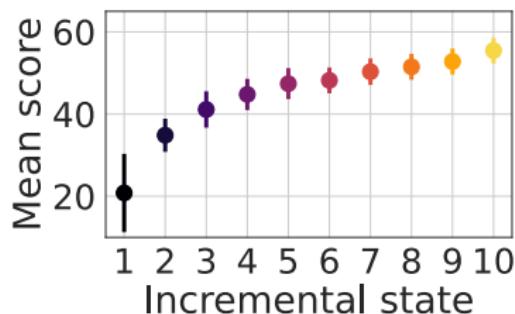
TransIL: Dataset Knowledge Transfer for Class IL (WACV 2022)

TransIL: Dataset Knowledge Transfer for Class IL (Slim et al., 2022, WACV)

- Fine Tuning based
- Bias in the mean classification scores after *LwF* and *LUCIR*



LwF (Li and Hoiem, 2016)



LUCIR (Hou et al., 2019)

Mean prediction scores and standard deviation

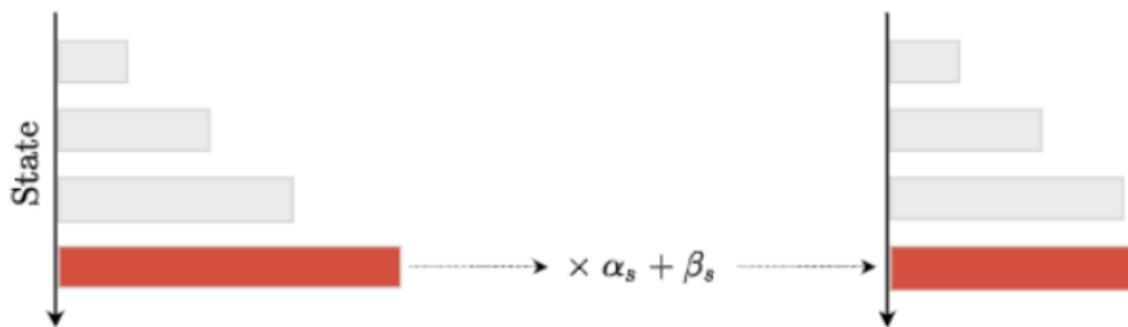
Class-Incremental Learning without memory

TransIL: Dataset Knowledge Transfer for Class IL (WACV 2022)

Enable the use of Bias Correction layers in a memoryless scenario

- BiC : Bias Correction (Wu et al., 2019)

$$BiC(\mathbf{o}_t^k) = \begin{cases} \mathbf{o}_t^k & \text{if } k \in [1, t-1] \\ \alpha_t \mathbf{o}_t^k + \beta_t \cdot \mathbf{1} & \text{if } k = t \end{cases} \quad (11)$$



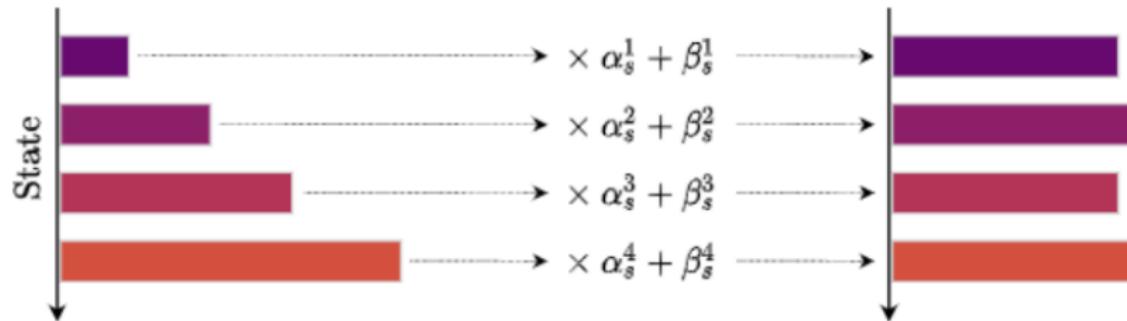
Class-Incremental Learning without memory

TransIL: Dataset Knowledge Transfer for Class IL (WACV 2022)

- adBiC : Adaptive Bias Correction (proposed)

$$adBiC(\mathbf{o}_t^k) = \alpha_t^k \mathbf{o}_t^k + \beta_t^k \cdot \mathbf{1} ; \quad k \in [1, t] \quad (12)$$

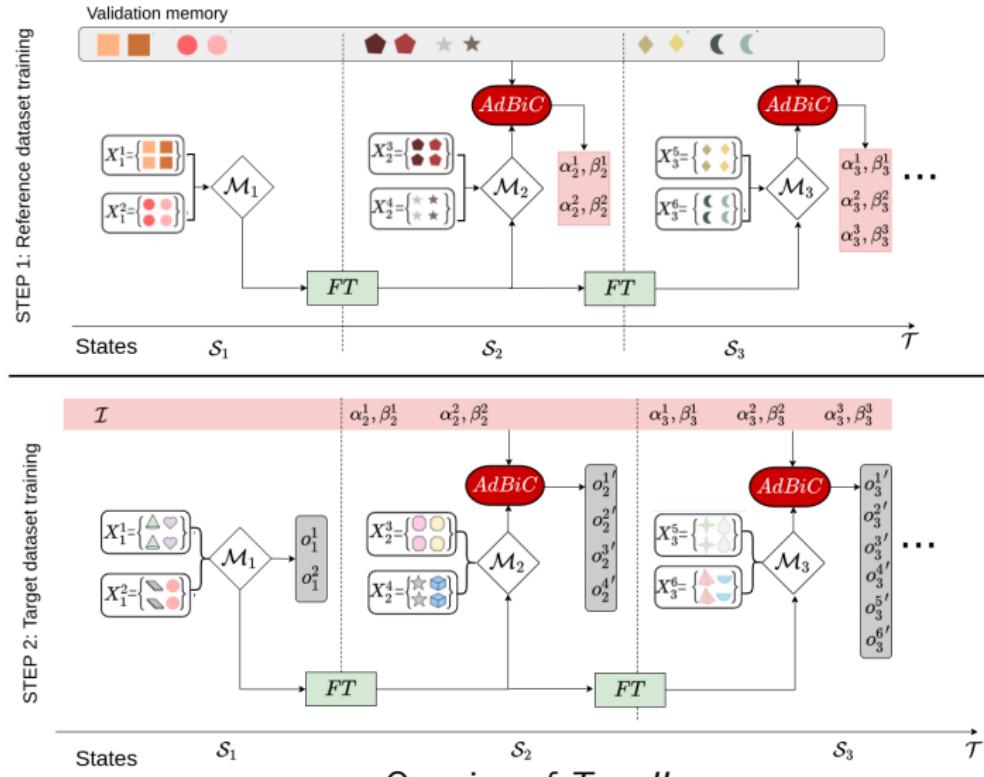
where α_t^k, β_t^k are the parameters applied in state S_t to classes first learned in state S_k .



Class-Incremental Learning without memory

TransIL: Dataset Knowledge Transfer for Class IL (WACV 2022)

- Dataset knowledge transfer

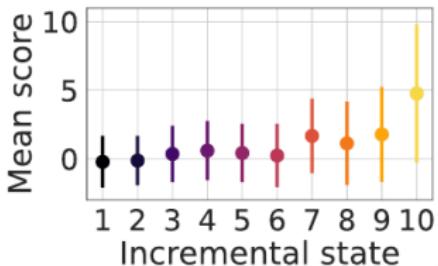


Class-Incremental Learning without memory

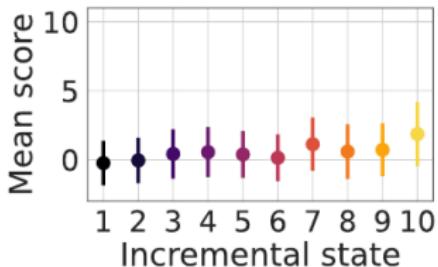
TransIL: Dataset Knowledge Transfer for Class IL (WACV 2022)

- Effect on classification scores

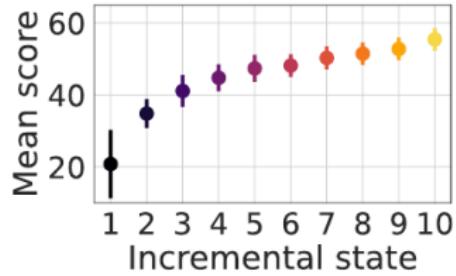
Before



After



LwF (Li and Hoiem, 2016)



LUCIR (Hou et al., 2019)

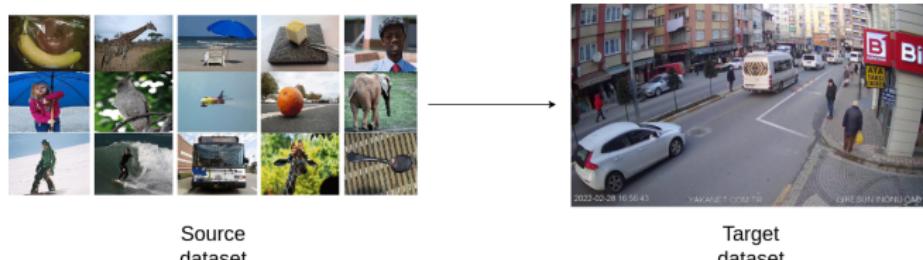
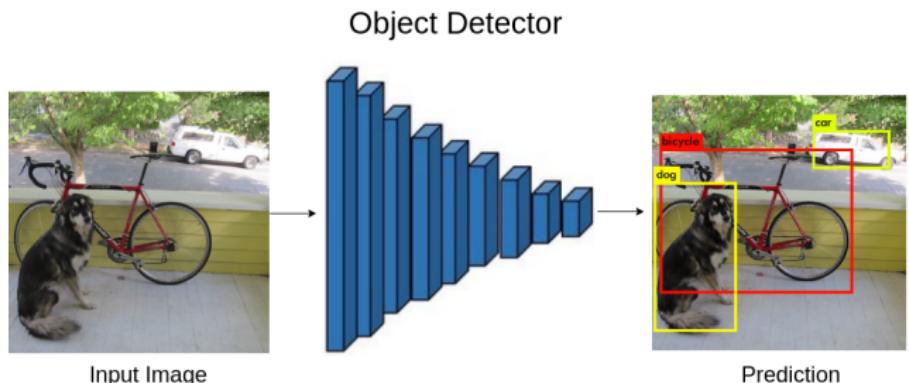
4. Continual Learning for Object Detection on the Edge

Continual Learning for Object Detection on the Edge

Context Adaptation with Continual Learning

Object Detection: From generic to specific

- Adapt pretrained models to specialized domains (fixed camera, few set of classes, fixed context...)

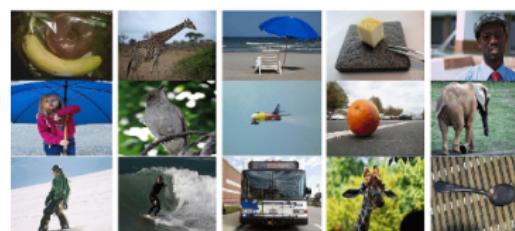


Continual Learning for Object Detection on the Edge

Context Adaptation with Continual Learning

Challenges

- ▶ Data is not annotated
- ▶ Limited resources in memory and computational power
- ▶ Overfitting
- ▶ Catastrophic Forgetting (McCloskey and Cohen, 1989)
- ▶ Domain shift, low image resolution ...etc



Source
dataset



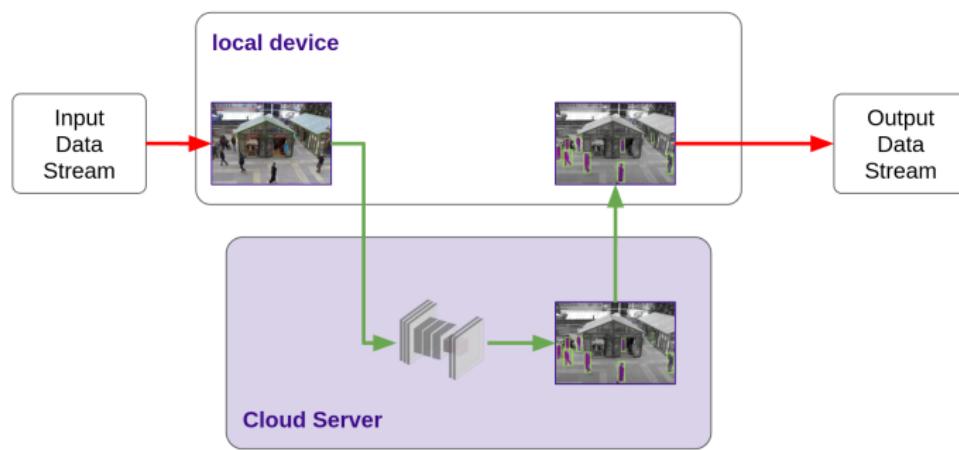
Target
dataset

Continual Learning for Object Detection on the Edge

Context Adaptation with Continual Learning

Classical solution: infer a large model on the cloud

- ▶ (+) Excellent performance
- ▶ (+) Straight forward deployment
- ▶ (-) Data sent to the cloud → not GDPR compliant
- ▶ (-) Frequent internet access
- ▶ (-) High cost

