#### Modelisation des reseaux biologiques

Madalena Chaves madalena.chaves@inria.fr (INRIA, Macbes)

Travaux diriges ---> projet computationnel, **scilab** 

Jean-Luc Gouze jean-luc.gouze@inria.fr (INRIA, Macbes)

Cours

Modalites: examen (70%), projet (30%)

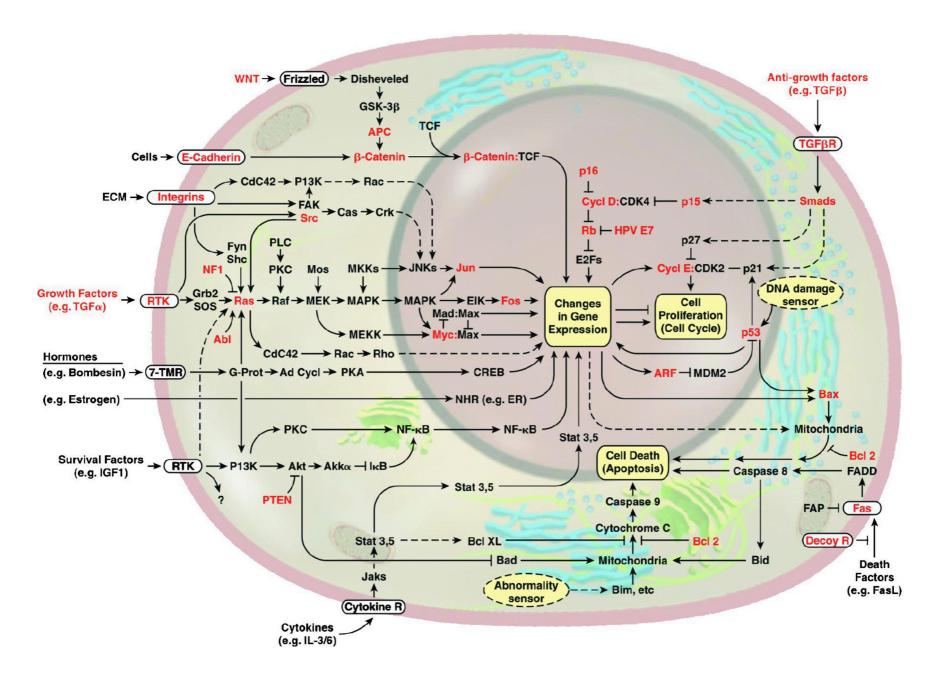
#### <u>Useful references</u>:

## Mathematical models in biology, Edelstein-Keshet, SIAM classics 2004

#### Systems Biology in practice, Klipp, Herwig et al , Wiley 2005

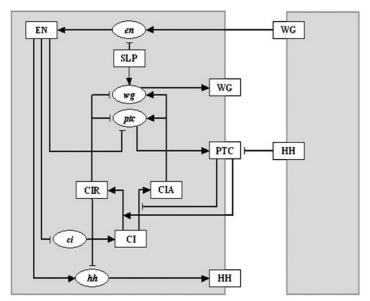
- H. de Jong and D. Thieffry. Modelisation, analyse et simulation des reseaux genetiques. Medecine/Sciences, 18:492–502, 2002.
- L. Segel. Modeling dynamic phenomena in molecular and cellular biology. Cambridge University Press, New York, 1984.
- S.I. Rubinow. Introduction to Mathematical Biology.
- E.D. Sontag. Lecture notes in mathematical biology http://www.math.rutgers.edu/ sontag/613.html.

## Cell and cellular signalling

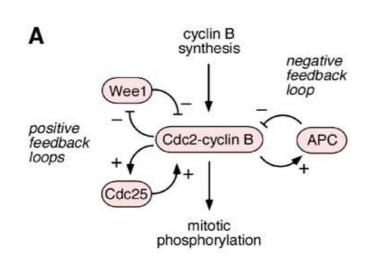


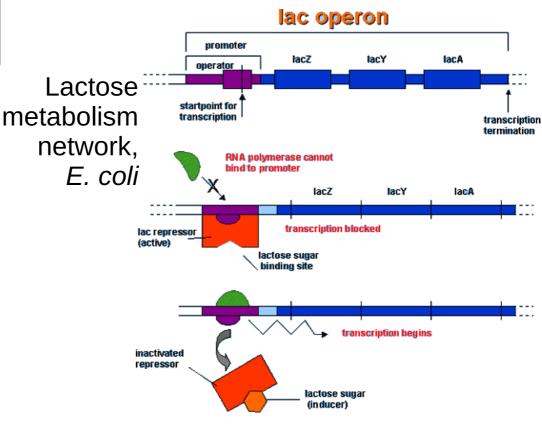
#### Examples of biological systems and data

