

# ES\_LPC177x/8x

## Errata sheet LPC177x/8x

Rev. 2.2 — 17 January 2012

Errata sheet

### Document information

Info	Content
<b>Keywords</b>	LPC1788FBD208, LPC1788FET208, LPC1788FET180, LPC1788FBD144, LPC1787FBD208, LPC1786FBD208, LPC1785FBD208, LPC1778FBD208, LPC1778FET208, LPC1778FET180, LPC1778FBD144, LPC1777FBD208, LPC1776FBD208, LPC1776FET180, LPC1774FBD208, LPC1774FBD144, LPC177x/8x errata
<b>Abstract</b>	<p>This errata sheet describes both the known functional problems and any deviations from the electrical specifications known at the release date of this document.</p> <p>Each deviation is assigned a number and its history is tracked in a table at the end of the document.</p>



## Revision history

Rev	Date	Description
2.2	20120117	<ul style="list-style-type: none"><li>Added ADC.2.</li></ul>
2.1	20111101	<ul style="list-style-type: none"><li>Added Rev 'E'.</li></ul>
2	20110901	<ul style="list-style-type: none"><li>Added ISP.1.</li><li>Added Rev 'A'.</li></ul>
1.1	20110601	<ul style="list-style-type: none"><li>Added WDT.1.</li><li>Added DPD.1.</li><li>Added USART.</li></ul>
1	20110525	<ul style="list-style-type: none"><li>Initial version.</li></ul>

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## 1. Product identification

The LPC177x/8x devices typically have the following top-side marking:

LPC17xxXXX

xxxxxxx

xxYYWWR[x]

The last digit in the last line (field 'R') will identify the device revision. Note: Pre-production parts are marked differently and this system does not apply. This Errata Sheet covers the following revisions of the LPC177x/8x:

**Table 1. Device revision table**

Revision identifier (R)	Revision description
'L'	Initial device revision
'A'	Second device revision
'E'	Third device revision

Field 'YY' states the year the device was manufactured. Field 'WW' states the week the device was manufactured during that year.

## 2. Errata overview

**Table 2. Functional problems table**

Functional problems	Short description	Revision identifier	Detailed description
ADC.1	External sync inputs not operational	'L', 'A', 'E'	<a href="#">Section 3.1</a>
ADC.2	A/D Global Data register should not be used with burst mode or hardware triggering.	'L', 'A', 'E'	<a href="#">Section 3.2</a>
ISP.1	Maximum UART ISP baud rate limited to 57,600	'L', 'A', 'E'	<a href="#">Section 3.3</a>
RTC.1	The RTC may lose time when RESET is toggled	'L', 'A', 'E'	<a href="#">Section 3.4</a>
USART.1	Smart Card TX retry error interrupt not working	'L', 'A', 'E'	<a href="#">Section 3.5</a>
USART.2	'False positive' break indicator events may occur	'L', 'A', 'E'	<a href="#">Section 3.6</a>
USB.1	USB host controller hangs on a dribble bit	'L', 'A', 'E'	<a href="#">Section 3.7</a>
WDT.1	WDT timeout does not wake from deep sleep	'L', 'A', 'E'	<a href="#">Section 3.8</a>

**Table 3. AC/DC deviations table**

AC/DC deviations	Short description	Revision identifier	Detailed description
DPD.1	Increase of Deep power-down leakage current over time	'L'	<a href="#">Section 4.1</a>

**Table 4. Errata notes table**

Errata notes	Short description	Revision identifier	Detailed description
n/a	n/a	n/a	n/a

### 3. Functional problems detail

#### 3.1 ADC.1: External sync inputs not operational

##### Introduction:

In software-controlled mode (BURST bit is 0), the 10-bit ADC can start conversion by using the following options in the A/D Control Register:

**32.5.1 A/D Control Register (AD0CR - 0x4003 4000)**

**Table 656: A/D Control Register (AD0CR - address 0x4003 4000) bit description**

Bit	Symbol	Value	Description	Reset value
7:0	SEL		Selects which of the AD0[7:0] pins is (are) to be sampled and converted. For AD0, bit 0 selects Pin A/D0[0] and bit 7 selects pin A/D0[7]. In software-controlled mode, only one of	0x01
26:24	START		When the BURST bit is 0, these bits control whether and when an A/D conversion is started:	0
		000	No start (this value should be used when clearing PDN to 0).	
		001	Start conversion now.	
		010	Start conversion when the edge selected by bit 27 occurs on the P2[10] pin.	
		011	Start conversion when the edge selected by bit 27 occurs on the P1[27] pin.	
		100	Start conversion when the edge selected by bit 27 occurs on MAT0.1. Note that this does not require that the MAT0.1 function appear on a device pin.	
		101	Start conversion when the edge selected by bit 27 occurs on MAT0.3. Note that it is not possible to cause the MAT0.3 function to appear on a device pin.	
		110	Start conversion when the edge selected by bit 27 occurs on MAT1.0. Note that this does not require that the MAT1.0 function appear on a device pin.	
		111	Start conversion when the edge selected by bit 27 occurs on MAT1.1. Note that this does not require that the MAT1.1 function appear on a device pin.	

