

Pisa, 21/10/2020

Cultural Dynamics: Axelrod Model

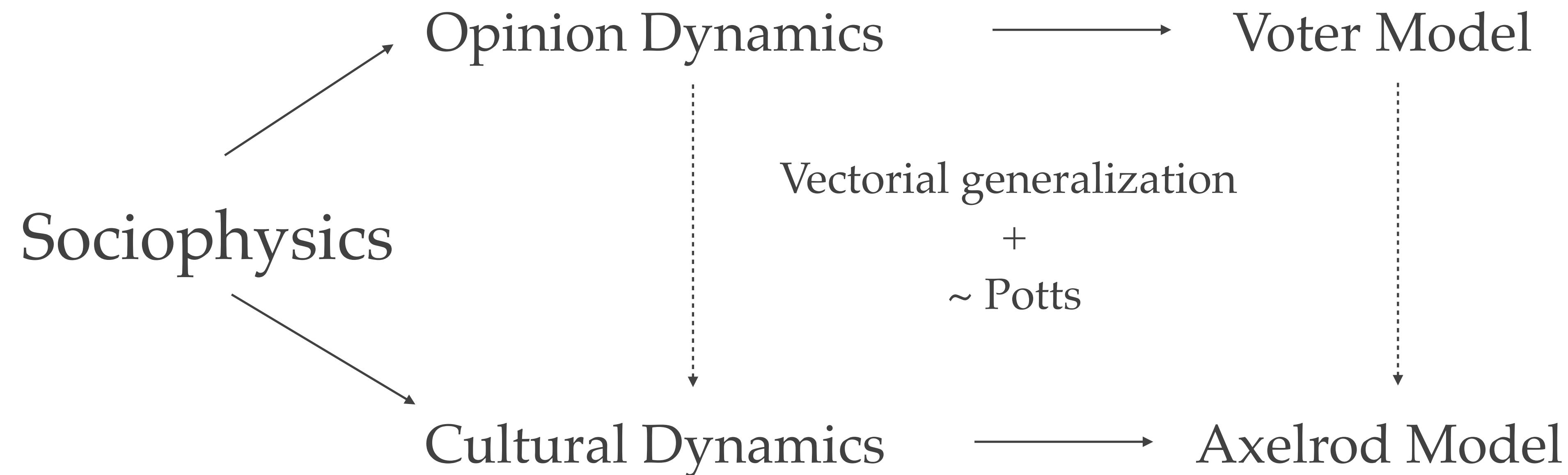
Seminar for the Complex Systems
class exam

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Report

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Introduction



Voter Model

Agent $\rightarrow s_i \in \{-1, +1\}$

Nearest neighbor random interaction

$$S_i \leftrightarrow S_j$$



$$S_i = S_j$$

A non-equilibrium stochastic processes that can be solved exactly in any dimension d

Voter Model

Spin flip probability:

$$W_k(S) \equiv W(s_k \rightarrow -s_k) = \frac{d}{4} \left(1 - \frac{1}{2d} s_k \sum_j s_j \right)$$

Where j runs over all $2d$ nearest neighbors and the prefactor is chosen to normalize

