

## Advanced Mathematics

## Lab 7: Gradient, curl, divergence in curvilinear coordinates

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GEODÄTISCHES INSTITUT

der Universität Stuttgart

anerkannt

91%

1	2	3a	3b	4a	4b	exercise points
17	18	12	9	25	10	

## Spherical and cylindrical coordinates

1. Determine the *divergence* and the *curl* of the vector field

$$\mathbf{G} = \frac{-\cos \lambda}{4 \cos \vartheta} \hat{\mathbf{h}}_r + \operatorname{artanh} \left( \cot \frac{\vartheta}{2} \right) \cos \lambda \hat{\mathbf{h}}_\vartheta + r^2 \hat{\mathbf{h}}_\lambda$$

w.r.t. to spherical coordinates ( $\lambda$  : longitude,  $\vartheta$  : co-latitude,  $r$  : radius).

(17 points)

2. Calculate the curl and the divergence of the vector field

$$\mathbf{G}_{\mu,\nu} = z \sin(\varphi + \mu) \hat{\mathbf{h}}_\rho + z \sin(\lambda + \nu) \hat{\mathbf{h}}_\varphi + \rho \sin(\varphi) \hat{\mathbf{h}}_z$$

in cylindrical coordinates. For which values of  $\{\mu, \nu\}$  is the field curl-free, for which divergence-free? (22 points)

## Planar curvilinear coordinate systems

3. A curvilinear coordinate system is given by the relation

$$x = \frac{1}{N} \sinh \alpha$$

$$y = \frac{1}{N} \sin \beta$$

with  $N := \cosh \alpha - \cos \beta$ ,  $\alpha \in \mathbb{R}$  and  $\beta \in [0, 2\pi]$ .

- a) Derive the gradient in this system w.r.t. the normalized 'frame vectors'. (14 points)

- b) Express the frame vectors  $\hat{\mathbf{h}}_{q_i}$  of standard polar coordinates by the coordinates  $\{\alpha, \beta\}$ .

The final answer can be given as matrix-vector product without explicit multiplication. To avoid ambiguities, only the first quadrant can be considered. (12 points)

(final exam WS 17/18)



## Ellipsoidal coordinates

4. The transformation from Cartesian to ellipsoidal (geodetic) coordinates is given by

$$x = (N + H) \cos B \cos L$$

$$y = (N + H) \cos B \sin L$$

$$z = ((1 - E^2)N + H) \sin B$$

$$\text{with } N = \frac{A}{\sqrt{1 - E^2 \sin^2 B}}, \quad M = \frac{A(1 - E^2)}{(1 - E^2 \sin^2 B)^{3/2}}, \quad \frac{\partial N}{\partial B} = (N - M) \tan B.$$

- Determine the *gradient* in curvilinear coordinates of an arbitrary scalar field  $\Phi(L, B, H)$  described on the ellipsoid. (25 points)
- Calculate the curl of the vector field  $G(L, B, H) = \cos B \sin L \hat{h}_H + \cos L \hat{h}_L + H \cos B \hat{h}_B$  via the general formula:

$$\text{curl } G(\alpha, \beta, \gamma) = \frac{1}{h_\alpha h_\beta h_\gamma} \det \begin{pmatrix} h_\alpha \hat{h}_\alpha & h_\beta \hat{h}_\beta & h_\gamma \hat{h}_\gamma \\ \frac{\partial}{\partial \alpha} & \frac{\partial}{\partial \beta} & \frac{\partial}{\partial \gamma} \\ h_\alpha G_\alpha & h_\beta G_\beta & h_\gamma G_\gamma \end{pmatrix}$$

which is valid for all orthogonal coordinates systems  $\{\alpha, \beta, \gamma\}$

(10 points)

## [V] Ellipsoidal coordinates 2

v Another ellipsoidal frame is given by

$$x = \cosh \alpha \cos \beta \cos \varphi$$

$$y = \cosh \alpha \cos \beta \sin \varphi$$

$$z = \sinh \alpha \sin \beta.$$

Express the gradient of an arbitrary field and the scalar function

$$f = \sqrt{\sinh^2 \alpha \cos^2 \beta + \cosh^2 \alpha \sin^2 \beta}$$

in this system.



$$\underline{G} = \frac{-\cos\lambda}{4\cos\theta} \hat{r} + \operatorname{artanh}\left(\cot\frac{\theta}{2}\right)\cos\lambda \hat{\theta} + r^2 \hat{\lambda}$$

