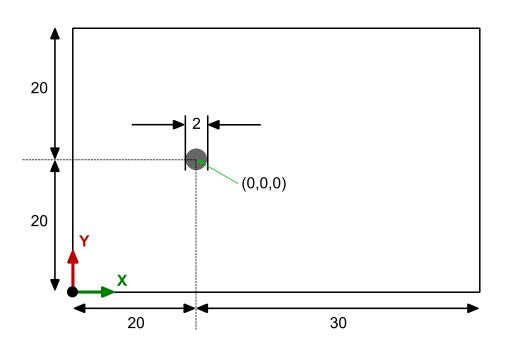
# Flow around a cylinder – 10 < Re < 2 000 000 Incompressible and compressible flow

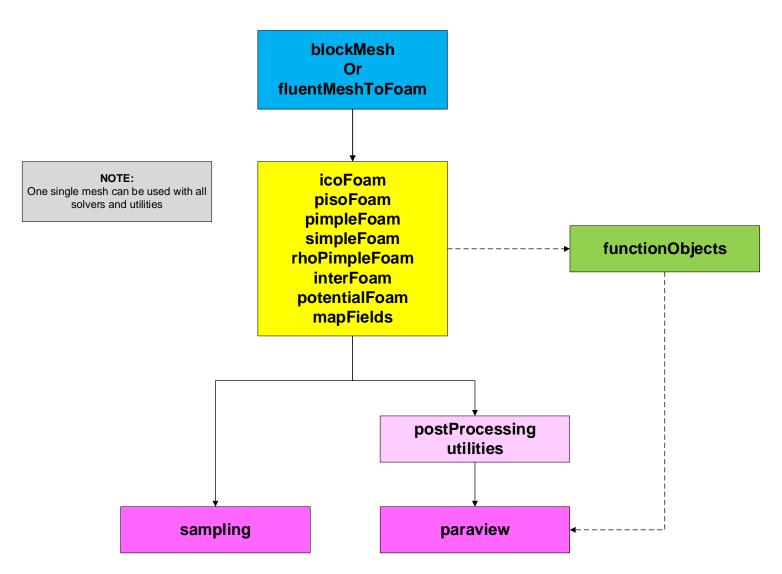


All the dimensions are in meters

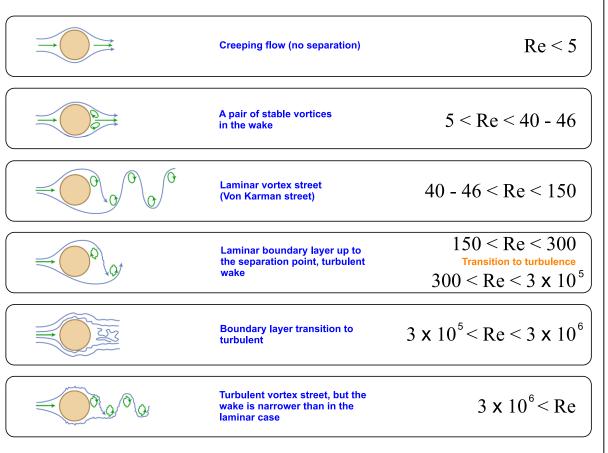
# Physical and numerical side of the problem:

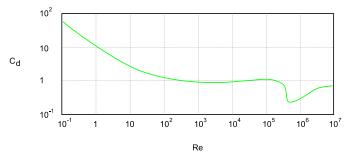
- In this case we are going to solve the flow around a cylinder. We are going to use incompressible and compressible solvers in laminar and turbulent regime.
- Therefore, the governing equations of the problem are the incompressible/compressible laminar/turbulent Navier-Stokes equations.
- We are going to work in a 2D domain.
- Depending on the Reynolds number, the flow can be steady or unsteady.
- This problem has a lot of validation data.

#### Workflow of the case

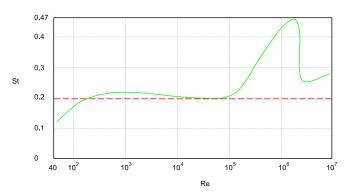


## Vortex shedding behind a cylinder





Drag coefficient



Strouhal number

# Some experimental (E) and numerical (N) results of the flow past a circular cylinder at various Reynolds numbers

Reference	$c_d - Re = 20$	L <sub>rb</sub> – Re = 20	$c_d - Re = 40$	L <sub>rb</sub> – Re = 40
[1] Tritton (E)	2.22	-	1.48	-
[2] Cuntanceau and Bouard (E)	-	0.73	-	1.89
[3] Russel and Wang (N)	2.13	0.94	1.60	2.29
[4] Calhoun and Wang (N)	2.19	0.91	1.62	2.18
[5] Ye et al. (N)	2.03	0.92	1.52	2.27
[6] Fornbern (N)	2.00	0.92	1.50	2.24
[7] Guerrero (N)	2.20	0.92	1.62	2.21

 $\mathbf{L_{rb}}$  = length of recirculation bubble,  $\mathbf{c_d}$  = drag coefficient,  $\mathbf{Re}$  = Reynolds number,

- [1] D. Tritton. Experiments on the flow past a circular cylinder at low Reynolds numbers. Journal of Fluid Mechanics, 6:547-567, 1959.
- [2] M. Cuntanceau and R. Bouard. Experimental determination of the main features of the viscous flow in the wake of a circular cylinder in uniform translation. Part 1. Steady flow. Journal of Fluid Mechanics, 79:257-272, 1973.
- [3] D. Rusell and Z. Wang. A cartesian grid method for modeling multiple moving objects in 2D incompressible viscous flow. Journal of Computational Physics, 191:177-205, 2003.
- [4] D. Calhoun and Z. Wang. A cartesian grid method for solving the two-dimensional streamfunction-vorticity equations in irregular regions. Journal of Computational Physics. 176:231-275, 2002.
- [5] T. Ye, R. Mittal, H. Udaykumar, and W. Shyy. An accurate cartesian grid method for viscous incompressible flows with complex immersed boundaries. Journal of Computational Physics, 156:209-240, 1999.
- [6] B. Fornberg. A numerical study of steady viscous flow past a circular cylinder. Journal of Fluid Mechanics, 98:819-855, 1980.
- [7] J. Guerrero. Numerical simulation of the unsteady aerodynamics of flapping flight. PhD Thesis, University of Genoa, 2009.

# Some experimental (E) and numerical (N) results of the flow past a circular cylinder at various Reynolds numbers

Reference	$c_d - Re = 100$	c <sub>I</sub> – Re = 100	c <sub>d</sub> – Re = 200	c <sub>I</sub> – Re = 200
[1] Russel and Wang <sup>(N)</sup>	1.38 ± 0.007	± 0.322	1.29 ± 0.022	± 0.50
[2] Calhoun and Wang <sup>(N)</sup>	1.35 ± 0.014	± 0.30	1.17 ± 0.058	± 0.67
[3] Braza et al. (N)	1.386± 0.015	± 0.25	$1.40\pm0.05$	± 0.75
[4] Choi et al. (N)	1.34 ± 0.011	± 0.315	1.36 ± 0.048	± 0.64
[5] Liu et al. (N)	1.35 ± 0.012	± 0.339	1.31 ± 0.049	± 0.69
[6] Guerrero (N)	1.38 ± 0.012	± 0.333	1.408 ± 0.048	± 0.725

 $c_1$  = lift coefficient,  $c_d$  = drag coefficient, Re = Reynolds number

<sup>[1]</sup> D. Rusell and Z. Wang. A cartesian grid method for modeling multiple moving objects in 2D incompressible viscous flow. Journal of Computational Physics, 191:177-205, 2003.

<sup>[2]</sup> D. Calhoun and Z. Wang. A cartesian grid method for solving the two-dimensional streamfunction-vorticity equations in irregular regions. Journal of Computational Physics. 176:231-275, 2002.

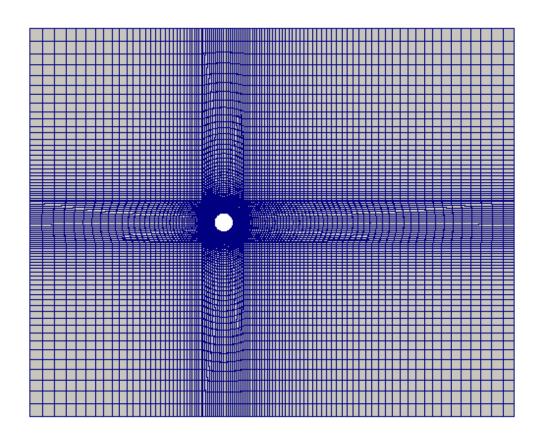
<sup>[3]</sup> M. Braza, P. Chassaing, and H. Hinh. Numerical study and physical analysis of the pressure and velocity fields in the near wake of a circular cylinder. Journal of Fluid Mechanics, 165:79-130, 1986.

<sup>[4]</sup> J. Choi, R. Oberoi, J. Edwards, an J. Rosati. An immersed boundary method for complex incompressible flows. Journal of Computational Physics, 224:757-784, 2007.

<sup>[5]</sup> C. Liu, X. Zheng, and C. Sung. Preconditioned multigrid methods for unsteady incompressible flows. Journal of Computational Physics, 139:33-57, 1998.

<sup>[6]</sup> J. Guerrero. Numerical Simulation of the unsteady aerodynamics of flapping flight. PhD Thesis, University of Genoa, 2009.

At the end of the day you should get something like this



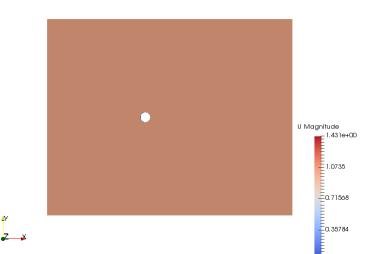


Mesh

#### At the end of the day you should get something like this

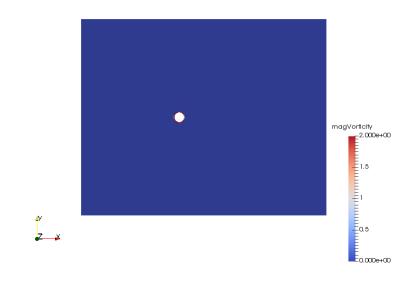


Time: 0.000000



Instantaneous velocity magnitude field www.wolfdynamics.com/wiki/cylinder vortex shedding/movymag.gif

Time: 0.000000

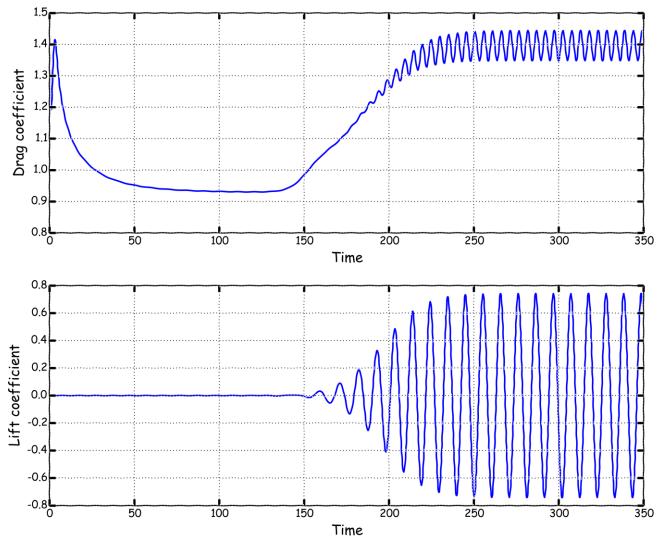


Instantaneous vorticity magnitude field www.wolfdynamics.com/wiki/cylinder vortex shedding/movvort.gif

Incompressible flow - Reynolds 200

E0.000e+00

### At the end of the day you should get something like this



Let us run our first case. Go to the directory:

## vortex\_shedding



- From this point on, please follow me.
- We are all going to work at the same pace.
- Remember, \$PTOFC is pointing to the path where you unpacked the tutorials.

