

Linear DC-Servomotors

9,2 N

with Analog Hall Sensors

LM 2070 ... 11

Values at 22°C		LM 2070 ... 11	
Continuous force	$F_{e \max.}$	9,2	N
Peak force	$F_{p \max.}$	27,6	N
Continuous current	$I_{e \max.}$	0,79	A
Peak current	$I_{p \max.}$	2,4	A
Back-EMF constant	k_E	9,5	V/m/s
Force constant	k_F	11,64	N/A
Terminal resistance, phase-phase	R	10,83	Ω
Terminal inductance, phase-phase	L	1 125	μH
Thermal resistance	R_{th1} / R_{th2}	3,1 / 9,3	K/W
Thermal time constant	τ_{w1} / τ_{w2}	30 / 1 200	s
Operating temperature range		-20 ... +125	°C
Magnetic pitch	τ_m	24	mm
Rod bearings		polymer sleeves	
Housing material		metal, non-magnetic	
Direction of movement		electronically reversible	

	LM 2070-	040-11	080-11	120-11	160-11	220-11	
Stroke length	$S_{\max.}$	40	80	120	160	220	mm
Repeatability	σ_r	60	60	60	60	80	μm
Accuracy	σ_a	200	300	400	500	600	μm
Acceleration	$a_{e \max.}$	83,7	61,3	51,1	43,8	35,4	m/s^2
Speed	$v_{e \max.}$	1,8	2,2	2,6	2,6	2,8	m/s
Rod length	L_1	134	182	218	254	314	mm
Rod mass	m_m	110	150	180	210	260	g
Total mass	m_t	248	288	318	348	398	g

Note: These motors are for operation with DC-voltage < 75 V DC. The given values are for free standing motors.
Other rod lengths available on request.

Motor characteristic curves

Trapezoidal motion profile ($t_1 = t_2 = t_3$)

Displacement distance: 40 mm
Friction coefficient: 0,2
Slope angle: 0°
Rest time: 0,1 s

Load:

The max. applicable load (incl. rod) at a given speed with an external force of 0 N

External force:

The max. permissible external force at a given speed with a load (incl. rod) of:

- 0,5 kg —————
- 1,0 kg - - - - -
- 2,0 kg · · · · ·



