Test 2

Problem 1 Let A be an $n \times n$ matrix such that $A^4 + A^2 = O$. Show that

$$(A^2 - A + I)^{-1} = A^2 + A + I$$

Proof. Consider $A^2 + A + I$.

$$(A^{2} + A + I)(A^{2} - A + I) = A^{4} - A^{3} + A^{2} + A^{3} - A^{2} + A + A^{2} - A + I^{2} = A^{4} + A^{2} + I$$
$$(A^{2} - A + I)(A^{2} + A + I) = A^{4} + A^{3} + A^{2} - A^{3} - A^{2} - A + A^{2} + A + I^{2} = A^{4} + A^{2} + I$$

If $A^4 + A^2 = O$, we can simplify further:

$$A^4 + A^2 + I = O + I$$
 since $A^4 + A^2 = O$
$$= I$$
$$\therefore (A^2 + A + I)(A^2 - A + I) = I$$
$$\therefore (A^2 - A + I)(A^2 + A + I) = I$$

Since $(A^2 + A + I)(A^2 - A + I) = I$ and $(A^2 - A + I)(A^2 + A + I) = I$, therefore if $A^4 + A^2 = O$, then $(A^2 - A + I)^{-1} = A^2 + A + I$.

Problem 2 In \mathbb{R}^3 , let $\vec{v}_1 = (-3, 1, 4), \vec{v}_2 = (-4, 2, 5)$, and $\vec{v}_3 = (-1, 0, 2)$. Express $\vec{u} = (5, -4, 2)$ as a linear combination of \vec{v}_1, \vec{v}_3 , and \vec{v}_3 by finding the MATRIX INVERSE.

Work. Let k_1, k_2 , and $k_3 \in \mathbb{R}$ such that $k_1\vec{v}_1 + k_2\vec{v}_2 + k_3\vec{v}_3 = \vec{u}$. That is, $k_1(-3, 1, 4) + k_2(-4, 2, 5) + k_3(-1, 0, 2) = (5, -4, 2)$. This equation can be converted into a matrix equation.

$$\begin{pmatrix} -3 & -4 & -1 \\ 1 & 2 & 0 \\ 4 & 5 & 2 \end{pmatrix} \begin{pmatrix} k_1 \\ k_2 \\ k_3 \end{pmatrix} = \begin{pmatrix} 5 \\ -4 \\ 2 \end{pmatrix}$$

In order to solve this equation, we must use the inverse algorithm.

$$\begin{pmatrix} -3 & -4 & -1 & 1 & 0 & 0 \\ 1 & 2 & 0 & 0 & 1 & 0 \\ 4 & 5 & 2 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_1 + 3R_2} \begin{pmatrix} 0 & 2 & -1 & 1 & 3 & 0 \\ 1 & 2 & 0 & 0 & 1 & 0 \\ 0 & -3 & 2 & 0 & -4 & 1 \end{pmatrix} \xrightarrow{R_3 + 2R_1} \xrightarrow{R_2 - R_1} \begin{pmatrix} 0 & 2 & -1 & 1 & 3 & 0 \\ 1 & 0 & -1 & -1 & -2 & 0 \\ 0 & 1 & 0 & 2 & 2 & 1 \end{pmatrix} \xrightarrow{R_1 - 2R_3} \begin{pmatrix} 0 & 0 & -1 & -3 & -1 & -2 \\ 1 & 0 & -1 & -1 & -2 & 0 \\ 0 & 1 & 0 & 2 & 2 & 1 \end{pmatrix} \xrightarrow{R_2 + R_1} \begin{pmatrix} 0 & 0 & -1 & -3 & -1 & -2 \\ 1 & 0 & -1 & -1 & -2 & 0 \\ 0 & 1 & 0 & 2 & 2 & 1 \end{pmatrix} \xrightarrow{R_2 + R_1} \begin{pmatrix} 1 & 0 & 0 & -4 & -3 & -2 \\ 0 & 1 & 0 & 2 & 2 & 1 \\ 0 & 0 & 1 & 3 & 1 & 2 \end{pmatrix}$$

Though the use of the inverse algorithm, we know that

$$\begin{pmatrix} -3 & -4 & -1 \\ 1 & 2 & 0 \\ 4 & 5 & 2 \end{pmatrix}^{-1} = \begin{pmatrix} -4 & -3 & -2 \\ 2 & 2 & 1 \\ 3 & 1 & 2 \end{pmatrix}.$$