Pattern formation, fly embryo



Cell cycle oscillator, eukaryotes



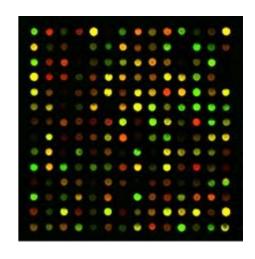


#### Experimental data available

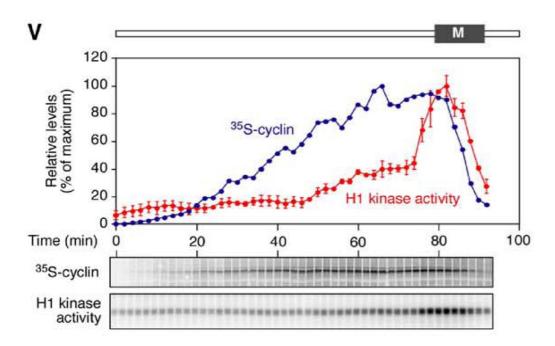
Expression
of gene
wingless,
fly embryo
(dark: highly
expressed)



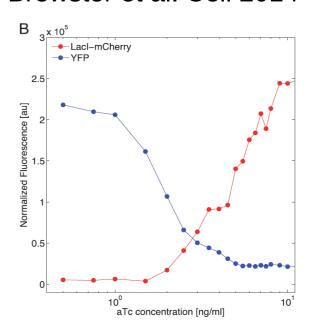
Microarray relative changes (red: expression increased)



Cdc2, cyclin B, Pomerening et al. Cell 2005



#### Lac gene expression, Brewster et al. Cell 2014



### Construct a model: why?

#### 1. Not all molecules can be measured simultaneously

## 2. Understand the underlying mechanisms of the system and its dynamics or behavior along time:

- → dose-response curves, steady states, oscillations
- → numerically, by computer simulations,
- → or by "pencil and paper" to be sure (prove mathematically) that some (desired or) dynamical behavior does happen

#### 3. Predict the response of a system to given stimuli

#### 4. Control, regulate or act on the system:

- → add a certain quantity of a ligand
- → schedule a therapeutic treatment

#### 5. Which quantities to model?

- → concentrations protein, messenger RNA
- → quantities you can measure through GFP, western blots, micro-arrays,...
- → interactions how the different proteins affect each other

## Mathematical analysis

**System of equations:** with  $x = (x_1, x_2, ..., x_N)$ 

$$\frac{dx}{dt} = f(x)$$

$$< = >$$

$$\frac{dx_1}{dt} = f_1(x_1, x_2, ..., x_N)$$

$$\frac{dx_2}{dt} = f_2(x_1, x_2, ..., x_N)$$

$$...$$

$$\frac{dx_N}{dt} = f_N(x_1, x_2, ..., x_N)$$

#### Solutions for a given initial condition:

a vector function 
$$x(t)$$
 satisfying  $\frac{dx}{dt} = f(x)$ ,  $x(0) = x_0$ 

**Equilibrium points (or steady states):**  $f(\bar{x}) = 0$ 

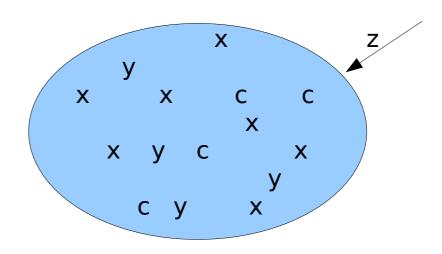
**Questions:** stability of equilibrium points, oscillatory behaviour, ...

