

# Lateral Stability and Tail Sizing

## Lecture 11

ME EN 415

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# Lateral Stability

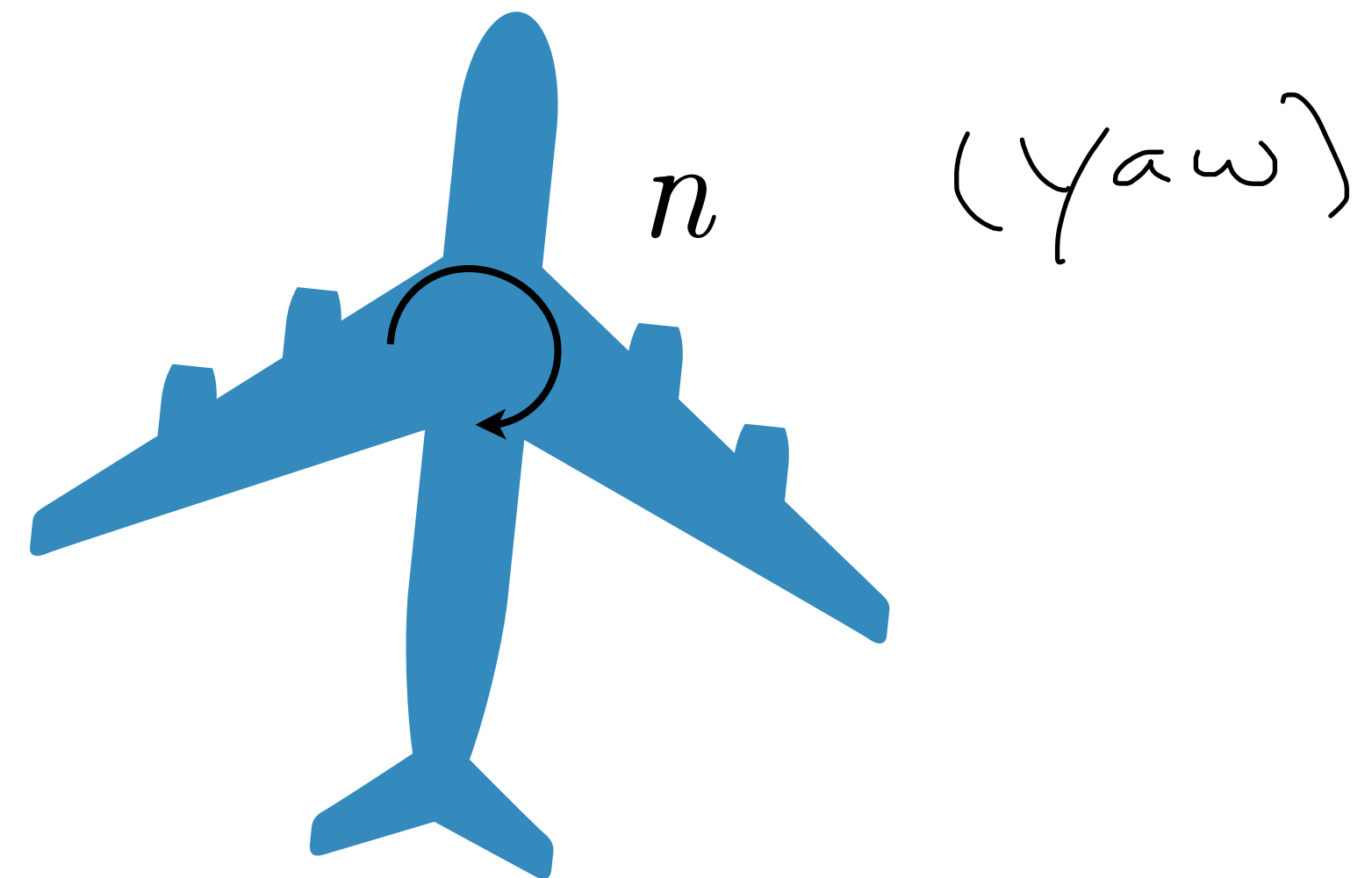
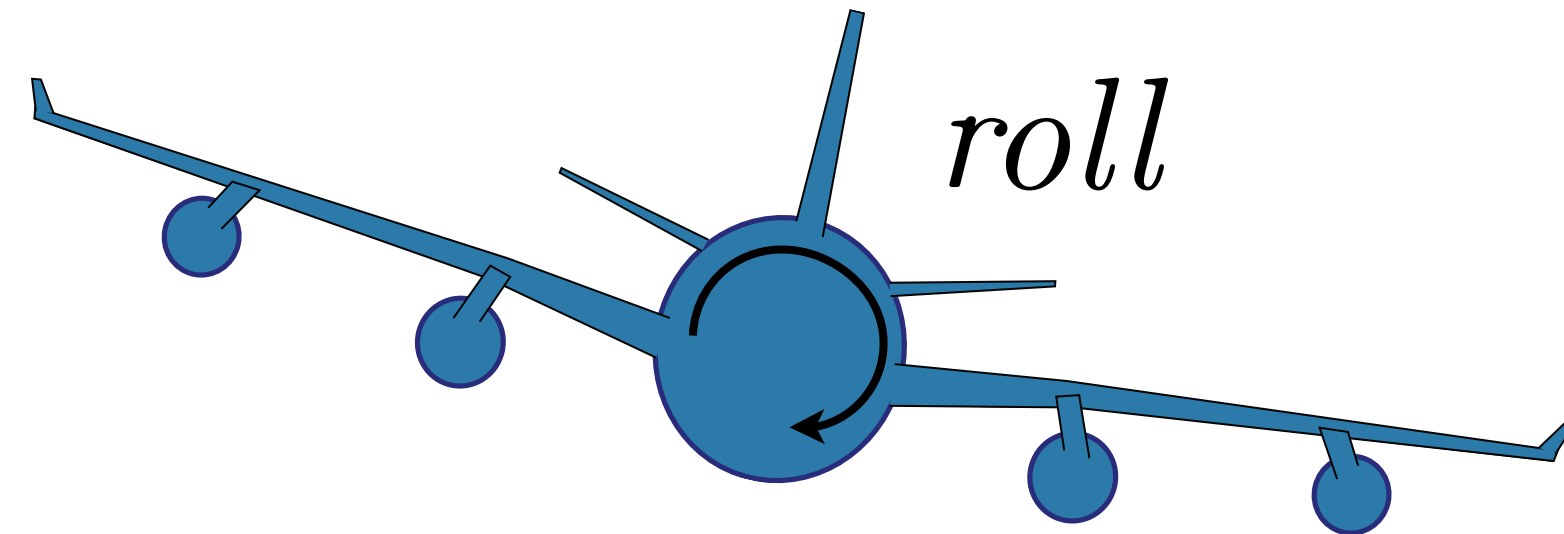
# Coefficients (moments)

