MAT 369 Introduction to Graph Theory

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1 Introduction

1.1 Graphs and Graph Models

Graph Definition

A (simple) **graph** is an ordered pair (V, E) where

- \bullet V is a nonempty set of objects called "vertices"
- E is a set containing some two-subsets of V called "edges". E may be empty.

Graphs are often represented pictorially. For example consider

$$G = (V, E)$$
 where $V = \{1, 2, 3, 4, 5\}$ and $E = \{\{1, 4\}, \{2, 3\}, \{2, 4\}, \{3, 4\}\}$

G

5



- Vertices 1 and 4 are **adjacent** because they are joined by an edge.
- Vertex 2 and edge 2-3 are **indicent**.
- Edges 2-3 and 3-4 are **adjacent**.

Order Definition

The **order** of a graph G is |V(G)|, or the number of vertices.

Size Definition

The **size** of a graph G is |E(G)|, or the number of edges. The graph G from above has order 5 and size 4.

1.2 Connected Graphs

Subgraph Definition

Let G and H be graphs. H is a subgraph of G, notated as $H \subseteq G$, if

$$V(H) \subseteq V(G)$$
 and $E(H) \subseteq E(G)$.

Proper Subgraph Definition

H is a **proper subgraph** of G if $H \subseteq G$ and either

$$V(H) \subseteq V(G)$$
 or $E(H) \subseteq E(G)$.

Spanning Subgraph Definition

Graph H is a spanning subgraph if $H \subseteq G$ and V(H) = V(G).

Induced Subgraph Definition

Graph H is a **induced subgraph** if $H \subseteq G$ and if

$$u, v \in V(H)$$
 and $u, v \in E(G) \implies u, v \in E(H)$.

Essentially, H contains all valid edges it can take from G. Notation for **induced subgraph** is

G[S], where S is a set of vertices from G.

Edge-induced Subgraph Definition

G[X] is an **edge-induced subgraph** of G if G[X] has edge set $X \subseteq E(G)$ and a vertex set of all vertices incident with at least one edge of X. Interesting fact: G[E(G)] removes any isolated vertices.

More on Spanning and Induced Subgraphs

Let G be a graph with vertex v and edge e. Then,

- G e is the spanning subgraph of G whose edge set is $E(G) \{e\}$. This definition can be expanded to G - X for $X \subseteq E(G)$.
- G v is the *induced subgraph* of G whose vertex set is $V(G) \{v\}$ and edge set includes all edges of G except those incident with v.

This definition can be expanded to G - U for $U \subseteq V(G)$.

Let G be a graph, $u, v \in V(G)$ and $e = uv \notin E(G)$. Then G + e is the graph with vertex set V(G) and edge set $E(G) \cup \{e\}$. G is a spanning subgraph of G + e

Walk, Trail, Path, Circuit, and Cycle Definitions

Let $u, v \in V(G)$. A u - v walk in G is a sequence of vertices

$$(u = v_0, v_1, \dots, v_k = v)$$

beginning with u, ending with v, and consecutive vertices are adjacent.

A **trail** is a walk in which *no edges* are repeated. A **path** is a walk in which *no vertices* are repeated. Every *path* is a *trail* is a *walk*.

A **circuit** is a closed trail of length ≥ 3 . A **cycle** is a circuit with no repeated vertices, except for the first and the last, which are the same. A k-**cycle** is a cycle of length k. Every cycle is a circuit is a walk.

Closed and Open Walks

A u-v walk with u=v is called a **closed** walk. A u-v walk with $u\neq v$ is called a **open** walk.

Walk and Path Theorem

If G contains a u-v walk of length ℓ , then G contains a u-v path of length $\leq \ell$.

Proof. Let $P = (u = u_0, u_1, \dots, u_k = v)$ be a u - v walk of smallest length $k \leq \ell$.

Claim. P is a u-v path.

If **not**, then $u_i = u_j$, for some $i \neq j$. Then $(u = u_0, u_1, \dots, u_i = u_j, \dots, u_k = v)$ will be a smaller u - v than P. This contradicts our assertion that P was the *smallest* walk.