#### What are we going to do?

- We will use this case to learn how to use different solvers and utilities.
- We will learn how to convert the mesh from a third party software.
- We will learn how to use setFields to accelerate the convergence.
- We will learn how to map a solution from a coarse mesh to a fine mesh.
- We will learn how to setup a compressible solver.
- We will learn how to setup a turbulence case.
- We will use gnuplot to plot and compute the mean values of the lift and drag coefficients.
- We will visualize unsteady data.

### Running the case

- Let us first convert the mesh from a third-party format (Fluent format).
- You will find this tutorial in the directory \$PTOFC/1010F/vortex\_shedding/c2
- In the terminal window type:

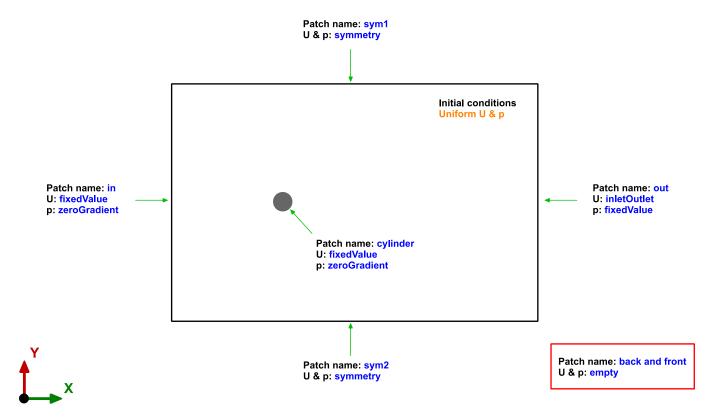
```
    $> foamCleanTutorials
    $> fluent3DMeshToFoam ../../meshes_and_geometries/vortex_shedding/ascii.msh
    $> checkMesh
    $> paraFoam
```

- In step 2, we convert the mesh from Fluent format to OpenFOAM® format. Have in mind that the Fluent mesh must be in ascii format.
- If we try to open the mesh using paraFoam (step 4), it will crash. Can you tell what is the problem (read the screen)?

### Running the case

- To avoid this problem, type in the terminal,
  - 1. | \$> paraFoam -builtin
- Basically, the problem is related to the names and type of the patches in the file
   boundary and the boundary conditions (U, p). Notice that OpenFOAM® is telling you
   what and where is the error.

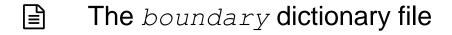
- Remember, when converting meshes the name and type of the patches are not always set as you would like, so it is always a good idea to take a look at the file boundary and modify it according to your needs.
- Let us modify the boundary dictionary file.
- In this case, we would like to setup the following primitive type boundary conditions.



## The boundary dictionary file

```
19
20
           out
               type
                                 patch;
               nFaces
                                 80:
               startFace
                                 18180;
26
           sym1
               type
                                 symmetry;
               inGroups
                                 1 (symmetry);
               nFaces
                                 100:
31
               startFace
                                 18260;
32
33
           sym2
               type
                                 symmetry;
               inGroups
                                 1 (symmetry);
37
               nFaces
                                 100;
               startFace
                                 18360:
39
          }
40
          in
41
               type
                                 patch;
43
               nFaces
44
               startFace
                                 18460:
```

- This dictionary is located in the constant/polyMesh directory.
- This file is automatically created when converting the mesh.
- The type of the out patch is OK.
- The type of the sym1 patch is OK.
- The type of the sym2 patch is OK.
- The type of the in patch is OK.



```
cylinder
47
                                wall;
               type
                                1 (wall);
               inGroups
               nFaces
               startFace
                                18540;
53
          back
54
               type
                                patch;
                                9200:
               nFaces
               startFace
                                18620:
          }
          front
61
               type
                                patch;
                                9200;
               nFaces
               startFace
                                27820:
```

- The type of the **cylinder** patch is OK.
- The type of the back patch is NOT OK.
   Remember, this is a 2D simulation, therefore the type should be empty.
- The type of the front patch is NOT OK.
   Remember, this is a 2D simulation, therefore the type should be empty.
- Remember, we assign the primitive type boundary conditions (numerical values), in the field files found in the directory o

- At this point, check that the **name** and **type** of the **base type** boundary conditions and **primitive type** boundary conditions are consistent. If everything is ok, we are ready to go.
- Do not forget to explore the rest of the dictionary files, namely:
  - 0/p (p is defined as relative pressure)
  - 0/U
  - constant/transportProperties
  - system/controlDict
  - system/fvSchemes
  - system/fvSolution
- Reminder:
  - The diameter of the cylinder is 2.0 m.
  - And we are targeting for a Re = 200.

$$\nu = \frac{\mu}{\rho} \qquad Re = \frac{\rho \times U \times D}{\mu} = \frac{U \times D}{\nu}$$

### Running the case

- You will find this tutorial in the directory \$PTOFC/1010F/vortex\_shedding/c2
- In the folder c1 you will find the same setup, but to generate the mesh we use blockMesh (the mesh is identical).
- To run this case, in the terminal window type:

```
1. | $> renumberMesh -overwrite
```

- 2. | \$> icoFoam > log.icofoam &
- 3. | \$> pyFoamPlotWatcher.py log.icofoam
- 4. \$\frac{\\$> \text{gnuplot scripts0/plot\_coeffs}}{\text{You will need to launch this script in a different terminal}}\$
- 5. | \$> paraFoam

### Running the case

- In step 1 we use the utility renumberMesh to make the linear system more diagonal dominant, this will speed-up the linear solvers. This is inexpensive (even for large meshes), therefore is highly recommended to always do it.
- In step 2 we run the simulation and save the log file. Notice that we are sending the
  job to background.
- In step 3 we use pyFoamPlotWatcher.py to plot the residuals on-the-fly. As the job is running in background, we can launch this utility in the same terminal tab.
- In step 4 we use the gnuplot script scripts0/plot\_coeffs to plot the force coefficients on-the-fly. Besides monitoring the residuals, is always a good idea to monitor a quantity of interest. Feel free to take a look at the script and to reuse it.
- The force coefficients are computed using functionObjects.
- After the simulation is over, we use paraFoam to visualize the results. Remember to
  use the VCR Controls to animate the solution.
- In the folder c1 you will find the same setup, but to generate the mesh we use blockMesh (the mesh is identical).

- At this point try to use the following utilities. In the terminal type:
  - \$> postProcess -func vorticity -noZero
    This utility will compute and write the vorticity field. The -noZero option means do not compute the vorticity field for the solution in the directory 0. If you do not add the -noZero option, it will compute and write the vorticity field for all the saved solutions, including 0
  - \$> postprocess -func 'grad(U)' -latestTime
    This utility will compute and write the velocity gradient or grad(U) in the whole domain (including at the walls). The
    -latestTime option means compute the velocity gradient only for the last saved solution.
  - \$> postprocess -func 'grad(p)'
     This utility will compute and write the pressure gradient or grad(U) in the whole domain (including at the walls).
  - \$> postProcess -func 'div(U)'
    This utility will compute and write the divergence of the velocity field or grad(U) in the whole domain (including at the walls). You will need to add the keyword div(U) Gauss linear; in the dictionary fvSchemes.
  - \$> foamToVTK -time 50:300

    This utility will convert the saved solution from OpenFOAM® format to VTK format. The -time 50:300 option means convert the solution to VTK format only for the time directories 50 to 300
  - \$> pisoFoam -postProcess -func CourantNo

    This utility will compute and write the Courant number. This utility needs to access the solver database for the physical properties and additional quantities, therefore we need to tell what solver we are using. As the solver icoFoam does not accept the option -postProcess, we can use the solver pisoFoam instead. Remember, icoFoam is a fully laminar solver and pisoFoam is a laminar/turbulent solver.
  - \$> pisoFoam -postProcess -func wallShearStress
    This utility will compute and write the wall shear stresses at the walls. As no arguments are given, it will save the wall shear stresses for all time steps.

### Let us run the same case but using a non-uniform field

- In the previous case, it took about 150 seconds to onset the instability.
- If you are not interested in the initial transient, we can add a perturbation in order to promote the onset of the instability. Let us use setFields to initialize a non-uniform flow.
- This case is already setup in the directory

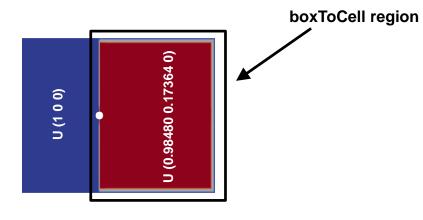
\$PTOFC/1010F/vortex\_shedding/c3

#### Let us run the same case but using a non-uniform field



```
17
      defaultFieldValues
18
19
          volVectorFieldValue U (1 0 0)
20
      );
21
22
      regions
23
24
          boxToCell
25
26
              box (0 -100 -100) (100 100 100);
27
              fieldValues
28
29
                   volVectorFieldValue U (0.98480 0.17364 0)
30
              );
31
32
      );
```

- This dictionary file is located in the directory system.
- In lines 17-20 we set the default value of the velocity vector to be (0 0 0) in the whole domain.
- In lines 24-31, we initialize a rectangular region (box) just behind the cylinder with a velocity vector equal to (0.98480 0.17364 0)
- In this case, setFields will look for the dictionary file U
  and it will overwrite the original values according to the
  regions defined in setFieldsDict.