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$$C_{roll} = \frac{roll}{q_{\infty} S_w b_w}$$

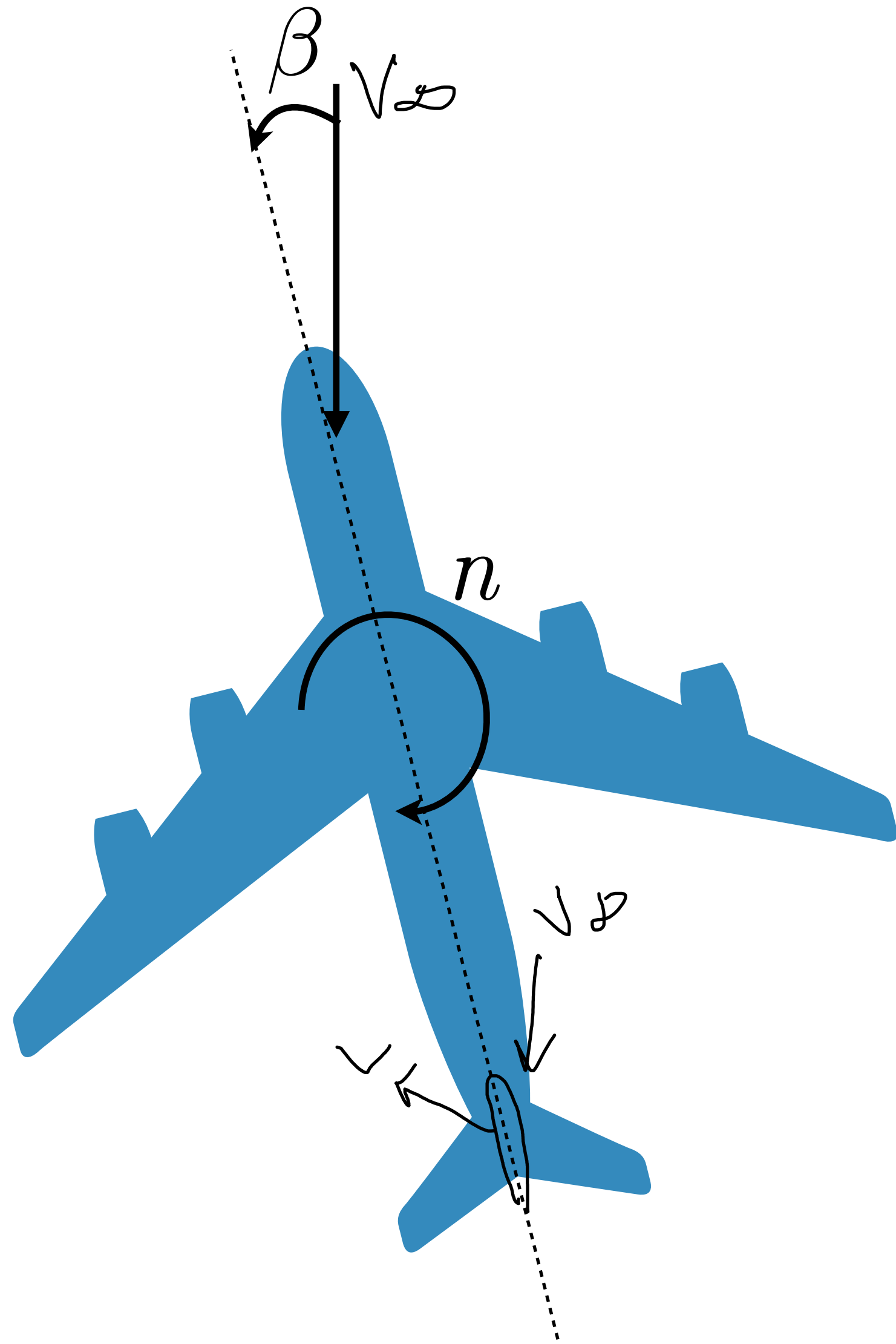
$$C_l = \frac{l}{q_{\infty} S_w b_w}$$

$$C_n = \frac{n}{q_{\infty} S_w b_w}$$



# Yaw Stability (directional stability)

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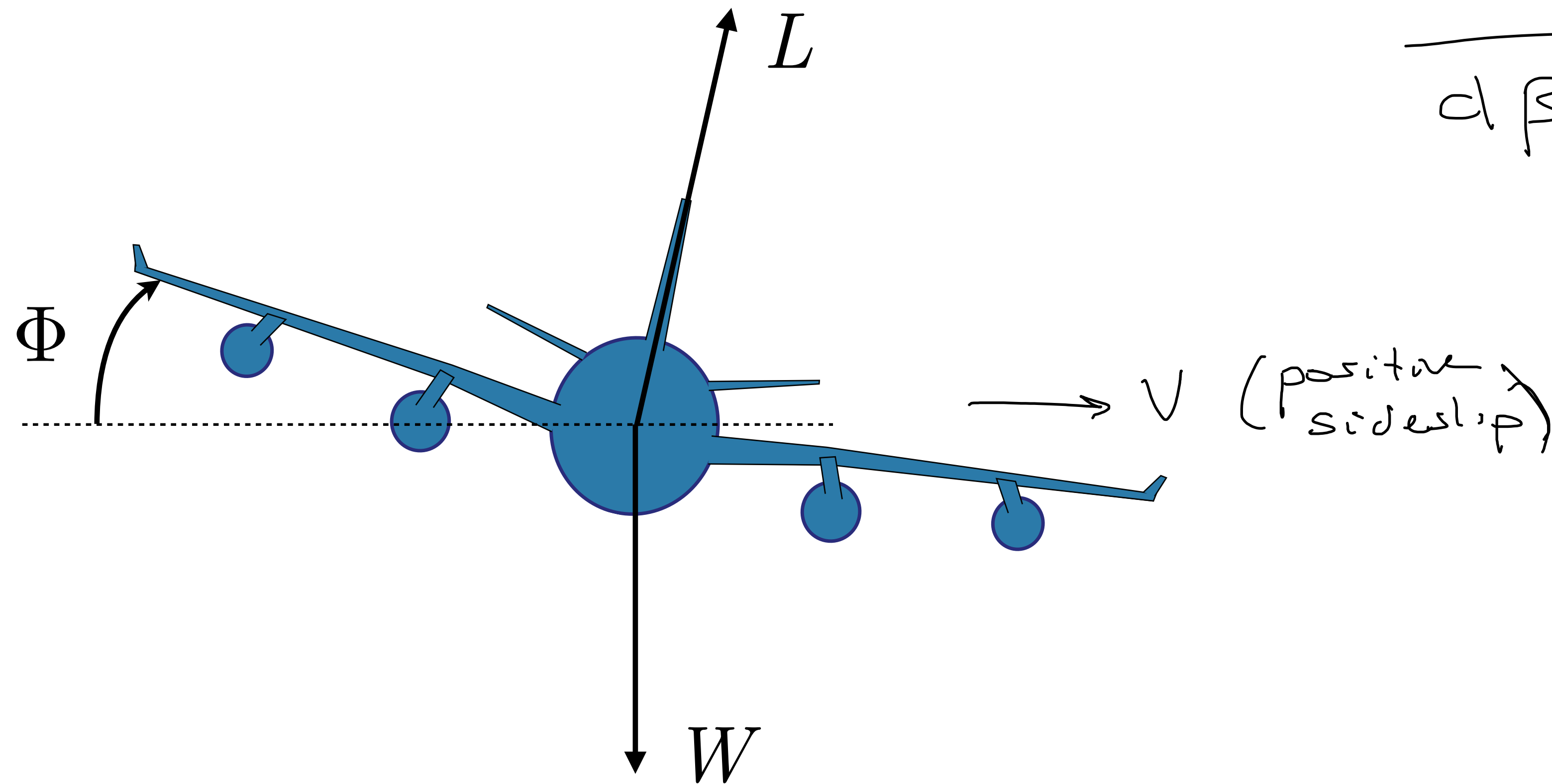
$$\frac{dC_n}{d\beta} > 0$$

$$C_{n,\beta} > 0$$



# Roll Stability

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$$\frac{dC_{roll}}{d\beta} < 0$$