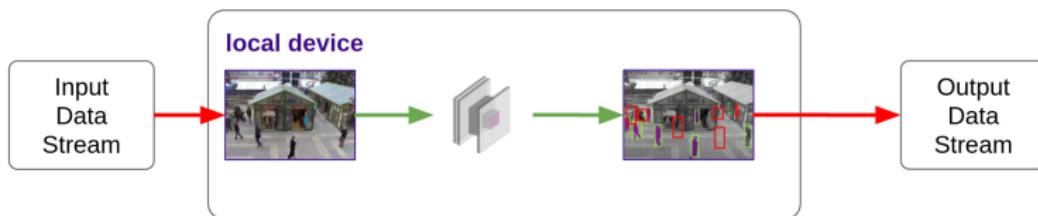


Continual Learning for Object Detection on the Edge

Context Adaptation with Continual Learning

Wanted solution: infer tiny model on the edge

- ▶ (+) Straight forward deployment
- ▶ (+) GDPR compliant
- ▶ (+) No internet access
- ▶ (+) Low cost
- ▶ (-) Very poor performance

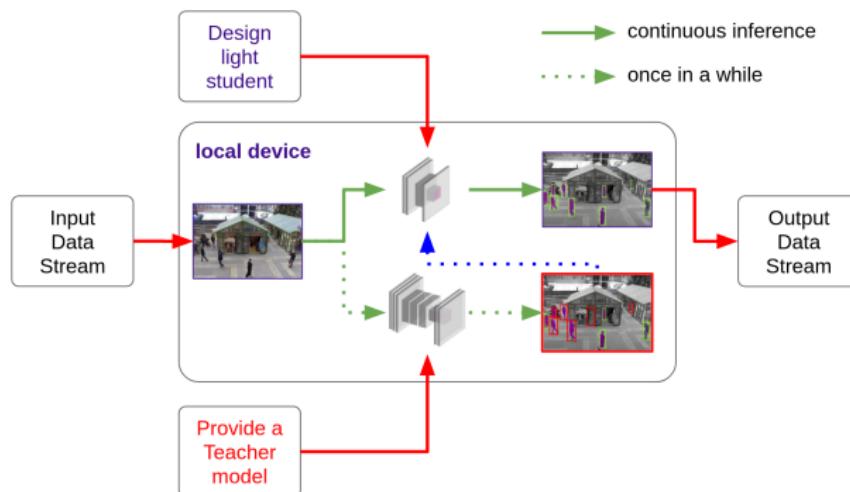


Continual Learning for Object Detection on the Edge

Context Adaptation with Continual Learning

Solution 1: run both large and tiny model on the edge

- (+) Good performance
- (+) GDPR compliant
- (+) No internet access
- (+) Low cost
- (-) Assumes that the large model can fit the edge device

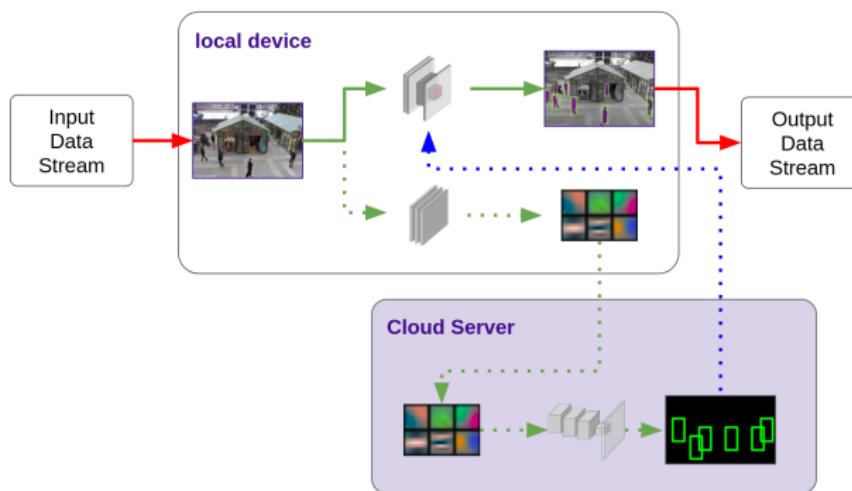


Continual Learning for Object Detection on the Edge

Context Adaptation with Continual Learning

Solution 2: run only part of large model on the edge

- ▶ (+) Good performance
- ▶ (+) GDPR compliant
- ▶ (+) Energy consumption
- ▶ (-) Frequent internet access
- ▶ (-) Cloud cost



Experiments and Results

Experiments and Results

Experimental protocol

- Evaluation of *DeeSIL*, *IL2M*, *ScalL*, and *SIW*

Dataset	#Train	#Test	#Classes	$\mu(\text{train})$	$\sigma(\text{train})$
ILSVRC (Russakovsky et al., 2015)	1,231,167	50,000	1,000	1231.2	70.2
VGGFACE2 (Cao et al., 2018)	491,746	50,000	1,000	491.7	49.4
LANDMARKS (Noh et al., 2017)	374,367	20,000	1,000	374.4	103.8
CIFAR-100 (Krizhevsky, 2009)	50,000	10,000	100	500.00	0.00

Summary of the datasets used for evaluation

- ▶ Architecture: a ResNet-18 network
- ▶ Memory size : $|\mathcal{K}| = \{2\%, 1\%, 0.5\%\}$ of the training set, and no memory.
- ▶ Number of states: $\mathcal{T} = \{10, 20, 50\}$

Experiments and Results

Experimental protocol

- Evaluation of *TransIL*

10 Reference datasets

10 random 100 leaf classes from ImageNet (Deng et al., 2009)	
Train	500 images per class
Val	200 images per class

4 Test datasets

CIFAR-100 (Krizhevsky, 2009), IMN-100 (Deng et al., 2009), BIRDS-100 (Deng et al., 2009), FOOD-100 (Bossard et al., 2014)	
Train	500 images per class
Test	100 images per class

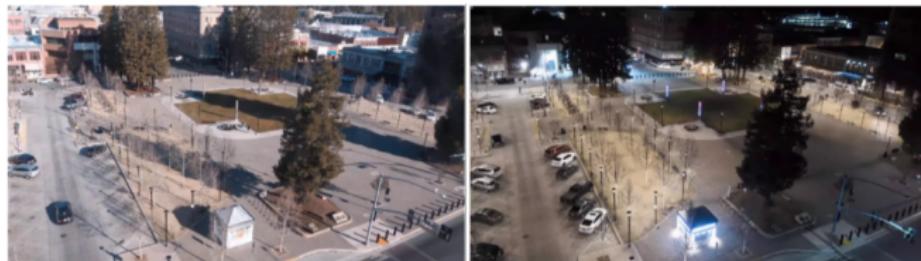
- ▶ Architecture: a ResNet-18 network
- ▶ No memory of the past
- ▶ Number of states: $\mathcal{T} = \{5, 10, 20\}$

Experiments and Results

Experimental protocol

Evaluation of Object Detection Model

Dataset	Total hours	# splits	# train (mn)	# val (mn)	classes
	10	10	40	20	car
Set	Total frames	1 frame per second		1 frame per two seconds	
Train	72000	1200		600	
Val	36000	x		300	



Morning view

Night view

- ▶ Large model: YOLO-V4
- ▶ Small model: MobileNet-V1 + SSD with FPN

Experiments and Results

Experimental protocol

- Class-IL baselines - with memory

Method	works without memory?
<i>FT</i>	✓
<i>FR</i>	✓
<i>iCaRL</i> (Rebuffi et al., 2017)	<i>LwF</i> (Li and Hoiem, 2016)
<i>LUCIR</i> (Hou et al., 2019)	✓
<i>BiC</i> (Wu et al., 2019)	✗
<i>REMIND</i> (Hayes et al., 2019)	✓

- Class-IL baselines - without memory

- ▶ *FT*, *FR*, *LwF* (Li and Hoiem, 2016), *LUCIR* (Hou et al., 2019), *REMIND* (Hayes et al., 2019)
- ▶ *FT+* (Masana et al., 2021)
- ▶ *Deep-SLDA* (Hayes and Kanan, 2019)

Experiments and Results

Experimental protocol

- Plugins applied on top of Class-IL *FT*
 - ▶ **init** - use of initial classifiers of past classes (used in *ScalL* and *SIW*)
 - ▶ **L2** - L2 normalization of the weights matrix
 - ▶ **mc** - mean state calibration (used in *IL2M* and *SIW*)
 - ▶ **th** - threshold calibration (Buda et al., 2018)
 - ▶ **BAL** - balanced fine tuning (Castro et al., 2018)
 - ▶ **NEM** - nearest exemplars mean (Rebuffi et al., 2017)
- Upper bound of Class IL
 - ▶ **Joint** - full training with all data

Experiments and Results

Experimental protocol

- Class-IL Evaluation metrics

- ▶ Average incremental accuracy (Castro et al., 2018)
- ▶ G_{IL} aggregation measure

$$G_{IL} = \frac{1}{C} \times \sum_{c=1}^C \frac{A(c) - A(Joint)}{A_{max} - A(Joint)} \quad (13)$$

C - number of tested configurations; $A(c)$ - accuracy of each configuration ; $A(Joint)$ - accuracy of *Joint* ; $A_{max} = 100$

- Object Detection metric

- ▶ Mean Average Precision at [0.5:0.05:0.95] IoU thresholds

Results and discussion

Class-Incremental Learning with memory

Top-5 results with herding (\mathcal{T} fixed, $|\mathcal{K}|$ variable)

States	$\mathcal{T} = 10$											
	ILSVRC			VGGFACE2			LANDMARKS			CIFAR-100		
$ \mathcal{K} $	2%	1%	0.5%	2%	1%	0.5%	2%	1%	0.5%	2%	1%	0.5%
iCaRL	79.3	76.5	71.0	96.0	95.3	93.9	95.1	94.0	91.8	66.5	56.1	47.9
FT	79.4	74.4	65.9	96.4	94.5	91.3	96.6	94.7	91.4	82.4	77.9	70.7
FT+init	79.2	76.5	73.0	95.9	95.2	94.6	97.0	95.5	92.7	83.4	80.5	75.2
FT+NEM	81.4	79.0	75.0	96.4	95.4	94.0	96.1	94.6	92.6	85.1	81.7	76.0
FT+BAL	84.0	80.9	76.5	97.0	95.7	92.4	96.9	95.3	92.2	80.0	74.0	69.0
FT+th	84.3	82.1	78.3	97.2	96.3	94.8	97.2	95.8	94.0	86.4	83.9	79.1
LUCIR	79.9	76.4	72.6	97.2	96.9	96.5	97.2	96.6	96.1	79.8	75.4	69.9
BiC	85.5	82.8	79.7	97.3	96.6	95.7	97.9	97.3	96.6	88.8	87.6	83.5
ScAIL	82.0	79.8	76.6	96.5	95.8	95.2	97.3	96.0	94.0	85.6	83.2	79.1
IL2M	80.9	78.1	73.9	96.7	95.4	93.4	96.5	94.7	92.5	81.8	77.0	71.2
FR	76.7	76.6	76.4	91.7	91.5	89.7	93.8	93.5	93.5	79.5	79.4	78.7
DeeSIL	75.5	75.1	74.3	92.7	92.5	92.2	94.0	93.7	93.2	66.9	65.8	64.2
REMIND	80.9	80.7	78.2	94.7	93.2	93.0	96.3	95.8	94.7	60.7	60.7	60.7
Joint	92.3			99.2			99.1			91.2		

Results and discussion

Class-Incremental Learning with memory

Top-5 results with herding (\mathcal{T} fixed, $|\mathcal{K}|$ variable)