#### Some hypotheses:

- homogeneously distributed molecules
- a sufficiently large number of molecules

Molecules of type X, Y

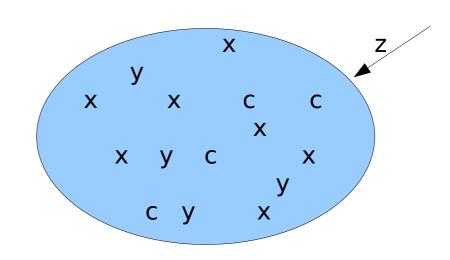
Combine/bind to generate C



### Some hypotheses:

- homogeneously distributed molecules
- a sufficiently large number of molecules

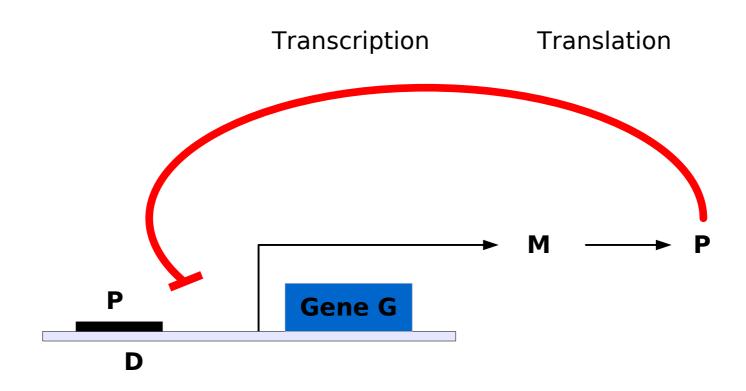
# Concentration of molecules of type X



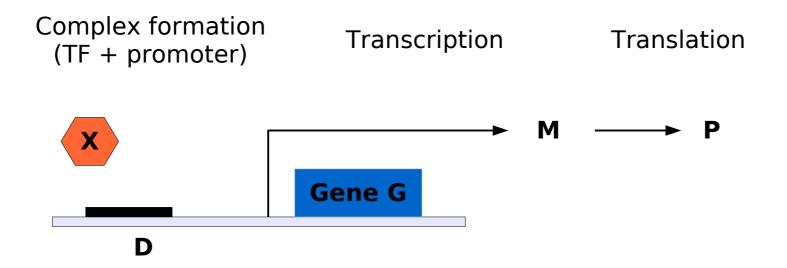
Describe by a continuous ordinary differential equation (ODE)

rate of change = production - degradation
$$\frac{dx}{dt} = f(x, y, c, z) - g(x, y, c, z)$$