#### Let us run the same case but using a non-uniform field – Running the case

- You will find this tutorial in the directory \$PTOFC/1010F/vortex shedding/c3
- Feel free to use the Fluent mesh or the mesh generated with blockMesh.
- In this case, we will use blockMesh.
- To run this case, in the terminal window type:
  - 1. | \$> foamCleanTutorials
  - 2. | \$> blockMesh
  - 3. \$ > rm rf 0 > /dev/null 2 > &1
  - 4. | \$> cp -r 0 org/ 0
  - 5. | \$> setFields
  - 6. | \$> renumberMesh -overwrite
  - 7. | \$> icoFoam > log.icofoam &
  - 8. | \$> pyFoamPlotWatcher.py log.icofoam
  - 9. | \$> gnuplot scripts0/plot\_coeffs
    - You will need to launch this script in a different terminal
  - **10**. | \$> paraFoam

## Running the case Let us run the same case but using a non-uniform field

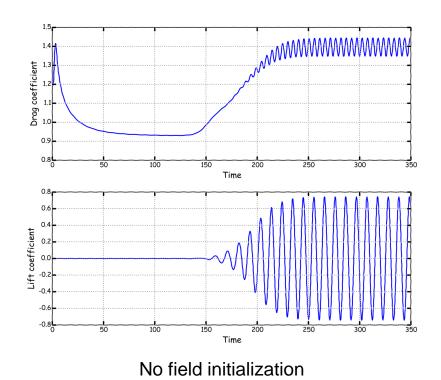
- In step 2 we generate the mesh using blockMesh. The name and type of the patches are already set in the dictionary blockMeshDict so there is no need to modify the boundary file.
- In step 4 we copy the original files to the directory  $\mathbf{0}$ . We do this to keep a backup of the original files as the file  $\mathcal{O}/\mathcal{U}$  will be overwritten.
- In step 5 we initialize the solution using setFields.
- In step 6 we use the utility renumberMesh to make the linear system more diagonal dominant, this will speed-up the linear solvers.
- In step 7 we run the simulation and save the log file. Notice that we are sending the
  job to background.
- In step 8 we use pyFoamPlotWatcher.py to plot the residuals on-the-fly. As the job is running in background, we can launch this utility in the same terminal tab.
- In step 9 we use the gnuplot script scripts0/plot\_coeffs to plot the lift and drag coefficients on-the-fly. Besides monitoring the residuals, is always a good idea to monitor a quantity of interest. Feel free to take a look at the script and to reuse it.

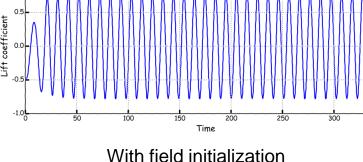
#### Does field initialization make a difference?

A picture is worth a thousand words. No need to tell you yes, even if the solutions are slightly different.

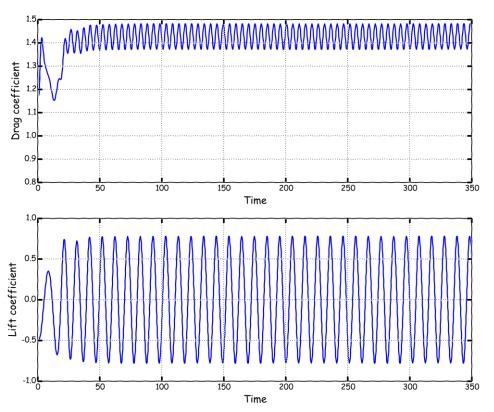
Drag coefficient

This bring us to the next subject, for how long should we run the simulation?



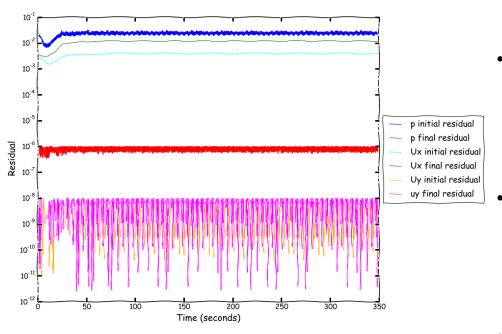


### For how long should run the simulation?



- This is the difficult part when dealing with unsteady flows.
- Usually you run the simulation until the behavior of a quantity of interest does not oscillates or it becomes periodic.
- In this case we can say that after the 50 seconds mark the solution becomes periodic, therefore there is no need to run up to 350 seconds.
- We can stop the simulation at 150 seconds (or maybe less), and do the average of the quantities between 100 and 150 seconds.

#### What about the residuals?



- Residuals are telling you a lot, but they are difficult to interpret.
- In this case the fact that the initial residuals are increasing after about 10 seconds, does not mean that the solution is diverging. This is in indication that something is happening (in this case the onset of the instability).
- Remember, the residuals should always drop to the tolerance criteria set in the fvSolution dictionary. If they do not drop to the desired tolerance, we are talking about unconverged time-steps.
- Things that are not clear from the residuals:
  - For how long should we run the simulation?
  - Is the solution is converging to the right value?

#### How to compute force coefficients

```
68
       functions
69
195
           forceCoeffs object
196
205
                type forceCoeffs;
206
                functionObjectLibs ("libforces.so");
208
               patches (cylinder);
209
210
                pName p;
211
                Uname U:
212
                rhoName rhoInf;
213
                rhoInf 1.0;
214
215
               //// Dump to file
216
                log true;
217
218
                CofR (0.0 0 0);
219
                liftDir (0 1 0);
220
                dragDir (1 \ 0 \ 0);
221
               pitchAxis (0 0 1);
222
               magUInf 1.0;
223
               lRef 1.0;
224
               Aref 2.0;
225
226
               outputControl
                                timeStep;
227
               outputInterval 1;
228
           }
255
       };
```

- To compute the force coefficients we use functionObjects.
- Remember, functionObjects are defined at the end of the controlDict dictionary file.
- In line 195 we give a name to the functionObject.
- In line 208 we define the patch where we want to compute the forces.
- In lines 212-213 we define the reference density value.
- In line 218 we define the center of rotation (for moments).
- In line 219 we define the lift force axis.
- In line 220 we define the drag force axis.
- In line 221 we define the axis of rotation for moment computation.
- In line 223 we give the reference length (for computing the moments)
- In line 224 we give the reference area (in this case the frontal area).
- The output of this functionObject is saved in the file forceCoeffs.dat located in the directory forceCoeffs object/0/

### Can we compute basic statistics of the force coefficients using gnuplot?

Yes we can. Enter the gnuplot prompt and type:

- 1. gnuplot> stats 'postProcessing/forceCoeffs\_object/0/forceCoeffs.dat' u 3
  This will compute the basic statistics of all the rows in the file forceCoeffs.dat (we are sampling column 3 in the input file)
- 2. gnuplot> stats 'postProcessing/forceCoeffs\_object/0/forceCoeffs.dat' every ::3000::7000 u 3
  This will compute the basic statistics of rows 3000 to 7000 in the file forceCoeffs.dat (we are sampling column 3 in the input file)
- 3. gnuplot> plot 'postProcessing/forceCoeffs\_object/0/forceCoeffs.dat' u 3 w 1 This will plot column 3 against the row number (iteration number)
- 4. gnuplot> exit
  To exit gnuplot

Remember the force coefficients information is saved in the file forceCoeffs.dat located in the directory postProcessing/forceCoeffs\_object/0

#### On the solution accuracy

```
17
      ddtSchemes
18
20
        default
                         backward;
22
23
24
      gradSchemes
31
          default.
                             leastSquares;
37
38
39
      divSchemes
40
41
          default
45
          div(phi,U)
                           Gauss linearUpwind default;
49
50
51
      laplacianSchemes
52
59
          default
                           Gauss linear limited 1;
60
61
62
      interpolationSchemes
63
64
          default
                           linear;
66
68
      snGradSchemes
69
71
          default
                           limited 1;
72
```

- At the end of the day we want a solution that is second order accurate.
- We define the discretization schemes (and therefore the accuracy) in the dictionary fvSchemes.
- In this case, for time discretization (ddtSchemes) we are using the backward method.
- For gradient discretization (gradSchemes) we are using the leastSquares method.
- For the discretization of the convective terms (divSchemes)
  we are using linearUpwind interpolation method for the term
  div(rho,U).
- For the discretization of the Laplacian (laplacianSchemes and snGradSchemes) we are using the Gauss linear limited 1 method
- This method is second order accurate.

#### On the solution tolerance and linear solvers

```
17
      solvers
18
31
          р
32
33
               solver
                                 GAMG:
34
               tolerance
                                 1e-6:
35
               relTol
36
                                 GaussSeidel:
               smoother
37
               nPreSweeps
                                 0:
38
               nPostSweeps
39
               cacheAgglomeration on;
40
               agglomerator
                                 faceAreaPair:
41
               nCellsInCoarsestLevel 100;
42
               mergeLevels
43
          }
44
45
          pFinal
46
47
               $p;
               relTol
48
49
50
51
          U
52
53
               solver
                                PBiCG:
54
               preconditioner
55
               tolerance
                                1e-08;
56
               relTol
                                0;
57
          }
69
70
71
      PISO
72
73
          nCorrectors
74
          nNonOrthogonalCorrectors 2;
77
```

- We define the solution tolerance and linear solvers in the dictionary fvSolution.
- To solve the pressure (p) we are using the GAMG method with an absolute tolerance of 1e-6 and a relative tolerance relTol of 0.01.
- The entry pFinal refers to the final correction of the PISO loop. It is possible to use a tighter convergence criteria only in the last iteration.
- To solve U we are using the solver PBiCG and the DILU preconditioner, with an absolute tolerance of 1e-8 and a relative tolerance relTol of 0 (the solver will stop iterating when it meets any of the conditions).
- Solving for the velocity is relative inexpensive, whereas solving for the pressure is expensive.
- The PISO sub-dictionary contains entries related to the pressure-velocity coupling (in this case the PISO method). Hereafter we are doing two PISO correctors (nCorrectors) and two non-orthogonal corrections (nNonOrthogonalCorrectors).

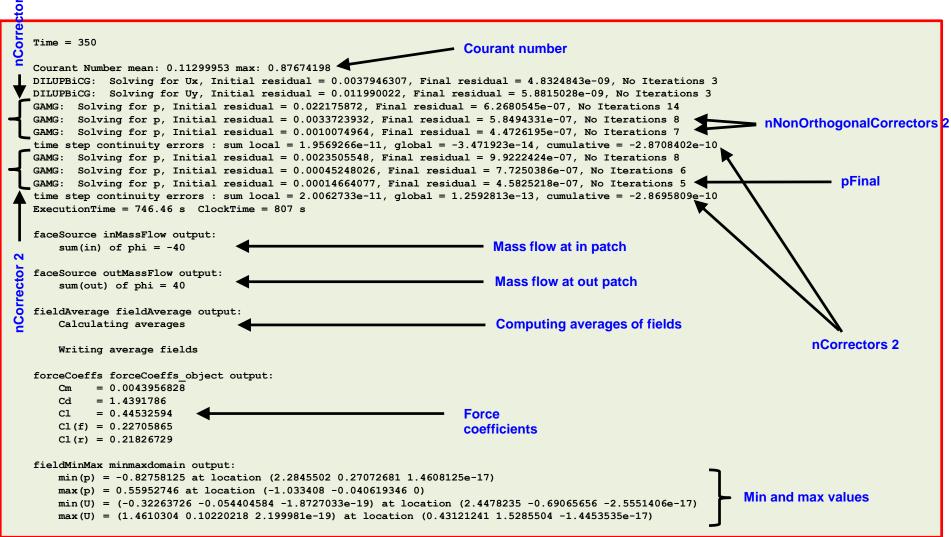
#### On the runtime parameters

```
17
       application
                        icoFoam;
18
20
       startFrom
                        latestTime;
21
22
       startTime
                        0:
23
24
       stopAt
                        endTime;
26
27
       endTime
                        350:
29
33
       deltaT
                        0.05:
34
35
       writeControl
                        runTime;
43
44
       writeInterval
45
52
       purgeWrite
                        0 :
53
54
       writeFormat
                        ascii;
55
56
       writePrecision 8;
57
58
       writeCompression off;
59
60
       timeFormat
                        general;
61
62
       timePrecision
63
64
       runTimeModifiable true;
```

- This case starts from the latest saved solution (startFrom).
- In this case as there are no saved solutions, it will start from 0 (startTime).
- It will run up to 350 seconds (endTime).
- The time step of the simulation is 0.05 seconds (deltaT). The time step has been chosen in such a way that the Courant number is less than 1
- It will write the solution every 1 second (**writeInterval**) of simulation time (**runTime**).
- It will keep all the solution directories (purgeWrite).
- It will save the solution in ascii format (writeFormat).
- The write precision is 8 digits (writePrecision).
- And as the option runTimeModifiable is on, we can modify all these entries while we are running the simulation.