**Fig 1. A/D control register options**

##### Problem:

The external start conversion feature, AD0CR:START = 0x2 or 0x3, may not work reliably and ADC external trigger edges on P2.10 or P1.27 may be missed. The occurrence of this problem is peripheral clock (PCLK) dependent. The probability of error (missing a ADC trigger from GPIO) is estimated as follows:

- For PCLK = 100 MHz, probability error = 12 %
- For PCLK = 50 MHz, probability error = 6 %
- For PCLK = 12 MHz, probability error = 1.5 %

The probability of error is not affected by the frequency of ADC start conversion edges.

##### Work-around:

In software-controlled mode (BURST bit is 0), the START conversion options (bits 26:24 set to 0x1 or 0x4 or 0x5 or 0x6 or 0x7) can be used. The user can also start a conversion by connecting an external trigger signal to a capture input pin (CAPx) from a Timer peripheral to generate an interrupt. The timer interrupt routine can then start the ADC conversion by setting the START bits (26:24) to 0x1. The trigger can also be generated from a timer match register.

### 3.2 ADC.2: A/D Global Data register should not be used with burst mode or hardware triggering

#### Introduction:

On the LPC177x/8x, the START field and the BURST bit in the A/D control register specify whether A/D conversions are initiated via software command, in response to some hardware trigger, or continuously in burst ("hardware-scan") mode. Results of the ADC conversions can be read in one of two ways. One is to use the A/D Global Data Register to read all data from the ADC. Another is to use the individual A/D Channel Data Registers.

#### Problem:

If the burst mode is enabled (BURST bit set to '1') or if hardware triggering is specified, the A/D conversion results read from the A/D Global Data register could be incorrect. If conversions are only launched directly by software command (BURST bit = '0' and START = '001'), the results read from the A/D Global Data register will be correct provided the previous result is read prior to launching a new conversion.

#### Work-around:

When using either burst mode or hardware triggering, the individual A/D Channel Data registers should be used instead of the A/D Global Data register to read the A/D conversion results.

### 3.3 ISP.1: Maximum UART ISP baud rate limited to 57,600

#### Introduction:

In-System Programming (ISP) is programming or reprogramming the on-chip flash memory, using the boot loader software and UART0 serial port. This can be done when the part resides in the end-user board.

#### Problem:

UART ISP cannot be used at rates higher than 57,600 bits per second.

#### Work-around:

UART ISP must be used at 57,600 bits per second or a lower communications speed.

### 3.4 RTC.1: RTC may lose time when RESET is toggled

#### Introduction:

The Real Time Clock (RTC) is a set of counters for measuring time when system power is on, and optionally when it is off. It uses very little power when its registers are not being accessed by the CPU, especially in reduced power modes.

#### Problem:

RTC temporarily pauses and loses fractions of a second during the rising and falling edges of RESET. This occurs only in the LQFP packages with certain voltage swings and ramp rates. The problem is exacerbated by low temperatures. Reducing the voltage swing and/or ramp rate of the reset pulse will eliminate this loss of time counts. When this issue occurs, the impact on RTC accuracy is expected to be one second every several thousand reset events.

#### Work-around:

Adding an RC filter between the reset pin and the external reset input to control the reset signal voltage ramp rate can prevent this problem.

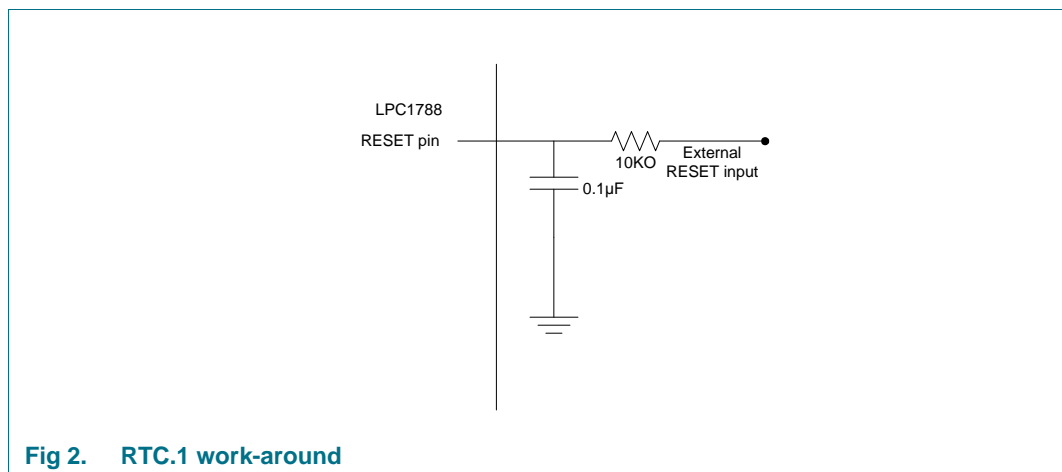


Fig 2. RTC.1 work-around

### 3.5 USART.1: Smart Card TX retry error interrupt not working

#### Introduction:

USART4 includes a synchronous mode and a Smart Card mode supporting ISO 7816-3. This allows smart cards to be interfaced to support high security applications.