Hence, P is a u-v path of length $k \leq \ell$.

Connectivity Definition

A graph G is said to be **connected** if $\forall u, v \in V(G)$, G contains a u - v path. If this is not true, i.e. $\exists u, v \in V(G)$ where there is no u - v path, then G is said to be **disconnected**.

Component Definition

A connected subgraph of G that is not a proper subgraph of any other connected subgraph of G is a **component** of G. The number of components of a graph G is denoted by k(G). A graph G is connected if and only if k(G) = 1. Additionally, a graph is the union of its components.

Components and Equivalence Relations Theorem

Define a relation R on the V(G) so that uRv if G contains a u-v walk. Then R is an equivalence relation.

Proof. An equivalence relation must be reflexive, symmetric, and transitive.

- 1. Reflexive: $\forall u \in V(G)$, (u) is a u-u walk, so uRu.
- 2. Symmetric: Suppose uRv. There is a u-v walk $(u=u_0,u_1,\ldots,u_n=v)$. Then reversing the walk gives the v-u walk $(v=u_n,\ldots,u_1,u_0=u)$. So vRu.
- 3. Transitive: Suppose uRv and vRw. There is a u-v walk $(u=u_0,u_1,\ldots,u_n=v)$, and v-w walk $(v=v_0,v_1,\ldots,v_m=w)$. Then there is a u-w walk $(u=u_0,u_1,\ldots,u_n=v=v_0,\ldots,v_m=w)$. So uRw.

What are the equivalence classes?

 $[u] = \{v \in V(G) \mid uRv\}$ $= \{v \in V(G) \mid \text{there is a } u - v \text{ walk in } G\}$ = the connected component containing u

Subtractive Connectivity Theorem (weak)

Let G be a graph of order ≥ 3 . If $\exists u, v \in V(G)$ such that G - u and G - v are connected, then G is connected.

Proof. Suppose G has order at least 3 and $\exists u, v \in V(G)$ such that G - u and G - v are connected. Let $x, y \in V(G)$.

Case 1 $\{x,y\} \neq \{u,v\}$, meaning at least one is different. Say (WLOG) $u \notin \{x,y\}$. Then $x,y \in V(G-u)$, which is connected, contains an x-y walk.

Case 2 $\{x,y\} = \{u,v\}$. Say (WLOG) x = u and y = v.

Consider $z \in V(G - u)$ and $z \in V(G - v)$.

Then $x, z \in V(G - v)$ contains a x - z walk $(x = x_0, \dots, x_n = z)$, since it is connected.

Then $z, y \in V(G - u)$ contains a z - y walk $(z = z_0, \dots, z_m = y)$, since it is connected.

Now consider $(x = x_0, \dots, x_n = z = z_0, \dots, z_m = y)$. This is an x - y walk in G.

Distance, Geodesic, Diameter, and Girth Definitions

The **distance** between vertices u and v, denoted as d(u,v) or $d_G(u,v)$ is the smallest length of any u-v path in G. If u and v are in different components, then d(u,v) is undefined.

A u-v path of shortest length d(u,v) is called a **geodesic**. The **diameter** of a connected graph G, denoted as diam(G), is the largest *geodesic* between any two vertices of G. The **girth** of a connected graph G is the length of the shortest cycle in G.

Subtractive Connectivity Theorem (strong)

Let G be a graph of order ≥ 3 . Then G is connected if and only if $\exists u, v \in V(G)$ such that G - u and G - v are connected.

Proof. \implies is already proven by the weak version of this theorem.

 \Leftarrow Suppose G is connected. Then $\exists u, v \in V(G)$ such that d(u, v) = diam(G).

Suppose to the contrary, WLOG, that G - v is disconnected. Then exists $x, y \in V(G - v)$ such that there is no x - y walk in G - v. But G is connected, so there exist x - u and u - y paths in G.

Let P' be an x-u geodesic in G and P'' be a u-y geodesic in G.

v cannot be on P' or P'' because if it was, then d(x,u) > d(u,v) or d(y,u) > d(u,v), violating our assertion that $d(u,v) = \operatorname{diam}(G)$.