### The output screen

This is the output screen of the icoFoam solver.



#### Let us run the same case but this time using a potential solver

- In this case we are going to use the potential solver potential Foam (remember potential solvers are inviscid, irrotational and incompressible)
- This solver is super fast and it can be used to find a solution to be used as initial conditions (non-uniform field) for an incompressible solver.
- This case is already setup in the directory

- Do not forget to explore the dictionary files.
- The following dictionaries are different
  - system/fvSchemes
  - system/fvSolution

Try to spot the differences.

# Running the case Let us run the same case but this time using a potential solver

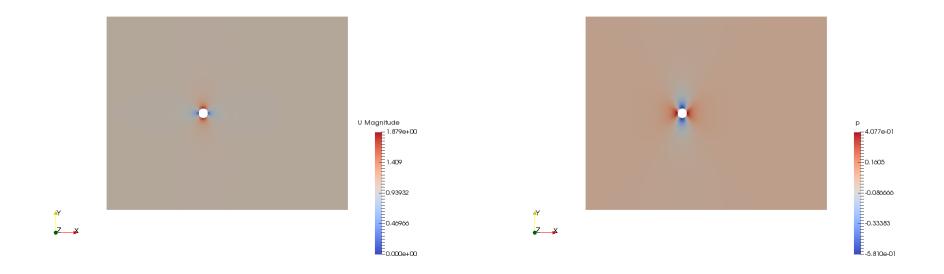
- You will find this tutorial in the directory \$PTOFC/1010F/vortex\_shedding/c4
- Feel free to use the Fluent mesh or the mesh generated with blockMesh. In this case we will use blockMesh.
- To run this case, in the terminal window type:
  - 1. \$> foamCleanTutorials
  - 2. | \$> blockMesh
  - 3. | \$ > rm rf 0 > /dev/null 2 > &1
  - 4. | \$> cp -r 0\_org 0
  - 5. | \$> potentialFoam -noFunctionObjects -initialiseUBCs -writep -writePhi
  - 6. | \$> paraFoam

# Running the case Let us run the same case but this time using a potential solver

- In step 2 we generate the mesh using blockMesh. The name and type of the patches are already set in the dictionary blockMeshDict so there is no need to modify the boundary file.
- In step 4 we copy the original files to the directory 0. We do this to keep a backup of the original files as they will be overwritten by the solver potentialFoam.
- In step 5 we run the solver. We use the option -noFunctionObjects to avoid conflicts with the functionobjects. The options -writep and -writePhi will write the pressure field and fluxes respectively.
- At this point, if you want to use this solution as initial conditions for an incompressible solver, just copy the files U and p into the start directory of the incompressible case you are looking to run. Have in mind that the meshes need to be the same.
- Be careful with the name and type of the boundary conditions, they should be same between the potential case and incompressible case.

#### **Potential solution**

- Using a potential solution as initial conditions is much better than using a uniform flow. It will speed up the solution and it will give you more stability.
- Finding a solution using the potential solver is inexpensive.

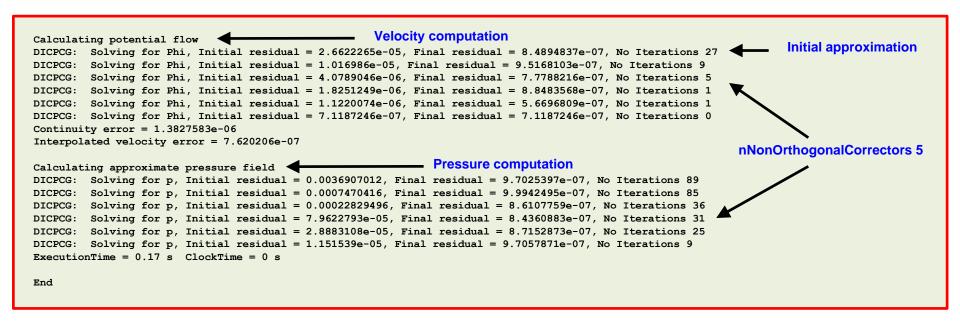


Velocity field

Pressure field

#### The output screen

- This is the output screen of the potentialFoam solver.
- The output of this solver is also a good indication of the sensitivity of the mesh quality
  to gradients computation. If you see that the number of iterations are dropping
  iteration after iteration, it means that it is a good mesh.
- If the number of iterations remain stalled, it means that the mesh is sensitive to gradients.
- In this case we have a good mesh.



#### Let us map a solution from a coarse mesh to a finer mesh

- It is also possible to map the solution from a coarse mesh to a finer mesh (and all the way around).
- For instance, you can compute a full Navier Stokes solution in a coarse mesh (fast solution), and then map it to a finer mesh.
- Let us map the solution from the potential solver to a finer mesh (if you want you can map the solution obtained using icoFoam). To do this we will use the utility mapFields.
- This case is already setup in the directory

\$PTOFC/1010F/vortex\_shedding/c6

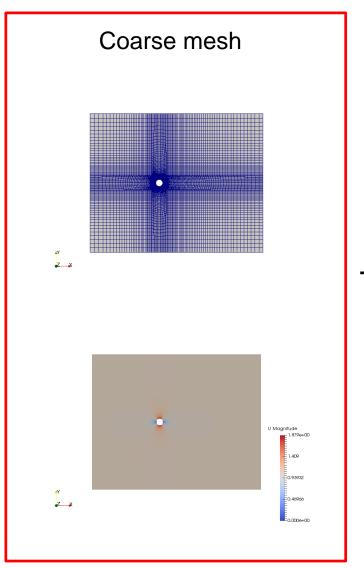
#### Running the case Let us map a solution from a coarse mesh to a finer mesh

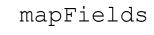
- You will find this tutorial in the directory \$PTOFC/1010F/vortex\_shedding/c6
- To generate the mesh, use blockMesh (remember this mesh is finer).
- To run this case, in the terminal window type:
  - 1. | \$> foamCleanTutorials
  - 2. | \$> blockMesh
  - 3. | \$ > rm rf 0 > /dev/null 2 > &1
  - 4. | \$> cp -r 0\_org 0
  - 5. | \$> mapfields ../c4 -consistent -noFunctionObjects -mapMethod cellPointInterpolate -sourceTime 0
  - 6. | \$> paraFoam

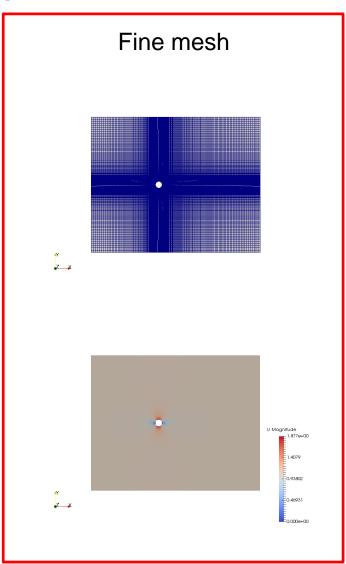
#### Running the case Let us map a solution from a coarse mesh to a finer mesh

- In step 2 we generate a finer mesh using blockMesh. The name and type of the patches are already set in the dictionary blockMeshDict so there is no need to modify the boundary file.
- In step 4 we copy the original files to the directory 0. We do this to keep a backup of the original files as they will be overwritten by the utility mapFields.
- In step 5 we use the utility mapFields with the following options:
  - We copy the solution from the directory . . / c4
  - The options -consistent is used when the domains and BCs are the same.
  - The option -noFunctionObjects is used to avoid conflicts with the functionObjects.
  - The option -mapMethod cellPointInterpolate defines the interpolation method.
  - The option -sourceTime 0 defines the time from which we want to interpolate the solution.

#### The meshes and the mapped fields

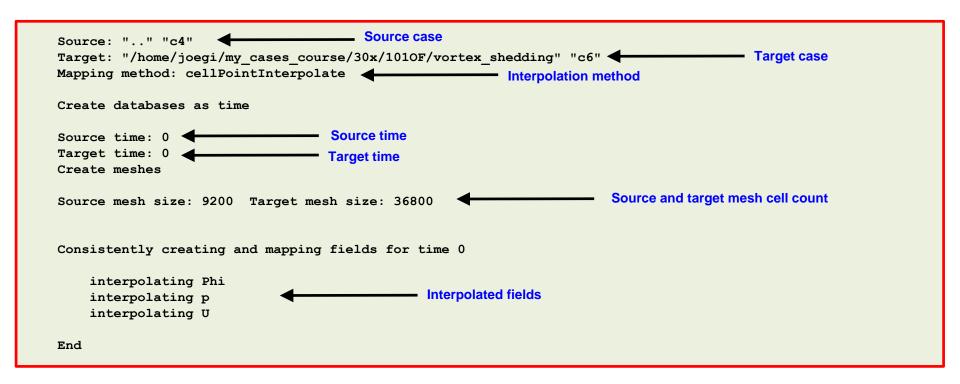






#### The output screen

- This is the output screen of the mapFields utility.
- The utility mapFields, will try to interpolate all fields in the source directory.
- You can control the target time via the startFrom and startTime keywords in the controlDict dictionary file.