$\qquad\qquad\qquad q_1 \qquad\qquad\qquad q_2 \qquad\qquad\qquad q_3$

spherical coordinates:

$$\operatorname{div}(\underline{G}) = \frac{1}{r^2} \cdot \frac{\partial}{\partial r}(r^2 \cdot G_1) + \frac{1}{r\sin\theta} \frac{\partial}{\partial\theta}(\sin\theta \cdot G_2) + \frac{1}{r\sin\theta} \frac{\partial}{\partial\lambda}(G_3)$$

$$= \frac{1}{r^2} \cdot \left(2r \cdot \frac{-\cos\lambda}{4\cos\theta}\right) + \frac{1}{r\sin\theta} \cdot \cos\lambda \left(\cos\theta \operatorname{artanh}\left(\cot\frac{\theta}{2}\right) + \frac{\sin\theta}{2\cos\theta}\right) + 0$$

$$= \frac{-\cos\lambda}{2r\cos\theta} + \frac{\cos\lambda \cos\theta \operatorname{artanh}\left(\cot\frac{\theta}{2}\right)}{r\sin\theta} + \frac{\cos\lambda}{2r\cos\theta}$$

$$= \frac{\cos\lambda \cot\theta \operatorname{artanh}\left(\cot\frac{\theta}{2}\right)}{r}$$

$$\operatorname{curl}(\underline{G}) = \frac{1}{r\sin\theta} \left( \frac{\partial}{\partial\theta}(\sin\theta \cdot G_3) - \frac{\partial G_2}{\partial\lambda} \right) \hat{r}$$

$$+ \left( \frac{1}{r\sin\theta} \cdot \frac{\partial G_1}{\partial\lambda} - \frac{1}{r} \cdot \frac{\partial}{\partial r}(r \cdot G_3) \right) \hat{\theta}$$

$$+ \left( \frac{1}{r} \cdot \frac{\partial}{\partial r}(r \cdot G_2) - \frac{1}{r} \cdot \frac{\partial G_1}{\partial\theta} \right) \hat{\lambda}$$

$$= \frac{1}{r\sin\theta} \cdot \left( r^2 \cos\theta + \operatorname{artanh}\left(\cot\frac{\theta}{2}\right) \sin\lambda \right) \hat{r}$$

$$+ \left( \frac{1}{r\sin\theta} \cdot \frac{\sin\lambda}{4\cos\theta} - \frac{1}{r} \cdot 3r^2 \right) \hat{\theta} + \left( \frac{1}{r} \cdot \operatorname{artanh}\left(\cot\frac{\theta}{2}\right) \cos\lambda + \frac{1}{r} \cdot \frac{\cos\lambda \sin\theta}{4\cos^2\theta} \right) \hat{\lambda}$$

$$= \left[ r \cot\theta + \frac{\operatorname{artanh}\left(\cot\frac{\theta}{2}\right) \sin\lambda}{r\sin\theta} \right] \hat{r} + \left( \frac{\sin\lambda}{2r\sin^2\theta} - 3r \right) \hat{\theta} + \frac{\cos\lambda}{r} \left( \operatorname{artanh}\left(\cot\frac{\theta}{2}\right) + \frac{\sin\theta}{4\cos^2\theta} \right) \hat{\lambda}$$



Should " $\lambda$ " be " $\varphi$ "? both are right.

$$2. \quad \underline{G_{\mu\nu} = z \sin(\varphi + \mu) \hat{h}_\rho + z \sin(\varphi + \nu) \hat{h}_\varphi + \rho \sin(\varphi) \hat{h}_z}$$

$$\text{div}(\underline{G}) = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho G_1) + \frac{1}{\rho} \frac{\partial G_2}{\partial \varphi} + \frac{\partial G_3}{\partial z}$$

$$= \frac{1}{\rho} \cdot z \sin(\varphi + \mu) + \frac{1}{\rho} \cdot z \cos(\varphi + \nu)$$

$$= \frac{1}{\rho} \cdot z (\sin(\varphi + \mu) + \cos(\varphi + \nu))$$

$$\text{curl}(\underline{G}) = \left( \frac{1}{\rho} \frac{\partial G_2}{\partial \varphi} - \frac{\partial G_1}{\partial z} \right) \hat{h}_\rho + \left( \frac{\partial G_1}{\partial z} - \frac{\partial G_3}{\partial \rho} \right) \hat{h}_\varphi + \left( \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho G_3) - \frac{1}{\rho} \frac{\partial G_1}{\partial \varphi} \right) \hat{h}_z$$