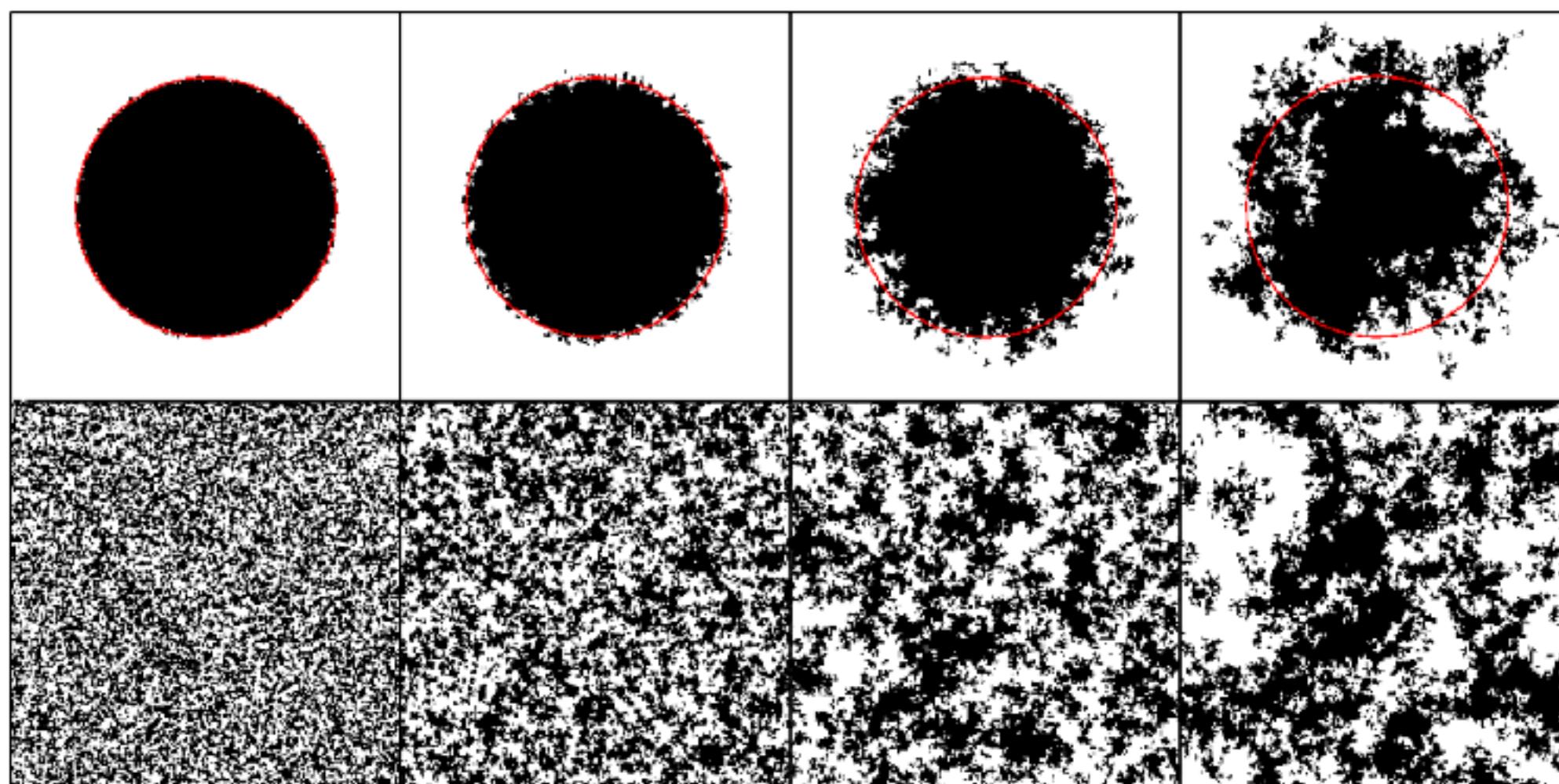
Master Equation:

$$\frac{d}{dt} P(S, t) = \sum_k [W_k(S^k)P(S^k, t) - W_k(S)P(S, t)]$$

Where S^k equal to $S=\{s_i\}$ except for the flipped spin s_k .

Voter Model

Voter dynamics tends to increase the order of the system \Rightarrow cluster



Interfaces are very rough, fluctuations.

Pressure of the majority only in an average sense.

Axelrod Model

Agent → $q_i = \{ q_{i,0}, q_{i,1}, \dots, q_{i,F} \}$



$q_{i,f} \in \{ 0, 1, \dots, Q \}$

Cultural features:

“language, art,
technical standards
and social norms” [1]

Cultural features traits:

No central institutions or mass media, only social interactions.

