

Linear Algebra

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1 Brief Review

Commonly Used Sets

- \mathbb{N} : set of **natural numbers**
could be *positive* integers
could be *nonnegative* integers
- \mathbb{Z} : set of **integers**
- \mathbb{Q} : set of **rational numbers**
- \mathbb{R} : set of **real numbers**

Set Building

To denote sets too large to just list, we use **set builder** notation:

$$\{\text{candidate} : \text{condition}\}$$

Examples:

$$\begin{aligned} &\{x \text{ is a fruit} : x \text{ is of yellow color}\} \\ &\{x \text{ is a human being} : x \text{ is a president of the U.S.}\} \\ &\{x \text{ is a city} : x \text{ is a capitol of a country}\} \end{aligned}$$

Other Notations

- \forall : for all
- \exists : there exists
- s.t.: such that
- $\rightarrow\leftarrow$: contradiction
- WTS: want to show

2 Real Vector Spaces

A **real vector space** is simply a *nonempty set* that satisfies 10 properties called **10 axioms of a real vector space**.

- $\vec{v} \in$ vector space V can be *anything*
- **Never** assume that an element $\vec{v} \in V$ is an ordered pair

Addition

- denoted by \oplus
- simply a map

$$\oplus : V \times V \rightarrow V$$

Example of a definition of \oplus for $V = \{\text{apple, orange, banana}\}$:

\oplus	apple	orange	banana
apple	banana	banana	apple
orange	orange	apple	banana
banana	banana	orange	orange

$$\oplus(\text{apple, orange}) = \text{banana} = \text{apple} \oplus \text{orange}$$

Scalar Multiplication

- denoted by \odot
- simply a map
- *must* be $r \times \vec{v}$ for $r \in \mathbb{R}, \vec{v} \in V$

$$\odot : \mathbb{R} \times V \rightarrow V$$

Example of a definition of \odot for $V = \{\text{apple, orange, banana}\}$:

$$\begin{aligned} k \odot \text{apple} &= \text{orange}, \forall k \in \mathbb{R} \\ k \odot \text{orange} &= \begin{cases} \text{orange}, & \text{if } k \leq 2, \\ \text{banana}, & \text{if } k > 2, \end{cases} \\ k \odot \text{banana} &= \begin{cases} \text{banana}, & \text{if } k < -5\sqrt{2}, \\ \text{apple}, & \text{if } -5\sqrt{2} \leq k < 1.2, \\ \text{banana}, & \text{if } k = 1.2, \\ \text{orange}, & \text{if } k > 2, \end{cases} \end{aligned}$$

$$\odot(3, \text{orange}) = \text{banana} = 3 \odot \text{orange}$$

10 Good Properties of Addition and Scalar Multiplication

1. **Closed Under Addition** $\forall \vec{v}, \vec{u} \in V$,

$$\vec{u} \oplus \vec{v} \in V$$

2. **Commutativity Under Addition** $\forall \vec{v}, \vec{u} \in V$,

$$\vec{u} \oplus \vec{v} = \vec{v} \oplus \vec{u}$$

3. **Associativity Under Addition** $\forall \vec{v}, \vec{u}, \vec{w} \in V$,

$$\vec{u} \oplus (\vec{v} \oplus \vec{w}) = (\vec{u} \oplus \vec{v}) \oplus \vec{w}$$

4. **Additive Identity Exists** $\exists \vec{u} \forall \vec{v} \in V$,

$$\vec{u} \oplus \vec{v} = \vec{v} \oplus \vec{u} = \vec{v}$$

\vec{u} is called the additive identity, **id**

5. **Additive Inverse Always Exists** $\forall \vec{v} \exists \vec{w} \in V$,

$$\vec{v} \oplus \vec{w} = \vec{w} \oplus \vec{v} = \mathbf{id}$$

$\vec{w} = -\vec{v}$ and is pronounced as *bar- \vec{v}*

6. **Closed Under Scalar Multiplication** $\forall k \in \mathbb{R}, \vec{v} \in V$,

$$k \odot \vec{v} \in V$$

7. **Distributivity Over \oplus** $\forall k \in \mathbb{R}, \vec{u}, \vec{v} \in V$,