$$= \left( \frac{1}{\rho} \cdot [z \cos(\varphi + \nu) - \sin(\varphi + \mu)] \right) \hat{h}_\rho + (\sin(\varphi + \mu) - \sin \varphi) \hat{h}_\varphi + \left( \frac{1}{\rho} \cdot z \sin(\varphi + \nu) - \frac{1}{\rho} \cdot z \cdot \cos(\varphi + \mu) \right) \hat{h}_z$$

$$= [\cos \varphi - \sin(\varphi + \nu)] \hat{h}_\rho + (\sin(\varphi + \mu) - \sin \varphi) \hat{h}_\varphi + \frac{z}{\rho} [\sin(\varphi + \nu) - \cos(\varphi + \mu)] \hat{h}_z$$

curl-free  $\Rightarrow \text{curl}(\underline{G}) = 0$ , i.e.

$$\begin{cases} \cos \varphi = \sin(\varphi + \nu) \\ \sin(\varphi + \mu) = \sin \varphi \\ \sin(\varphi + \nu) = \cos(\varphi + \mu) \end{cases}$$

$$\Rightarrow \begin{cases} \mu = 2k_1\pi, & k_1, k_2 \in \mathbb{Z} \\ \nu = 2k_2\pi + \frac{\pi}{2} \end{cases}$$

divergence-free  $\Rightarrow \text{div}(\text{curl}(\underline{G})) = 0$

$$\text{div} \underline{G} = 0.$$

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$$\text{div}(\text{curl}(\underline{G})) = \frac{1}{\rho} \cdot [\cos \varphi - \sin(\varphi + \nu)] + \frac{1}{\rho} \cdot [\sin(\varphi + \mu) - \cos \varphi] + \frac{1}{\rho} [\sin(\varphi + \nu) - \cos(\varphi + \mu)]$$

$$= \frac{1}{\rho} [\cos \varphi - \cos \varphi - \sin(\varphi + \nu) + \sin(\varphi + \nu) + \sin(\varphi + \mu) - \sin(\varphi + \mu)]$$

$$= 0.$$

$\Rightarrow$  For  $\forall \mu, \nu \in \mathbb{R}$ , it is divergence-free.



$$x = \frac{1}{N} \sinh \alpha$$

$$y = \frac{1}{N} \sin \beta \quad , \quad N = \cosh \alpha - \cos \beta \quad , \quad \alpha \in \mathbb{R}, \beta \in [0, 2\pi]$$

$$a) \quad h_\alpha = \left( \frac{\partial x}{\partial \alpha}, \frac{\partial y}{\partial \alpha} \right)^T = \begin{bmatrix} \frac{1 - \cosh \alpha \cos \beta}{(\cosh \alpha - \cos \beta)^2} \\ -\frac{\sinh \alpha \sin \beta}{(\cosh \alpha - \cos \beta)^2} \end{bmatrix} \quad , \quad |h_\alpha| = \frac{\sqrt{(1 - \cosh \alpha \cos \beta)^2 + \sinh^2 \alpha}}{(\cosh \alpha - \cos \beta)^2} = \frac{1}{N}$$

$$\hat{h}_\alpha = \begin{bmatrix} \frac{1 - \cosh \alpha \cos \beta}{\sqrt{(1 - \cosh \alpha \cos \beta)^2 + \sinh^2 \alpha}} & -\frac{\sinh \alpha \sin \beta}{\sqrt{(1 - \cosh \alpha \cos \beta)^2 + \sinh^2 \alpha}} \end{bmatrix}^T \quad \text{simplify} \quad = \frac{1}{N}$$

$$h_\beta = \left( \frac{\partial x}{\partial \beta}, \frac{\partial y}{\partial \beta} \right)^T = \begin{bmatrix} -\frac{\sinh \alpha \sin \beta}{N^2} & \frac{\cosh \alpha \sin \beta - 1}{N^2} \end{bmatrix}^T \quad , \quad |h_\beta| = \frac{\sqrt{\sinh^2 \alpha \sin^2 \beta + (\cosh \alpha \sin \beta - 1)^2}}{N^2}$$

