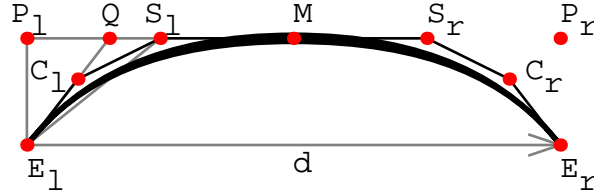


1 Slur control points

We display slurs as two cubic Bézier curves, joined at the center point (thickest point of the slur). In this document, we name the control points as follows (from left to right):

- E_l : left endpoint
- C_l : point that controls the left corner shape
- S_l : point that controls the pronouncedness of the left "shoulder"
- M : midpoint (highest and thickest point, where both Bézier curves join)
- S_r : point that controls the pronouncedness of the right "shoulder"
- C_r : point that controls the right corner shape
- E_r : right endpoint



This means we have seven points and therefore 14 degrees of freedom. For a smooth transition between the two Bézier curves in point M , we will require S_lMS_r to lie on a straight line and the division ratios of MP_rS_r and of MP_lS_l to be equal. This reduces the degrees of freedom to twelve, therefore we have to provide 12 parameters as follows:

- 4 parameters are given by specifying the endpoints
- 2 parameters specify the position of the helper points P_l and P_r
- 1 parameter specifies the position of M
- 1 parameter specifies the position of S_l and S_r
- 2·2 parameters specify the tangent angle in the endpoints and the curvature

2 Paremetrization

2.1 Endpoints E_l and E_r

The endpoints E_l and E_r are the most important parameters.

2.2 Tilt t and height h

The tilt paramter t and the height parameter h define the positions of the two helper points P_l and P_r . Those two points are the reference points for calculating all other points. For defining the four coordinates of the two points, we need two more conditions in addition to the two parameters t and h . So, we define that the lines E_lP_l and E_rP_r shall always be parallel, i.e. $\square E_lE_rP_rP_l$ always is a trapezoid.

$$E_lP_l \parallel E_rP_r \quad (1)$$

Additionally, the angles $\angle P_lE_lE_r$ and $\angle P_rE_rE_l$ shall be right angles.

$$E_lP_l \perp P_lP_r \quad (2)$$

((2) also implies $E_rP_r \perp P_lP_r$ because of (1).)

We define two special values for the tilt parameter t . For $t = 1$, the tangent in the thickest point shall be parallel to the base line E_lE_r . For $t = 0$, the tangent in the thickest point shall be horizontal. We achieve this by defining the direction vector of the parallel vectors $\overrightarrow{E_lP_l}$ and $\overrightarrow{E_rP_r}$ as being

$$v = \begin{pmatrix} -td_y \\ d_x \end{pmatrix} \quad (3)$$

where

$$\begin{pmatrix} d_x \\ d_y \end{pmatrix} = (E_r - E_l)$$

Like this, v is perpendicular to $\overrightarrow{E_lE_r}$ for $t = 1$ (and because of (2) $\overrightarrow{E_lE_r}$ and $\overrightarrow{P_lP_r}$ are parallel). For $t = 0$, v is vertical (and because of (2), $\overrightarrow{P_lP_r}$ is horizontal). For convenience, we introduce the normalized unit vector belonging to v

$$\hat{v} = \frac{v}{\|v\|}$$

For $t = 1$, $\|E_lP_l\| =: h_l$ and $\|E_rP_r\| =: h_r$ shall be equal to h , the height of the slur. This means,

$$\begin{aligned} P_l(t = 1) &= E_l + h\hat{v} \\ P_r(t = 1) &= E_r + h\hat{v} \end{aligned} .$$

For $t \neq 1$, the two lengths can obviously not be equal, but we require their arithmetic mean to be equal to h . This can be achieved by adding the same value c to one length and subtract it from the other. This value is somehow dependent on t (for $t = 1$ it's 0).

$$\begin{aligned} h_l &= h + c(t) \\ h_r &= h - c(t) \end{aligned} \quad (4)$$

We need h_l and h_r to calculate P_l and P_r :

$$\begin{aligned} P_l &= E_l + h_l \hat{v} \\ P_r &= E_r + h_r \hat{v} \end{aligned}$$

Using condition (2), we derive a calculation rule for $c(t)$ via the standard dot product of v and $\overrightarrow{P_l P_r}$, which is required to be 0 as condition (2) demands the two vectors to be perpendicular.

$$\begin{aligned} \langle P_r - P_l, v \rangle &= \langle [E_r + h_r \hat{v}] - [E_l + h_l \hat{v}], v \rangle \\ &= \langle [E_r + (h - c(t))\hat{v}] - [E_l + (h + c(t))\hat{v}], v \rangle \\ &= \langle [E_r - E_l] + [(h - c(t)) - (h + c(t))]\hat{v}, v \rangle \\ &= \left\langle \begin{pmatrix} d_x \\ d_y \end{pmatrix} + [-2c(t)] \frac{v}{||v||}, v \right\rangle \\ &= \left\langle \begin{pmatrix} d_x \\ d_y \end{pmatrix} - \frac{2c(t)}{||v||} \begin{pmatrix} -td_y \\ d_x \end{pmatrix}, \begin{pmatrix} -td_y \\ d_x \end{pmatrix} \right\rangle \\ &= (d_x + \frac{2c(t)}{||v||} td_y)(-td_y) + (d_y - \frac{2c(t)}{||v||} d_x) d_x \\ &= -d_x td_y - \frac{2c(t)}{||v||} t^2 d_y^2 + d_y d_x - \frac{2c(t)}{||v||} d_x^2 \\ &= d_x d_y (1 - t) - \frac{2c(t)}{||v||} (t^2 d_y^2 + d_x^2) \\ &\stackrel{t^2 d_y^2 + d_x^2 = ||v||^2}{=} d_x d_y (1 - t) - 2c(t) ||v|| \\ &\stackrel{!}{=} 0 \\ \Rightarrow c(t) &= \frac{(1 - t) d_x d_y}{2 ||v||} \end{aligned}$$