States	$\mathcal{T} = 10$											
	ILSVRC			VGGFACE2			LANDMARKS			CIFAR-100		
$ \mathcal{K} $	2%	1%	0.5%	2%	1%	0.5%	2%	1%	0.5%	2%	1%	0.5%
iCaRL	79.3	76.5	71.0	96.0	95.3	93.9	95.1	94.0	91.8	66.5	56.1	47.9
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FT+BAL	84.0	80.9	76.5	97.0	95.7	92.4	96.9	95.3	92.2	80.0	74.0	69.0
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LUCIR	79.9	76.4	72.6	97.2	96.9	96.5	97.2	96.6	96.1	79.8	75.4	69.9
BiC	85.5	82.8	79.7	97.3	96.6	95.7	97.9	97.3	96.6	88.8	87.6	83.5
ScAIL	82.0	79.8	76.6	96.5	95.8	95.2	97.3	96.0	94.0	85.6	83.2	79.1
IL2M	80.9	78.1	73.9	96.7	95.4	93.4	96.5	94.7	92.5	81.8	77.0	71.2
FR	76.7	76.6	76.4	91.7	91.5	89.7	93.8	93.5	93.5	79.5	79.4	78.7
DeeSIL	75.5	75.1	74.3	92.7	92.5	92.2	94.0	93.7	93.2	66.9	65.8	64.2
REMIND	80.9	80.7	78.2	94.7	93.2	93.0	96.3	95.8	94.7	60.7	60.7	60.7
Joint	92.3			99.2			99.1			91.2		

Results and discussion

Class-Incremental Learning with memory

Top-5 results with herding (\mathcal{T} fixed, $|\mathcal{K}|$ variable)

States	$\mathcal{T} = 10$											
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$ \mathcal{K} $	2%	1%	0.5%	2%	1%	0.5%	2%	1%	0.5%	2%	1%	0.5%
iCaRL	79.3	76.5	71.0	96.0	95.3	93.9	95.1	94.0	91.8	66.5	56.1	47.9
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BiC	85.5	82.8	79.7	97.3	96.6	95.7	97.9	97.3	96.6	88.8	87.6	83.5
ScAIL	82.0	79.8	76.6	96.5	95.8	95.2	97.3	96.0	94.0	85.6	83.2	79.1
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DeeSIL	75.5	75.1	74.3	92.7	92.5	92.2	94.0	93.7	93.2	66.9	65.8	64.2
REMIND	80.9	80.7	78.2	94.7	93.2	93.0	96.3	95.8	94.7	60.7	60.7	60.7
Joint	92.3			99.2			99.1			91.2		

Results and discussion

Class-Incremental Learning with memory

Top-5 results with herding (\mathcal{T} fixed, $|\mathcal{K}|$ variable)

States	$\mathcal{T} = 10$											
	ILSVRC			VGGFACE2			LANDMARKS			CIFAR-100		
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LUCIR	79.9	76.4	72.6	97.2	96.9	96.5	97.2	96.6	96.1	79.8	75.4	69.9
BiC	85.5	82.8	79.7	97.3	96.6	95.7	97.9	97.3	96.6	88.8	87.6	83.5
ScAIL	82.0	79.8	76.6	96.5	95.8	95.2	97.3	96.0	94.0	85.6	83.2	79.1
IL2M	80.9	78.1	73.9	96.7	95.4	93.4	96.5	94.7	92.5	81.8	77.0	71.2
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DeeSIL	75.5	75.1	74.3	92.7	92.5	92.2	94.0	93.7	93.2	66.9	65.8	64.2
REMIND	80.9	80.7	78.2	94.7	93.2	93.0	96.3	95.8	94.7	60.7	60.7	60.7
Joint	92.3			99.2			99.1			91.2		

Results and discussion

Class-Incremental Learning with memory

Top-5 results with herding (\mathcal{T} fixed, $|\mathcal{K}|$ variable)

States	$\mathcal{T} = 10$											
	ILSVRC			VGGFACE2			LANDMARKS			CIFAR-100		
$ \mathcal{K} $	2%	1%	0.5%	2%	1%	0.5%	2%	1%	0.5%	2%	1%	0.5%
iCaRL	79.3	76.5	71.0	96.0	95.3	93.9	95.1	94.0	91.8	66.5	56.1	47.9
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FT+BAL	84.0	80.9	76.5	97.0	95.7	92.4	96.9	95.3	92.2	80.0	74.0	69.0
FT+th	84.3	82.1	78.3	97.2	96.3	94.8	97.2	95.8	94.0	86.4	83.9	79.1
LUCIR	79.9	76.4	72.6	97.2	96.9	96.5	97.2	96.6	96.1	79.8	75.4	69.9
BiC	85.5	82.8	79.7	97.3	96.6	95.7	97.9	97.3	96.6	88.8	87.6	83.5
ScAIL	82.0	79.8	76.6	96.5	95.8	95.2	97.3	96.0	94.0	85.6	83.2	79.1
IL2M	80.9	78.1	73.9	96.7	95.4	93.4	96.5	94.7	92.5	81.8	77.0	71.2
FR	76.7	76.6	76.4	91.7	91.5	89.7	93.8	93.5	93.5	79.5	79.4	78.7
DeeSIL	75.5	75.1	74.3	92.7	92.5	92.2	94.0	93.7	93.2	66.9	65.8	64.2
REMIND	80.9	80.7	78.2	94.7	93.2	93.0	96.3	95.8	94.7	60.7	60.7	60.7
Joint	92.3			99.2			99.1			91.2		

Results and discussion

Class-Incremental Learning with memory

Top-5 results with herding (\mathcal{T} fixed, $|\mathcal{K}|$ variable)

States	$\mathcal{T} = 10$											
	ILSVRC			VGGFACE2			LANDMARKS			CIFAR-100		
$ \mathcal{K} $	2%	1%	0.5%	2%	1%	0.5%	2%	1%	0.5%	2%	1%	0.5%
iCaRL	79.3	76.5	71.0	96.0	95.3	93.9	95.1	94.0	91.8	66.5	56.1	47.9
FT	79.4	74.4	65.9	96.4	94.5	91.3	96.6	94.7	91.4	82.4	77.9	70.7
FT+init	79.2	76.5	73.0	95.9	95.2	94.6	97.0	95.5	92.7	83.4	80.5	75.2
FT+NEM	81.4	79.0	75.0	96.4	95.4	94.0	96.1	94.6	92.6	85.1	81.7	76.0
FT+BAL	84.0	80.9	76.5	97.0	95.7	92.4	96.9	95.3	92.2	80.0	74.0	69.0
FT+th	84.3	82.1	78.3	97.2	96.3	94.8	97.2	95.8	94.0	86.4	83.9	79.1
LUCIR	79.9	76.4	72.6	97.2	96.9	96.5	97.2	96.6	96.1	79.8	75.4	69.9
BiC	85.5	82.8	79.7	97.3	96.6	95.7	97.9	97.3	96.6	88.8	87.6	83.5
ScAIL	82.0	79.8	76.6	96.5	95.8	95.2	97.3	96.0	94.0	85.6	83.2	79.1
IL2M	80.9	78.1	73.9	96.7	95.4	93.4	96.5	94.7	92.5	81.8	77.0	71.2
FR	76.7	76.6	76.4	91.7	91.5	89.7	93.8	93.5	93.5	79.5	79.4	78.7
DeeSIL	75.5	75.1	74.3	92.7	92.5	92.2	94.0	93.7	93.2	66.9	65.8	64.2
REMIND	80.9	80.7	78.2	94.7	93.2	93.0	96.3	95.8	94.7	60.7	60.7	60.7
Joint	92.3			99.2			99.1			91.2		

Results and discussion

Class-Incremental Learning with memory

Top-5 results with herding ($|\mathcal{K}|$ fixed, \mathcal{T} variable)

States	$ \mathcal{K} = 0.5\%$								G_{IL}	
Dataset	ILSVRC		VGGFACE2		LANDMARKS		CIFAR-100			
\mathcal{T}	20	50	20	50	20	50	20	50		
<i>iCaRL</i>	55.9	45.0	88.5	78.2	86.8	82.4	35.5	35.4	-7.36	
<i>FT</i>	69.4	64.3	91.6	89.2	90.9	89.0	64.3	54.8	-5.19	
<i>FT+init</i>	73.6	67.3	94.6	91.4	91.2	88.5	63.6	44.1	-4.43	
<i>FT+NEM</i>	76.5	69.0	94.0	91.1	91.9	89.9	68.8	55.9	-4.28	
<i>FT+BAL</i>	75.9	67.1	92.3	89.5	91.2	88.9	62.9	54.2	-4.70	
<i>FT+th</i>	78.6	71.2	94.3	91.6	92.9	90.7	71.4	57.9	-3.62	
<i>LUCIR</i>	63.9	55.3	93.5	88.3	93.7	90.5	53.5	47.9	-4.13	
<i>BiC</i>	74.6	63.9	92.3	85.3	94.7	90.5	50.5	19.6	-4.03	
<i>Scall</i>	76.6	70.9	95.0	92.4	92.6	90.4	69.8	51.0	-3.70	
<i>IL2M</i>	70.9	60.6	92.5	88.4	90.8	88.1	61.5	51.0	-4.95	
<i>FR</i>	69.2	58.2	85.8	75.2	89.3	82.8	62.3	33.5	-7.62	
<i>DeeSIL</i>	73.0	58.1	87.2	80.0	90.5	85.1	63.9	44.0	-6.92	
<i>REMIND</i>	73.9	65.0	87.4	80.1	92.8	88.6	52.8	46.4	-6.02	
<i>Joint</i>	92.3		99.2		99.1		91.2		-	

Results and discussion

Class-Incremental Learning with memory

Top-5 results with herding ($|\mathcal{K}|$ fixed, \mathcal{T} variable)

States	$ \mathcal{K} = 0.5\%$								G_{IL}	
Dataset	ILSVRC		VGGFACE2		LANDMARKS		CIFAR-100			
\mathcal{T}	20	50	20	50	20	50	20	50		
<i>iCaRL</i>	55.9	45.0	88.5	78.2	86.8	82.4	35.5	35.4	-7.36	
<i>FT</i>	69.4	64.3	91.6	89.2	90.9	89.0	64.3	54.8	-5.19	
<i>FT+init</i>	73.6	67.3	94.6	91.4	91.2	88.5	63.6	44.1	-4.43	
<i>FT+NEM</i>	76.5	69.0	94.0	91.1	91.9	89.9	68.8	55.9	-4.28	
<i>FT+BAL</i>	75.9	67.1	92.3	89.5	91.2	88.9	62.9	54.2	-4.70	
FT+th	78.6	71.2	94.3	91.6	92.9	90.7	71.4	57.9	-3.62	
<i>LUCIR</i>	63.9	55.3	93.5	88.3	93.7	90.5	53.5	47.9	-4.13	
<i>BiC</i>	74.6	63.9	92.3	85.3	94.7	90.5	50.5	19.6	-4.03	
<i>Scall</i>	76.6	70.9	95.0	92.4	92.6	90.4	69.8	51.0	-3.70	
<i>IL2M</i>	70.9	60.6	92.5	88.4	90.8	88.1	61.5	51.0	-4.95	
<i>FR</i>	69.2	58.2	85.8	75.2	89.3	82.8	62.3	33.5	-7.62	
<i>DeeSIL</i>	73.0	58.1	87.2	80.0	90.5	85.1	63.9	44.0	-6.92	
<i>REMIND</i>	73.9	65.0	87.4	80.1	92.8	88.6	52.8	46.4	-6.02	
<i>Joint</i>	92.3		99.2		99.1		91.2		-	

Results and discussion

Class-Incremental Learning with memory

Top-5 results with herding ($|\mathcal{K}|$ fixed, \mathcal{T} variable)

States	$ \mathcal{K} = 0.5\%$								G_{IL}	
Dataset	ILSVRC		VGGFACE2		LANDMARKS		CIFAR-100			
\mathcal{T}	20	50	20	50	20	50	20	50		
<i>iCaRL</i>	55.9	45.0	88.5	78.2	86.8	82.4	35.5	35.4	-7.36	
<i>FT</i>	69.4	64.3	91.6	89.2	90.9	89.0	64.3	54.8	-5.19	
<i>FT+init</i>	73.6	67.3	94.6	91.4	91.2	88.5	63.6	44.1	-4.43	
<i>FT+NEM</i>	76.5	69.0	94.0	91.1	91.9	89.9	68.8	55.9	-4.28	
<i>FT+BAL</i>	75.9	67.1	92.3	89.5	91.2	88.9	62.9	54.2	-4.70	
<i>FT+th</i>	78.6	71.2	94.3	91.6	92.9	90.7	71.4	57.9	-3.62	
<i>LUCIR</i>	63.9	55.3	93.5	88.3	93.7	90.5	53.5	47.9	-4.13	
<i>BiC</i>	74.6	63.9	92.3	85.3	94.7	90.5	50.5	19.6	-4.03	
<i>ScalL</i>	76.6	70.9	95.0	92.4	92.6	90.4	69.8	51.0	-3.70	
<i>IL2M</i>	70.9	60.6	92.5	88.4	90.8	88.1	61.5	51.0	-4.95	
<i>FR</i>	69.2	58.2	85.8	75.2	89.3	82.8	62.3	33.5	-7.62	
<i>DeeSIL</i>	73.0	58.1	87.2	80.0	90.5	85.1	63.9	44.0	-6.92	
<i>REMIND</i>	73.9	65.0	87.4	80.1	92.8	88.6	52.8	46.4	-6.02	
<i>Joint</i>	92.3		99.2		99.1		91.2		-	