Then P'P'' x - u - y is an x - y walk in G - v.

This contradicts our selection that x and y do not have a walk in G-v. Hence G-v and G-u are connected.

1.3 Common Classes of Graphs

Name	Symbol	Order	Size
Path	P_n	n	n-1
Cycle	C_n	$n \ge 3$	n
Complete	K_n	n	$\binom{n}{2}$
Complete Bipartite	$K_{s,t}$	s+t	$s \cdot t$

Bipartite Graph Definition

G is bipartite if V(G) can be partitioned into partite sets U and W so that every edge joins a vertex of U and a vertex of W.

Odd Cycle and Bipartite-ness

G is bipartite if and only if G contains no odd cycles.

K-partite Definition

G is a k-partite graph if V(G) can be partitioned into partite sets U_1, \ldots, U_k so that every edge joins a vertex from U_i and a vertex of U_j where $i \neq j$.

Constructing New Graphs from Old Graphs

Disjoint Union

For two graphs G and H, $G \cup H$ is defined as...

$$V(G \cup H) = V(G) \cup V(H)$$

$$E(G \cup H) = E(G) \cup E(H)$$

Complement

For one graph G, \overline{G} is defined as...

$$V(\overline{G}) = V(G)$$

$$E(\overline{G}) = \{uv|u, v \in V(G), u \neq v, uv \notin E(G)\}$$

Join

For two graph, G and H, G + H is defined as...

Start with $G \cup H$ and draw all edges join a vertex of G and a vertex of H

Cartesian Product

For two graphs, G and H, $G \times H$ is defined as...

$$V(G\times H)=\{(u,v)|u\in V(G) \text{ and } v\in V(H)\}$$

$$(u,v)-(x,y) \text{ if } u=x \text{ and } vy\in E(H)\vee v=y \text{ and } ux\in E(G)$$

A cartesian product between two graphs has the practical effect of duplicating one graph, and connecting the duplicates in the way of the other graph.

Complement Connectivity Theorem

If G is disconnected, then \overline{G} is connected.

1.4 Multigraphs and Digraphs

Multigraph Definition

A multigraph is a graph where a pair of vertices may be joined by any finite number of edges.

• Multiple edges: OK

• Loops: NOT OK

Pseudograph Definition

A **pseudograph** is a *multigraph* where loops are allowed

• Multiple edges: OK

• Loops: OK

Digraph Definition

A directed graph is a graph where E(G) is a set of ordered pairs (rather than sets) of distinct vertices called directed edges, or arcs.

Oriented Graph Definition

An **oriented graph** is a digraph in $\forall u, v \in V(G)$, (u, v) and (v, u) are not both edges.

2 Degrees

2.1 Degree of a Vertex

Vertex Degree Definition

The **degree** of a vertex v, denoted as $\deg v$ or $\deg_G v$, is the number of edges incident with v. If the $\deg v = 0$, then v is an **isolated vertex**. If $\deg v = 1$, then v is a **leaf**.

- $\delta(G) = \min\{\deg v \mid v \in V(G)\}$, the minimum degree of G
- $\Delta(G) = \max\{\deg v \mid v \in V(G)\}$, the maximum degree of G

For any graph G and $v \in V(G)$,

$$0 \le \delta(G) \le \deg v \le \Delta(G) \le n - 1.$$

Neighborhood of a Vertex Definition

The **neighborhood** of a vertex v, denoted as N(v), is the set of all vertices adjacent to v. So $|N(v)| = \deg v$.

Handshaking Theorem

For a graph G of size m, the total degree of $G \sum_{v \in V(G)} = 2m$.

Handshaking Corollary

Every graph has an even number of odd degree vertices.

Sum Degree and Connectivity Theorem

Consider graph G of order n. If deg $u + \deg v \ge n - 1$ for all non-adjacent $(u, v) \in V(G)$, then G is connected.

Sum Degree and Connectivity Corollary

If G has order n and $\delta(G) \geq \frac{n-1}{2}$, then G is connected.

2.2 Regular Graphs

Regular Graph Definition

Graph G is regular if every vertex has the same degree. Graph G is r-regular if every vertex has degree r.