Axelrod Model

Interaction probability
between agent i and j :

$$\omega_{ij} = \frac{1}{F} \sum_{f=1}^F \delta_{q_{i,f} q_{j,f}}$$

Also known as overlap

Interaction:

Choose one of the different traits and set
the second one equal to the first one:

$$q_{i,f} \neq q_{j,f} \implies q_{j,f} = q_{i,f}$$

Axelrod Model

Main properties:

1. individuals are more likely to interact with others who already share many of their cultural attributes (homophily);
2. interaction increases the number of features that individuals share

Algorithm

Square lattice $L \times L$

$$i \in \{1, \dots, N = L^2\}$$

$$f \in \{1, \dots, F\}$$

$$q_{i,f} \in \{1, \dots, Q\}$$

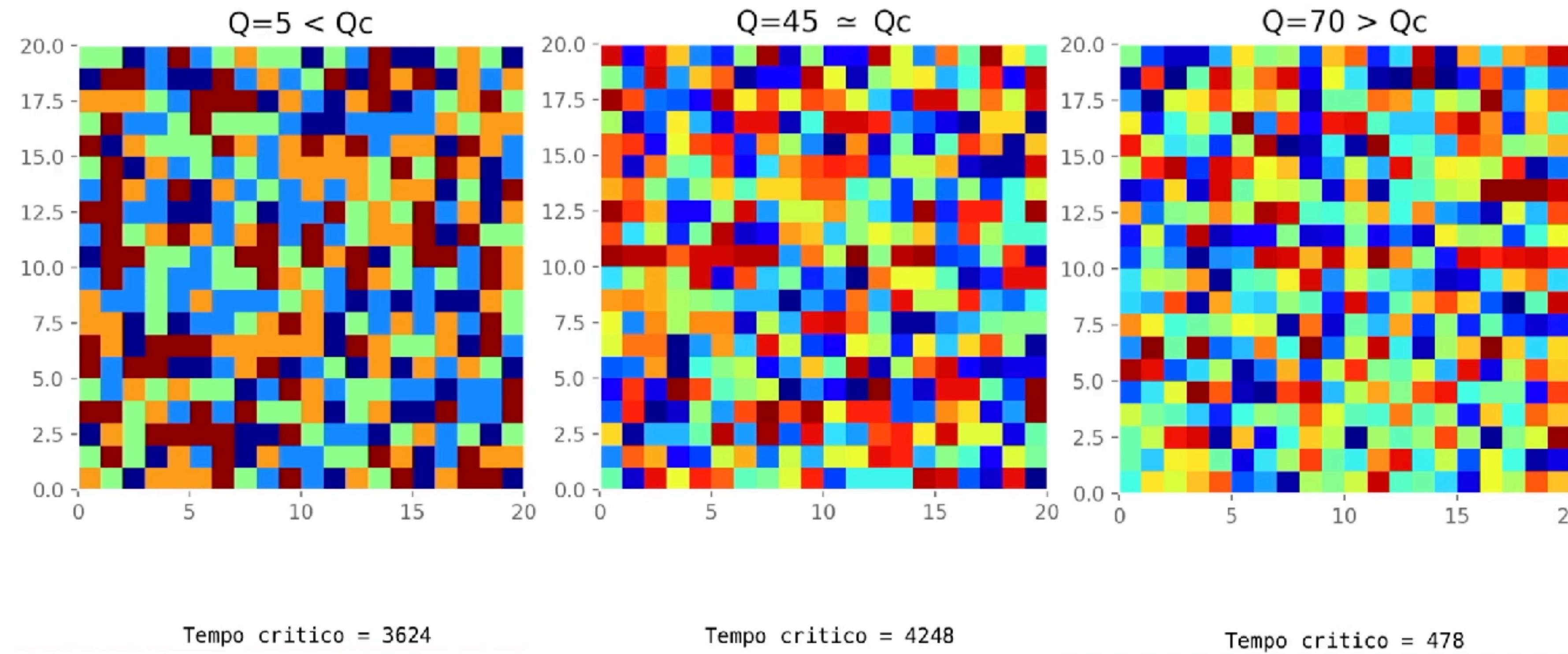
Random initial state

1. i randomly chosen between 0 and N
2. j randomly chosen among the i nearest neighbour
3. f randomly chosen between 0 and F
4. If $q_{i,f} \neq q_{j,f}$:
 - A. Next temporal step
5. Otherwise $q_{i,f} = q_{j,f}$:
 - A. f' randomly chosen such that $q_{i,f'} \neq q_{j,f'}$
 - B. Impose $q_{i,f'} = q_{j,f'}$
 - C. Next temporal step

If $\forall i, j \in S \quad q_{i,f} = q_{j,f} \circ q_{i,f} \neq q_{j,f} \quad \forall f \Rightarrow \omega_{ij} = 1,0 \Rightarrow$ Algorithm stops.