Results and discussion

Class-Incremental Learning with memory

Top-5 results with herding ($|\mathcal{K}|$ fixed, \mathcal{T} variable)

States	$ \mathcal{K} = 0.5\%$								G_{IL}	
Dataset	ILSVRC		VGGFACE2		LANDMARKS		CIFAR-100			
\mathcal{T}	20	50	20	50	20	50	20	50		
<i>iCaRL</i>	55.9	45.0	88.5	78.2	86.8	82.4	35.5	35.4	-7.36	
<i>FT</i>	69.4	64.3	91.6	89.2	90.9	89.0	64.3	54.8	-5.19	
<i>FT+init</i>	73.6	67.3	94.6	91.4	91.2	88.5	63.6	44.1	-4.43	
<i>FT+NEM</i>	76.5	69.0	94.0	91.1	91.9	89.9	68.8	55.9	-4.28	
<i>FT+BAL</i>	75.9	67.1	92.3	89.5	91.2	88.9	62.9	54.2	-4.70	
<i>FT+th</i>	78.6	71.2	94.3	91.6	92.9	90.7	71.4	57.9	-3.62	
<i>LUCIR</i>	63.9	55.3	93.5	88.3	93.7	90.5	53.5	47.9	-4.13	
<i>BiC</i>	74.6	63.9	92.3	85.3	94.7	90.5	50.5	19.6	-4.03	
<i>Scall</i>	76.6	70.9	95.0	92.4	92.6	90.4	69.8	51.0	-3.70	
<i>IL2M</i>	70.9	60.6	92.5	88.4	90.8	88.1	61.5	51.0	-4.95	
<i>FR</i>	69.2	58.2	85.8	75.2	89.3	82.8	62.3	33.5	-7.62	
<i>DeeSIL</i>	73.0	58.1	87.2	80.0	90.5	85.1	63.9	44.0	-6.92	
<i>REMIND</i>	73.9	65.0	87.4	80.1	92.8	88.6	52.8	46.4	-6.02	
<i>Joint</i>	92.3		99.2		99.1		91.2		-	

Results and discussion

Class-Incremental Learning with memory

Top-5 results with herding ($|\mathcal{K}|$ fixed, \mathcal{T} variable)

States	$ \mathcal{K} = 0.5\%$								G_{IL}	
Dataset	ILSVRC		VGGFACE2		LANDMARKS		CIFAR-100			
\mathcal{T}	20	50	20	50	20	50	20	50		
<i>iCaRL</i>	55.9	45.0	88.5	78.2	86.8	82.4	35.5	35.4	-7.36	
<i>FT</i>	69.4	64.3	91.6	89.2	90.9	89.0	64.3	54.8	-5.19	
<i>FT+init</i>	73.6	67.3	94.6	91.4	91.2	88.5	63.6	44.1	-4.43	
<i>FT+NEM</i>	76.5	69.0	94.0	91.1	91.9	89.9	68.8	55.9	-4.28	
<i>FT+BAL</i>	75.9	67.1	92.3	89.5	91.2	88.9	62.9	54.2	-4.70	
<i>FT+th</i>	78.6	71.2	94.3	91.6	92.9	90.7	71.4	57.9	-3.62	
<i>LUCIR</i>	63.9	55.3	93.5	88.3	93.7	90.5	53.5	47.9	-4.13	
<i>BiC</i>	74.6	63.9	92.3	85.3	94.7	90.5	50.5	19.6	-4.03	
<i>Scall</i>	76.6	70.9	95.0	92.4	92.6	90.4	69.8	51.0	-3.70	
<i>IL2M</i>	70.9	60.6	92.5	88.4	90.8	88.1	61.5	51.0	-4.95	
<i>FR</i>	69.2	58.2	85.8	75.2	89.3	82.8	62.3	33.5	-7.62	
<i>DeeSIL</i>	73.0	58.1	87.2	80.0	90.5	85.1	63.9	44.0	-6.92	
<i>REMIND</i>	73.9	65.0	87.4	80.1	92.8	88.6	52.8	46.4	-6.02	
<i>Joint</i>	92.3		99.2		99.1		91.2		-	

Results and discussion

Class-Incremental Learning without memory

Top-5 results without memory

Dataset	ILSVRC			VGGFACE2			LANDMARKS			CIFAR-100			G_{IL}
States \mathcal{T}	10	20	50	10	20	50	10	20	50	10	20	50	
FT	20.6	13.4	7.1	21.3	13.6	7.1	21.3	13.6	7.1	21.3	13.7	17.4	-54.91
<i>LwF</i>	45.3	37.6	27.1	53.3	42.6	30.8	58.8	49.2	35.2	79.5	65.3	39.0	-34.72
FT+init	61.0	44.9	23.8	90.9	64.4	33.1	68.8	49.4	22.2	55.1	40.8	19.9	-28.99
FT+init+L2	51.6	43.3	34.5	76.8	66.8	55.1	61.4	52.5	39.2	47.5	39.3	22.5	-26.80
FT+init+L2+mc	53.6	42.7	35.6	86.9	71.4	53.6	66.2	52.6	37.9	52.6	43.1	18.2	-25.02
<i>SIW(FT)</i>	64.4	54.3	41.4	88.6	84.1	62.6	79.5	64.5	43.2	59.7	44.3	18.4	-19.38
<i>SIW(LwF)</i>	54.0	45.8	35.1	70.4	59.3	45.2	61.0	53.8	42.2	80.0	68.8	44.6	-28.06
<i>LUCIR</i>	57.6	39.4	21.9	91.4	68.2	32.2	87.8	63.7	32.3	57.5	35.3	21.0	-24.75
<i>FR</i>	74.0	66.9	49.2	88.7	83.0	54.4	93.6	88.1	71.2	73.1	54.8	27.4	-16.30
<i>DeeSIL</i>	73.9	67.5	53.9	92.3	87.5	75.1	93.6	91.1	82.1	65.2	63.4	32.3	-9.22
<i>REMIND</i>	62.2	56.3	44.4	86.8	81.4	69.2	84.5	79.6	69.0	52.7	40.5	25.7	-22.00
<i>Deep-SLDA</i>	70.3	64.5	56.0	90.2	85.4	78.2	89.3	86.4	81.3	68.9	64.4	54.5	-15.40
<i>Joint</i>	92.3			99.2			99.1			91.2			-

Results and discussion

Class-Incremental Learning without memory

Top-5 results without memory

Dataset	ILSVRC			VGGFACE2			LANDMARKS			CIFAR-100			G_{IL}
States \mathcal{T}	10	20	50	10	20	50	10	20	50	10	20	50	
FT	20.6	13.4	7.1	21.3	13.6	7.1	21.3	13.6	7.1	21.3	13.7	17.4	-54.91
LwF	45.3	37.6	27.1	53.3	42.6	30.8	58.8	49.2	35.2	79.5	65.3	39.0	-34.72
FT+init	61.0	44.9	23.8	90.9	64.4	33.1	68.8	49.4	22.2	55.1	40.8	19.9	-28.99
FT+init+L2	51.6	43.3	34.5	76.8	66.8	55.1	61.4	52.5	39.2	47.5	39.3	22.5	-26.80
FT+init+L2+mc	53.6	42.7	35.6	86.9	71.4	53.6	66.2	52.6	37.9	52.6	43.1	18.2	-25.02
SIW(FT)	64.4	54.3	41.4	88.6	84.1	62.6	79.5	64.5	43.2	59.7	44.3	18.4	-19.38
SIW(LwF)	54.0	45.8	35.1	70.4	59.3	45.2	61.0	53.8	42.2	80.0	68.8	44.6	-28.06
LUCIR	57.6	39.4	21.9	91.4	68.2	32.2	87.8	63.7	32.3	57.5	35.3	21.0	-24.75
FR	74.0	66.9	49.2	88.7	83.0	54.4	93.6	88.1	71.2	73.1	54.8	27.4	-16.30
DeeSIL	73.9	67.5	53.9	92.3	87.5	75.1	93.6	91.1	82.1	65.2	63.4	32.3	-9.22
REMIND	62.2	56.3	44.4	86.8	81.4	69.2	84.5	79.6	69.0	52.7	40.5	25.7	-22.00
Deep-SLDA	70.3	64.5	56.0	90.2	85.4	78.2	89.3	86.4	81.3	68.9	64.4	54.5	-15.40
Joint	92.3			99.2			99.1			91.2			-

Results and discussion

Class-Incremental Learning without memory

Top-5 results without memory

Dataset	ILSVRC			VGGFACE2			LANDMARKS			CIFAR-100			G_{IL}
States \mathcal{T}	10	20	50	10	20	50	10	20	50	10	20	50	
FT	20.6	13.4	7.1	21.3	13.6	7.1	21.3	13.6	7.1	21.3	13.7	17.4	-54.91
LwF	45.3	37.6	27.1	53.3	42.6	30.8	58.8	49.2	35.2	79.5	65.3	39.0	-34.72
FT+init	61.0	44.9	23.8	90.9	64.4	33.1	68.8	49.4	22.2	55.1	40.8	19.9	-28.99
FT+init+L2	51.6	43.3	34.5	76.8	66.8	55.1	61.4	52.5	39.2	47.5	39.3	22.5	-26.80
FT+init+L2+mc	53.6	42.7	35.6	86.9	71.4	53.6	66.2	52.6	37.9	52.6	43.1	18.2	-25.02
SIW(FT)	64.4	54.3	41.4	88.6	84.1	62.6	79.5	64.5	43.2	59.7	44.3	18.4	-19.38
SIW(LwF)	54.0	45.8	35.1	70.4	59.3	45.2	61.0	53.8	42.2	80.0	68.8	44.6	-28.06
LUCIR	57.6	39.4	21.9	91.4	68.2	32.2	87.8	63.7	32.3	57.5	35.3	21.0	-24.75
FR	74.0	66.9	49.2	88.7	83.0	54.4	93.6	88.1	71.2	73.1	54.8	27.4	-16.30
DeeSIL	73.9	67.5	53.9	92.3	87.5	75.1	93.6	91.1	82.1	65.2	63.4	32.3	-9.22
REMIND	62.2	56.3	44.4	86.8	81.4	69.2	84.5	79.6	69.0	52.7	40.5	25.7	-22.00
Deep-SLDA	70.3	64.5	56.0	90.2	85.4	78.2	89.3	86.4	81.3	68.9	64.4	54.5	-15.40
Joint	92.3			99.2			99.1			91.2			-

Results and discussion

Class-Incremental Learning without memory

Top-5 results without memory

Dataset	ILSVRC			VGGFACE2			LANDMARKS			CIFAR-100			G_{IL}
States \mathcal{T}	10	20	50	10	20	50	10	20	50	10	20	50	
FT	20.6	13.4	7.1	21.3	13.6	7.1	21.3	13.6	7.1	21.3	13.7	17.4	-54.91
<i>LwF</i>	45.3	37.6	27.1	53.3	42.6	30.8	58.8	49.2	35.2	79.5	65.3	39.0	-34.72
FT+init	61.0	44.9	23.8	90.9	64.4	33.1	68.8	49.4	22.2	55.1	40.8	19.9	-28.99
FT+init+L2	51.6	43.3	34.5	76.8	66.8	55.1	61.4	52.5	39.2	47.5	39.3	22.5	-26.80
FT+init+L2+mc	53.6	42.7	35.6	86.9	71.4	53.6	66.2	52.6	37.9	52.6	43.1	18.2	-25.02
<i>SIW(FT)</i>	64.4	54.3	41.4	88.6	84.1	62.6	79.5	64.5	43.2	59.7	44.3	18.4	-19.38
<i>SIW(LwF)</i>	54.0	45.8	35.1	70.4	59.3	45.2	61.0	53.8	42.2	80.0	68.8	44.6	-28.06
<i>LUCIR</i>	57.6	39.4	21.9	91.4	68.2	32.2	87.8	63.7	32.3	57.5	35.3	21.0	-24.75
<i>FR</i>	74.0	66.9	49.2	88.7	83.0	54.4	93.6	88.1	71.2	73.1	54.8	27.4	-16.30
<i>DeeSIL</i>	73.9	67.5	53.9	92.3	87.5	75.1	93.6	91.1	82.1	65.2	63.4	32.3	-9.22
<i>REMIND</i>	62.2	56.3	44.4	86.8	81.4	69.2	84.5	79.6	69.0	52.7	40.5	25.7	-22.00
<i>Deep-SLDA</i>	70.3	64.5	56.0	90.2	85.4	78.2	89.3	86.4	81.3	68.9	64.4	54.5	-15.40
<i>Joint</i>	92.3			99.2			99.1			91.2			-