$$C_{roll,\beta} < 0$$

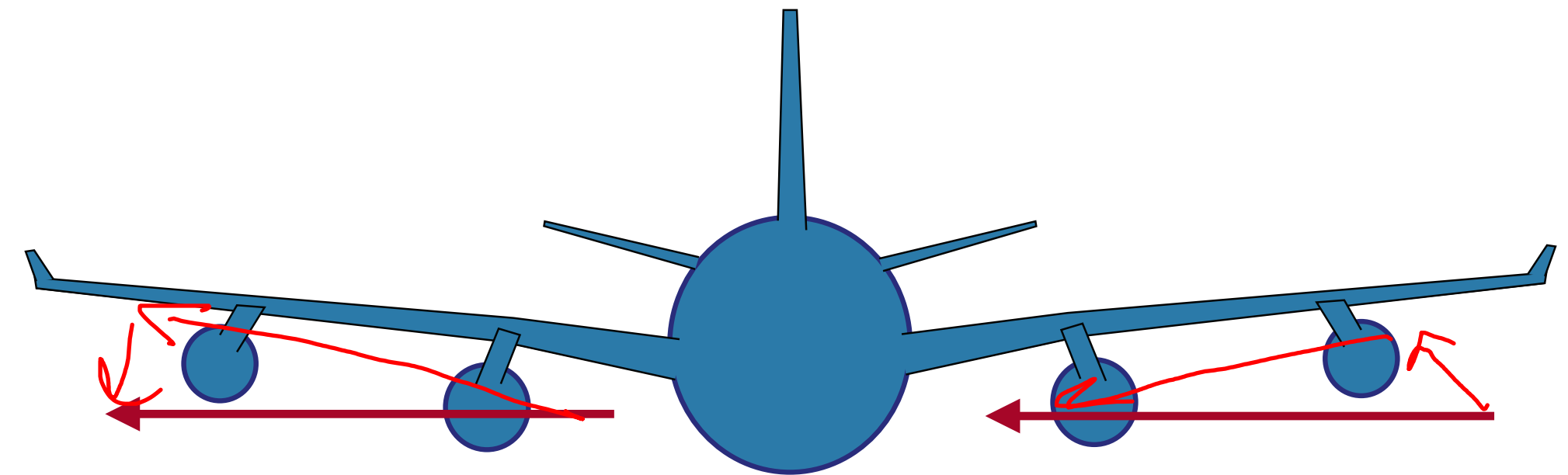
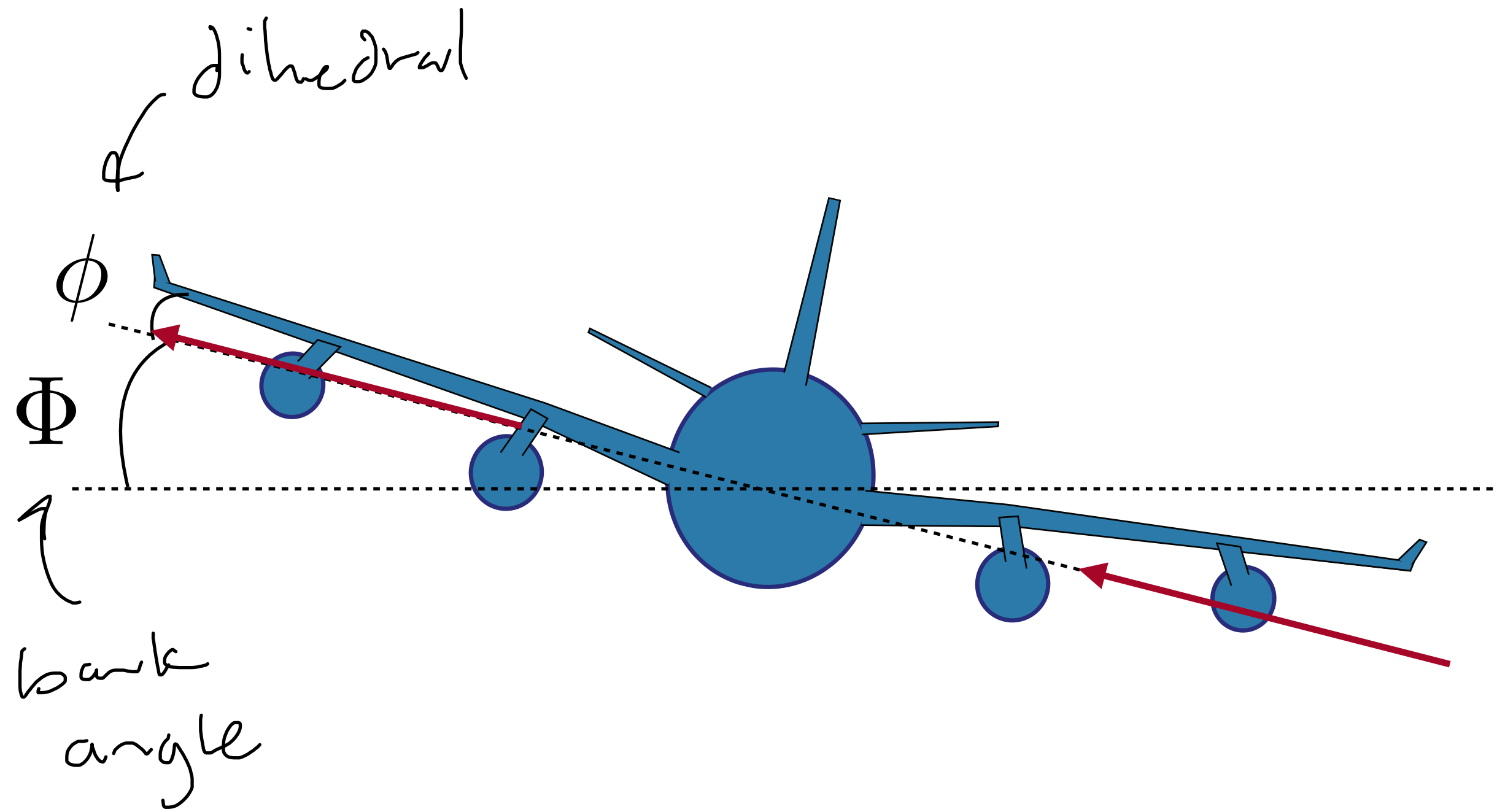
"effective dihedral"