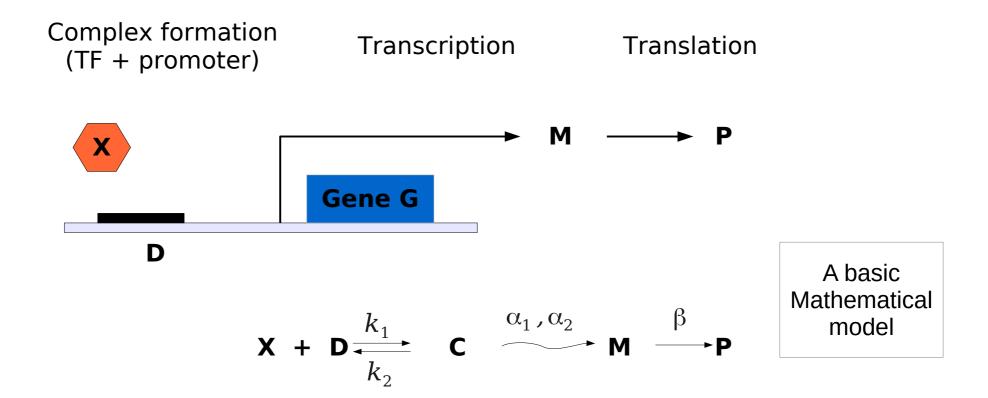
## Example: an auto-repressed gene



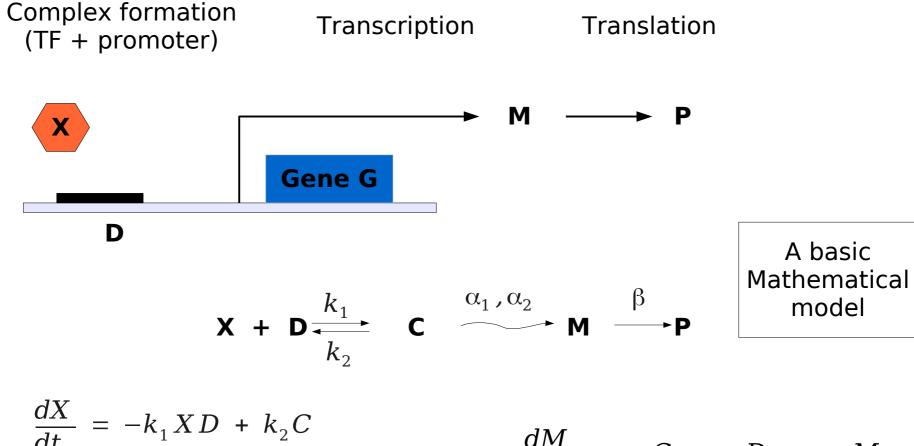
## Genetic networks: transcription and translation



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$$\frac{dX}{dt} = -k_1 X D + k_2 C 
\frac{dD}{dt} = -k_1 X D + k_2 C 
\frac{dC}{dt} = k_1 X D - k_2 C$$

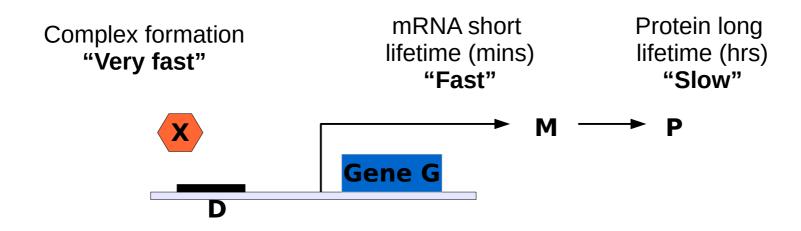
$$\frac{dM}{dt} = \alpha_1 C + \alpha_2 D - \gamma_M M 
\frac{dP}{dt} = \beta M - \gamma_P P$$

## Model reduction and simplification

1. Conservation laws: X, D or C are not "consumed" during transcription/translation

$$X + C = X_{total}$$
  
 $D + C = D_{total}$ 

2. **Three Timescales** for biological processes



Binding interactions are fast compared with transcription, translation:

$$\frac{dC}{dt} \approx 0 \quad \Leftrightarrow \quad k_1 D X - k_2 C = 0$$

Total [D] (bound+free DNA) is constant:

$$D_T = D + C \Leftrightarrow D = D_T - C$$

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Total [D] (bound+free DNA) is constant:

$$D_T = D + C \Leftrightarrow D = D_T - C$$

Substitute into the [C] equation:

$$k_1(D_T - C)X - k_2C = 0$$

$$\Leftrightarrow k_1 D_T X - (k_2 + k_1 X)C = 0$$

#### Solve with respect to [C] to obtain:

$$k_1 D_T X - (k_2 + k_1 X)C = 0$$

$$\Rightarrow C = k_1 D_T \frac{X}{k_2 + k_1 X} = D_T \frac{X}{\frac{k_2}{k_1} + X}$$

#### Michaelis-Menten equation

#### If *n molecules of X* are involved in binding D:

$$\frac{dC}{dt} \approx 0 \quad \Leftrightarrow \quad k_1 X^n D - k_2 C = 0$$

$$D_T = D + C \Leftrightarrow D = D_T - C$$

#### Obtain the **Hill equation**:

$$\Rightarrow C = D_T \frac{X^n}{\frac{k_2}{k_1} + X^n} \equiv D_T \frac{X^n}{\frac{k_1^n + X^n}{k_1^n}}$$

*n* is called the Hill exponent

The system of 5 variables is reduced to 2 variables:

$$\frac{dM}{dt} = \alpha_1 C + \alpha_2 D - \gamma_M M$$

$$\frac{dP}{dt} = \beta M - \gamma_P P$$

With:

$$C = D_T \frac{X^n}{k_X^n + X^n}$$

$$D = D_T - C = D_T - D_T \frac{X^n}{k_X^n + X^n} = D_T \frac{k_X^n}{k_X^n + X^n}$$