Results and discussion

Class-Incremental Learning without memory

Top-5 results without memory

Dataset	ILSVRC			VGGFACE2			LANDMARKS			CIFAR-100			G_{IL}
States \mathcal{T}	10	20	50	10	20	50	10	20	50	10	20	50	
FT	20.6	13.4	7.1	21.3	13.6	7.1	21.3	13.6	7.1	21.3	13.7	17.4	-54.91
<i>LwF</i>	45.3	37.6	27.1	53.3	42.6	30.8	58.8	49.2	35.2	79.5	65.3	39.0	-34.72
FT+init	61.0	44.9	23.8	90.9	64.4	33.1	68.8	49.4	22.2	55.1	40.8	19.9	-28.99
FT+init+L2	51.6	43.3	34.5	76.8	66.8	55.1	61.4	52.5	39.2	47.5	39.3	22.5	-26.80
FT+init+L2+mc	53.6	42.7	35.6	86.9	71.4	53.6	66.2	52.6	37.9	52.6	43.1	18.2	-25.02
<i>SIW(FT)</i>	64.4	54.3	41.4	88.6	84.1	62.6	79.5	64.5	43.2	59.7	44.3	18.4	-19.38
<i>SIW(LwF)</i>	54.0	45.8	35.1	70.4	59.3	45.2	61.0	53.8	42.2	80.0	68.8	44.6	-28.06
<i>LUCIR</i>	57.6	39.4	21.9	91.4	68.2	32.2	87.8	63.7	32.3	57.5	35.3	21.0	-24.75
<i>FR</i>	74.0	66.9	49.2	88.7	83.0	54.4	93.6	88.1	71.2	73.1	54.8	27.4	-16.30
<i>DeeSIL</i>	73.9	67.5	53.9	92.3	87.5	75.1	93.6	91.1	82.1	65.2	63.4	32.3	-9.22
<i>REMIND</i>	62.2	56.3	44.4	86.8	81.4	69.2	84.5	79.6	69.0	52.7	40.5	25.7	-22.00
<i>Deep-SLDA</i>	70.3	64.5	56.0	90.2	85.4	78.2	89.3	86.4	81.3	68.9	64.4	54.5	-15.40
<i>Joint</i>	92.3			99.2			99.1			91.2			-

Results and discussion

Class-Incremental Learning without memory

Top-5 results without memory

Dataset	ILSVRC			VGGFACE2			LANDMARKS			CIFAR-100			G_{IL}
States \mathcal{T}	10	20	50	10	20	50	10	20	50	10	20	50	
FT	20.6	13.4	7.1	21.3	13.6	7.1	21.3	13.6	7.1	21.3	13.7	17.4	-54.91
<i>LwF</i>	45.3	37.6	27.1	53.3	42.6	30.8	58.8	49.2	35.2	79.5	65.3	39.0	-34.72
FT+init	61.0	44.9	23.8	90.9	64.4	33.1	68.8	49.4	22.2	55.1	40.8	19.9	-28.99
FT+init+L2	51.6	43.3	34.5	76.8	66.8	55.1	61.4	52.5	39.2	47.5	39.3	22.5	-26.80
FT+init+L2+mc	53.6	42.7	35.6	86.9	71.4	53.6	66.2	52.6	37.9	52.6	43.1	18.2	-25.02
<i>SIW(FT)</i>	64.4	54.3	41.4	88.6	84.1	62.6	79.5	64.5	43.2	59.7	44.3	18.4	-19.38
<i>SIW(LwF)</i>	54.0	45.8	35.1	70.4	59.3	45.2	61.0	53.8	42.2	80.0	68.8	44.6	-28.06
<i>LUCIR</i>	57.6	39.4	21.9	91.4	68.2	32.2	87.8	63.7	32.3	57.5	35.3	21.0	-24.75
<i>FR</i>	74.0	66.9	49.2	88.7	83.0	54.4	93.6	88.1	71.2	73.1	54.8	27.4	-16.30
<i>DeeSIL</i>	73.9	67.5	53.9	92.3	87.5	75.1	93.6	91.1	82.1	65.2	63.4	32.3	-9.22
<i>REMIND</i>	62.2	56.3	44.4	86.8	81.4	69.2	84.5	79.6	69.0	52.7	40.5	25.7	-22.00
<i>Deep-SLDA</i>	70.3	64.5	56.0	90.2	85.4	78.2	89.3	86.4	81.3	68.9	64.4	54.5	-15.40
<i>Joint</i>	92.3			99.2			99.1			91.2			-

Results and discussion

Class-Incremental Learning without memory

Top-1 results without memory

Method States	CIFAR-100			BIRDS-100			FOOD-100		
	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$
LwF	53.0	44.0	29.1	53.7	41.8	30.1	42.9	31.8	22.2
w/ BiC	54.0 + 1.0	45.5 + 1.5	30.8 + 1.7	54.6 + 0.9	43.1 + 1.3	31.8 + 1.7	43.4 + 0.5	32.6 + 0.8	23.8 + 1.6
w/ AdBiC	54.3 + 1.3	46.4 + 2.4	32.3 + 3.2	55.0 + 1.3	44.0 + 2.2	32.8 + 2.7	43.5 + 0.6	33.3 + 1.5	24.7 + 2.5
w/ AdBiC + ⊕	54.9 + 1.9	47.3 + 3.3	32.6 + 3.5	55.8 + 2.1	44.8 + 3.0	33.3 + 3.2	44.0 + 1.1	34.2 + 2.4	25.3 + 3.1
LUCIR	50.1	33.7	19.5	50.8	31.4	17.9	44.2	26.4	15.5
w/ BiC	52.5 + 2.4	37.1 + 3.4	22.4 + 2.9	56.0 + 5.2	37.7 + 6.3	20.6 + 2.7	49.9 + 5.7	31.5 + 5.1	17.2 + 1.7
w/ AdBiC	54.8 + 4.7	42.2 + 8.5	28.4 + 8.9	58.5 + 7.7	45.4 + 14.0	27.3 + 9.4	52.0 + 7.8	37.1 + 10.7	17.7 + 2.2
w/ AdBiC + ⊕	55.5 + 5.4	43.6 + 9.9	31.2 + 11.7	59.0 + 8.2	46.0 + 14.6	28.8 + 10.9	52.6 + 8.4	38.2 + 11.8	21.0 + 5.5
SIW	29.9	22.7	14.8	30.6	23.2	14.9	29.4	21.6	14.1
w/ BiC	31.4 + 1.5	22.8 + 0.1	14.7 - 0.1	32.8 + 2.2	22.7 - 0.5	12.8 - 2.1	29.1 - 0.3	20.3 - 1.3	12.1 - 2.0
w/ AdBiC	31.7 + 1.8	24.1 + 1.4	15.8 + 1.0	33.0 + 2.4	25.2 + 2.0	15.3 + 0.4	30.9 + 1.5	21.3 - 0.3	14.5 + 0.4
w/ AdBiC + ⊕	32.8 + 2.9	25.0 + 2.3	16.5 + 1.7	34.4 + 3.8	26.2 + 3.0	16.3 + 1.4	31.5 + 2.1	22.6 + 1.0	15.1 + 1.0
FT+	28.9	22.6	14.5	29.7	23.3	13.5	28.7	21.1	13.3
w/ BiC	30.7 + 1.8	22.5 - 0.1	14.8 + 0.3	32.3 + 2.6	22.5 - 0.8	12.4 - 1.1	28.6 - 0.1	20.6 - 0.5	11.8 - 1.5
w/ AdBiC	31.9 + 3.0	23.6 + 1.0	15.0 + 0.5	34.0 + 4.3	25.0 + 1.7	14.2 + 0.7	30.8 + 2.1	22.2 + 1.1	14.2 + 0.9
w/ AdBiC + ⊕	32.5 + 3.6	24.6 + 2.0	15.9 + 1.4	34.5 + 4.8	25.7 + 2.4	15.4 + 1.9	31.3 + 2.6	22.7 + 1.6	14.5 + 1.2
Joint	72.7			80.9			71.03		

gains, losses

Results and discussion

Class-Incremental Learning without memory

Top-1 results without memory

Method States	CIFAR-100			BIRDS-100			FOOD-100		
	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$
LwF	53.0	44.0	29.1	53.7	41.8	30.1	42.9	31.8	22.2
w/ BiC	54.0 + 1.0	45.5 + 1.5	30.8 + 1.7	54.6 + 0.9	43.1 + 1.3	31.8 + 1.7	43.4 + 0.5	32.6 + 0.8	23.8 + 1.6
w/ AdBiC	54.3 + 1.3	46.4 + 2.4	32.3 + 3.2	55.0 + 1.3	44.0 + 2.2	32.8 + 2.7	43.5 + 0.6	33.3 + 1.5	24.7 + 2.5
w/ AdBiC + ⊕	54.9 + 1.9	47.3 + 3.3	32.6 + 3.5	55.8 + 2.1	44.8 + 3.0	33.3 + 3.2	44.0 + 1.1	34.2 + 2.4	25.3 + 3.1
LUCIR	50.1	33.7	19.5	50.8	31.4	17.9	44.2	26.4	15.5
w/ BiC	52.5 + 2.4	37.1 + 3.4	22.4 + 2.9	56.0 + 5.2	37.7 + 6.3	20.6 + 2.7	49.9 + 5.7	31.5 + 5.1	17.2 + 1.7
w/ AdBiC	54.8 + 4.7	42.2 + 8.5	28.4 + 8.9	58.5 + 7.7	45.4 + 14.0	27.3 + 9.4	52.0 + 7.8	37.1 + 10.7	17.7 + 2.2
w/ AdBiC + ⊕	55.5 + 5.4	43.6 + 9.9	31.2 + 11.7	59.0 + 8.2	46.0 + 14.6	28.8 + 10.9	52.6 + 8.4	38.2 + 11.8	21.0 + 5.5
SIW	29.9	22.7	14.8	30.6	23.2	14.9	29.4	21.6	14.1
w/ BiC	31.4 + 1.5	22.8 + 0.1	14.7 - 0.1	32.8 + 2.2	22.7 - 0.5	12.8 - 2.1	29.1 - 0.3	20.3 - 1.3	12.1 - 2.0
w/ AdBiC	31.7 + 1.8	24.1 + 1.4	15.8 + 1.0	33.0 + 2.4	25.2 + 2.0	15.3 + 0.4	30.9 + 1.5	21.3 - 0.3	14.5 + 0.4
w/ AdBiC + ⊕	32.8 + 2.9	25.0 + 2.3	16.5 + 1.7	34.4 + 3.8	26.2 + 3.0	16.3 + 1.4	31.5 + 2.1	22.6 + 1.0	15.1 + 1.0
FT+	28.9	22.6	14.5	29.7	23.3	13.5	28.7	21.1	13.3
w/ BiC	30.7 + 1.8	22.5 - 0.1	14.8 + 0.3	32.3 + 2.6	22.5 - 0.8	12.4 - 1.1	28.6 - 0.1	20.6 - 0.5	11.8 - 1.5
w/ AdBiC	31.9 + 3.0	23.6 + 1.0	15.0 + 0.5	34.0 + 4.3	25.0 + 1.7	14.2 + 0.7	30.8 + 2.1	22.2 + 1.1	14.2 + 0.9
w/ AdBiC + ⊕	32.5 + 3.6	24.6 + 2.0	15.9 + 1.4	34.5 + 4.8	25.7 + 2.4	15.4 + 1.9	31.3 + 2.6	22.7 + 1.6	14.5 + 1.2
Joint		72.7			80.9			71.03	