flying into page



# Dihedral

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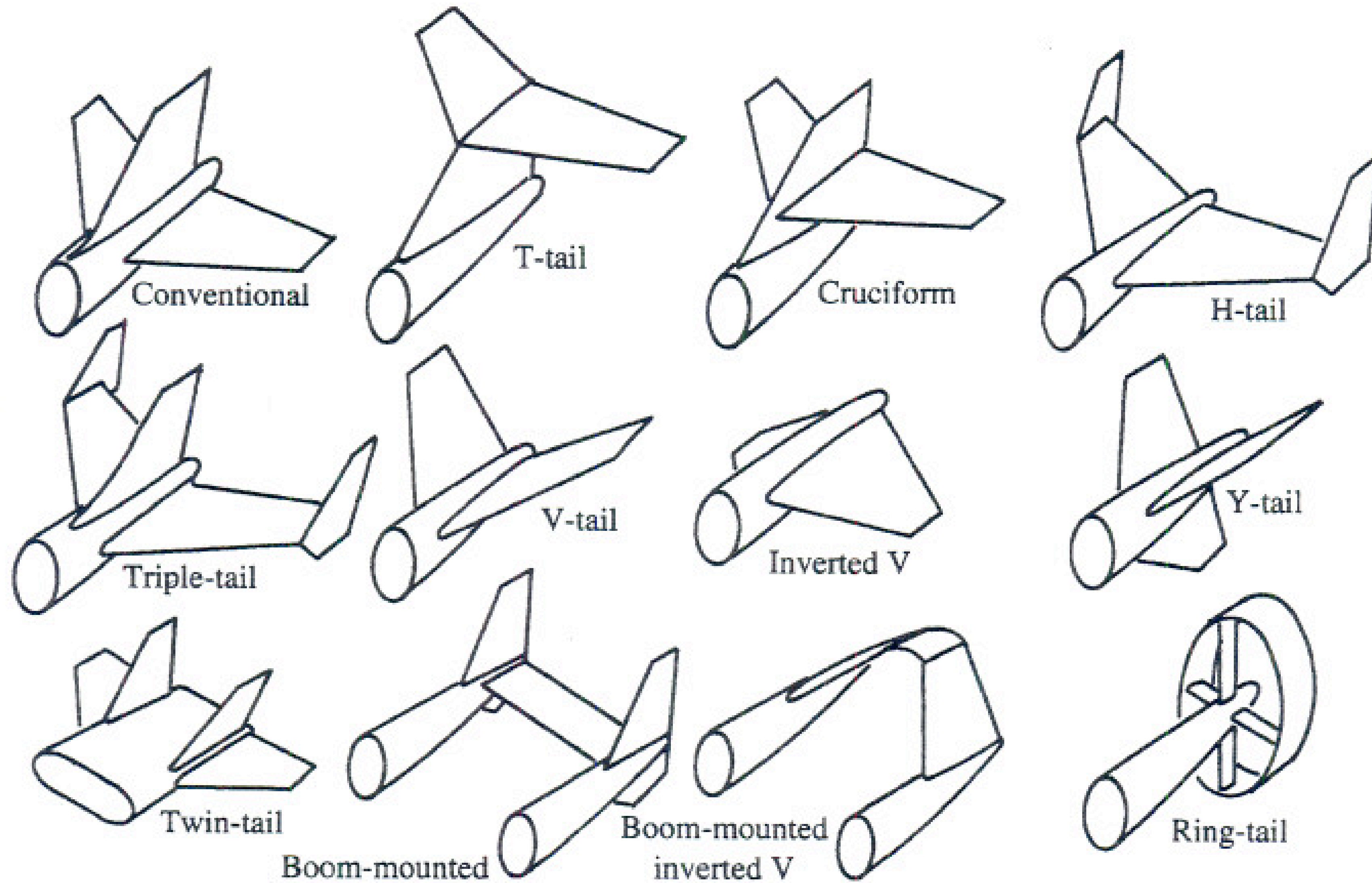