$$k \odot (\vec{u} \oplus \vec{v}) = k \odot \vec{u} \oplus k \odot \vec{v}$$

8. **Distributivity Over $+$** $\forall k, \ell \in \mathbb{R}, \vec{v} \in V$,

$$(k + \ell) \odot \vec{v} = k \odot \vec{v} \oplus \ell \odot \vec{v}$$

9. **Associativity Over Scalar Multiplication** $\forall k, \ell \in \mathbb{R}, \vec{v} \in V$,

$$(k \cdot \ell) \odot \vec{v} = k \odot (\ell \odot \vec{v})$$

10. **1 Fixes Every Element In V By \odot** $\forall \vec{v} \in V$,

$$1 \odot \vec{v} = \vec{v}$$

Tips To Remember The 10 Axioms

- first 5 axioms deal with addition ONLY, the next 5 axioms involve scalar multiplication
- first of the 5 axioms for addition and scalar multiplication deal with closure
- axioms 4 and 5 are about the existence of something
- axioms 8 and 9 are the only axioms that involve 2 real numbers

Verifying the 10 Axioms

- .. Axioms (1) and (6): proof of closure
- .. Axioms (4) and (5): show existence
- .. Axioms (2), (3), (7), (8), (9), (10): proof for all elements

Standard Addition and Scalar Multiplication for \mathbb{R}^n

$\forall \vec{u} = (u_1, u_2, \dots, u_n), \vec{v} = (v_1, v_2, \dots, v_n) \in V$ and $\forall k \in \mathbb{R}$,

$$\vec{u} \oplus \vec{v} = (u_1 + v_1, u_2 + v_2, \dots, u_n + v_n)$$

$$k \odot \vec{u} = (ku_1, ku_2, \dots, ku_n)$$

3 Axiom-Based Theorems

Given that V is a real vector space, there are a number of theorems that are always true, because they are built upon the axioms.

Theorem A

Let V be a vector space. $\forall \vec{v} \in V$:

$$0 \odot \vec{v} = \mathbf{id}$$

Theorem B

Let V be a vector space. $\forall k \in \mathbb{R}$:

$$k \odot \mathbf{id} = \mathbf{id}$$

Theorem C

Let V be a vector space. $\forall \vec{v} \in V$:

$$(-1) \odot \vec{v} = -\vec{v}$$

Theorem D

Let V be a vector space. If $k \odot \vec{v} = \mathbf{id}$, then:

$$k = 0 \quad \text{and/or} \quad \vec{v} = \mathbf{id}$$

4 Subspaces

Let V be a vector space, with \oplus and \odot denoting its addition and scalar multiplication operations respectively. A *nonempty set* W is a **subspace** of V if these three properties are satisfied.

1. $W \subseteq V$
2. Addition and scalar multiplication operations in W are *inherited* from V : $\oplus_W = \oplus_V$ and $\odot_W = \odot_V$
3. W is a vector space

Theorem 3: Needed Axioms for a Subspace

Let V be a vector space, and let W be a nonempty subset V such that the addition and scalar multiplication are inherited from V . Then W is a subspace of V if and only if Axioms 1 and 6 hold for W .

Linear Combination and Span

Let V be a vector space, and let $S = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\} \subseteq V$. A **linear combination** of $S = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is

$$k_1\vec{v}_1 + k_2\vec{v}_2 + \dots + k_n\vec{v}_n, \text{ where } k_i \text{ are scalars}$$

The **span** of $S = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is the set of ALL linear combinations of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$, which is

$$\text{span}(S) = \{\vec{v} \in V : \vec{v} = k_1\vec{v}_1 + k_2\vec{v}_2 + \dots + k_n\vec{v}_n, \text{ where } k_1, k_2, \dots, k_n \in \mathbb{R}\}$$

If $S = \emptyset$, then we define $\text{span}(S) = \{\mathbf{id}\}$

Theorem 16: Smallest Subspace of a Vector Space

Let V be a vector space, and let $S = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\} \subseteq V$. Then $\text{span}(S)$ is the **smallest** subspace of V containing S .

Theorem 19: Span Equality

Let V be a vector space, and let S and T be two finite subsets of V . Then

$$\text{span}(S) = \text{span}(T) \iff S \subseteq \text{span}(T) \text{ and } T \subseteq \text{span}(S)$$

Gauss-Jordan Elimination