Regular Graph Existence Theorem

Let $r, n \in \mathbb{Z}$ such that $0 \le r \le n-1$. Then there exists an r-regular graph of order n if and only if at least one of r and n is even.

Harary Graph

An Harary Graph, denoted as $H_{r,n}$, is an r-regular graph of order n.

Induced Regular Subgraph Theorem

For every graph G, and every integer $r \geq \Delta(G)$, there exists on r-regular graph H, containing G as an induced subgraph.

2.3 Degree Sequences

Degree Sequence Definition

A degree sequence is a sequence of the degree of the vertices of a graph, typically, written in largest to smallest order.

Graphical Degree Sequence Definition

A finite sequence of non-negative integers is **graphical** if it is the degree sequence of some graph.

Graphical Degree Sequence Theorem

A non-increasing sequence $S: d_1, d_2, \ldots, d_n$, where $n \geq n$, of non-negative integers is graphical if and only if

$$S_1: d_2-1, d_3-1, \ldots, d_{d_1+1}, d_{d_1+2}, d_n$$

is graphical.

2.4 Graph and Matrices

Adjacency Matrix Definition

The adjacency matrix of G is the $n \times n$ matrix $A = [a_{ij}]$, where

$$a_{ij} = \begin{cases} 1, & \text{if } v_i v_j \in E(G) \\ 0 & \text{otherwise;} \end{cases}$$

The entry a_{ij} in A^n is the number of walks of length n from v_i to v_j .

3 Isomorphic Graphs

3.1 The Definition of Isomorphism

Graph Equality Definition

Two graphs are **equal**, denoted as G = H, if V(G) = V(H) and E(G) = E(H).

Graph Isomorphic Definition

Two (labels) graphs G and H are **isomorphic**, denoted as $G \cong H$, if they have the same structure, meaning there is a bijection $\phi: V(G) \to V(H)$ such that for $u, v \in V(G), \phi(u)\phi(v) \in E(H)$ if and only if $uv \in E(G)$.

Isomorphic Degree Theorem

If $G \cong H$, with isomorphic $\phi: V(G) \to V(H)$, then $\deg_G u = \deg_H \phi(u)$.

Isomorphic Degree Corollary

If $G \cong H$, their degree sequences are equal.

Graph Invariants

- To prove $G \cong H$, find an isomorphism.
- To prove $G \ncong H$, find a graph invariant, where G and H differ.

Graph Invariants

- Order and Size
- Degree Sequence
- Cycles
- Diameter
- k (number of components)
- \bullet k-partite-ness
- (Other things)

Adjacency and Non-adjacency under Isomorphism Theorem

 $G \cong H$ if and only if $\overline{G} \cong \overline{H}$.

3.2 Isomorphism as a Relation

Equivalence Relations and Isomorphism Theorem

Isomorphism is an equivalence relation.

4 Trees

4.1 Cut Edges

Cut-edge and Bridge Definition

An edge e of graph G is a **cut-edge**, or **bridge**, if G - e has more components than G.

Cut-edges and Cycles Theorem

An edge e of a graph G is a cut-edge if and only if e lies on no cycle in G.

4.2 Trees

Tree and Forest Definitions

A **tree** is an acyclic connected graph. A **forest** is an acyclic graph, where each component is a *tree*. A **Rooted tree** is a tree with a specific vertex designated as a root and drawn down.

Every edge of a tree is a cut-edge.

Unique Path in Trees Theorem

Graph G is a tree if and only if every 2 vertices are connected by a unique path.

Leaf Theorem

Every nontrivial tree has at least 2 leaves.

Autumn Theorem

If tree T has order $t \ge 1$, then T - v, where v is a leaf, is a tree of order t - 1.

Tree Size Theorem

Every tree of order n has size n-1.

Forest Size Theorem

Every forest of order n with k components has size n - k.

Minimum Size of a Connected Graph Theorem

The size of every connected graph of order n is at least n-1. Trees has minimal size among connected graphs of given order.