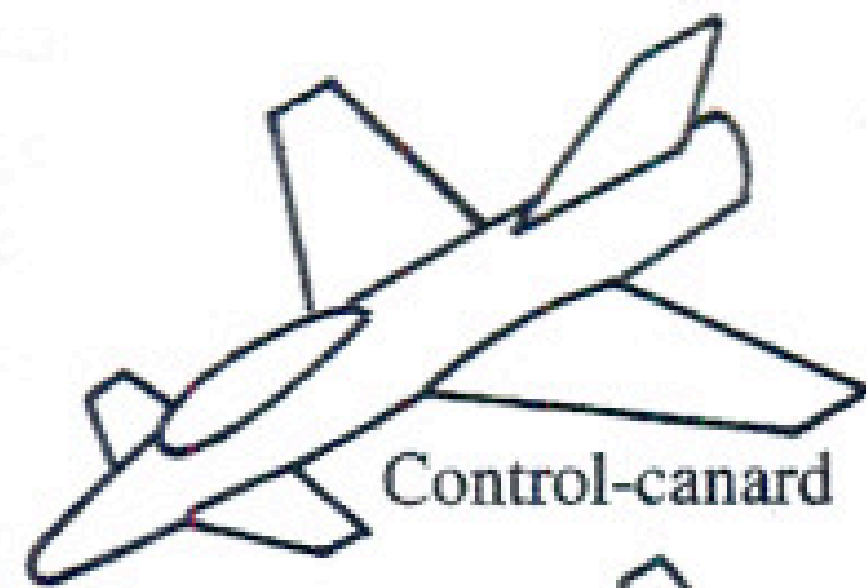
# Statistical Tail Sizing



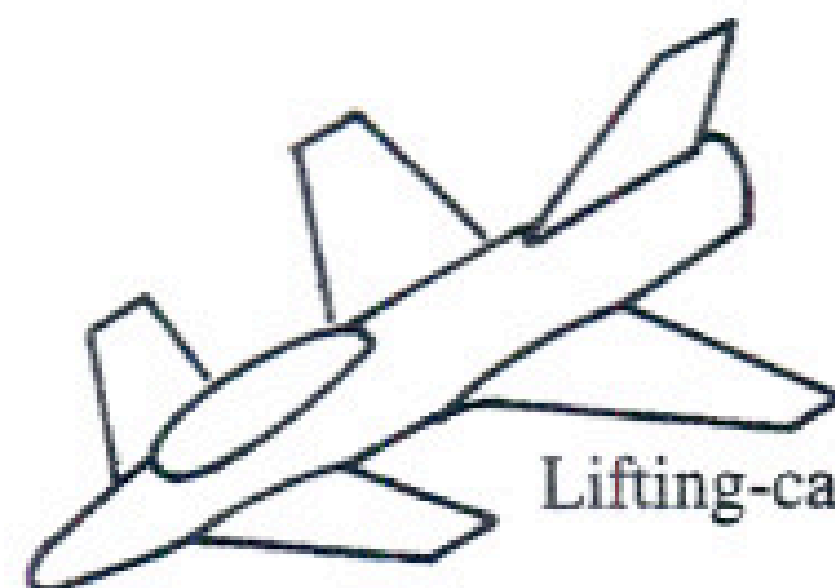
# Tail Types

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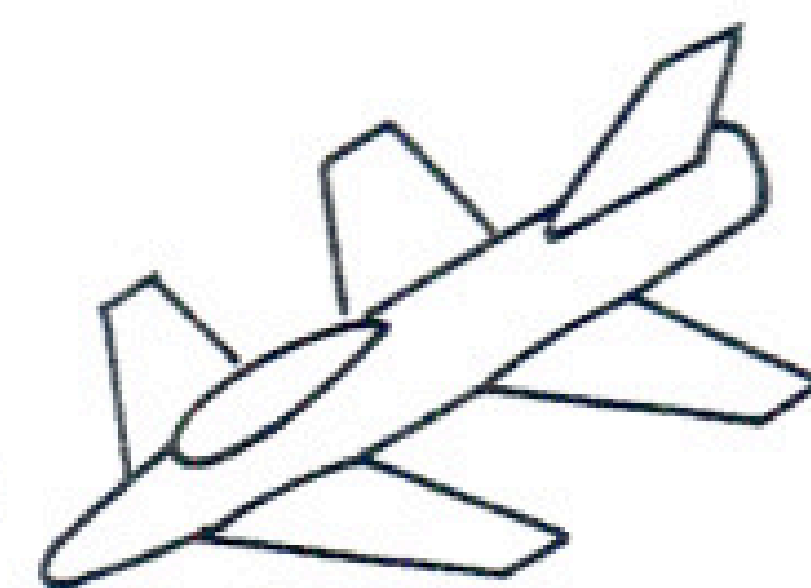