gains, losses

Results and discussion

Class-Incremental Learning without memory

Top-1 results without memory

Method States	CIFAR-100			BIRDS-100			FOOD-100		
	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$
LwF	53.0	44.0	29.1	53.7	41.8	30.1	42.9	31.8	22.2
w/ BiC	54.0 + 1.0	45.5 + 1.5	30.8 + 1.7	54.6 + 0.9	43.1 + 1.3	31.8 + 1.7	43.4 + 0.5	32.6 + 0.8	23.8 + 1.6
w/ AdBiC	54.3 + 1.3	46.4 + 2.4	32.3 + 3.2	55.0 + 1.3	44.0 + 2.2	32.8 + 2.7	43.5 + 0.6	33.3 + 1.5	24.7 + 2.5
w/ AdBiC + ⊙	54.9 + 1.9	47.3 + 3.3	32.6 + 3.5	55.8 + 2.1	44.8 + 3.0	33.3 + 3.2	44.0 + 1.1	34.2 + 2.4	25.3 + 3.1
LUCIR	50.1	33.7	19.5	50.8	31.4	17.9	44.2	26.4	15.5
w/ BiC	52.5 + 2.4	37.1 + 3.4	22.4 + 2.9	56.0 + 5.2	37.7 + 6.3	20.6 + 2.7	49.9 + 5.7	31.5 + 5.1	17.2 + 1.7
w/ AdBiC	54.8 + 4.7	42.2 + 8.5	28.4 + 8.9	58.5 + 7.7	45.4 + 14.0	27.3 + 9.4	52.0 + 7.8	37.1 + 10.7	17.7 + 2.2
w/ AdBiC + ⊙	55.5 + 5.4	43.6 + 9.9	31.2 + 11.7	59.0 + 8.2	46.0 + 14.6	28.8 + 10.9	52.6 + 8.4	38.2 + 11.8	21.0 + 5.5
SIW	29.9	22.7	14.8	30.6	23.2	14.9	29.4	21.6	14.1
w/ BiC	31.4 + 1.5	22.8 + 0.1	14.7 - 0.1	32.8 + 2.2	22.7 - 0.5	12.8 - 2.1	29.1 - 0.3	20.3 - 1.3	12.1 - 2.0
w/ AdBiC	31.7 + 1.8	24.1 + 1.4	15.8 + 1.0	33.0 + 2.4	25.2 + 2.0	15.3 + 0.4	30.9 + 1.5	21.3 - 0.3	14.5 + 0.4
w/ AdBiC + ⊙	32.8 + 2.9	25.0 + 2.3	16.5 + 1.7	34.4 + 3.8	26.2 + 3.0	16.3 + 1.4	31.5 + 2.1	22.6 + 1.0	15.1 + 1.0
FT+	28.9	22.6	14.5	29.7	23.3	13.5	28.7	21.1	13.3
w/ BiC	30.7 + 1.8	22.5 - 0.1	14.8 + 0.3	32.3 + 2.6	22.5 - 0.8	12.4 - 1.1	28.6 - 0.1	20.6 - 0.5	11.8 - 1.5
w/ AdBiC	31.9 + 3.0	23.6 + 1.0	15.0 + 0.5	34.0 + 4.3	25.0 + 1.7	14.2 + 0.7	30.8 + 2.1	22.2 + 1.1	14.2 + 0.9
w/ AdBiC + ⊙	32.5 + 3.6	24.6 + 2.0	15.9 + 1.4	34.5 + 4.8	25.7 + 2.4	15.4 + 1.9	31.3 + 2.6	22.7 + 1.6	14.5 + 1.2
Joint	72.7			80.9			71.03		

gains, losses

Results and discussion

Class-Incremental Learning without memory

Top-1 results without memory

Method States	CIFAR-100			BIRDS-100			FOOD-100		
	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$
LwF	53.0	44.0	29.1	53.7	41.8	30.1	42.9	31.8	22.2
w/ BiC	54.0 + 1.0	45.5 + 1.5	30.8 + 1.7	54.6 + 0.9	43.1 + 1.3	31.8 + 1.7	43.4 + 0.5	32.6 + 0.8	23.8 + 1.6
w/ AdBiC	54.3 + 1.3	46.4 + 2.4	32.3 + 3.2	55.0 + 1.3	44.0 + 2.2	32.8 + 2.7	43.5 + 0.6	33.3 + 1.5	24.7 + 2.5
w/ AdBiC + ○	54.9 + 1.9	47.3 + 3.3	32.6 + 3.5	55.8 + 2.1	44.8 + 3.0	33.3 + 3.2	44.0 + 1.1	34.2 + 2.4	25.3 + 3.1
LUCIR	50.1	33.7	19.5	50.8	31.4	17.9	44.2	26.4	15.5
w/ BiC	52.5 + 2.4	37.1 + 3.4	22.4 + 2.9	56.0 + 5.2	37.7 + 6.3	20.6 + 2.7	49.9 + 5.7	31.5 + 5.1	17.2 + 1.7
w/ AdBiC	54.8 + 4.7	42.2 + 8.5	28.4 + 8.9	58.5 + 7.7	45.4 + 14.0	27.3 + 9.4	52.0 + 7.8	37.1 + 10.7	17.7 + 2.2
w/ AdBiC + ○	55.5 + 5.4	43.6 + 9.9	31.2 + 11.7	59.0 + 8.2	46.0 + 14.6	28.8 + 10.9	52.6 + 8.4	38.2 + 11.8	21.0 + 5.5
SIW	29.9	22.7	14.8	30.6	23.2	14.9	29.4	21.6	14.1
w/ BiC	31.4 + 1.5	22.8 + 0.1	14.7 - 0.1	32.8 + 2.2	22.7 - 0.5	12.8 - 2.1	29.1 - 0.3	20.3 - 1.3	12.1 - 2.0
w/ AdBiC	31.7 + 1.8	24.1 + 1.4	15.8 + 1.0	33.0 + 2.4	25.2 + 2.0	15.3 + 0.4	30.9 + 1.5	21.3 - 0.3	14.5 + 0.4
w/ AdBiC + ○	32.8 + 2.9	25.0 + 2.3	16.5 + 1.7	34.4 + 3.8	26.2 + 3.0	16.3 + 1.4	31.5 + 2.1	22.6 + 1.0	15.1 + 1.0
FT+	28.9	22.6	14.5	29.7	23.3	13.5	28.7	21.1	13.3
w/ BiC	30.7 + 1.8	22.5 - 0.1	14.8 + 0.3	32.3 + 2.6	22.5 - 0.8	12.4 - 1.1	28.6 - 0.1	20.6 - 0.5	11.8 - 1.5
w/ AdBiC	31.9 + 3.0	23.6 + 1.0	15.0 + 0.5	34.0 + 4.3	25.0 + 1.7	14.2 + 0.7	30.8 + 2.1	22.2 + 1.1	14.2 + 0.9
w/ AdBiC + ○	32.5 + 3.6	24.6 + 2.0	15.9 + 1.4	34.5 + 4.8	25.7 + 2.4	15.4 + 1.9	31.3 + 2.6	22.7 + 1.6	14.5 + 1.2
Joint	72.7			80.9			71.03		

gains, losses

Results and discussion

Class-Incremental Learning without memory

Top-1 results without memory

Method States	CIFAR-100			BIRDS-100			FOOD-100		
	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$
LwF	53.0	44.0	29.1	53.7	41.8	30.1	42.9	31.8	22.2
w/ BiC	54.0 + 1.0	45.5 + 1.5	30.8 + 1.7	54.6 + 0.9	43.1 + 1.3	31.8 + 1.7	43.4 + 0.5	32.6 + 0.8	23.8 + 1.6
w/ AdBiC	54.3 + 1.3	46.4 + 2.4	32.3 + 3.2	55.0 + 1.3	44.0 + 2.2	32.8 + 2.7	43.5 + 0.6	33.3 + 1.5	24.7 + 2.5
w/ AdBiC + ○	54.9 + 1.9	47.3 + 3.3	32.6 + 3.5	55.8 + 2.1	44.8 + 3.0	33.3 + 3.2	44.0 + 1.1	34.2 + 2.4	25.3 + 3.1
LUCIR	50.1	33.7	19.5	50.8	31.4	17.9	44.2	26.4	15.5
w/ BiC	52.5 + 2.4	37.1 + 3.4	22.4 + 2.9	56.0 + 5.2	37.7 + 6.3	20.6 + 2.7	49.9 + 5.7	31.5 + 5.1	17.2 + 1.7
w/ AdBiC	54.8 + 4.7	42.2 + 8.5	28.4 + 8.9	58.5 + 7.7	45.4 + 14.0	27.3 + 9.4	52.0 + 7.8	37.1 + 10.7	17.7 + 2.2
w/ AdBiC + ○	55.5 + 5.4	43.6 + 9.9	31.2 + 11.7	59.0 + 8.2	46.0 + 14.6	28.8 + 10.9	52.6 + 8.4	38.2 + 11.8	21.0 + 5.5
SIW	29.9	22.7	14.8	30.6	23.2	14.9	29.4	21.6	14.1
w/ BiC	31.4 + 1.5	22.8 + 0.1	14.7 - 0.1	32.8 + 2.2	22.7 - 0.5	12.8 - 2.1	29.1 - 0.3	20.3 - 1.3	12.1 - 2.0
w/ AdBiC	31.7 + 1.8	24.1 + 1.4	15.8 + 1.0	33.0 + 2.4	25.2 + 2.0	15.3 + 0.4	30.9 + 1.5	21.3 - 0.3	14.5 + 0.4
w/ AdBiC + ○	32.8 + 2.9	25.0 + 2.3	16.5 + 1.7	34.4 + 3.8	26.2 + 3.0	16.3 + 1.4	31.5 + 2.1	22.6 + 1.0	15.1 + 1.0
FT+	28.9	22.6	14.5	29.7	23.3	13.5	28.7	21.1	13.3
w/ BiC	30.7 + 1.8	22.5 - 0.1	14.8 + 0.3	32.3 + 2.6	22.5 - 0.8	12.4 - 1.1	28.6 - 0.1	20.6 - 0.5	11.8 - 1.5
w/ AdBiC	31.9 + 3.0	23.6 + 1.0	15.0 + 0.5	34.0 + 4.3	25.0 + 1.7	14.2 + 0.7	30.8 + 2.1	22.2 + 1.1	14.2 + 0.9
w/ AdBiC + ○	32.5 + 3.6	24.6 + 2.0	15.9 + 1.4	34.5 + 4.8	25.7 + 2.4	15.4 + 1.9	31.3 + 2.6	22.7 + 1.6	14.5 + 1.2
Joint	72.7			80.9			71.03		

gains, losses

Results and discussion

Class-Incremental Learning without memory

Top-1 results without memory

Method States	CIFAR-100			BIRDS-100			FOOD-100		
	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$
LwF	53.0	44.0	29.1	53.7	41.8	30.1	42.9	31.8	22.2
w/ BiC	54.0 + 1.0	45.5 + 1.5	30.8 + 1.7	54.6 + 0.9	43.1 + 1.3	31.8 + 1.7	43.4 + 0.5	32.6 + 0.8	23.8 + 1.6
w/ AdBiC	54.3 + 1.3	46.4 + 2.4	32.3 + 3.2	55.0 + 1.3	44.0 + 2.2	32.8 + 2.7	43.5 + 0.6	33.3 + 1.5	24.7 + 2.5
w/ AdBiC + ⊕	54.9 + 1.9	47.3 + 3.3	32.6 + 3.5	55.8 + 2.1	44.8 + 3.0	33.3 + 3.2	44.0 + 1.1	34.2 + 2.4	25.3 + 3.1
LUCIR	50.1	33.7	19.5	50.8	31.4	17.9	44.2	26.4	15.5
w/ BiC	52.5 + 2.4	37.1 + 3.4	22.4 + 2.9	56.0 + 5.2	37.7 + 6.3	20.6 + 2.7	49.9 + 5.7	31.5 + 5.1	17.2 + 1.7
w/ AdBiC	54.8 + 4.7	42.2 + 8.5	28.4 + 8.9	58.5 + 7.7	45.4 + 14.0	27.3 + 9.4	52.0 + 7.8	37.1 + 10.7	17.7 + 2.2
w/ AdBiC + ⊕	55.5 + 5.4	43.6 + 9.9	31.2 + 11.7	59.0 + 8.2	46.0 + 14.6	28.8 + 10.9	52.6 + 8.4	38.2 + 11.8	21.0 + 5.5
SIW	29.9	22.7	14.8	30.6	23.2	14.9	29.4	21.6	14.1
w/ BiC	31.4 + 1.5	22.8 + 0.1	14.7 - 0.1	32.8 + 2.2	22.7 - 0.5	12.8 - 2.1	29.1 - 0.3	20.3 - 1.3	12.1 - 2.0
w/ AdBiC	31.7 + 1.8	24.1 + 1.4	15.8 + 1.0	33.0 + 2.4	25.2 + 2.0	15.3 + 0.4	30.9 + 1.5	21.3 - 0.3	14.5 + 0.4
w/ AdBiC + ⊕	32.8 + 2.9	25.0 + 2.3	16.5 + 1.7	34.4 + 3.8	26.2 + 3.0	16.3 + 1.4	31.5 + 2.1	22.6 + 1.0	15.1 + 1.0
FT+	28.9	22.6	14.5	29.7	23.3	13.5	28.7	21.1	13.3
w/ BiC	30.7 + 1.8	22.5 - 0.1	14.8 + 0.3	32.3 + 2.6	22.5 - 0.8	12.4 - 1.1	28.6 - 0.1	20.6 - 0.5	11.8 - 1.5
w/ AdBiC	31.9 + 3.0	23.6 + 1.0	15.0 + 0.5	34.0 + 4.3	25.0 + 1.7	14.2 + 0.7	30.8 + 2.1	22.2 + 1.1	14.2 + 0.9
w/ AdBiC + ⊕	32.5 + 3.6	24.6 + 2.0	15.9 + 1.4	34.5 + 4.8	25.7 + 2.4	15.4 + 1.9	31.3 + 2.6	22.7 + 1.6	14.5 + 1.2
Joint		72.7			80.9			71.03	