$$\hat{h}_\beta = \begin{bmatrix} -\frac{\sinh \alpha \sin \beta}{\sqrt{\sinh^2 \alpha \sin^2 \beta + (\cosh \alpha \sin \beta - 1)^2}} & \frac{\cosh \alpha \sin \beta - 1}{\sqrt{\sinh^2 \alpha \sin^2 \beta + (\cosh \alpha \sin \beta - 1)^2}} \end{bmatrix}^T$$

$$\Rightarrow \nabla f = \frac{1}{h_\alpha} \frac{\partial f}{\partial \alpha} \hat{h}_\alpha + \frac{1}{h_\beta} \frac{\partial f}{\partial \beta} \hat{h}_\beta$$

$$= \frac{(\cosh \alpha - \cos \beta)^2}{\sqrt{(1 - \cosh \alpha \cos \beta)^2 + \sinh^2 \alpha}} \frac{\partial f}{\partial \alpha} \hat{h}_\alpha + \frac{(\cosh \alpha - \cos \beta)^2}{\sqrt{\sinh^2 \alpha \sin^2 \beta + (\cosh \alpha \sin \beta - 1)^2}} \frac{\partial f}{\partial \beta} \hat{h}_\beta$$

$$= |N| \frac{\partial f}{\partial \alpha} \hat{h}_\alpha + |N| \frac{\partial f}{\partial \beta} \hat{h}_\beta \quad -2$$

b) standard polar coordinates:  $\rho = \sqrt{x^2 + y^2}$ ,  $\varphi = \arctan \frac{y}{x}$

$$\Rightarrow \rho = \frac{1}{N} \sqrt{\sinh^2 \alpha + \sin^2 \beta} \quad , \quad \varphi = \arctan \left( \frac{\sin \beta}{\sinh \alpha} \right) \quad , \quad \begin{cases} \cos \varphi = \frac{x}{\sqrt{x^2 + y^2}} \\ \sin \varphi = \frac{y}{\sqrt{x^2 + y^2}} \end{cases}$$

~~h~~ in polar coordinates:  $\begin{cases} x = \rho \cos \varphi \\ y = \rho \sin \varphi \end{cases}$

$$\Rightarrow h_\rho = \left[ \frac{\partial x}{\partial \rho}, \frac{\partial y}{\partial \rho} \right]^T = [\cos \varphi, \sin \varphi]^T \quad , \quad \hat{h}_\rho = [\cos \varphi, \sin \varphi]^T$$

$$h_\varphi = \left[ \frac{\partial x}{\partial \varphi}, \frac{\partial y}{\partial \varphi} \right]^T = [-\rho \sin \varphi, \rho \cos \varphi]^T \quad , \quad \hat{h}_\varphi = [-\sin \varphi, \cos \varphi]^T$$

$$\Rightarrow \begin{cases} \hat{h}_\rho = \left[ \cos \left( \arctan \frac{\sin \beta}{\sinh \alpha} \right), \sin \left( \arctan \frac{\sin \beta}{\sinh \alpha} \right) \right]^T \\ \hat{h}_\varphi = \left[ -\sin \left( \arctan \frac{\sin \beta}{\sinh \alpha} \right), \cos \left( \arctan \frac{\sin \beta}{\sinh \alpha} \right) \right]^T \end{cases} \quad \text{or} \quad \begin{cases} \hat{h}_\rho = \left[ \frac{\sinh \alpha}{\sqrt{\sinh^2 \alpha + \sin^2 \beta}}, \frac{\sin \beta}{\sqrt{\sinh^2 \alpha + \sin^2 \beta}} \right]^T \\ \hat{h}_\varphi = \left[ -\frac{\sin \beta}{\sqrt{\sinh^2 \alpha + \sin^2 \beta}}, \frac{\sinh \alpha}{\sqrt{\sinh^2 \alpha + \sin^2 \beta}} \right]^T \end{cases}$$

$$\hat{h}_\rho = \begin{bmatrix} \hat{h}_\alpha \\ \hat{h}_\beta \end{bmatrix} \quad ? \quad -3$$



in polar coordinates:

$$\begin{cases} x = \rho \cos \varphi \\ y = \rho \sin \varphi \end{cases} \Rightarrow \begin{aligned} h_\rho &= \left[ \frac{\partial x}{\partial \rho}, \frac{\partial y}{\partial \rho} \right]^T = [\cos \varphi, \sin \varphi]^T \\ h_\varphi &= \left[ \frac{\partial x}{\partial \varphi}, \frac{\partial y}{\partial \varphi} \right]^T = [-\rho \sin \varphi, \rho \cos \varphi]^T \end{aligned}$$