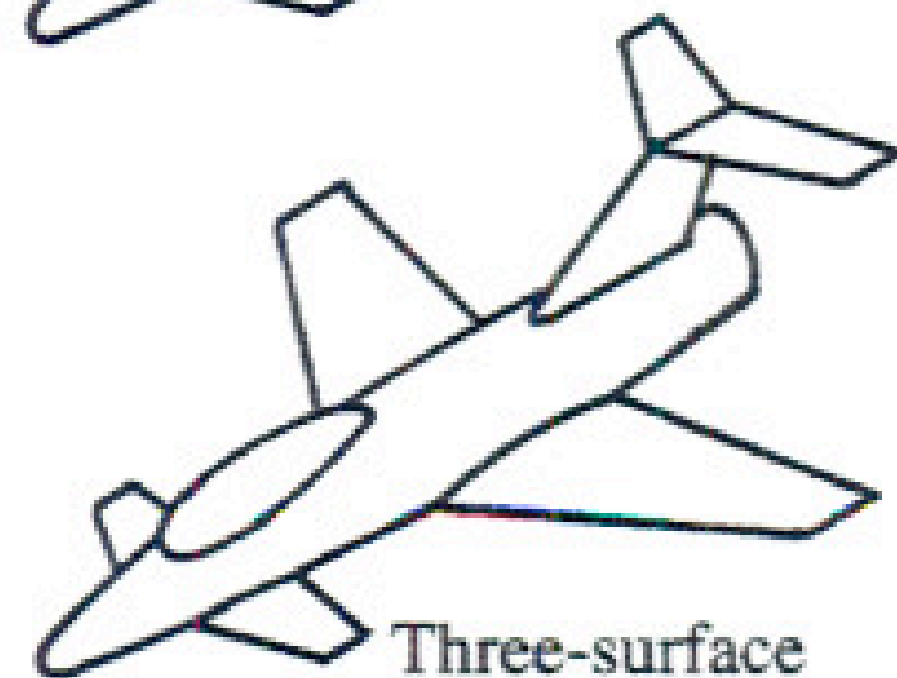
Control-canard



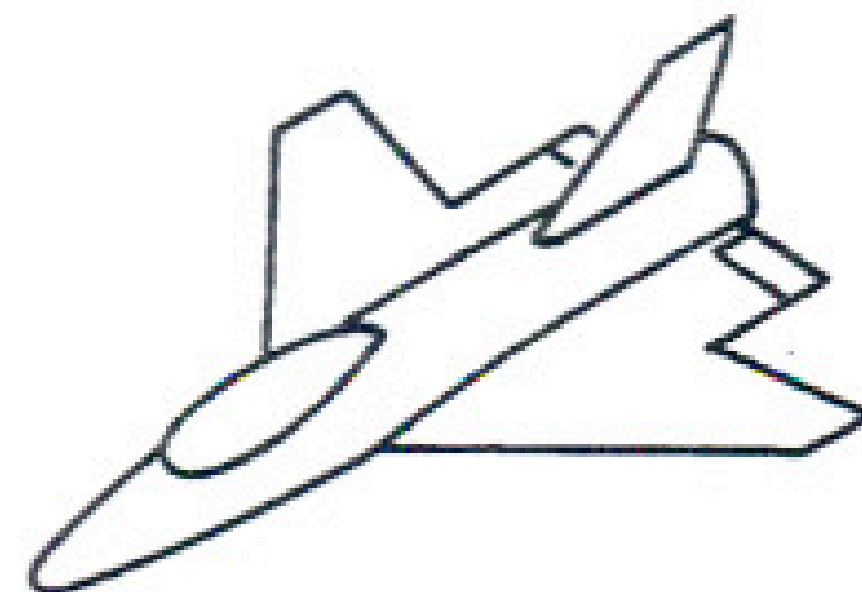
Lifting-canard



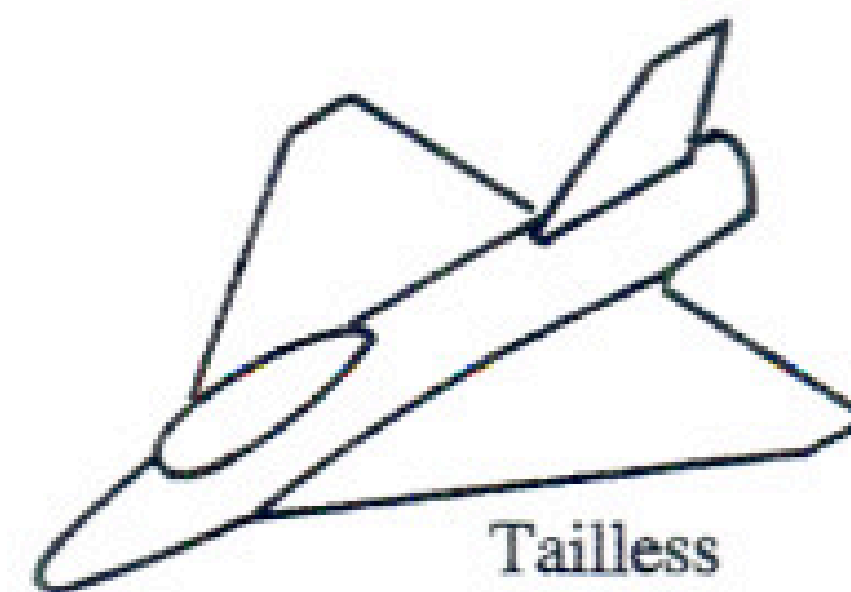
Tandem wing



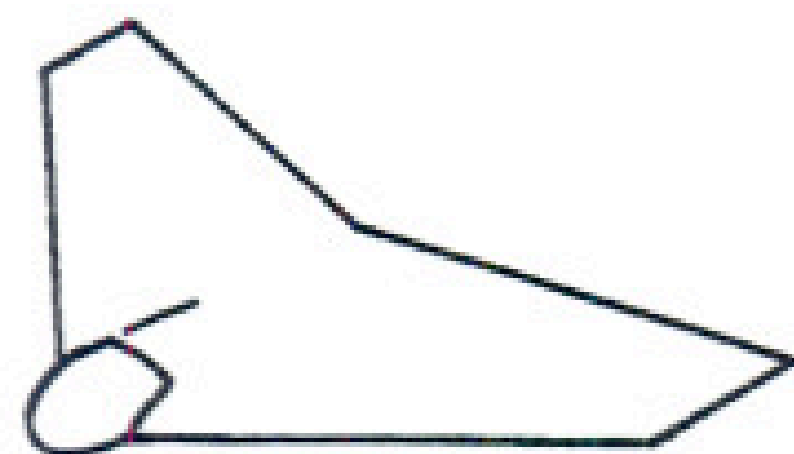
Three-surface



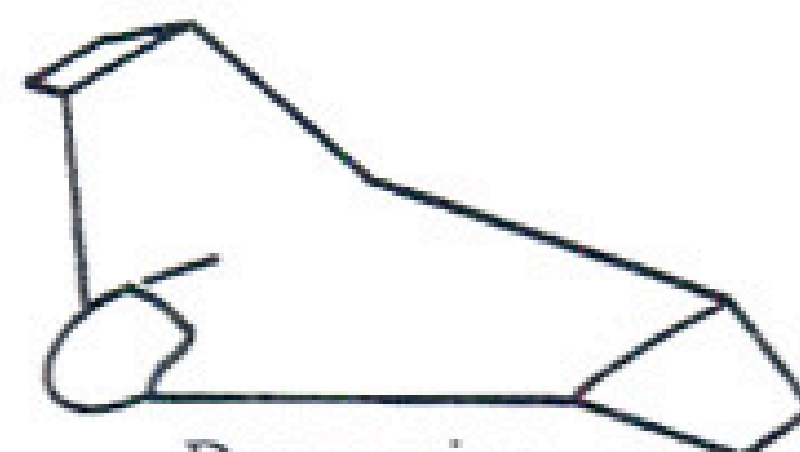
Aft-strake or back porch