Now we can calculate P_l and P_r as follows:

$$\begin{aligned} P_l &= E_l + h_l \hat{v} = E_l + (h + c(t)) \hat{v} \\ P_r &= E_r + h_r \hat{v} = E_r + (h - c(t)) \hat{v} \end{aligned} \tag{5}$$

2.3 Shift f of the midpoint M

The midpoint's position between P_l and P_r is defined by its "shift" f . f makes the midpoint travel along an imaginry rail that goes from P_l to P_r . For $f = 0$ it's centered between P_l and P_r , for $f = -1$, M falls together with P_l and for $f = 1$ it falls together with P_r . The formula for M is

$$M = P_l + \frac{f + 1}{2} (P_r - P_l)$$

2.4 Shoulder parameter s and shoulder points S_l and S_r

The "shoulder" parameter s defines the position of the Bézier control points S_l and S_r . This parameter should take on values between 0 and 1 and moves the E points further to the center or further to the sides. $s = 0$ means that the slur's shoulder is minimal and the shoulder points move to the center, i.e. $S_l = S_r = M$. $s = 1$ means that the shoulder is as pronounced as possible, i.e. $S_l = P_l$ and $S_r = P_r$. The formula for S_l is

$$S_l = M + s(P_l - M)$$

and S_r works analogously.

As a smooth transition between the two Bézier curves is desired we're using the same s on both sides. The most widely used method to make the transition look smooth is to make S_l and S_r symmetric with M as point of symmetry (i.e. $M - S_l = S_r - M$, compare e.g. SVG's smooth curve commands). We're not using this method because it doesn't work well for asymmetric slurs. This method only guarantees mathematically strict continuity of curvature at M in the symmetry case, anyway. Our method guarantees this as well.

2.5 Endpoint angle a

The parameters a_l and a_r define the tangents in the slur's endpoints. (The tangents could be controlled individually for each side using a_l and a_r , or by a parameter a that controls both sides.) The tangents are the lines E_lQ_l and E_rQ_r . Q_l and Q_r are usually located on the line segments $\overline{P_lS_l}$ and $\overline{P_rS_r}$. If they were closer to M , the control polygons would not be concave any more. If they were further outside, the slur would get "potbellies" that are protruding over the edges E_l and E_r .

Q_l and Q_r are calculated in the same way as S_l and S_r :

$$Q_l = S_l + a_l(P_l - S_l)$$

(analogously for Q_r). This means, for $a = 0$ the slur shape starts/levels off as flat as possible and for $a = 1$ it's as steep as possible.

2.6 Curvature parameters c_l and c_r

The parameters c_l and c_r fix the C control points by describing their "height" over the line E_lE_r . This can be thought of as influencing the curvature (therefore c). With all other parameters set, $c = 0$ makes the curvature minimal ("slow", wide curve) and $c = 1$ makes it maximal ("sharper" turn), while keeping the control polygon convex. C_l and C_r are calculated in the familiar manner

$$C_l = E_l + c_l(Q_l - E_l)$$

(analogously for C_r).

2.7 Thickness parameters t_{min} , t_{max} and w

The maximum thickness (in point M) is defined by the parameter t_{max} , the minimum thickness (in the endpoints) by parameter t_{min} . How "fast" the slur gets thicker towards the center can be influenced with the swelling rate parameter w . The swelling rate on the left and right sides could also be controlled individually by w_l and w_r parameters. All those parameters are needed to calculate the actual control points for the slur outline as described below.

3 Slur profile

As slurs are thinner at the tips and thicker at the center, we need a "sandwich" of Bézier curves (two top and two bottom curves). To achieve the profile, we use control points that—compared to the ones shown in the illustration—are offset slightly upwards or downwards.

M , S_l and S_r are offset by half of the desired width in the center—minus half of the desired width at the tips as we're stroking the outlines to get rounded tips with a defined thickness. How far the points C_l and C_r are offset is defined by parameter w . For $w = 1$, they are offset by the same vector as M , for $w = 0$, they are not offset at all.

The offset vector for M , S_l and S_r , which we call o , is calculated as follows:

$$o = (t_{max} - t_{min})\hat{v}$$

The offset vector for S_l and S_r is

$$o_l = w_l o$$

$$o_r = w_r o$$

The sandwich consists of the following control points: On the top we have E_l , C_{tl} , S_{tl} , M_t , S_{tr} , C_{tr} and E_r .

On the bottom we have analogously

E_l , C_{bl} , S_{bl} , M_b , S_{br} , C_{br} and E_r .

Those offset points on the left half are calculated as follows:

$$C_{tl} = C + wo$$

$$C_{bl} = C - wo$$

$$S_{tl} = S_l + o$$

$$S_{bl} = S_l - o$$

$$M_t = M + o$$

$$M_b = M - o$$