#### Setting a turbulent case

- So far we have only used laminar incompressible solvers.
- Let us do a turbulent simulation.
- When doing turbulent simulations, we need to choose the turbulence model, define the boundary and initial conditions for the turbulent quantities, and modify the fvSchemes and fvSolution dictionaries to take account for the new variables we are solving (the transported turbulent quantities).
- This case is already setup in the directory

\$PTOFC/1010F/vortex\_shedding/c14

- The following dictionaries remain unchanged
  - system/blockMeshDict
  - constant/polyMesh/boundary
  - 0/p
  - 0/U
- The following dictionaries need to be adapted for the turbulence case
  - constant/transportProperties
  - system/controlDict
  - system/fvSchemes
  - system/fvSolution
- The following dictionaries need to be adapted for the turbulence case
  - constant/turbulenceProperties

- The transportProperties dictionary file
- This dictionary file is located in the directory constant.
- In this file we set the transport model and the kinematic viscosity (nu).

```
16 transportModel Newtonian;
17
19 nu nu [ 0 2 -1 0 0 0 0 ] 0.0002;
```

- Reminder:
  - The diameter of the cylinder is 2.0 m.
  - And we are targeting for a Re = 10000.

$$\nu = \frac{\mu}{\rho} \qquad Re = \frac{\rho \times U \times D}{\mu} = \frac{U \times D}{\nu}$$

#### The turbulenceProperties dictionary file

- This dictionary file is located in the directory constant.
- In this dictionary file we select what model we would like to use (laminar or turbulent).
- In this case we are interested in modeling turbulence, therefore the dictionary is as follows:

```
17
       simulationType RAS;
                                         RANS type simulation
18
19

    RANS sub-dictionary

20
                                                              RANS model to use
21
            RASModel
                               kOmegaSST;
22
            turbulence
                                                       Turn on/off turbulence. Runtime modifiable
23
24
                                                       Print coefficients at the beginning
25
            printCoeffs
26
```

If you want to know the models available use the banana method.

#### The controlDict dictionary

```
17
       application
                        pimpleFoam;
18
20
       startFrom
                        latestTime;
21
22
       startTime
                       0:
23
24
       stopAt
                        endTime;
25
26
                       500:
       endTime
27
28
       deltaT
                       0.001:
32
33
                       runTime;
       writeControl
41
42
       writeInterval
43
50
       purgeWrite
51
52
       writeFormat
                        ascii:
53
54
       writePrecision 8;
55
56
       writeCompression off;
57
58
       timeFormat
                        general;
59
60
       timePrecision
61
62
       runTimeModifiable yes;
63
64
       adjustTimeStep yes;
65
66
       maxCo
67
       maxDeltaT
                       0.1:
```

- This case will start from the last saved solution (**startFrom**). If there is no solution, the case will start from time 0 (**startTime**).
- It will run up to 500 seconds (endTime).
- The initial time step of the simulation is 0.001 seconds (**deltaT**).
- It will write the solution every 1 second (**writeInterval**) of simulation time (**runTime**).
- It will keep all the solution directories (purgeWrite).
- It will save the solution in ascii format (writeFormat).
- The write precision is 8 digits (writePrecision).
- And as the option runTimeModifiable is on, we can modify all these entries while we are running the simulation.
- In line 64 we turn on the option adjustTimeStep. This option will automatically adjust the time step to achieve the maximum desired courant number maxCo (line 66).
- We also set a maximum time step **maxDeltaT** in line 67.
- Remember, the first time step of the simulation is done using the value set in line 28 and then it is automatically scaled to achieve the desired maximum values (lines 66-67).
- The feature adjustTimeStep is only present in the PIMPLE family solvers, but it can be added to any solver by modifying the source code.



#### The fvSchemes dictionary

```
17
      ddtSchemes
18
21
          default
                           CrankNicolson 0.5;
22
24
      gradSchemes
25
31
          default
                            leastSquares;
36
                             cellMDLimited Gauss linear 1;
          grad(U)
37
39
      divSchemes
40
41
          default
                           none;
47
          div(phi,U)
                           Gauss linearUpwindV grad(U);
49
          div((nuEff*dev2(T(grad(U))))) Gauss linear;
51
          div(phi,k)
                               Gauss linearUpwind default;
52
          div(phi,omega)
                               Gauss linearUpwind default;
63
65
      laplacianSchemes
66
74
           default
                            Gauss linear limited 1;
75
77
      interpolationSchemes
78
79
          default.
                           linear;
81
83
      snGradSchemes
84
86
          default
                           limited 1:
87
89
      wallDist
90
91
          method meshWave:
92
```

- In this case, for time discretization (ddtSchemes) we are using the blended CrankNicolson method. The blending coefficient goes from 0 to 1, where 0 is equivalent to the Euler method and 1 is a pure Crank Nicolson.
- For gradient discretization (gradSchemes) we are using as default option the leastSquares method. For grad(U) we are using Gauss linear with slope limiters (cellMDLimited). You can define different methods for every term in the governing equations, for example, you can define a different method for grad(p).
- For the discretization of the convective terms (divSchemes) we are using linearUpwindV interpolation method with slope limiters for the term div(phi,U).
- For the terms div(phi,k) and div(phi,omega) we are using linearUpwind interpolation method with no slope limiters. These terms are related to the turbulence modeling.
- For the term div((nuEff\*dev2(T(grad(U))))) we are using linear interpolation (this term is related to turbulence modeling).
- For the discretization of the Laplacian (laplacianSchemes and snGradSchemes) we are using the Gauss linear limited 1 method.
- To compute the distance to the wall and normals to the wall, we use the method meshWave. This only applies when using wall functions (turbulence modeling).
- This method is second order accurate.

```
17
       solvers
18
31
            р
32
33
                solver
                                   GAMG:
34
                tolerance
                                   1e-6:
35
                relTol
                                   0.001;
36
                                   GaussSeidel:
                smoother
37
                nPreSweeps
                                  0:
38
                nPostSweeps
39
                cacheAgglomeration on;
40
                agglomerator
                                   faceAreaPair;
41
                nCellsInCoarsestLevel 100;
42
                mergeLevels
44
                minIter
                                 2;
45
            }
46
47
            pFinal
48
49
                solver
                                  PCG:
50
                preconditioner DIC;
51
                                 1e-06:
                tolerance
52
                relTol
                                 0 ;
54
                minIter
                                3;
55
            }
56
57
            U
58
59
                                  PBiCG:
60
                preconditioner
                                 DILU;
61
                                 1e-08;
                tolerance
62
                relTol
                                 0;
63
                minIter
                                 3:
64
```

- To solve the pressure (p) we are using the GAMG method, with an absolute tolerance of 1e-6 and a relative tolerance relTol of 0.001.
   Notice that we are fixing the number of minimum iterations (miniter).
- To solve the final pressure correction (pFinal) we are using the PCG method with the DIC preconditioner, with an absolute tolerance of 1e-6 and a relative tolerance relTol of 0.
- Notice that we can use different methods between p and pFinal. In this
  case we are using a tighter tolerance for the last iteration.
- We are also fixing the number of minimum iterations (**miniter**). This entry is optional.
- To solve U we are using the solver PBiCG with the DILU preconditioner, an absolute tolerance of 1e-8 and a relative tolerance relTol of 0.
   Notice that we are fixing the number of minimum iterations (miniter).

```
17
       solvers
18
77
            UFinal
78
79
                                  PBiCG:
                solver
80
                                 DILU;
                preconditioner
81
                                 1e-08;
                tolerance
82
                relTol
                                 0;
83
                minIter
                                  3:
84
            }
85
86
            omega
87
                                  PBiCG;
88
                solver
89
                preconditioner DILU;
                                 1e-08;
90
                tolerance
91
                relTol
                                 0 :
                minIter
92
                                  3:
93
94
95
            omegaFinal
96
97
                                  PBiCG;
98
                preconditioner DILU;
99
                tolerance
                                 1e-08:
100
                relTol
                                 0 :
101
                minIter
                                  3;
102
            }
103
104
            k
105
106
                solver
                                  PBiCG:
107
                preconditioner
                                 DILU;
108
                tolerance
                                 1e-08:
109
                relTol
                                 0;
110
                minIter
                                  3:
111
```

- To solve UFinal we are using the solver PBiCG with an absolute tolerance of 1e-8 and a relative tolerance relTol of 0. Notice that we are fixing the number of minimum iterations (miniter).
- To solve omega and omegaFinal we are using the solver PBiCG with an absolute tolerance of 1e-8 and a relative tolerance relTol of 0.
   Notice that we are fixing the number of minimum iterations (miniter).
- To solve k we are using the solver PBiCG with an absolute tolerance of 1e-8 and a relative tolerance relTol of 0. Notice that we are fixing the number of minimum iterations (miniter).

```
113
           kFinal
114
115
                                 PBiCG:
                solver
116
                preconditioner DILU;
117
                tolerance
                                1e-08:
118
                relTol
                                0;
119
                                3:
                minIter
120
           }
121
122
123
       PIMPLE
124
126
                //nOuterCorrectors 1;
127
                nOuterCorrectors 2;
128
129
                nCorrectors 2;
130
                nNonOrthogonalCorrectors 1;
133
134
135
       relaxationFactors
136
137
           fields
138
139
                                0.3;
140
141
           equations
142
143
                U
                                0.7;
144
                                 0.7:
145
                                0.7:
                omega
146
147
```

- To solve kFinal we are using the solver PBiCG with an absolute tolerance of 1e-8 and a relative tolerance relTol of 0. Notice that we are fixing the number of minimum iterations (miniter).
- In lines 123-133 we setup the entries related to the pressure-velocity coupling method used (PIMPLE in this case). Setting the keyword nOuterCorrectors to 1 is equivalent to running using the PISO method.
- To gain more stability we are using 2 outer correctors (nOuterCorrectors), 2 inner correctors or PISO correctors (nCorrectors), and 1 correction due to non-orthogonality (nNonOrthogonalCorrectors).
- · Remember, adding corrections increase the computational cost.
- In lines 135-147 we setup the under relaxation factors used during the outer corrections (pseudo transient iterations). If you are working in PISO mode (only one outer correction or nOuterCorrectors), these values are ignored.

- The following dictionaries are new
  - 0/k
  - 0/omega
  - 0/nut

These are the field variables related to the closure equations of the turbulent model.

- As we are going to use the  $\kappa-\omega~SST~$  model we need to define the initial conditions and boundaries conditions.
- To define the IC/BC we will use the free stream values of  $\kappa$  and  $\omega$

## $\kappa-\omega~SST~$ Turbulence model free-stream boundary conditions

• The initial value for the turbulent kinetic energy  $\kappa$  can be found as follows

$$\kappa = \frac{3}{2}(UI)^2$$

• The initial value for the specific kinetic energy  $\,\omega\,$  can be found as follows

$$\omega = \frac{\rho \kappa}{\mu} \frac{\mu_t}{\mu}^{-1}$$

- Where  $\frac{\mu_t}{\mu}$  is the viscosity ratio and  $I=\frac{u'}{\overline{u}}$  is the turbulence intensity.
- If you are working with external aerodynamics or virtual wind tunnels, you can use the following reference values for the turbulence intensity and the viscosity ratio. They work most of the times, but it is a good idea to have some experimental data or a better initial estimate

	Low	Medium	High
I	1.0 %	5.0 %	10.0 %
$\mu_t/\mu$	1	10	100



#### The file 0/k

```
19
      internalField
                       uniform 0.00015;
20
21
      boundaryField
22
23
           out
24
25
               type
                                inletOutlet;
26
               inletValue
                                uniform 0.00015;
27
               value
                                uniform 0.00015;
28
           }
29
           sym1
30
           {
31
               type
                                 symmetryPlane;
32
33
           sym2
34
35
                                 symmetryPlane;
               type
36
37
           in
38
39
                                fixedValue;
               type
                                 uniform 0.00015;
40
               value
41
42
           cylinder
43
                                kqRWallFunction;
               type
45
               value
                                uniform 0.00015;
46
47
           back
48
49
               type
                                 empty;
50
51
           front
52
53
               type
                                 empty;
54
55
```

- We are using uniform initial conditions (line 19).
- For the in patch we are using a fixedValue boundary condition.
- For the out patch we are using an inletOutlet boundary condition (this boundary condition avoids backflow).
- For the cylinder patch (which is base type wall), we are using the kqRWallFunction boundary condition. This is a wall function, we are going to talk about this when we deal with turbulence modeling. Remember, we can use wall functions only if the patch is of base type wall.
- The rest of the patches are constrained.
- FYI, the inlet velocity is 1 and the turbulence intensity is equal to 1%.