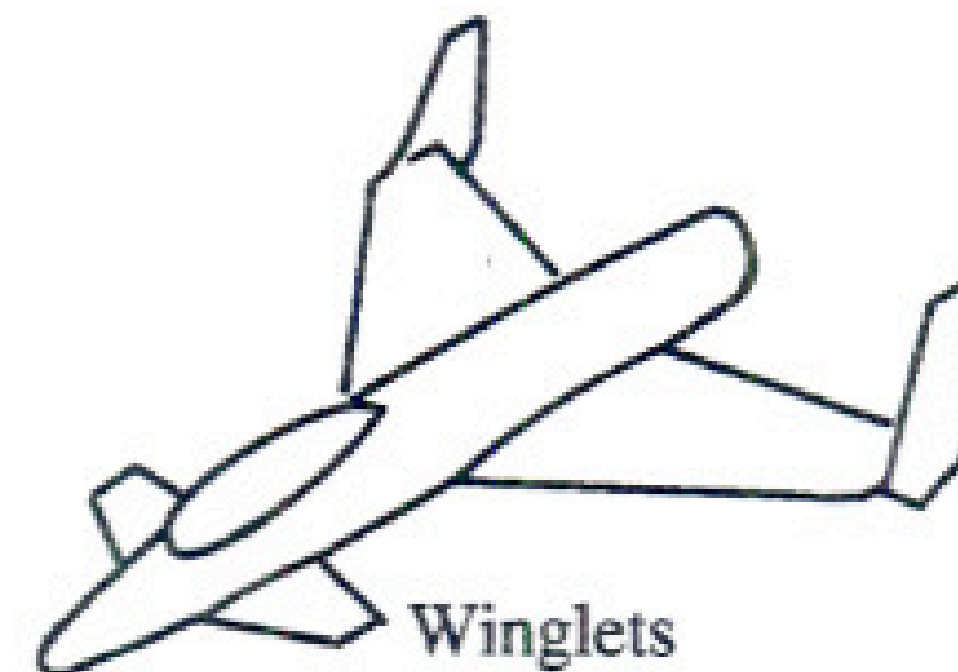
Tailless



Flying wing



Droop wing  
outer panels



Winglets

# Statistical Tail Sizing

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$$V_H = \frac{l_H S_H}{c_w S_w}$$

horizontal tail  
volume coefficient

$$V_V = \frac{l_V S_V}{b_w S_w}$$

vertical tail  
volume coefficient.