gains, losses

Results and discussion

Class-Incremental Learning without memory

Top-1 results without memory

Method States	CIFAR-100			BIRDS-100			FOOD-100		
	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$
LwF	53.0	44.0	29.1	53.7	41.8	30.1	42.9	31.8	22.2
w/ BiC	54.0 + 1.0	45.5 + 1.5	30.8 + 1.7	54.6 + 0.9	43.1 + 1.3	31.8 + 1.7	43.4 + 0.5	32.6 + 0.8	23.8 + 1.6
w/ AdBiC	54.3 + 1.3	46.4 + 2.4	32.3 + 3.2	55.0 + 1.3	44.0 + 2.2	32.8 + 2.7	43.5 + 0.6	33.3 + 1.5	24.7 + 2.5
w/ AdBiC + ⊕	54.9 + 1.9	47.3 + 3.3	32.6 + 3.5	55.8 + 2.1	44.8 + 3.0	33.3 + 3.2	44.0 + 1.1	34.2 + 2.4	25.3 + 3.1
LUCIR	50.1	33.7	19.5	50.8	31.4	17.9	44.2	26.4	15.5
w/ BiC	52.5 + 2.4	37.1 + 3.4	22.4 + 2.9	56.0 + 5.2	37.7 + 6.3	20.6 + 2.7	49.9 + 5.7	31.5 + 5.1	17.2 + 1.7
w/ AdBiC	54.8 + 4.7	42.2 + 8.5	28.4 + 8.9	58.5 + 7.7	45.4 + 14.0	27.3 + 9.4	52.0 + 7.8	37.1 + 10.7	17.7 + 2.2
w/ AdBiC + ⊕	55.5 + 5.4	43.6 + 9.9	31.2 + 11.7	59.0 + 8.2	46.0 + 14.6	28.8 + 10.9	52.6 + 8.4	38.2 + 11.8	21.0 + 5.5
SIW	29.9	22.7	14.8	30.6	23.2	14.9	29.4	21.6	14.1
w/ BiC	31.4 + 1.5	22.8 + 0.1	14.7 - 0.1	32.8 + 2.2	22.7 - 0.5	12.8 - 2.1	29.1 - 0.3	20.3 - 1.3	12.1 - 2.0
w/ AdBiC	31.7 + 1.8	24.1 + 1.4	15.8 + 1.0	33.0 + 2.4	25.2 + 2.0	15.3 + 0.4	30.9 + 1.5	21.3 - 0.3	14.5 + 0.4
w/ AdBiC + ⊕	32.8 + 2.9	25.0 + 2.3	16.5 + 1.7	34.4 + 3.8	26.2 + 3.0	16.3 + 1.4	31.5 + 2.1	22.6 + 1.0	15.1 + 1.0
FT+	28.9	22.6	14.5	29.7	23.3	13.5	28.7	21.1	13.3
w/ BiC	30.7 + 1.8	22.5 - 0.1	14.8 + 0.3	32.3 + 2.6	22.5 - 0.8	12.4 - 1.1	28.6 - 0.1	20.6 - 0.5	11.8 - 1.5
w/ AdBiC	31.9 + 3.0	23.6 + 1.0	15.0 + 0.5	34.0 + 4.3	25.0 + 1.7	14.2 + 0.7	30.8 + 2.1	22.2 + 1.1	14.2 + 0.9
w/ AdBiC + ⊕	32.5 + 3.6	24.6 + 2.0	15.9 + 1.4	34.5 + 4.8	25.7 + 2.4	15.4 + 1.9	31.3 + 2.6	22.7 + 1.6	14.5 + 1.2
Joint		72.7			80.9			71.03	

gains, losses

Results and discussion

Class-Incremental Learning without memory

Top-1 results without memory

Method States	CIFAR-100			BIRDS-100			FOOD-100		
	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$
LwF	53.0	44.0	29.1	53.7	41.8	30.1	42.9	31.8	22.2
w/ BiC	54.0 + 1.0	45.5 + 1.5	30.8 + 1.7	54.6 + 0.9	43.1 + 1.3	31.8 + 1.7	43.4 + 0.5	32.6 + 0.8	23.8 + 1.6
w/ AdBiC	54.3 + 1.3	46.4 + 2.4	32.3 + 3.2	55.0 + 1.3	44.0 + 2.2	32.8 + 2.7	43.5 + 0.6	33.3 + 1.5	24.7 + 2.5
w/ AdBiC + ○	54.9 + 1.9	47.3 + 3.3	32.6 + 3.5	55.8 + 2.1	44.8 + 3.0	33.3 + 3.2	44.0 + 1.1	34.2 + 2.4	25.3 + 3.1
LUCIR	50.1	33.7	19.5	50.8	31.4	17.9	44.2	26.4	15.5
w/ BiC	52.5 + 2.4	37.1 + 3.4	22.4 + 2.9	56.0 + 5.2	37.7 + 6.3	20.6 + 2.7	49.9 + 5.7	31.5 + 5.1	17.2 + 1.7
w/ AdBiC	54.8 + 4.7	42.2 + 8.5	28.4 + 8.9	58.5 + 7.7	45.4 + 14.0	27.3 + 9.4	52.0 + 7.8	37.1 + 10.7	17.7 + 2.2
w/ AdBiC + ○	55.5 + 5.4	43.6 + 9.9	31.2 + 11.7	59.0 + 8.2	46.0 + 14.6	28.8 + 10.9	52.6 + 8.4	38.2 + 11.8	21.0 + 5.5
SIW	29.9	22.7	14.8	30.6	23.2	14.9	29.4	21.6	14.1
w/ BiC	31.4 + 1.5	22.8 + 0.1	14.7 - 0.1	32.8 + 2.2	22.7 - 0.5	12.8 - 2.1	29.1 - 0.3	20.3 - 1.3	12.1 - 2.0
w/ AdBiC	31.7 + 1.8	24.1 + 1.4	15.8 + 1.0	33.0 + 2.4	25.2 + 2.0	15.3 + 0.4	30.9 + 1.5	21.3 - 0.3	14.5 + 0.4
w/ AdBiC + ○	32.8 + 2.9	25.0 + 2.3	16.5 + 1.7	34.4 + 3.8	26.2 + 3.0	16.3 + 1.4	31.5 + 2.1	22.6 + 1.0	15.1 + 1.0
FT+	28.9	22.6	14.5	29.7	23.3	13.5	28.7	21.1	13.3
w/ BiC	30.7 + 1.8	22.5 - 0.1	14.8 + 0.3	32.3 + 2.6	22.5 - 0.8	12.4 - 1.1	28.6 - 0.1	20.6 - 0.5	11.8 - 1.5
w/ AdBiC	31.9 + 3.0	23.6 + 1.0	15.0 + 0.5	34.0 + 4.3	25.0 + 1.7	14.2 + 0.7	30.8 + 2.1	22.2 + 1.1	14.2 + 0.9
w/ AdBiC + ○	32.5 + 3.6	24.6 + 2.0	15.9 + 1.4	34.5 + 4.8	25.7 + 2.4	15.4 + 1.9	31.3 + 2.6	22.7 + 1.6	14.5 + 1.2
Joint	72.7			80.9			71.03		

gains, losses

Results and discussion

Class-Incremental Learning without memory

Top-1 results without memory

Method States	CIFAR-100			BIRDS-100			FOOD-100		
	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$
LwF	53.0	44.0	29.1	53.7	41.8	30.1	42.9	31.8	22.2
w/ BiC	54.0 + 1.0	45.5 + 1.5	30.8 + 1.7	54.6 + 0.9	43.1 + 1.3	31.8 + 1.7	43.4 + 0.5	32.6 + 0.8	23.8 + 1.6
w/ AdBiC	54.3 + 1.3	46.4 + 2.4	32.3 + 3.2	55.0 + 1.3	44.0 + 2.2	32.8 + 2.7	43.5 + 0.6	33.3 + 1.5	24.7 + 2.5
w/ AdBiC + ⊕	54.9 + 1.9	47.3 + 3.3	32.6 + 3.5	55.8 + 2.1	44.8 + 3.0	33.3 + 3.2	44.0 + 1.1	34.2 + 2.4	25.3 + 3.1
LUCIR	50.1	33.7	19.5	50.8	31.4	17.9	44.2	26.4	15.5
w/ BiC	52.5 + 2.4	37.1 + 3.4	22.4 + 2.9	56.0 + 5.2	37.7 + 6.3	20.6 + 2.7	49.9 + 5.7	31.5 + 5.1	17.2 + 1.7
w/ AdBiC	54.8 + 4.7	42.2 + 8.5	28.4 + 8.9	58.5 + 7.7	45.4 + 14.0	27.3 + 9.4	52.0 + 7.8	37.1 + 10.7	17.7 + 2.2
w/ AdBiC + ⊕	55.5 + 5.4	43.6 + 9.9	31.2 + 11.7	59.0 + 8.2	46.0 + 14.6	28.8 + 10.9	52.6 + 8.4	38.2 + 11.8	21.0 + 5.5
SIW	29.9	22.7	14.8	30.6	23.2	14.9	29.4	21.6	14.1
w/ BiC	31.4 + 1.5	22.8 + 0.1	14.7 - 0.1	32.8 + 2.2	22.7 - 0.5	12.8 - 2.1	29.1 - 0.3	20.3 - 1.3	12.1 - 2.0
w/ AdBiC	31.7 + 1.8	24.1 + 1.4	15.8 + 1.0	33.0 + 2.4	25.2 + 2.0	15.3 + 0.4	30.9 + 1.5	21.3 - 0.3	14.5 + 0.4
w/ AdBiC + ⊕	32.8 + 2.9	25.0 + 2.3	16.5 + 1.7	34.4 + 3.8	26.2 + 3.0	16.3 + 1.4	31.5 + 2.1	22.6 + 1.0	15.1 + 1.0
FT+	28.9	22.6	14.5	29.7	23.3	13.5	28.7	21.1	13.3
w/ BiC	30.7 + 1.8	22.5 - 0.1	14.8 + 0.3	32.3 + 2.6	22.5 - 0.8	12.4 - 1.1	28.6 - 0.1	20.6 - 0.5	11.8 - 1.5
w/ AdBiC	31.9 + 3.0	23.6 + 1.0	15.0 + 0.5	34.0 + 4.3	25.0 + 1.7	14.2 + 0.7	30.8 + 2.1	22.2 + 1.1	14.2 + 0.9
w/ AdBiC + ⊕	32.5 + 3.6	24.6 + 2.0	15.9 + 1.4	34.5 + 4.8	25.7 + 2.4	15.4 + 1.9	31.3 + 2.6	22.7 + 1.6	14.5 + 1.2
Joint	72.7			80.9			71.03		