#### The file 0/omega

```
19
      internalField
                        uniform 0.075;
20
21
      boundaryField
22
23
           out
24
25
               type
                                 inletOutlet:
26
               inletValue
                                 uniform 0.075;
27
               value
                                 uniform 0.075;
28
29
           sym1
30
           {
31
               type
                                 symmetryPlane;
32
33
           sym2
34
           {
35
                                 symmetryPlane;
               type
36
37
           in
38
39
               type
                                 fixedValue:
40
               value
                                 uniform 0.075;
41
42
           cylinder
43
44
               type
                                 omegaWallFunction;
45
               Cmu
                                 0.09;
                                 0.41:
46
               kappa
47
                                 9.8:
48
               beta1
                                 0.075:
49
               value
                                 uniform 0.075;
50
51
           back
52
53
               type
                                 empty;
54
55
           front
56
57
               type
                                 empty;
58
59
```

- We are using uniform initial conditions (line 19).
- For the in patch we are using a fixedValue boundary condition.
- For the out patch we are using an inletOutlet boundary condition (this boundary condition avoids backflow).
- For the cylinder patch (which is base type wall), we are using the omegaWallFunction boundary condition. This is a wall function, we are going to talk about this when we deal with turbulence modeling. Remember, we can use wall functions only if the patch is of base type wall.
- The rest of the patches are constrained.
- FYI, the inlet velocity is 1 and the eddy viscosity ratio is equal to 10.

#### The file 0/nut

```
19
      internalField
                        uniform 0;
20
21
      boundaryField
22
23
           out
24
25
               type
                                 calculated;
26
               value
                                 uniform 0;
27
28
           sym1
29
30
               type
                                 symmetryPlane;
31
32
           sym2
33
34
                                 symmetryPlane;
               type
35
36
           in
37
38
               type
                                 calculated;
39
               value
                                 uniform 0;
40
41
           cylinder
42
43
                                 nutkWallFunction:
               type
                                 0.09;
44
               Cmu
45
                                 0.41:
               kappa
46
                                 9.8:
47
               value
                                 uniform 0;
48
49
           back
50
51
               type
                                 empty;
52
53
           front
54
55
               type
                                 empty;
56
57
```

- We are using uniform initial conditions (line 19).
- For the in patch we are using the calculated boundary condition (nut is computed from kappa and omega)
- For the out patch we are using the calculated boundary condition (nut is computed from kappa and omega)
- For the cylinder patch (which is base type wall), we are using the nutkWallFunction boundary condition. This is a wall function, we are going to talk about this when we deal with turbulence modeling. Remember, we can use wall functions only if the patch is of base type wall.
- The rest of the patches are constrained.
- Remember, the turbulent viscosity  $V_t$  (nut) is equal to

 $\frac{\kappa}{\omega}$ 

#### Running the case – Setting a turbulent case

- You will find this tutorial in the directory \$PTOFC/1010F/vortex\_shedding/c14
- Feel free to use the Fluent mesh or the mesh generated with blockMesh. In this case we will use blockMesh.
- To run this case, in the terminal window type:
  - 1. | \$> foamCleanTutorials
  - 2. | \$> blockMesh
  - 3. | \$> renumberMesh -overwrite
  - 4. | \$> pimpleFoam > log &
  - 5. | \$> pyFoamPlotWatcher.py log
  - 6. \$\ \text{snuplot scripts0/plot\_coeffs}\$ You will need to launch this script in a different terminal}\$
  - 7. | \$> yPlus
  - 8. | \$> paraFoam

# Running the case Setting a turbulent case

- In step 3 we use the utility renumberMesh to make the linear system more diagonal dominant, this will speed-up the linear solvers.
- In step 4 we run the simulation and save the log file. Notice that we are sending the
  job to background.
- In step 5 we use pyFoamPlotWatcher.py to plot the residuals on-the-fly. As the job is running in background, we can launch this utility in the same terminal tab.
- In step 6 we use the gnuplot script scripts0/plot\_coeffs to plot the force coefficients on-the-fly. Besides monitoring the residuals, is always a good idea to monitor a quantity of interest. Feel free to take a look at the script and to reuse it.
- In step 7 we use the utility yPlus to compute the  $y^+$  value of each saved solution (we are going to talk about  $y^+$  when we deal with turbulence modeling).

pimpleFoam output screen

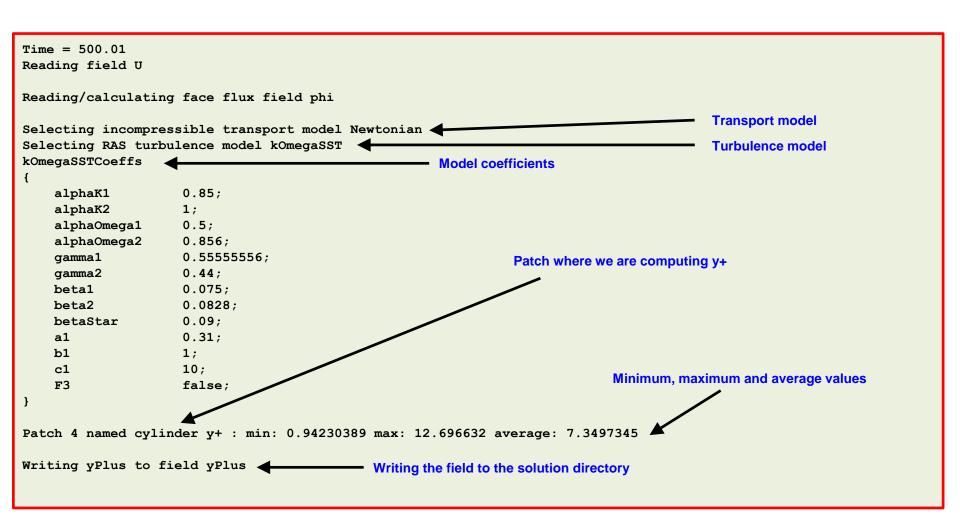
```
Courant number
Courant Number mean: 0.088931706 max: 0.90251464
deltaT = 0.040145538
                                                                                           Simulation time
Time = 499.97

    Outer iteration 1 (nOuterCorrectors)

DILUPBICG: Solving for Ux, Initial residual = 0.0028528538, Final residual = 9.5497298e-11, No Iterations 3
DILUPBICG: Solving for Uy, Initial residual = 0.0068876991, Final residual = 7.000938e-10, No Iterations 3
GAMG: Solving for p, Initial residual = 0.25644342, Final residual = 0.00022585963, No Iterations 7
GAMG: Solving for p. Initial residual = 0.0073871161, Final residual = 5.2798526e-06, No Iterations 8
time step continuity errors : sum local = 3.2664019e-10, qlobal = -1.3568363e-12, cumulative = -9.8446438e-08
GAMG: Solving for p, Initial residual = 0.16889316, Final residual = 0.00014947209, No Iterations 7
GAMG: Solving for p, Initial residual = 0.0051876466, Final residual = 3.7123156e-06, No Iterations 8
time step continuity errors : sum local = 2.2950163e-10, qlobal = -8.0710768e-13, cumulative = -9.8447245e-08
                           ————— Outer iteration 2 (nOuterCorrectors)
DILUPBICG: Solving for Ux, Initial residual = 0.0013482181, Final residual = 4.1395468e-10, No Iterations 3
DILUPBiCG: Solving for Uy, Initial residual = 0.0032433196, Final residual = 3.3969121e-09, No Iterations 3
GAMG: Solving for p, Initial residual = 0.10067317, Final residual = 8.9325549e-05, No Iterations 7
GAMG: Solving for p, Initial residual = 0.0042844521, Final residual = 3.0190597e-06, No Iterations 8
time step continuity errors : sum local = 1.735023e-10, global = -2.0653335e-13, cumulative = -9.8447452e-08
GAMG: Solving for p. Initial residual = 0.0050231165, Final residual = 3.2656397e-06, No Iterations 8
                                                                                                                        pFinal
DICPCG: Solving for p, Initial residual = 0.00031459519, Final residual = 9.4260163e-07, No Iterations 36
time step continuity errors : sum local = 5.4344408e-11, global = 4.0060595e-12, cumulative = -9.8443445e-08
DILUPBiCG: Solving for omega, Initial residual = 0.00060510266, Final residual = 1.5946601e-10, No Iterations 3
DILUPBiCG: Solving for k, Initial residual = 0.0032163247, Final residual = 6.9350899e-10, No Iterations 3
bounding k, min: -3.6865398e-05 max: 0.055400108 average: 0.0015914926
ExecutionTime = 1689.51 s ClockTime = 1704 s
fieldAverage fieldAverage output:
   Calculating averages
                                                                     Message letting you know that
                                                                                                                kappa and omega residuals
                                                                     the variable is becoming
forceCoeffs forceCoeffs object output:
                                                                     unbounded
         = 0.0023218797
         = 1.1832452
                                                                   Force coefficients
          = -1.3927646
   Cl(f) = -0.69406044
   Cl(r) = -0.6987042
fieldMinMax minmaxdomain output:
    \min(p) = -1.5466372 at location (-0.040619337 -1.033408 0)
   \max(p) = 0.54524589 at location (-1.033408 0.040619337 1.4015759e-17)
   \min(U) = (0.94205232 - 1.0407426 - 5.0319219e - 19) at location (-0.70200781 - 0.75945224 - 1.3630525e - 17)
                                                                                                                         Minimum and
   \max(U) = (1.8458167 \ 0.0047368607 \ 4.473279e-19) at location (-0.12989625 -1.0971865 2.4694467e-17)
                                                                                                                         maximum values
   \min(k) = 1e-15 at location (1.0972618\ 1.3921931\ -2.2329889e-17)
   \max(k) = 0.055400108 at location (2.1464795 0.42727634 0)
   min(omega) = 0.2355751 at location (29.403674 19.3304 0)
   \max(\text{omega}) = 21.477072 at location (1.033408\ 0.040619337\ 1.3245285e-17)
```

#### The output screen

This is the output screen of the yPlus utility.