$$V_H \sim 0.5 - 0.7$$

$$V_V \sim 0.02 - 0.04$$

$$R_H \sim 3 - 5$$

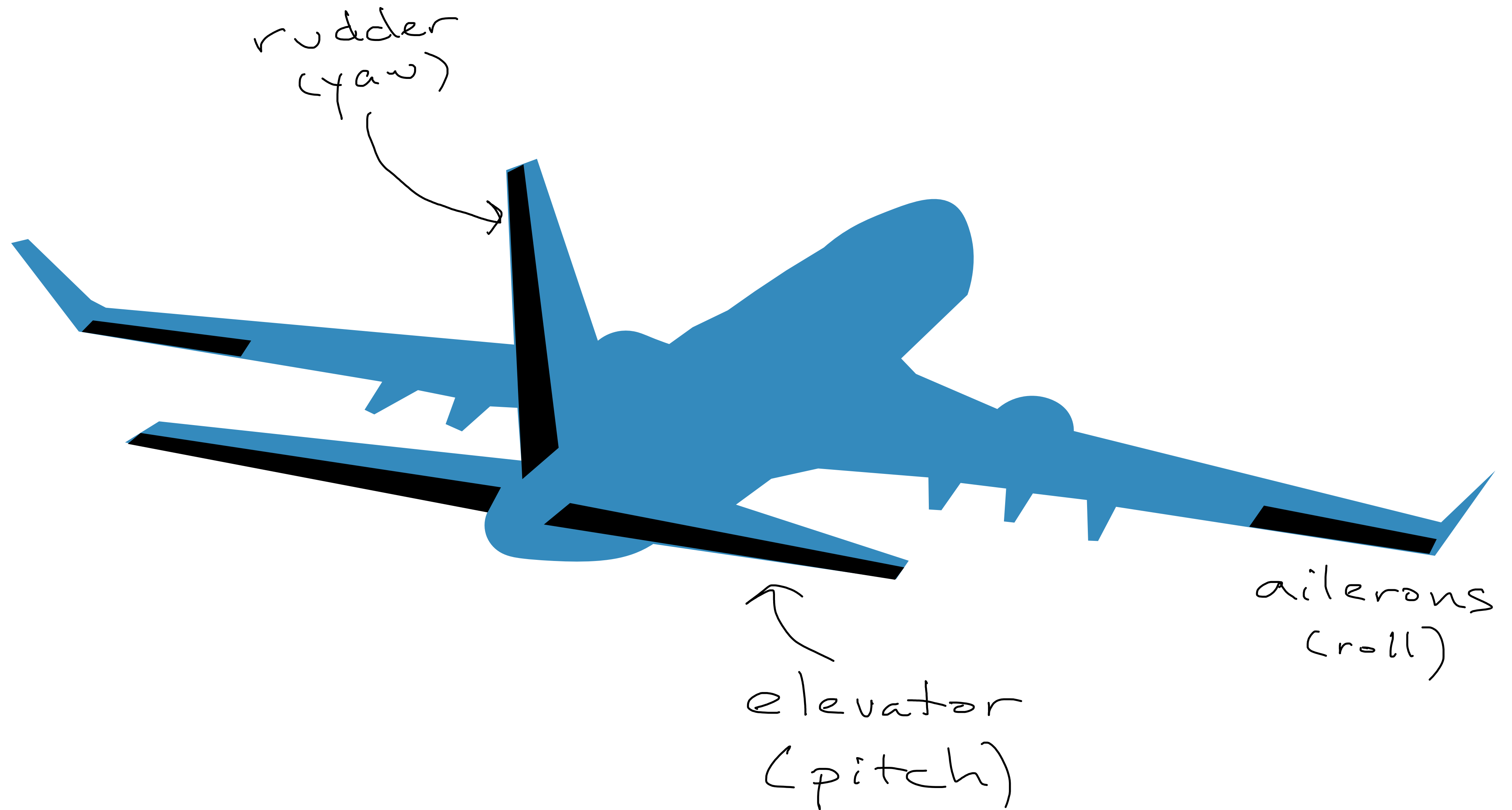
$$R_V \sim 1.3 - 2.0$$

$$\lambda \sim 0.4 - 0.6$$

# Control Surfaces

# Flight Controls

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# Flight Controls

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