gains, losses

Results and discussion

Class-Incremental Learning without memory

Top-1 results without memory

Method States	CIFAR-100			BIRDS-100			FOOD-100		
	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$
LwF	53.0	44.0	29.1	53.7	41.8	30.1	42.9	31.8	22.2
w/ BiC	54.0 + 1.0	45.5 + 1.5	30.8 + 1.7	54.6 + 0.9	43.1 + 1.3	31.8 + 1.7	43.4 + 0.5	32.6 + 0.8	23.8 + 1.6
w/ AdBiC	54.3 + 1.3	46.4 + 2.4	32.3 + 3.2	55.0 + 1.3	44.0 + 2.2	32.8 + 2.7	43.5 + 0.6	33.3 + 1.5	24.7 + 2.5
w/ AdBiC + ⊕	54.9 + 1.9	47.3 + 3.3	32.6 + 3.5	55.8 + 2.1	44.8 + 3.0	33.3 + 3.2	44.0 + 1.1	34.2 + 2.4	25.3 + 3.1
LUCIR	50.1	33.7	19.5	50.8	31.4	17.9	44.2	26.4	15.5
w/ BiC	52.5 + 2.4	37.1 + 3.4	22.4 + 2.9	56.0 + 5.2	37.7 + 6.3	20.6 + 2.7	49.9 + 5.7	31.5 + 5.1	17.2 + 1.7
w/ AdBiC	54.8 + 4.7	42.2 + 8.5	28.4 + 8.9	58.5 + 7.7	45.4 + 14.0	27.3 + 9.4	52.0 + 7.8	37.1 + 10.7	17.7 + 2.2
w/ AdBiC + ⊕	55.5 + 5.4	43.6 + 9.9	31.2 + 11.7	59.0 + 8.2	46.0 + 14.6	28.8 + 10.9	52.6 + 8.4	38.2 + 11.8	21.0 + 5.5
SIW	29.9	22.7	14.8	30.6	23.2	14.9	29.4	21.6	14.1
w/ BiC	31.4 + 1.5	22.8 + 0.1	14.7 - 0.1	32.8 + 2.2	22.7 - 0.5	12.8 - 2.1	29.1 - 0.3	20.3 - 1.3	12.1 - 2.0
w/ AdBiC	31.7 + 1.8	24.1 + 1.4	15.8 + 1.0	33.0 + 2.4	25.2 + 2.0	15.3 + 0.4	30.9 + 1.5	21.3 - 0.3	14.5 + 0.4
w/ AdBiC + ⊕	32.8 + 2.9	25.0 + 2.3	16.5 + 1.7	34.4 + 3.8	26.2 + 3.0	16.3 + 1.4	31.5 + 2.1	22.6 + 1.0	15.1 + 1.0
FT+	28.9	22.6	14.5	29.7	23.3	13.5	28.7	21.1	13.3
w/ BiC	30.7 + 1.8	22.5 - 0.1	14.8 + 0.3	32.3 + 2.6	22.5 - 0.8	12.4 - 1.1	28.6 - 0.1	20.6 - 0.5	11.8 - 1.5
w/ AdBiC	31.9 + 3.0	23.6 + 1.0	15.0 + 0.5	34.0 + 4.3	25.0 + 1.7	14.2 + 0.7	30.8 + 2.1	22.2 + 1.1	14.2 + 0.9
w/ AdBiC + ⊕	32.5 + 3.6	24.6 + 2.0	15.9 + 1.4	34.5 + 4.8	25.7 + 2.4	15.4 + 1.9	31.3 + 2.6	22.7 + 1.6	14.5 + 1.2
Joint	72.7			80.9			71.03		

gains, losses

Results and discussion

Continual Learning for Object Detection on the Edge

• Results without Continual Learning

	d1	d2	d3	d4	d5	n1	n2	n3	n4	n5	avg video	base
videos	0.714	0.53	0.013	0.031	0.113	0.076	0.009	0.169	0.156	0.174	0.198	0.137
d1	0.258	0.676	0.021	0.052	0.1	0.072	0.134	0.033	0.031	0.168	0.154	0.234
d2	0.005	0.257	0.727	0.229	0.262	0.07	0.078	0.004	0.005	0.018	0.166	0.268
d3	0.064	0.124	0.174	0.519	0.168	0.157	0.194	0.131	0.108	0.119	0.176	0.006
d4	0.0	0.179	0.081	0.021	0.801	0.577	0.3	0.005	0.014	0.157	0.213	0.285
d5	0.004	0.174	0.048	0.0	0.551	0.863	0.637	0.03	0.034	0.093	0.243	0.28
n1	0.263	0.299	0.002	0.0	0.432	0.687	0.978	0.174	0.155	0.275	0.326	0.51
n2	0.296	0.4	0.0	0.0	0.003	0.0	0.03	0.903	0.959	0.666	0.326	0.313
n3	0.481	0.315	0.0	0.0	0.002	0.017	0.041	0.88	0.96	0.696	0.339	0.305
n4	0.507	0.587	0.039	0.197	0.006	0.161	0.029	0.481	0.435	0.932	0.337	0.507
n5	0.259	0.354	0.11	0.105	0.244	0.268	0.243	0.281	0.286	0.33	-1.0	0.285
avg model												

Results and discussion

Continual Learning for Object Detection on the Edge

• Results with Continual Learning

	d1	d2	d3	d4	d5	n1	n2	n3	n4	n5	avg video	base
videos	0.755	0.621	0.381	0.182	0.19	0.286	0.32	0.451	0.475	0.428	0.409	0.137
n1	0.611	0.713	0.519	0.444	0.39	0.517	0.417	0.476	0.514	0.432	0.503	0.234
n2	0.201	0.409	0.783	0.465	0.458	0.48	0.457	0.175	0.157	0.379	0.396	0.268
n3	0.451	0.468	0.306	0.623	0.536	0.554	0.524	0.335	0.369	0.456	0.462	0.006
n4	0.253	0.364	0.49	0.504	0.885	0.841	0.794	0.419	0.362	0.395	0.531	0.285
n5	0.303	0.384	0.473	0.556	0.741	0.887	0.866	0.453	0.342	0.497	0.55	0.28
avg model	0.682	0.737	0.706	0.717	0.798	0.89	0.99	0.638	0.439	0.774	0.737	0.51
n3	0.679	0.65	0.485	0.372	0.255	0.517	0.498	0.968	0.97	0.859	0.625	0.313
n4	0.667	0.662	0.405	0.381	0.298	0.509	0.496	0.972	0.971	0.869	0.623	0.305
n5	0.624	0.665	0.464	0.351	0.308	0.567	0.636	0.745	0.658	0.968	0.599	0.507
avg	0.523	0.567	0.501	0.459	0.486	0.605	0.6	0.563	0.526	0.606	-1.0	0.285

Conclusions and future work

Conclusions

- ▶ In fine tuning, the classification layer is the most affected by catastrophic forgetting
- ▶ Fine-tuning-based methods are the best option when a memory is allowed
- ▶ Fixed representations are an appropriate choice without memory
- ▶ Usefulness of distillation is reduced at large scale
- ▶ We reduce the model's footprint by half compared to distillation-based methods
- ▶ In object detection, transfer learning is useful to tackle both overfitting and forgetting

Future work

- ▶ Focus more on continual learning without memory
- ▶ Find or create challenging datasets for continual learning
- ▶ Propose a class-incremental method for object detection

Thank you!

Appendix

Fixed-Representation-based methods:

DeeSIL (Belouadah and Popescu, 2018), *Deep-SLDA* (Hayes and Kanan, 2019), *REMIND* (Hayes et al., 2019), *FearNet* Kemker and Kanan, 2018.

Fine-Tuning-based methods:

DGM (Ostapenko et al., 2019), *DGR* (Shin et al., 2017), *GMNF* (Cong et al., 2020), *LwF* (Li and Hoiem, 2016), *EWC* (Kirkpatrick et al., 2016), *MAS* (Aljundi et al., 2018), *BiC* (Wu et al., 2019), *MDF* (Zhao et al., 2020), *LUCIR* (Hou et al., 2019), *iCaRL* (Rebuffi et al., 2017), *E2EIL* (Castro et al., 2018).

Parameter-isolation-based methods:

PackNet (Mallya and Lazebnik, 2018), *PiggyBack* (Mallya et al., 2018), *TFM* (Masana et al., 2020), *Expert – Gate* (Aljundi et al., 2017), *PNN* (Rusu et al., 2016), *DAN* (Rosenfeld and Tsotsos, 2017).

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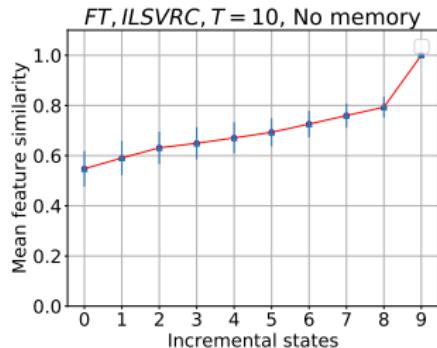
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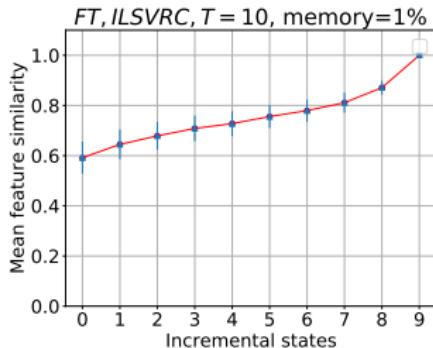
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Backup Slides

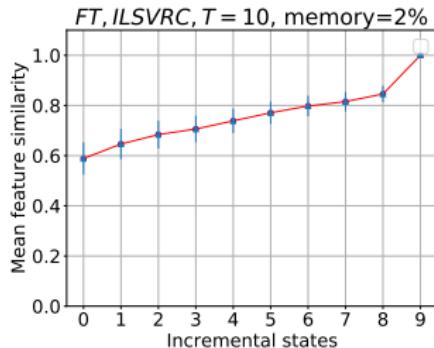
Mean Features Similarity



(a)



(b)



(c)

Mean feature similarities between incremental states for test images of the first state.

Backup Slides

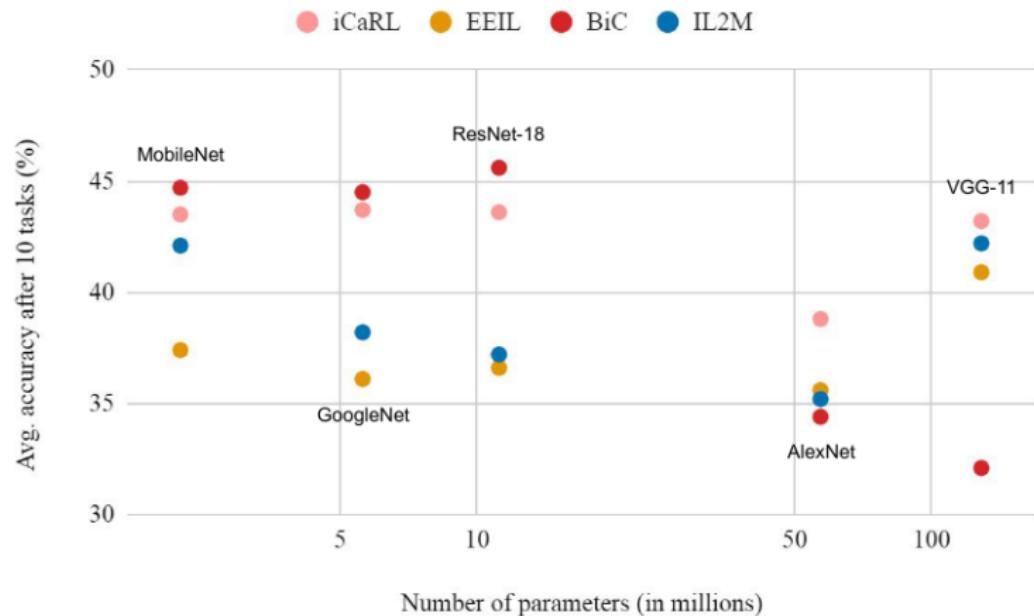
Additional Storage of our methods

Method	Additional Storage (AS) in float	AS for $N_T = 1000$				
		$\mathcal{T} = 5$	$\mathcal{T} = 10$	$\mathcal{T} = 20$	$\mathcal{T} = 50$	$\mathcal{T} = 100$
<i>DeeSIL</i>	0	0	0	0	0	0
<i>IL2M</i>	$\mathcal{T} + N_T$	4.02 KB	4.04 KB	4.08 KB	4.2 KB	4.4 KB
<i>Scall</i>	$N_T \times D$	2.05 MB	2.05 MB	2.05 MB	2.05 MB	2.05 MB
<i>SIW</i>	$\mathcal{T} + N_T \times D$	2.05 MB	2.05 MB	2.05 MB	2.05 MB	2.05 MB
<i>TransIL (AdBiC)</i>	$R \times (\mathcal{T} + 2) \times (\mathcal{T} - 1)$	1.12 KB	4.32 KB	16.72 KB	101.92 KB	403.92 KB
<i>TransIL (BiC)</i>	$2 \times R \times (\mathcal{T} - 1)$	320 B	720 B	1.52 KB	3.92 KB	7.92 KB

Additional Storage (AS) of our proposed IL approaches

Backup Slides

Results with other deep architectures



Results with other architectures (Masana et al., 2021)