We can use this identity to solve the original equation:

$$\begin{pmatrix} -3 & -4 & -1 \\ 1 & 2 & 0 \\ 4 & 5 & 2 \end{pmatrix} \begin{pmatrix} k_1 \\ k_2 \\ k_3 \end{pmatrix} = \begin{pmatrix} 5 \\ -4 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} -3 & -4 & -1 \\ 1 & 2 & 0 \\ 4 & 5 & 2 \end{pmatrix}^{-1} \begin{pmatrix} -3 & -4 & -1 \\ 1 & 2 & 0 \\ 4 & 5 & 2 \end{pmatrix} \begin{pmatrix} k_1 \\ k_2 \\ k_3 \end{pmatrix} = \begin{pmatrix} -3 & -4 & -1 \\ 1 & 2 & 0 \\ 4 & 5 & 2 \end{pmatrix}^{-1} \begin{pmatrix} 5 \\ -4 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} k_1 \\ k_2 \\ k_3 \end{pmatrix} = \begin{pmatrix} -4 & -3 & -2 \\ 2 & 2 & 1 \\ 3 & 1 & 2 \end{pmatrix} \begin{pmatrix} 5 \\ -4 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} k_1 \\ k_2 \\ k_3 \end{pmatrix} = \begin{pmatrix} -20 + 12 - 4 \\ 10 - 8 + 2 \\ 15 - 4 + 4 \end{pmatrix}$$

$$\begin{pmatrix} k_1 \\ k_2 \\ k_3 \end{pmatrix} = \begin{pmatrix} -12 \\ 4 \\ 15 \end{pmatrix}$$

This means that when $k_1 = -12$, $k_2 = 4$, and $k_3 = 15$, the equation $k_1\vec{v}_1 + k_2\vec{v}_2 + k_3\vec{v}_3 = \vec{u}$ is true. That is, -12(-3,1,4) + 4(-4,2,5) + 15(-1,0,2) = (5,-4,2).

Problem 3 Solve for the matrix A if

$$(I - 2A)^{-1} = \begin{pmatrix} 1 & -3 & 3 \\ -2 & 2 & -5 \\ 3 & -8 & 9 \end{pmatrix}.$$

Work.

$$\begin{pmatrix}
1 & -3 & 3 & | 1 & 0 & 0 \\
-2 & 2 & -5 & | 0 & 1 & 0 \\
3 & -8 & 9 & | 0 & 0 & 1
\end{pmatrix}
\xrightarrow{R_2+2R_1}
\xrightarrow{R_3-3R_1}
\begin{pmatrix}
1 & -3 & 3 & | 1 & 0 & 0 \\
0 & -4 & 1 & | 2 & 1 & 0 \\
0 & 1 & 0 & | -3 & 0 & 1
\end{pmatrix}
\xrightarrow{R_1+3R_3}
\begin{pmatrix}
1 & 0 & 3 & | -8 & 0 & 3 \\
0 & 0 & 1 & | -10 & 1 & 4 \\
0 & 1 & 0 & | -3 & 0 & 1
\end{pmatrix}$$

$$\xrightarrow{R_1-3R_2}
\begin{pmatrix}
1 & 0 & 0 & | 22 & -3 & -9 \\
0 & 0 & 1 & | -10 & 1 & 4 \\
0 & 1 & 0 & | -3 & 0 & 1
\end{pmatrix}
\xrightarrow{R_2 \leftrightarrow R_3}
\begin{pmatrix}
1 & 0 & 0 & | 22 & -3 & -9 \\
0 & 1 & 0 & | -3 & 0 & 1 \\
0 & 0 & 1 & | -10 & 1 & 4
\end{pmatrix}$$

Therefore, through the inverse algorithm,

$$\begin{pmatrix} 1 & -3 & 3 \\ -2 & 2 & -5 \\ 3 & -8 & 9 \end{pmatrix}^{-1} = \begin{pmatrix} 22 & -3 & -9 \\ -3 & 0 & 1 \\ -10 & 1 & 4 \end{pmatrix}$$

Using this fact, we can now solve the original equation.

$$(I-2A)^{-1} = \begin{pmatrix} 1 & -3 & 3 \\ -2 & 2 & -5 \\ 3 & -8 & 9 \end{pmatrix} \qquad -2A = \begin{pmatrix} 22 & -3 & -9 \\ -3 & 0 & 1 \\ -10 & 1 & 4 \end{pmatrix} - \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$I-2A = \begin{pmatrix} 1 & -3 & 3 \\ -2 & 2 & -5 \\ 3 & -8 & 9 \end{pmatrix}^{-1} \qquad -2A = \begin{pmatrix} 21 & -3 & -9 \\ -3 & -1 & 1 \\ -10 & 1 & 3 \end{pmatrix}$$

$$I-2A = \begin{pmatrix} 22 & -3 & -9 \\ -3 & 0 & 1 \\ -10 & 1 & 4 \end{pmatrix} \qquad A = \begin{pmatrix} -10\frac{1}{2} & 1\frac{1}{2} & 4\frac{1}{2} \\ 1\frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ 5 & -\frac{1}{2} & -1\frac{1}{2} \end{pmatrix}$$