Tree Requirements Graph

Graph G of order n and size m. Then G is a tree if it satisfies any 2 of these properties:

- 1. G is connected
- 2. G acyclic
- 3. m = n 1

Tree Isomorphic Subgraph Theorem

Let T be a tree of order k. Then for any graph G with $\delta(G) \geq k - 1$, T is isomorphic to a subgraph of G.

4.3 Minimum Spanning Tree

Spanning Tree Definition

Let G be a connected graph. A spanning subgraph of G that is a tree is called a spanning tree.

Spanning Tree Existence Theorem

Every connected graph contains a spanning tree.

Minimum Spanning Tree Definition

A minimum spanning tree is a spanning tree of minimum weight.

Algorithms For Constructing Minimum Spanning Trees

Kruskal's Algorithm

- 1. Pick an edge of minimum weight.
- 2. Repeat, never allowing the chosen edges to produce a cycle.
- 3. Stop once you have a spanning tree.

Prim's Algorithm

- 1. Choose any vertex $u \in V(G)$.
- 2. Let e be an edge of minimum weight incident with u.
- 3. Continue picking edges of minimum weight weight from the set of edges having exactly one of its vertices incident with an already selected edge.
- 4. Stop once you have a spanning tree.

4.4 Counting Labeled Trees

Cayley's Theorem

There are n^{n-2} distinct labeled trees on n vertices.

Prüfer Sequence

Encoding a Tree to a Sequence

- 1. Start with a labeled tree T, and i = 1.
- 2. Let $b_i = \text{smallest label on a leaf.}$
- 3. Let $a_i = \text{label of the adjacent vertex of } b_1$.
- 4. Remove b_i and record a_i in the sequence.
- 5. Repeat with b_{i+1} and a_{i+1} .
- 6. Stop once only vertices remain.

Decoding a Sequence to a Tree

- 1. Start with (a_1, \ldots, a_{n-2}) and i = 1.
- 2. Let $b_i = \text{smallest element of } \{1, \dots, n\}$ not in the sequence.

- 3. Draw edge $a_i b_i$.
- 4. Remove a_i from the sequence and b_i from the set.
- 5. Repeat with b_{i+1} and a_{i+1} .
- 6. Stop once the sequence is empty, and draw an edge between the last two elements in the set.

5 Connectivity

5.1 Cut Vertices

Cut-edge and Cut-vertex Definition

- Cut-edge: Removing cut-edge e creates a new component.
- Cut-vertex: Removing cut-vertex v creates new components(s).

Leaves and Cut-vertices Theorem

Let G be a connected graph with cut-edge e = uv. v is a cut-vertex if and only if deg $v \ge 2$, meaning that v is not a leaf.

Leaves and Cut-vertices Corollary 1

Every vertex of a non-trivial tree is either a leaf of a cut-vertex.

Leaves and Cut-vertices Corollary 2

Let G be a connected graph and of order at least 3. If G contains a cut-edge, then G contains a cut-vertex.

Paths and Cut-vertices Theorem

Let G be a connected graph with cut-vertex v. Let u, w be vertices in different components of G - v. Then v lies on every u - w path in G.

Paths and Cut-vertices Corollary

Let G be connected. $v \in V(G)$ is a cut-vertex if and only if $\exists u, w \in V(G) - \{v\}$ such that v lies on every u - w path in G.

Non-cut-vertex Theorem

Every nontrivial connected Graph contains at least 2 vertices that are not cut-vertices.

5.2 Blocks

Non-separable Definition

A graph is called **non-separable** if...

- 1. it is nontrivial,
- 2. it is connected,
- 3. it has no cut-vertices, meaning every edge is on a cycle.

Otherwise, it is called **separable**.

Common Cycle and Non-separability Theorem

A graph of order at least 3 is non-separable if and only if every 2 vertices (pairwise) lie on a common cycle.

Block Definition

A **block** of G is a maximal, non-separable subgraph of G.

5.3 Connectivity 5 CONNECTIVITY

Blocks are Equivalence Relations Theorem

Define a Relation R on E(G) where eRf if e=f or e and f lie on a common cycle of G. R is an equivalence relation, where equivalence classes of R are edge-induced blocks of G.

