# **EDISON ALTAMIRANO**

## Robotics Engineer

+52 8121987907 @ edisonaltamirano2000@outlook.com https://www.linkedin.com/in/edison-altamirano-avila-55a0341a3

#### **LANGUAGES**

Spanish	Native	••••
English	Proficient	••••
French	Intermediate	••••

## **SKILLS**

MATLAB		AUTOSAR		ROS2
ROS1		Python		Flutter
C++	ReactJS		PLC	KiCad
LTspice	А	WS	GCP	

#### **PUBLICATIONS**

## Visual Navigation Algorithms for Mobile Manipulators in Service Shops

**=** 11/2023

e https://doi.org/10.1007/978-3-031-47640-2\_19

## Towards a Mixed Virtual Reality **Environment Implementation to Enable Industrial Robot Programming** Competencies within a Cyber-Physical Factory

**=** 05/2023

### https://doi.org/10.1109/EDUCON54358.202 3.10125175

## A Digital Twin implementation for Mobile and collaborative robot scenarios for teaching robotics based on Robot Operating System

**m** 03/2022

@ https://doi.org/10.1109/EDUCON52537.202 2.9766583

## Work in Progress: Implementation of a Digital Twin as Technology to support Discrete Event Control Teaching

**=** 03/2022

### https://doi.org/10.1109/EDUNINE53672.202 2.9782154

#### CERTIFICATION

## Convolutional Neural Networks

DeepLearningAI (sept.2019)

Improving Deep Neural Networks: Hyperparameter tuning, Regularization and Optimization

DeepLearning.Al (jul.2019)

## Structuring Machine Learning Projects

DeepLearning.Al (jul.2019)

## Neural networks and Deep Learning

DeepLearning.AI (jun.2019)

#### **EDUCATION**

#### Digital Systems and Robotics Engineering

Instituto Tecnológico y de Estudios Superiores de Monterrey ITESM

**#** 08/2018 - 06/2023

#### **EXPERIENCE**

## Application Engineer

**ZF** Group

苗 11/2023 - Present Monterrey, Mexico

ZF is a global technology company supplying systems for commercial vehicles.

· Develop custom controllers for next-gen hydraulic axle modulators using Matlab and Vector software tools, ensuring Autosar compliance.

#### CTO

**CHAKRI** 

**=** 08/2020 - Present Quito, Ecuador

CHAKRI is a farm-to-home delivery platform for fresh groceries.

· Led development of 3 mobile apps for iOS and Android, alongside a logistics website linking local farmers and consumers, eliminating intermediaries. Engineered advanced algorithms for routing and delivery, automated logistics using cloud computing, and managed backend and frontend development of mobile apps. View the apps on Play Store or App Store: Link

## ADAS Validation Engineer

**ZF** Group

Led hardware and software development for Mexico's first autonomous shuttle, overseeing the acceleration module and light control system. Employed ROS2, STM32, and CAN for integrated module control. Recognized by top executives from BYD and ZF during key demonstrations. Watch the project in action: Link

#### Supply Chain Management Intern

John Deere

**m** 08/2022 - 06/2023

Monterrey, Mexico

John Deere leads in providing advanced products for agriculture and construction worldwide.

Implemented SAP Automation using ABAP programming, Microsoft Azure, Microsoft Power Platform, and Amazon Web Services applications to enhance supply management team performance.

## Robotics Researcher and Project Manager / Campus Job

Tecnológico de Monterrey

**=** 01/2019 - 08/2022

Monterrev. Mexico

- Integrate Warehouse Fleet Management with AGV and create technology to handle them using reinforcement learning, PLC, and industrial communication protocols.
- Trained {20+} professors in advanced robotics integration techniques for manufacturing applications.

#### **AWARDS**



## Most Consistent Solution in AIRLab Stacking Challenge

Hosted in the Netherlands, watch the project in action: Link



7 awards granted during RoboBoat, RoboSub 2020-2022

Hosted in the US: https://robonation.org/

## LEADERSHIP AND PROJECTS

## Lead Software Engineer

**m** 08/2020 - 06/2023

Monterrey, Mexico

Integrated control, vision, and navigation systems for virtual and real submarines in RoboSub and Roboat competitions from 2020 to 2022. Watch the project in action: Link

#### Software Developer

RoBorregos

Developed an autonomous butler for the RoboCup @Home category in 2022-2023. Managed robot's SLAM and planning system. Watch the project in action at the IROS event in Japan: Link