#### The system of 5 variables is reduced to 2 variables:

$$\frac{dM}{dt} = \alpha_1 C + \alpha_2 D - \gamma_M M$$

$$\frac{dP}{dt} = \beta M - \gamma_P P$$

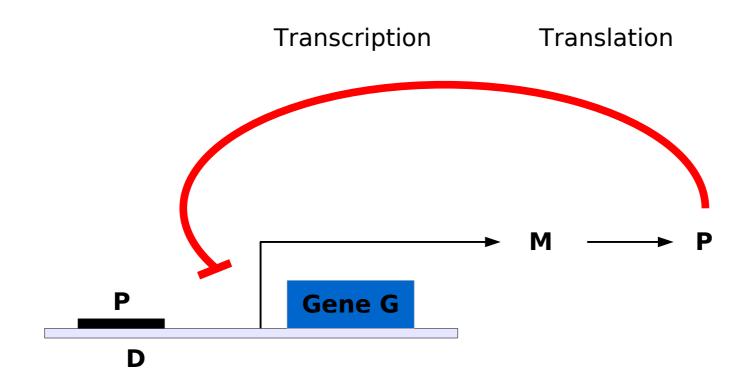
With:

$$C = D_T \frac{X^n}{k_X^n + X^n}$$

$$D = D_{T} - C = D_{T} - D_{T} \frac{X^{n}}{k_{X}^{n} + X^{n}} = D_{T} \frac{(k_{X}^{n})}{k_{X}^{n} + X^{n}}$$

X

#### Example: an auto-repressed gene



In the case of a **repression** 

TRANSCRIPTION is proportional to the amount of FREE PROMOTER, **D** 

**System equations? Equilibria?** 

#### Model reduction, continued

Timescales: lifetime(mRNA)<lifetime(protein)

so the **mRNA dynamics is faster** than the protein dynamics:

$$\frac{dM}{dt} = \mathbf{0} \qquad \Leftrightarrow \qquad \alpha_1 C + \alpha_2 D - \gamma_M M = 0$$

$$\frac{dP}{dt} = \beta M - \gamma_P P$$

#### Model reduction, continued

Obtain the following expression for *M*:

$$M = \frac{\alpha_1}{\gamma_M} D_T \frac{X^n}{k_X^n + X^n} + \frac{\alpha_2}{\gamma_M} D_T \frac{k_X^n}{k_X^n + X^n}$$

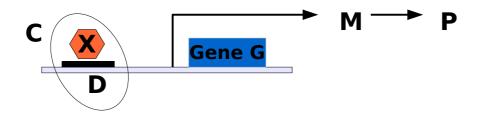
Finally, substitute this expression into P equation:

$$\frac{dP}{dt} = \beta \frac{\alpha_1}{\gamma_M} D_T \frac{X^n}{k_X^n + X^n} + \beta \frac{\alpha_2}{\gamma_M} D_T \frac{k_X^n}{k_X^n + X^n} - \gamma_p P$$

#### Modeling activation

#### X is an activator

(helps promote transcription)



Bound complex C strongly contributes to protein production:  $\alpha_1 \gg \alpha_2$ 

Rename parameters:  $\beta_1 = \frac{\alpha_1}{\gamma_M} D_T$ 

$$\frac{dP}{dt} = \beta_0 + \left(\beta_1 \frac{X^n}{X^n + k_X^n}\right) - \gamma_P P$$

Synthesis of protein is Increasingly proportional to amount of X

$$F(X)$$
  $k_X$   $X$ 

### Modeling repression

#### X is an inhibitor

(represses transcription)

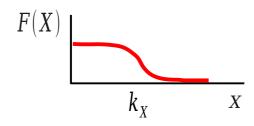


Unbound sites **D** strongly contribute to protein production:  $\alpha_1 \ll \alpha_2$ 