$$\Rightarrow \begin{aligned} \hat{h}_\rho &= [\cos \varphi, \sin \varphi]^T \\ \hat{h}_\varphi &= [-\sin \varphi, \cos \varphi]^T \end{aligned} \quad \text{i.e.} \quad \begin{bmatrix} \hat{h}_\rho \\ \hat{h}_\varphi \end{bmatrix} = \begin{bmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{bmatrix} \begin{bmatrix} \hat{i} \\ \hat{j} \end{bmatrix}$$

according to a),  $\begin{bmatrix} \hat{h}_\alpha \\ \hat{h}_\beta \end{bmatrix} = \begin{bmatrix} \frac{1 - \cos \alpha \cos \beta}{N} & \frac{-\sin \alpha \sin \beta}{N} \\ \frac{-\sin \alpha \sin \beta}{N} & \frac{\cos \alpha \cos \beta - 1}{N} \end{bmatrix} \begin{bmatrix} \hat{i} \\ \hat{j} \end{bmatrix}$

$$\begin{aligned} \begin{bmatrix} \hat{h}_\rho \\ \hat{h}_\varphi \end{bmatrix} &= \begin{bmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{bmatrix} \cdot \begin{bmatrix} \frac{1 - \cos \alpha \cos \beta}{N} & \frac{-\sin \alpha \sin \beta}{N} \\ \frac{-\sin \alpha \sin \beta}{N} & \frac{\cos \alpha \cos \beta - 1}{N} \end{bmatrix} \begin{bmatrix} \hat{h}_\alpha \\ \hat{h}_\beta \end{bmatrix} \\ &= \begin{bmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{bmatrix} \cdot \begin{bmatrix} \frac{\cos \alpha \cos \beta - 1}{N} & \frac{\sin \alpha \sin \beta}{N} \\ \frac{\sin \alpha \sin \beta}{N} & \frac{1 - \cos \alpha \cos \beta}{N} \end{bmatrix} \begin{bmatrix} \hat{h}_\alpha \\ \hat{h}_\beta \end{bmatrix} \end{aligned}$$



$$\begin{cases} x = (N+H) \cos B \cos L \\ y = (N+H) \cos B \sin L \\ z = ((1-E^2)N+H) \sin B \end{cases}$$

$$N = \frac{A}{\sqrt{1-E^2 \sin^2 B}}$$

$$M = \frac{A(1-E^2)}{(1-E^2 \sin^2 B)^{3/2}}$$

$$\frac{\partial N}{\partial B} = (N-M) \tan B$$

$$a) \quad \underline{h_L} = \left[ \frac{\partial x}{\partial L}, \frac{\partial y}{\partial L}, \frac{\partial z}{\partial L} \right]^T = \begin{bmatrix} -(N+H) \cos B \sin L \\ (N+H) \cos B \cos L \\ 0 \end{bmatrix}$$

$$|h_L| = \sqrt{[(N+H) \cos B \sin L]^2 + [(N+H) \cos B \cos L]^2} = (N+H) \cos B$$

$$\hat{h_L} = [-\sin L, \cos L, 0]^T$$

$$\underline{h_B} = \left[ \frac{\partial x}{\partial B}, \frac{\partial y}{\partial B}, \frac{\partial z}{\partial B} \right]^T = \begin{bmatrix} -(N-M) \tan B \cos B \cos L + (N+H) (-\sin B) \cos L \\ (N-M) \tan B \cos B \sin L + (N+H) (-\sin B) \sin L \\ (1-E^2)(N-M) \tan B \sin B + [(1-E^2)N+H] \cos B \end{bmatrix}$$

$$= \begin{bmatrix} -(N+H) \sin B \cos L \\ -(N+H) \sin B \sin L \\ (1-E^2) \frac{A E^2 \sin^2 B}{(1-E^2 \sin^2 B)^{3/2}} \cdot \frac{\sin^2 B}{\cos B} + (1-E^2) \cdot \frac{A(1-E^2 \sin^2 B) \cos B}{(1-E^2 \sin^2 B)^{3/2}} + H \cos B \end{bmatrix}$$

$$= \begin{bmatrix} -(N+H) \sin B \cos L \\ -(N+H) \sin B \sin L \\ (N+H) \cos B \end{bmatrix}$$