#### Using a compressible solver

- So far we have only used incompressible solvers.
- Let us use the compressible solver rhoPimpleFoam, which is a

Transient solver for laminar or turbulent flow of compressible fluids for HVAC and similar applications. Uses the flexible PIMPLE (PISO-SIMPLE) solution for time-resolved and pseudo-transient simulations.

- When working with compressible solver we need to define the thermodynamical properties of the working fluid and the temperature field (we are also solving the energy equation)
- This case is already setup in the directory

\$PTOFC/1010F/vortex\_shedding/c24

- The following dictionaries remain unchanged
  - system/blockMeshDict
  - constant/polyMesh/boundary

- Reminder:
  - The diameter of the cylinder is 0.0002 m.
  - The working fluid is air at 20° Celsius and at a sea level.
  - Isothermal flow.
  - And we are targeting for a Re = 200.

$$\nu = \frac{\mu}{\rho} \qquad Re = \frac{\rho \times U \times D}{\mu} = \frac{U \times D}{\nu}$$

- The constant directory
- In this directory, we will find the following compulsory dictionary files:
  - thermophysical Properties
  - turbulenceProperties
- thermophysicalProperties contains the definition of the physical properties of the working fluid.
- turbulenceProperties contains the definition of the turbulence model to use.

The thermophysical Properties dictionary file

```
18
      thermoType
19
20
                            hePsiThermo;
           type
21
          mixture
                            pureMixture:
22
          transport
                            const;
23
           thermo
                            hConst:
24
          equationOfState perfectGas;
25
          specie
                            specie;
26
          energy
                            sensibleEnthalpy;
27
28
29
      mixture
30
31
          specie
32
33
               nMoles
                            1;
34
               molWeight
                            28.9:
35
36
          thermodynamics
37
38
               Ср
                            1005:
39
               Ηf
40
41
          transport
42
43
                            1.84e-05;
44
                            0.713;
               Pr
45
```

- This dictionary file is located in the directory constant.
   Thermophysical models are concerned with energy, heat and physical properties.
- In the sub-dictionary **thermoType** (lines 18-27), we define the thermophysical models.
- The transport modeling concerns evaluating dynamic viscosity (line 22). In this case the viscosity is constant.
- The thermodynamic models (**thermo**) are concerned with evaluating the specific heat Cp (line 23). In this case Cp is constant
- The equationOfState keyword (line 24) concerns to the equation of state of the working fluid. In this case

$$\rho = \frac{p}{RT}$$

The form of the energy equation to be used in the solution is specified in line 26 (energy). In this case we are using enthalpy (sensibleEnthalpy).

The thermophysical Properties dictionary file

```
18
      thermoType
19
20
                            hePsiThermo;
           type
21
          mixture
                            pureMixture;
          transport
                            const;
23
          thermo
                            hConst:
24
          equationOfState perfectGas;
25
          specie
                            specie;
26
                            sensibleEnthalpy;
          energy
27
28
29
      mixture
30
31
          specie
32
33
               nMoles
                            1;
34
               molWeight
                            28.9;
35
36
           thermodynamics
37
38
               Ср
                            1005:
39
               Ηf
40
41
          transport
42
43
                            1.84e-05;
44
                            0.713;
               Pr
45
```

- In the sub-dictionary mixture (lines 29-46), we define the thermophysical properties of the working fluid.
- In this case, we are defining the properties for air at 20° Celsius and at a sea level.

- The turbulenceProperties dictionary file
- In this dictionary file we select what model we would like to use (laminar or turbulent).
- This dictionary is compulsory.
- As we do not want to model turbulence, the dictionary is defined as follows,

17 simulationType laminar;

- The 0 directory
- In this directory, we will find the dictionary files that contain the boundary and initial conditions for all the primitive variables.
- As we are solving the compressible laminar Navier-Stokes equations, we will find the following field files:
  - p (pressure)
  - T (temperature)
  - U (velocity field)

#### The file 0/p

```
17
      dimensions
                        [1 -1 -2 0 0 0 0];
18
19
      internalField
                       uniform 101325:
20
21
      boundaryField
22
23
          in
24
25
               type
                                zeroGradient;
26
28
          out
29
30
                                fixedValue:
               type
31
               value
                                uniform 101325;
32
34
          cylinder
35
36
               type
                                zeroGradient;
37
39
          sym1
40
41
               type
                                symmetryPlane;
42
44
          sym2
45
46
                                symmetryPlane;
               type
47
49
          back
50
51
               type
                                empty;
52
54
          front
55
56
               type
                                empty;
57
58
```

- This file contains the boundary and initial conditions for the scalar field pressure (p). We are working with absolute pressure.
- Contrary to incompressible flows where we defined relative pressure, this is the absolute pressure.
- Also, pay attention to the units (line 17). The pressure is defined in Pascal.
- We are using uniform initial conditions (line 19).
- For the in patch we are using a zeroGradient boundary condition.
- For the outlet patch we are using a fixedValue boundary condition.
- For the cylinder patch we are using a zeroGradient boundary condition.
- The rest of the patches are constrained.

#### The file 0/T

```
17
      dimensions
                        [0\ 0\ 0\ -1\ 0\ 0\ 0];
18
19
      internalField
                        uniform 293.15:
20
21
      boundaryField
22
23
           in
24
25
               type
                                 fixedValue:
26
               value
                                 $internalField:
27
29
           out
30
31
               type
                                 inletOutlet;
32
               value
                                 $internalField;
33
               inletValue
                                 $internalField:
34
           }
36
           cylinder
37
38
               type
                                 zeroGradient;
39
41
           sym1
42
43
                                 symmetryPlane;
               type
44
           sym2
47
48
               type
                                 symmetryPlane;
49
51
           back
52
53
               type
                                 empty;
54
56
           front
57
58
               type
                                 empty;
59
60
```

- This file contains the boundary and initial conditions for the scalar field temperature (T).
- Also, pay attention to the units (line 17). The temperature is defined in Kelvin.
- We are using uniform initial conditions (line 19).
- For the in patch we are using a fixedValue boundary condition.
- For the out patch we are using a inletOutlet boundary condition (in case of backflow).
- For the cylinder patch we are using a zeroGradient boundary condition.
- The rest of the patches are constrained.

#### The file 0/U

```
17
       dimensions
                         [0 \ 1 \ -1 \ 0 \ 0 \ 0 \ 0];
18
19
       internalField uniform (1.5 0 0);
20
21
      boundaryField
22
23
           in
24
25
                                 fixedValue;
               type
26
                                 uniform (1.5 0 0);
               value
27
29
           out
30
31
                                 inletOutlet:
                type
32
                phi
                                 phi;
33
                inletValue
                                 uniform (0 0 0);
34
                value
                                 uniform (0 0 0);
35
37
           cylinder
38
39
                                 fixedValue;
               type
40
               value
                                 uniform (0 0 0);
41
           }
43
           sym1
44
45
               type
                                 symmetryPlane;
46
48
           sym2
49
50
               type
                                 symmetryPlane;
51
53
           back
54
55
               type
                                 empty;
56
58
           front
59
60
               type
                                 empty;
61
62
```

- This file contains the boundary and initial conditions for the dimensional vector field **U**.
- We are using uniform initial conditions and the numerical value is (1.5 0 0) (keyword internalField in line 19).
- For the in patch we are using a fixedValue boundary condition.
- For the out patch we are using a inletOutlet boundary condition (in case of backflow).
- For the cylinder patch we are using a zeroGradient boundary condition.
- The rest of the patches are constrained.

- The **system** directory
- The system directory consists of the following compulsory dictionary files:
  - controlDict
  - fvSchemes
  - fvSolution

- controlDict contains general instructions on how to run the case.
- fvSchemes contains instructions for the discretization schemes that will be used for the different terms in the equations.
- fvSolution contains instructions on how to solve each discretized linear equation system.

#### The controlDict dictionary

```
17
       application
                        icoFoam;
18
19
       startFrom
                        startTime;
20
       //startFrom
                         latestTime;
21
22
       startTime
23
24
       stopAt
                        endTime:
25
       //stopAt writeNow;
26
27
       endTime
                       0.3:
28
29
       deltaT
                       0.00001;
30
31
       writeControl
                        adjustableRunTime;
32
33
       writeInterval
                       0.0025;
34
35
       purgeWrite
36
37
       writeFormat
                       ascii;
38
39
       writePrecision 10;
40
41
       writeCompression off;
42
43
       timeFormat
                        general;
44
45
       timePrecision
46
47
       runTimeModifiable true;
48
49
       adjustTimeStep
50
       maxCo
                        1:
51
       maxDeltaT
                       1;
```

- This case will start from the last saved solution (**startFrom**). If there is no solution, the case will start from time 0 (**startTime**).
- It will run up to 0.3 seconds (endTime).
- The initial time step of the simulation is 0.00001 seconds (**deltaT**).
- It will write the solution every 0.0025 seconds (writeInterval) of simulation time (adjustableRunTime). The option adjustableRunTime will adjust the time-step to save the solution at the precise intervals. This may add some oscillations in the solution as the CFL is changing.
- It will keep all the solution directories (purgeWrite).
- It will save the solution in ascii format (writeFormat).
- And as the option runTimeModifiable is on, we can modify all these entries while we are running the simulation.
- In line 49 we turn on the option **adjustTimeStep**. This option will automatically adjust the time step to achieve the maximum desired courant number (line 50).
- We also set a maximum time step in line 51.
- Remember, the first time step of the simulation is done using the value set in line 28 and then it is automatically scaled to achieve the desired maximum values (lines 66-67).
- The feature adjustTimeStep is only present in the PIMPLE family solvers, but it can be added to any solver by modifying the source code.

#### The controlDict dictionary

```
55
       functions
56
178
       forceCoeffs object
179
188
        type forceCoeffs;
189
        functionObjectLibs ("libforces.so");
190
        patches (cylinder);
191
192
        pName p;
193
        Uname U:
194
        //rhoName rhoInf;
195
        rhoInf 1.205;
196
197
        //// Dump to file
198
        log true;
199
200
       CofR (0.0 0 0);
201
        liftDir (0 1 0);
        dragDir (1 0 0);
202
203
        pitchAxis (0 0 1);
204
        magUInf 1.5;
        1Ref 0.001;
205
206
       Aref 0.000002;
207
208
        outputControl
                         timeStep;
209
        outputInterval 1;
210
235
236
       };
```

- As usual, at the bottom of the controlDict dictionary file we define the **functionObjects** (lines 55-236).
- Of special interest is the functionObject forceCoeffs\_object.
- As we changed the domain dimensions and the inlet velocity we need to update the reference values (lines 204-206).
- It is also important to update the reference density (line 195).