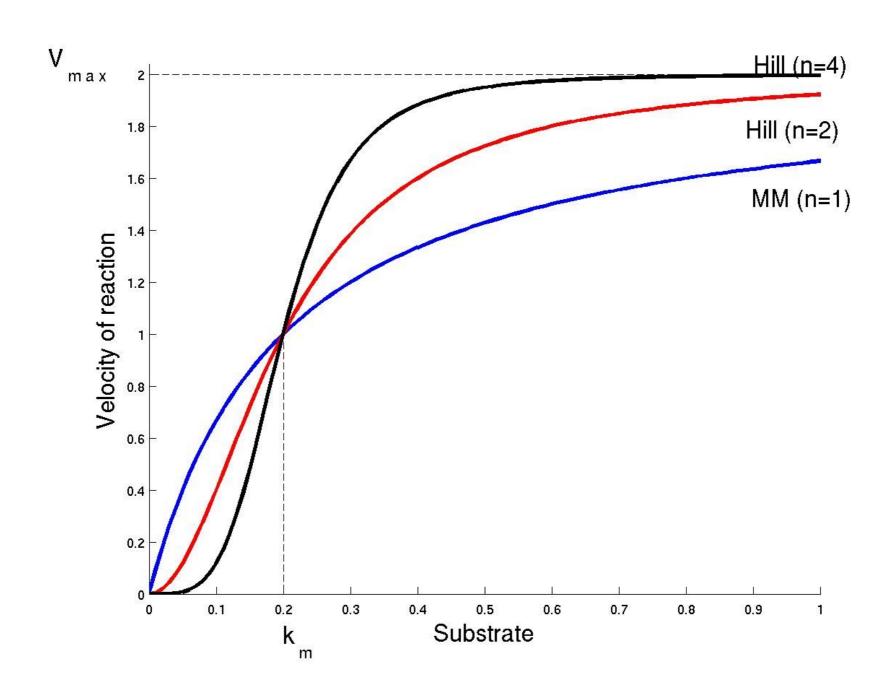
Rename parameters:  $\beta_2 = \frac{\alpha_2}{\gamma_M} D_T$ 

$$\frac{dP}{dt} = \beta_0 + \left(\beta_2 \frac{k_X^n}{X^n + k_X^n}\right) - \gamma_P P$$

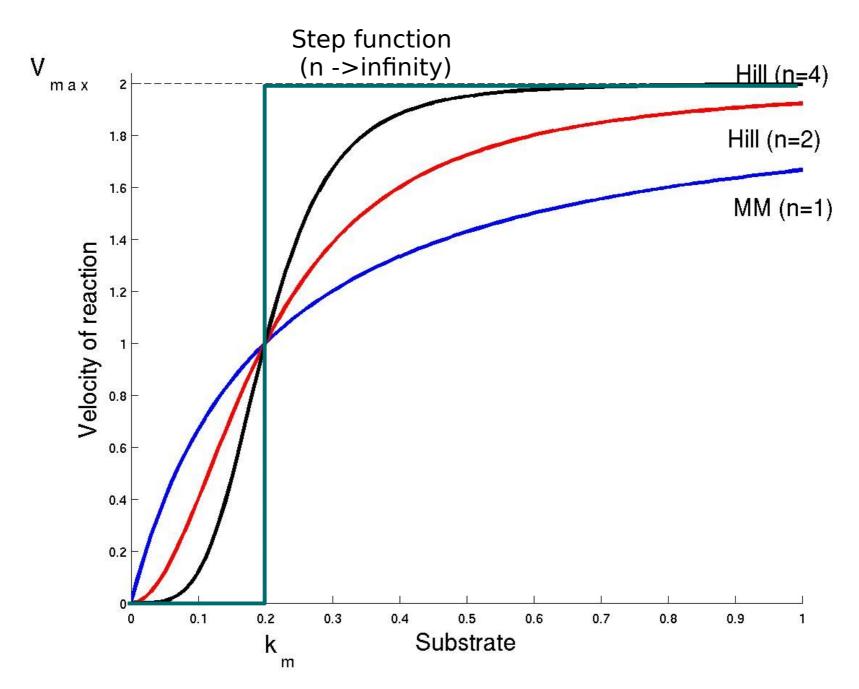
Synthesis of protein is decreasingly proportional to amount of X



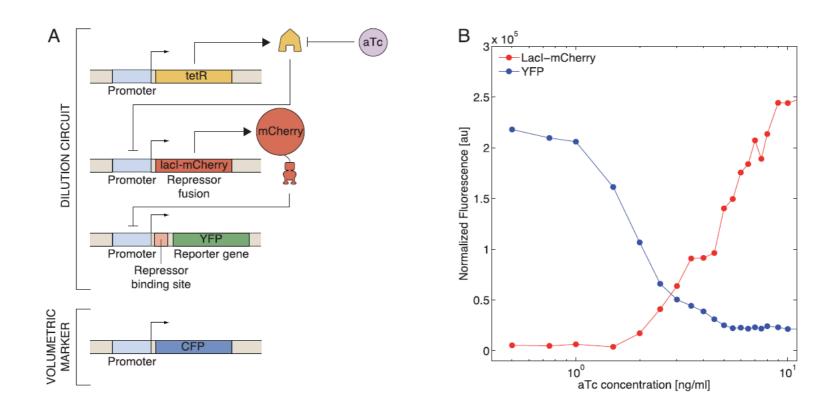
#### Michaelis-Menten and Hill functions