$$|\hat{h_B}| = \sqrt{[(N+H) \sin B \cos L]^2 + [(N+H) \sin B \sin L]^2 + [(N+H) \cos B]^2} = N+H$$

$$\hat{h_B} = \begin{bmatrix} -\sin B \cos L \\ -\sin B \sin L \\ \cos B \end{bmatrix}$$

$$\underline{h_H} = \left[ \frac{\partial x}{\partial H}, \frac{\partial y}{\partial H}, \frac{\partial z}{\partial H} \right]^T = \begin{bmatrix} \cos B \cos L \\ \cos B \sin L \\ \sin B \end{bmatrix}$$

$$|h_H| = \sqrt{(\cos B \cos L)^2 + (\cos B \sin L)^2 + \sin^2 B} = 1$$

$$\hat{h_H} = [-\sin B \cos L, -\sin B \sin L, \cos B]^T$$

$$\Rightarrow \text{gradient } \nabla \phi = \sum_{i=1}^3 \frac{1}{|h_i|} \cdot \frac{\partial \phi}{\partial q_i} \hat{h}_i = \frac{1}{(N+H) \cos B} \frac{\partial \phi}{\partial L} \hat{h_L} + \frac{1}{N+H} \frac{\partial \phi}{\partial B} \hat{h_B} + \frac{\partial \phi}{\partial H} \hat{h_H}$$

$$b) \quad \text{curl } G(L, B, H) = \frac{1}{h_L h_B h_H} \det \begin{pmatrix} h_L \hat{h_L} & h_B \hat{h_B} & h_H \hat{h_H} \\ \frac{\partial}{\partial L} & \frac{\partial}{\partial B} & \frac{\partial}{\partial H} \\ h_L G_L & h_B G_B & h_H G_H \end{pmatrix}$$



$$\frac{1}{(N+H)\cos B \cdot (M+H) \cdot 1} \cdot \det \begin{pmatrix} |h_L| \cdot \hat{h}_L & |h_B| \cdot \hat{h}_B & |h_H| \cdot \hat{h}_H \\ \frac{\partial}{\partial L} & \frac{\partial}{\partial B} & \frac{\partial}{\partial H} \\ |h_L| \cdot G_L & |h_B| \cdot G_B & |h_H| \cdot G_H \end{pmatrix}$$

$$\frac{1}{(N+H)\cos B \cdot (M+H)} \cdot \left[ |h_L| \cdot \hat{h}_L \cdot \left( \frac{\partial}{\partial B} (|h_H| \cdot G_H) - \frac{\partial}{\partial H} (|h_B| \cdot G_B) \right) - |h_B| \cdot \hat{h}_B \cdot \left( \frac{\partial}{\partial L} (|h_H| \cdot G_H) - \frac{\partial}{\partial H} (|h_L| \cdot G_L) \right) \right. \\ \left. + |h_H| \cdot \hat{h}_H \cdot \left( \frac{\partial}{\partial L} (|h_B| \cdot G_B) - \frac{\partial}{\partial B} (|h_L| \cdot G_L) \right) \right]$$

$$\frac{1}{(N+H) \cdot \cos B \cdot (M+H)} \cdot \left[ (N+H) \cos B \cdot \hat{h}_L \cdot \left( -\sin B \sin L - (M+2H) \cos B \right) - (M+H) \cdot \hat{h}_B \cdot \left( \cos B \cos L - \cos B \sin L \right) \right. \\ \left. + 1 \cdot \hat{h}_H \cdot \left( 0 - (N+H) \cdot (-\sin B) \cdot \cos L \right) \right]$$

$$\frac{\sin B \sin L - (M+2H) \cos B}{M+H} \hat{h}_L + \frac{\sin B \cos L}{\cos B (M+H)} \hat{h}_H$$



$$\begin{cases} x = r \sinh \alpha \cos \beta \cos \varphi \\ y = r \sinh \alpha \cos \beta \sin \varphi \\ z = r \sinh \alpha \sin \beta \end{cases}$$

$$f = \sqrt{\sinh^2 \alpha \cos^2 \beta + \sinh^2 \alpha \sin^2 \beta}$$

$$\Rightarrow h_\alpha = \left[ \frac{\partial x}{\partial \alpha}, \frac{\partial y}{\partial \alpha}, \frac{\partial z}{\partial \alpha} \right]^T = [\sinh \alpha \cos \beta \cos \varphi, \sinh \alpha \cos \beta \sin \varphi, r \cosh \alpha \sin \beta]^T$$