Blocks are Equivalence Relations Corollary

Let B_1 and B_2 be distinct blocks in a nontrivial connected graph G. Then,

- 1. $E(B_1) \cap E(B_2) = \emptyset$, meaning B_1 and B_2 are edge disjoint.
- 2. B_1 and B_2 have at most 1 vertex in common.
- 3. The common vertex, if is exists, is a cut-vertex.

5.3 Connectivity

Vertex-cut and Minimum Vertex-cut Definition

- A vertex-cut is a set $U \subseteq V(G)$ such that G U is disconnected.
- A minimum vertex-cut is a *vertex-cut* of minimum cardinality.

Connectivity Definition

The **connectivity** of graph G is

$$\kappa(G) = \min\{|U| \mid U \subseteq V(G), \text{ such that } G - U \text{ is disconnected or trivial.}\}$$

Note that $0 \le \kappa(G) \le n - 1$.

k-connectivity Definition

G is called k-connected if $\kappa(G) > k$.

Edge-cut, Minimal, and Minimum Edge-cut Definition

- An **edge-cut** is a set $X \subseteq E(G)$ such that G X is disconnected.
- A minimal edge-cut is an edge-cut X where no proper subset of X is also an edge-cut.
- A minimum edge-cut is an edge-cut of minimum cardinality.

Edge-connectivity Definition

The **edge-connectivity** of a nontrivial graph G is

$$\lambda(G) = \min\{|X| \mid X \subseteq E(G), \text{ such that } G - X \text{ is disconnected or trivial.}\}$$

Note that $0 \le \lambda(G) \le n - 1$.

k-edge-connectivity Definition

G is called k-edge-connected if $\lambda(G) \geq k$.

Edge-connectivity of Complete Graphs Theorem

$$\forall n \in \mathbb{N}, \ \lambda(K_n) = n - 1$$

5.3 Connectivity 5 CONNECTIVITY

Connectivity and Edge-connectivity Ordering Theorem

For a graph G,

$$\kappa(G) \le \lambda(G) \le \delta(G)$$

IMPORTANT: These proofs involve taking minimum-edge or minimum-vertex cuts and comparing their cardinalities.

Cubic Connectivity Theorem

If graph G is 3-regular, also called cubic, then

$$\kappa(G) = \lambda(G)$$

Upper Bound for Connectivity Theorem

If G has order n and size $m \geq n-1$, then

$$\kappa(G) \leq \lfloor \frac{2m}{n} \rfloor$$

6 Traversability

6.1 Eulerian Graphs

Seven Bridges of Königsberg Problem



Can you go for a walk, crossing each bridge exactly once? No

Eulerian Circuits and Trails Definition

- A Eulerian Circuit is a circuit containing every edge of graph G.
- A Eulerian Trail is an open trail containing every edge of graph G.
- A Eulerian Graph is a graph that contains an Eulerian Circuit

Even Degree and Eulerian Circuits Theorem

A nontrivial, connected graph is Eulerian if and only if every vertex has even degree.

Even Degree and Eulerian Trails Corollary

A connected graph G contains an Eulerian Trail, if and only if exactly 2 vertices of G have odd degree.

6.2 Hamiltonian Graphs

Hamiltonian Cycles and Paths Definition

- A Hamiltonian Cycle is a cycle containing every vertex of graph G.
- A Hamiltonian Path is a path containing every vertex of graph G.
- A Hamiltonian Graph is a graph that contains an Hamiltonian Cycle.

Degree Sum and Hamiltonian Graphs Theorem

Let G have order $n \geq 3$. If $\deg u + \deg v \geq n$ for all pairs of nonadjacent vertices $u, v \in V(G)$, then G is Hamiltonian. Note that this is only a *one way* statement.

Degree Sum and Hamiltonian Graphs Corollary

Let G have order $n \geq 3$. If deg $v \geq \frac{n}{2}$ for all $v \in V(G)$, then G is Hamiltonian. Note that this is only a *one* way statement.

7 Digraphs

8 Matchings and Factorization

9 Planarity

10 Coloring Graphs

11 Ramsey Numbers

12 Distance

13 Domination