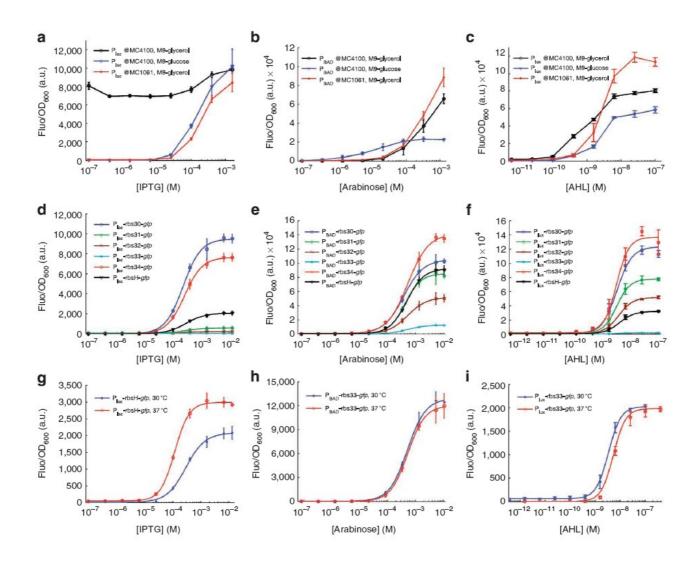
#### Michaelis-Menten and Hill functions



## Evidence for sigmoidal functions F(X)



## Evidence for sigmoidal functions F(X)



Wang et al. Nature Communications 2011 (engineering synthetic gates)

## Systèmes aux equations différentielles SOLUTIONS NUMERIQUES avec SCILAB

Telecharger et installer Scilab :

www.scilab.org

Telecharger un exemple :

www-sop.inria.fr/members/Madalena.Chaves/teaching

## Ecrire un code en Scilab : basiques

**Definitions:** 

**Equations**,

**Autres fonctions** 

Partie Principale:

Commandes
our la
Resolution,
Visualisation,
Analyse,
etc

```
//Creer fichier texte, eg.: mon_systeme.sci
 function [v] = circuit rhs(t,x,pr)
 endfunction
 function r = autre(x,s,n)
  endfunction
  //Partie principale
  x1 = ode(....);
  plot(.....);
```

//Definition du systeme d'equations differentielles, au debut fichier

```
function [v] = auto repressor rhs(t,x,pr)
//t: instant de temps
//x: variables d'etat
//pr: parametres du systeme; reprendre depuis la definition
//Renommer les parametres et les variables
alpha = pr(1);
beta = pr(2);
kP = pr(3);
gM = pr(4);
gP = pr(5);
n = pr(6);
M=x(1);
P = x(2);
//Initialisation du vecteur des derivees
V = []:
v(1) = alpha*(kP^n) / (kP^n + P^n) - gM * M;
v(2) = beta*M - gP * P;
endfunction;
```

```
//Partie principale
//Definition de parametres; vecteur de parametres;
//BIEN RESPECTER L'ORDRE DE DEFINITION DE pr
alpha = 3.1; beta = 2.3;
kP = 10:
gM = 0.1; gP = 0.01;
n = 2:
par = [alpha,beta,kP,gM,gP,n];
//Definition de condition(s) initiale(s),
//instant initial et vecteur de temps de simulation
x0 = [10;1];
t0 = 0:
dt = 0.05;
tvec = t0:dt:30;
//Commande de resolution du systeme d'equations differentielles
//methodes numeriques disponibles: "rk", "stiff",...
sol=ode("stiff",x0,t0,tvec, list(auto repressor rhs,par));
//Faire le graphe de la solution au cour du temps, dans la figure 1
//Options: couleur (r=red, b=blue,k=black,...), forme de ligne (-,--,:,-.)
figure(1);
plot(tvec,sol(1,:),'b-',tvec,sol(2,:),'r-');
```