#### The fvSchemes dictionary

```
17
      ddtSchemes
18
19
          default
                            Euler;
20
21
22
      gradSchemes
23
29
          default.
                             leastSquares;
34
35
36
      divSchemes
37
38
          default
                           none;
39
          div(phi,U)
                            Gauss linearUpwind default;
40
41
          div(phi,K)
                            Gauss linear;
42
          div(phi,h)
                            Gauss linear;
43
44
          div(((rho*nuEff)*dev2(T(grad(U))))) Gauss linear;
45
46
47
      laplacianSchemes
48
49
          default
                           Gauss linear limited 1;
50
51
52
      interpolationSchemes
53
54
          default
                            linear;
55
56
57
      snGradSchemes
59
          default
                           limited 1:
60
```

- In this case, for time discretization (**ddtSchemes**) we are using the **Euler** method.
- For gradient discretization (gradSchemes) we are using the leastSquares method.
- For the discretization of the convective terms (divSchemes)
  we are using linearUpwind interpolation with no slope limiters
  for the term div(phi,U).
- For the terms div(phi,K) (kinetic energy) and div(phi,h)
   (enthalpy) we are using linear interpolation method with no
  slope limiters.
- For the term div(((rho\*nuEff)\*dev2(T(grad(U))))) we are using linear interpolation (this term is related to the turbulence modeling).
- For the discretization of the Laplacian (laplacianSchemes and snGradSchemes) we are using the Gauss linear limited 1 method.
- This method is second order accurate.

```
17
       solvers
18
20
            р
21
22
                solver
                                 PCG;
23
                                 DIC;
                preconditioner
24
                                 1e-06:
                tolerance
25
                relTol
                                 0.01;
26
                minIter
                                  2:
27
            }
46
            pFinal
47
48
                $p;
                                 0;
49
                relTol
50
                minIter
                                  2:
51
            }
53
            "ט. *"
54
55
                                  PBiCG;
56
                                 DILU;
                preconditioner
57
                tolerance
                                 1e-08:
58
                relTol
                                 0;
59
                minIter
                                  2:
60
74
            hFinal
75
76
                solver
                                  PBiCG;
77
                preconditioner DILU;
78
                tolerance
                                 1e-08;
79
                relTol
                                 0 :
80
                minIter
                                  2;
81
83
            "rho.*"
84
85
                                 diagonal;
                solver
86
87
```

- To solve the pressure (p) we are using the PCG method with an absolute tolerance of 1e-6 and a relative tolerance relTol of 0.01.
- The entry **pFinal** refers to the final correction of the **PISO** loop. Notice that we are using macro expansion (**\$p**) to copy the entries from the sub-dictionary **p**.
- To solve U and UFinal (U.\*) we are using the solver PBiCG with an absolute tolerance of 1e-8 and a relative tolerance relTol of 0.
- To solve hFinal (enthalpy) we are using the solver PBiCG with an absolute tolerance of 1e-8 and a relative tolerance relTol of 0.
- To solve rho and rhoFinal (rho.\*) we are using the diagonal solver (remember rho is found from the equation of state, so this is a back-substitution).
- FYI, solving for the velocity is relative inexpensive, whereas solving for the pressure is expensive.
- Be careful with the enthalpy, it might cause oscillations.

```
88
89
       PIMPLE
90
91
           momentumPredictor yes;
92
           nOuterCorrectors 1;
93
           nCorrectors
94
           nNonOrthogonalCorrectors 1;
95
           rhoMin
                            0.5;
96
                            2.0:
           rhoMax
97
```

- The PIMPLE sub-dictionary contains entries related to the pressure-velocity coupling (in this case the PIMPLE method).
- Setting the keyword nOuterCorrectors to 1 is equivalent to running using the PISO method.
- Hereafter we are doing 2 PISO correctors (nCorrectors) and 1 non-orthogonal corrections (nNonOrthogonalCorrectors).
- In lines 95-96 we set the minimum and maximum physical values of rho (density).
- If we increase the number of nCorrectors and nNonOrthogonalCorrectors we gain more stability but at a higher computational cost.
- The choice of the number of corrections is driven by the quality of the mesh and the physics involve.
- You need to do at least one PISO loop (nCorrectors).

#### Running the case – Using a compressible solver

- You will find this tutorial in the directory \$PTOFC/1010F/vortex\_shedding/c23
- Feel free to use the Fluent mesh or the mesh generated with blockMesh. In this case we will use blockMesh.
- To run this case, in the terminal window type:

```
1. | $> foamCleanTutorials
```

- 2. | \$> blockMesh
- 3. | \$> transformPoints -scale '(0.001 0.001 0.001)'
- 4. | \$> renumberMesh -overwrite
- 5. | \$> rhoPimpleFoam > log &
- 6. | \$> pyFoamPlotWatcher.py log
- 7. \$\frac{\\$> \text{gnuplot scripts0/plot\_coeffs}}{\text{You will need to launch this script in a different terminal}}\$
- 8. \$> Mach
- 9. | \$> paraFoam

# Running the case Using a compressible solver

- In step 3 we scale the mesh.
- In step 4 we use the utility renumberMesh to make the linear system more diagonal dominant, this will speed-up the linear solvers.
- In step 5 we run the simulation and save the log file. Notice that we are sending the
  job to background.
- In step 6 we use pyFoamPlotWatcher.py to plot the residuals on-the-fly. As the job is running in background, we can launch this utility in the same terminal tab.
- In step 7 we use the gnuplot script scripts0/plot\_coeffs to plot the force coefficients on-the-fly. Besides monitoring the residuals, is always a good idea to monitor a quantity of interest. Feel free to take a look at the script and to reuse it.
- In step 8 we use the utility Mach to compute the Mach number.

rhoPimpleFoam output screen

```
Courant Number mean: 0.1280224248 max: 0.9885863338
                                                                           Courant number
deltaT = 3.816512052e-05
Time = 0.3
                                                                                                         Solving for density
diagonal: Solving for rho, Initial residual = 0, Final residual = 0, No Iterations 0
PIMPLE: iteration 1
DILUPBICG: Solving for Ux, Initial residual = 0.003594731129, Final residual = 3.026673755e-11, No Iterations 5
DILUPBiCG: Solving for Uy, Initial residual = 0.01296036298, Final residual = 1.223236662e-10, No Iterations 5

    h residuals

DILUPBICG: Solving for h, Initial residual = 0.01228951539, Final residual = 2.583236461e-09, No Iterations 4
DICPCG: Solving for p, Initial residual = 0.01967621449, Final residual = 8.797612158e-07, No Iterations 77
DICPCG: Solving for p, Initial residual = 0.003109422612, Final residual = 9.943030465e-07, No Iterations 69
diagonal: Solving for rho, Initial residual = 0, Final residual = 0, No Iterations 0
time step continuity errors : sum local = 6.835363016e-11, qlobal = 4.328592697e-12, cumulative = 2.366774797e-09
                                                                                                                             pFinal
rho max/min : 1.201420286 1.201382023
DICPCG: Solving for p. Initial residual = 0.003160602108, Final residual = 9.794177338e-07, No Iterations 69
DICPCG: Solving for p, Initial residual = 0.0004558492254, Final residual = 9.278622052e-07, No Iterations 58
                                                                                                              Solving for density (rhoFinal)
diagonal: Solving for rho, Initial residual = 0, Final residual = 0, No Iterations 0
time step continuity errors : sum local = 6.38639685e-11, global = 1.446434866e-12, cumulative = 2.368221232e-09
rho max/min : 1.201420288 1.201381976
                                                           Max/min density values
ExecutionTime = 480.88 s ClockTime = 490 s
faceSource inMassFlow output:
    sum(in) of phi = -7.208447027e-05
faceSource outMassFlow output:
    sum(out) of phi = 7.208444452e-05
fieldAverage fieldAverage output:
    Calculating averages
    Writing average fields
forceCoeffs forceCoeffs object output:
         = -0.001269886395
         = 1.419350733
         = 0.6247248606
                                                     Force coefficients
    Cl(f) = 0.3110925439
                                                                                                                  Minimum and
    Cl(r) = 0.3136323167
                                                                                                                  maximum values
fieldMinMax minmaxdomain output:
    \min(p) = 101322.7878 at location (-0.0001215826043 \ 0.001027092827 \ 0)
    \max(p) = 101326.4972 at location (-0.001033408037 -4.061934599e-05 0)
    \min(U) = (-0.526856427 - 0.09305459972 - 8.110485132e - 25) at location (0.002039092041 - 0.0004058872656 - 3.893823418e - 20)
    \max(U) = (2.184751599 \ 0.2867627526 \ 4.83091257e-25) at location (0.0001663574444 \ 0.001404596295 \ 0)
    min(T) = 293.1487423 at location (-5.556854517e-05 0.001412635233 0)
    \max(T) = 293.1509903 at location (-0.00117685237 -4.627394552e-05 3.016083257e-20)
```

In the directory:

vortex\_shedding

You will find 26 variations of the cylinder case involving different solvers and models. Feel free to explore all them.

- This is what you will find in each directory,
  - c1 = blockMesh icoFoam Re = 200.
  - c2 = fluentMeshToFoam icoFoam Re = 200.
  - c3 = blockMesh icoFoam Field initialization Re = 200.
  - c4 = blockMesh potentialFoam Re = 200.
  - c5 = blockMesh mapFields icoFoam original mesh Re = 200.
  - c6 = blockMesh mapFields icoFoam Finer mesh Re = 200.
  - c7 = blockMesh pimpleFoam Re = 200 No turbulent model.
  - c8 = blockMesh pisoFoam Re = 200 No turbulent model.
  - c9 = blockMesh pisoFoam Re = 200 K-Omega SST turbulent model.
  - c10 = blockMesh simpleFoam Re = 200 No turbulent model.
  - c11 = blockMesh simpleFoam Re = 40 No turbulent model.
  - c12 = blockMesh pisoFoam Re = 40 No turbulent model.
  - c14 = blockMesh pimpleFoam Re = 10000 K-Omega SST turbulent model with wall functions.
  - c15 = blockMesh pimpleFoam Re = 100000 K-Omega SST turbulent model with wall functions.
  - c16 = blockMesh simpleFoam Re = 100000 K-Omega SST turbulent model with no wall functions.
  - c17 = blockMesh simpleFoam Re = 100000 K-Omega SST turbulent model with wall functions.
  - c18 = blockMesh pisoFoam Re = 100000, LES Smagorinsky turbulent model.

- This is what you will find in each directory,
  - c19 = blockMesh pimpleFoam Re = 1000000 Spalart Allmaras turbulent model with no wall functions.
  - c20 = blockMesh sonicFoam Mach = 2.0 Compressible Laminar.
  - c21 = blockMesh sonicFoam Mach = 2.0 Compressible K-Omega SST turbulent model with wall functions.
  - c22 = blockMesh pimpleFoam Re = 200 No turbulent model Source terms (momentum)
  - c23 = blockMesh pimpleFoam Re = 200 No turbulent model Source terms (scalar transport)
  - c24 = blockMesh rhoPimpleFoam Re = 200 Laminar, isothermal
  - c26 = blockMesh pimpleDyMFoam Re = 200 Laminar, moving cylinder (oscillating).
  - c27 = blockMesh pimpleDyMFoam/pimpleFoam Re = 200 Laminar, rotating cylinder using AMI patches.
  - c28 = blockMesh interFoam Laminar, multiphase, free surface.