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Problem 4 Let

$$A = \begin{pmatrix} 1 & 0 & 3 \\ -2 & 0 & -5 \\ 0 & 2 & 0 \end{pmatrix}.$$

Write A as a product of elementary matrices.

Work.

$$\begin{pmatrix} 1 & 0 & 3 \\ -2 & 0 & -5 \\ 0 & 2 & 0 \end{pmatrix} \xrightarrow{R_2 + 2R_1} \begin{pmatrix} 1 & 0 & 3 \\ 0 & 0 & 1 \\ 0 & 2 & 0 \end{pmatrix} \xrightarrow{R_1 - 3R_2} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 2 & 0 \end{pmatrix} \xrightarrow{\frac{1}{2}R_3} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \xrightarrow{R_2 \leftrightarrow R_3} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Each of these row operations can be expressed as a left multiplication of an elementary matrix.

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 1 & -3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 3 \\ -2 & 0 & -5 \\ 0 & 2 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$
$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 1 & -3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$
$$\begin{pmatrix} 1 & 0 & 3 \\ -2 & 0 & -5 \\ 0 & 2 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & -3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$
$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

Problem 5 Find the conditions on b_1, b_2 , and b_3 such that the system

$$1x_1 - 1x_2 + 1x_3 = b_1$$
$$-4x_1 + 7x_2 + 2x_3 = b_2$$
$$-2x_1 + 3x_2 + 0x_3 = b_3$$

is consistent.

Work. The system of linear equations can be represented as an augmented matrix.

$$\left(\begin{array}{ccc|c}
1 & -1 & 1 & b_1 \\
-4 & 7 & 2 & b_2 \\
-2 & 3 & 0 & b_3
\end{array}\right)$$

Reducing this augmented matrix will provide the constraints on b_1, b_2 , and b_3 to make the system consistent.

$$\begin{pmatrix} 1 & -1 & 1 & b_1 \\ -4 & 7 & 2 & b_2 \\ -2 & 3 & 0 & b_3 \end{pmatrix} \xrightarrow{R_2 + 4R_1} \begin{pmatrix} 1 & -1 & 1 & b_1 \\ 0 & 3 & 6 & b_2 + 4b_1 \\ 0 & 1 & 2 & b_3 + 2b_1 \end{pmatrix}$$

$$\xrightarrow{R_2 - 3R_3} \begin{pmatrix} 1 & -1 & 1 & b_1 \\ 0 & 0 & 0 & b_2 + 4b_1 - 3b_3 - 6b_1 \\ 0 & 1 & 2 & b_3 + 2b_1 \end{pmatrix} \xrightarrow{R_2 \leftrightarrow R_3} \begin{pmatrix} 1 & -1 & 1 & b_1 \\ 0 & 1 & 2 & b_3 + 2b_1 \\ 0 & 0 & 0 & b_2 - 2b_1 - 3b_3 \end{pmatrix}$$

The last row represents the equation $0 = b_2 - 2b_1 - 3b_3$. If $0 = b_2 - 2b_1 - 3b_3$, then the augmented matrix can be put into reduced row echelon form without any leading 1's in the final column, and the matrix will be consistent. However, if $0 \neq b_2 - 2b_1 - 3b_3$, then the last row will have a leading entry in the last column, and thus there will no solution, meaning the system is not consistent.

Problem 7 Prove that for all $n \times n$ matrices A, the matrix $A^TA + 2AA^T$ is symmetric.

Proof. Consider square matrix A, and the matrix $A^TA + 2AA^T$. Now consider the transpose of this matrix, $(A^TA + 2AA^T)^T$.

$$(A^TA+2AA^T)^T=(A^TA)^T+(2AA^T)^T \qquad \qquad \text{by properties of transpose} \\ =A^T(A^T)^T+2(A^T)^TA^T \qquad \qquad \text{by properties of transpose} \\ (A^TA+2AA^T)^T=A^TA+2AA^T \\ \end{cases}$$

Since $(A^TA+2AA^T)^T=A^TA+2AA^T$, by definition, A^TA+2AA^T is a symmetric matrix, for all $A_{n\times n}$. \square