$$|h_\alpha| = \sqrt{(\sinh \alpha \cos \beta \cos \varphi)^2 + (\sinh \alpha \cos \beta \sin \varphi)^2 + (r \cosh \alpha \sin \beta)^2} = \sqrt{\sinh^2 \alpha + \sinh^2 \beta}$$

$$\hat{h}_\alpha = \frac{1}{\sqrt{\sinh^2 \alpha + \sinh^2 \beta}} [\sinh \alpha \cos \beta \cos \varphi, \sinh \alpha \cos \beta \sin \varphi, r \cosh \alpha \sin \beta]^T$$

$$h_\beta = \left[ \frac{\partial x}{\partial \beta}, \frac{\partial y}{\partial \beta}, \frac{\partial z}{\partial \beta} \right]^T = [-r \sinh \alpha \sin \beta \cos \varphi, -r \sinh \alpha \sin \beta \sin \varphi, \sinh \alpha \cos \beta]^T$$

$$|h_\beta| = \sqrt{(r \sinh \alpha \sin \beta \cos \varphi)^2 + (r \sinh \alpha \sin \beta \sin \varphi)^2 + (\sinh \alpha \cos \beta)^2} = \sqrt{(\sinh \alpha)^2 + \sinh^2 \beta}$$

$$\hat{h}_\beta = \frac{1}{\sqrt{\sinh^2 \alpha + \sinh^2 \beta}} [-r \sinh \alpha \sin \beta \cos \varphi, -r \sinh \alpha \sin \beta \sin \varphi, \sinh \alpha \cos \beta]^T$$

$$h_\varphi = \left[ \frac{\partial x}{\partial \varphi}, \frac{\partial y}{\partial \varphi}, \frac{\partial z}{\partial \varphi} \right]^T = [-r \sinh \alpha \cos \beta \sin \varphi, r \sinh \alpha \cos \beta \cos \varphi, 0]^T$$

$$|h_\varphi| = \sqrt{(r \sinh \alpha \cos \beta \sin \varphi)^2 + (r \sinh \alpha \cos \beta \cos \varphi)^2} = r \sinh \alpha \cos \beta$$

$$\hat{h}_\varphi = [-\sin \varphi, \cos \varphi, 0]^T$$

$$\Rightarrow \text{gradient, } \nabla f = \frac{1}{h_\alpha} \frac{\partial f}{\partial \alpha} \hat{h}_\alpha + \frac{1}{h_\beta} \frac{\partial f}{\partial \beta} \hat{h}_\beta + \frac{1}{h_\varphi} \frac{\partial f}{\partial \varphi} \hat{h}_\varphi$$

$$\text{while } \frac{\partial f}{\partial \alpha} = \frac{2 \sinh \alpha \cosh \alpha \cos^2 \beta + 2 \cosh \alpha \sinh \alpha \sin^2 \beta}{2 \sqrt{\sinh^2 \alpha \cos^2 \beta + \sinh^2 \alpha \sin^2 \beta}} = \frac{\sinh \alpha \cosh \alpha}{\sqrt{\sinh^2 \alpha (\cos^2 \beta + \sin^2 \beta) + \sinh^2 \beta}} = \frac{\sinh 2\alpha}{2 \sqrt{\sinh^2 \alpha + \sinh^2 \beta}}$$

$$\text{orly, } \frac{\partial f}{\partial \beta} = \frac{\sinh 2\beta}{2 \sqrt{\sinh^2 \alpha + \sinh^2 \beta}}$$

$$\frac{\partial f}{\partial \varphi} = 0$$

$$\Rightarrow \nabla f = \frac{1}{\sqrt{\sinh^2 \alpha + \sinh^2 \beta}} \cdot \frac{\sinh 2\alpha}{2 \sqrt{\sinh^2 \alpha + \sinh^2 \beta}} \hat{h}_\alpha + \frac{1}{\sqrt{\sinh^2 \alpha + \sinh^2 \beta}} \cdot \frac{\sinh 2\beta}{2 \sqrt{\sinh^2 \alpha + \sinh^2 \beta}} \hat{h}_\beta + 0$$

$$= \frac{\sinh 2\alpha}{\sinh^2 \alpha + \sinh^2 \beta} \hat{h}_\alpha + \frac{\sinh 2\beta}{\sinh^2 \alpha + \sinh^2 \beta} \hat{h}_\beta$$