#### Problem:

The USART4 Transmit Interrupt is entered after failed retries (based on NACK) but source of error is not given in IIR or LSR registers. This happens when the TX FIFO has one or more items still to be sent out. When there are no other items in the TX FIFO and the FIFO head item fails the retry, the interrupt works correctly with bit 8 flagged in the LSR.

#### Work-around:

A workaround is to avoid using the FIFO on USART4 in Smart Card mode. When there is data ready to transmit, hold it in a software queue until the FIFO is empty then send it one character at a time. Another workaround is to check all of the interrupt sources in the TX interrupt and if there is no interrupt source, to assume that a NAK could have been received. This allows use of the FIFO but could require changes to program logic.

### 3.6 USART.2: 'False positive' break interrupt events may occur

#### Introduction:

The LPC177x/8x device family features an option to operate the USART4 in synchronous mode.

#### Problem:

When using synchronous UART mode (USART) under the following conditions:

- CSCEN = 0 (SCK active only during transmission)
- CSRC = 0 (Synchronous Slave Mode)
- FES = 1 (Falling Edge Sampling)
- SSDIS = 0 (Use Start and Stop Bit)
- The external transmitting device (Master) sends start and stop bits
- The external device transmits 0x00

The Break Interrupt (BI) flag can become set, despite the fact that no break condition on the bus has occurred. This problem does not manifest when the external master device uses two stop bits.

#### Work-around:

None, however in some cases system designers have control over the protocol being used between devices and can avoid the error condition outlined above in their system design and/or communication protocol.



### 3.7 USB.1: USB host controller hangs on a dribble bit

#### Introduction:

Full-/low-speed signaling uses bit stuffing throughout the packet without exception. If the receiver sees seven consecutive ones anywhere in the packet, then a bit stuffing error has occurred and the packet should be ignored.

The time interval just before an EOP is a special case. The last data bit before the EOP can become stretched by hub switching skews. This is known as dribble and can lead to a situation where dribble introduces a sixth bit that does not require a bit stuff. Therefore, the receiver must accept a packet for which there are up to six full bit times at the port with no transitions prior to the EOP.

#### Problem:

The USB host controller will hang indefinitely if it sees a dribble bit on the USB bus. It will hang the first time a dribble bit is seen. Once it is in this state there is no recovery other than a hard chip reset. This problem has no effect on the USB device controller.

#### Work-around:

None.

### 3.8 WDT.1: WDT timeout does not wake from deep sleep

#### Introduction:

The purpose of the Watchdog Timer is to reset the microcontroller within a reasonable amount of time if it enters an erroneous state. When enabled, a watchdog event will be generated if the user program fails to "feed" (or reload) the Watchdog within a predetermined amount of time. The Watchdog event will cause a chip reset if configured to do so.

#### Problem:

WDT timeout operates in run and sleep modes, but does not wake the MCU from deep sleep mode.

#### Work-around:

None.

## 4. AC/DC deviations detail

### 4.1 DPD.1: Increase of Deep power-down leakage current over time

#### Introduction:

Deep power-down is a low-power mode that achieves currents in the low single-digit microamperes.

#### Problem:

Increase of  $I_{DDREG(3V3)}$  current in Deep power-down mode for on-chip regulator over time (to about 100-200 uA). There is no functional impact.

Expected time to result in high regulator Deep power-down current vs. temperature and bias is listed in [Table 5](#).

**Table 5. LPC177x/8x on-chip regulator expected time (years) to result in high regulator Deep power-down current under different bias and temp condition**

V <sub>DD</sub>	Years at 25°C	Years at 85°C
2.5 V	4.98E+05	7190.00
3.0 V	714	10.30
3.3 V	14.1	0.20

Identification of Changed Product: All Rev '-' devices.

#### Remarks:

1. Issue described will lead to problems only if customer puts bias on V<sub>DD\_REG</sub> at over 3.0 V with application sensitive to  $I_{DDREG(3V3)}$  current in Deep power-down mode (few hundred uA)
2. If the biased V<sub>DD</sub> can be restricted to 3.0 V then the expected time to result in high leakage current will be over 10 years at Industrial temp range.
3. Biased V<sub>DD</sub> of 3.3 V at 25°C (room temp) will also guarantee datasheet spec for over 10 years.
4. If  $I_{DDREG(3V3)}$  current in Deep power-down mode (few hundred uA) is a key parameter, it is not advised to bias V<sub>DD\_REG</sub> above 3.0 V.

#### Work-around:

None. This has been fixed in Rev 'A'.

## 5. Errata notes detail

### 5.1 n/a

## 6. Legal information

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Date of release: 17 January 2012

Document identifier: ES\_LPC177X\_8X