Implementation

$L=20, F=10$



Video available on: youtu.be/bV126I_cU1k

Implementation

Order parameters:

$$s_{max} = \max \left(\frac{\# \text{ of agents with same } q}{\# \text{ total agents}} \right)$$

n_A = # of active bonds

t_c = freezing time

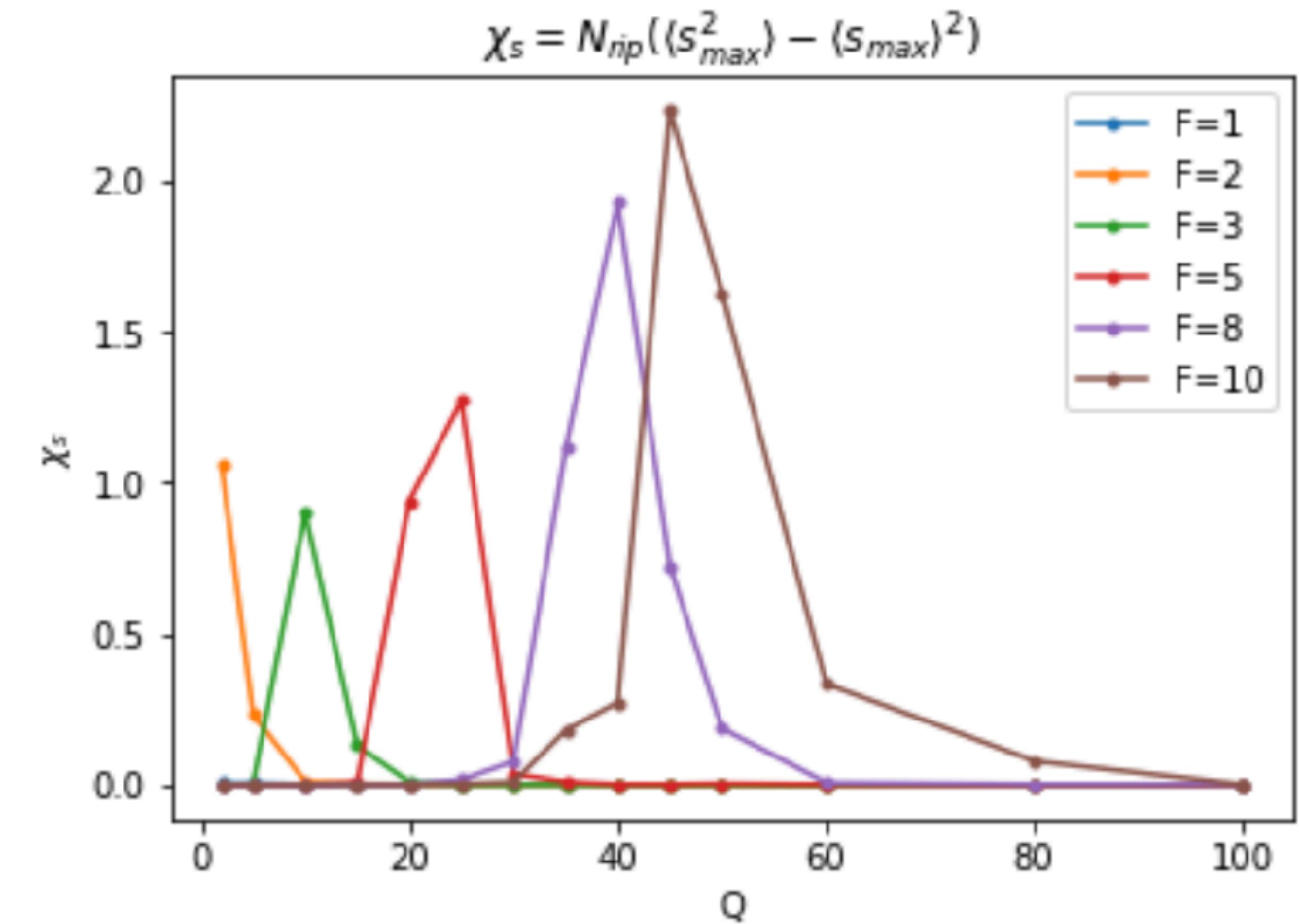
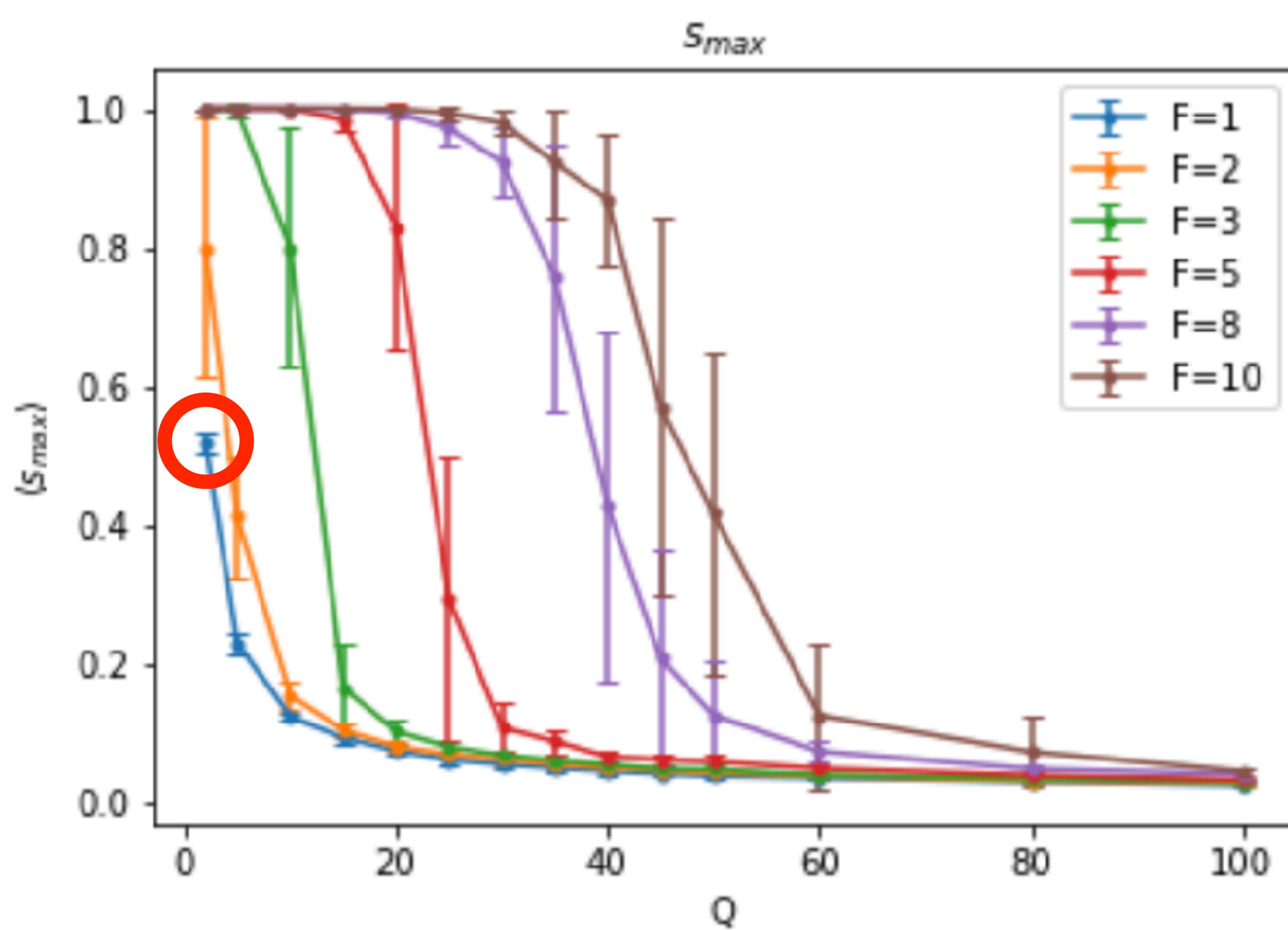
Control parameters:

Q = # of possible values of a feature

L = system size

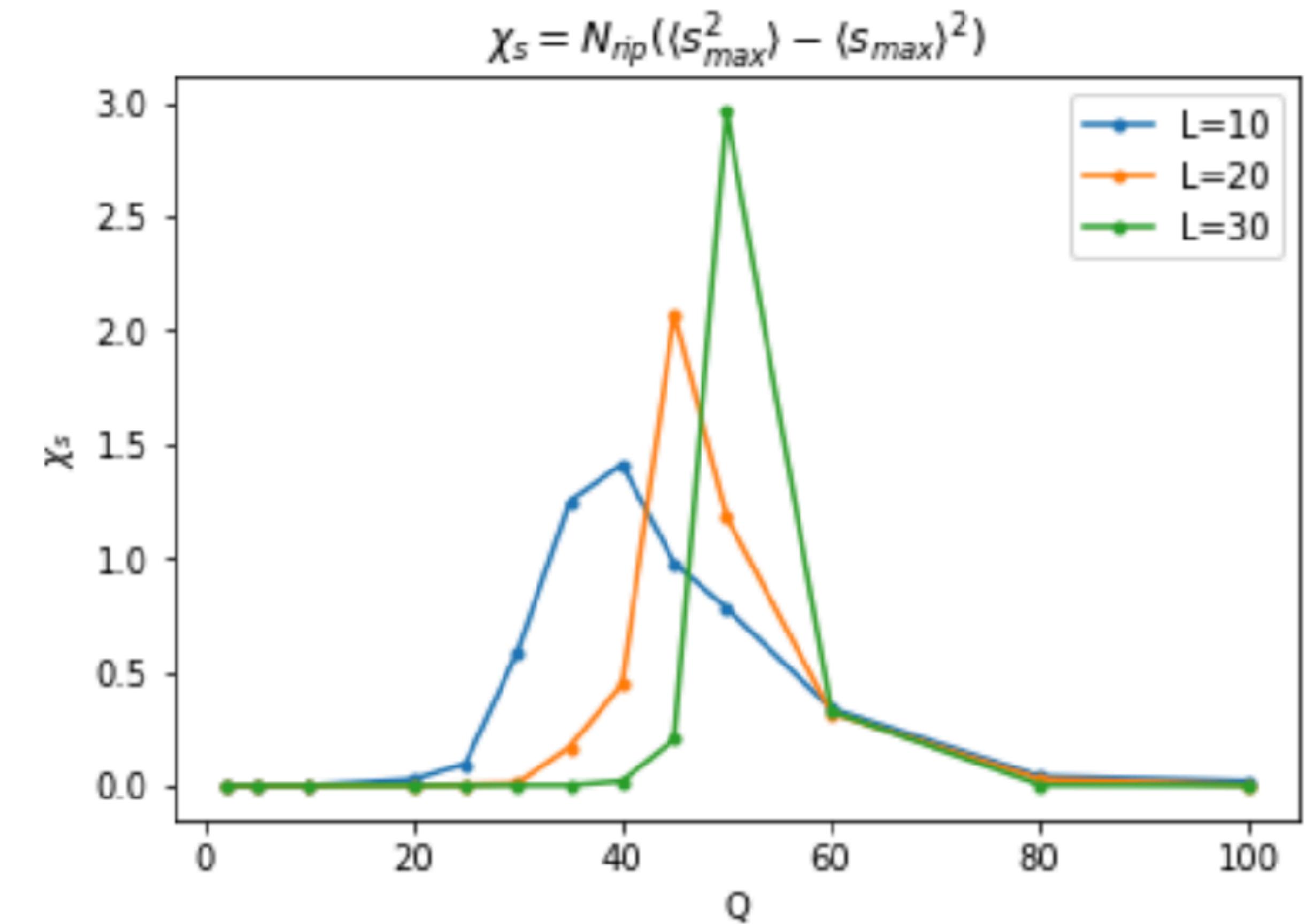
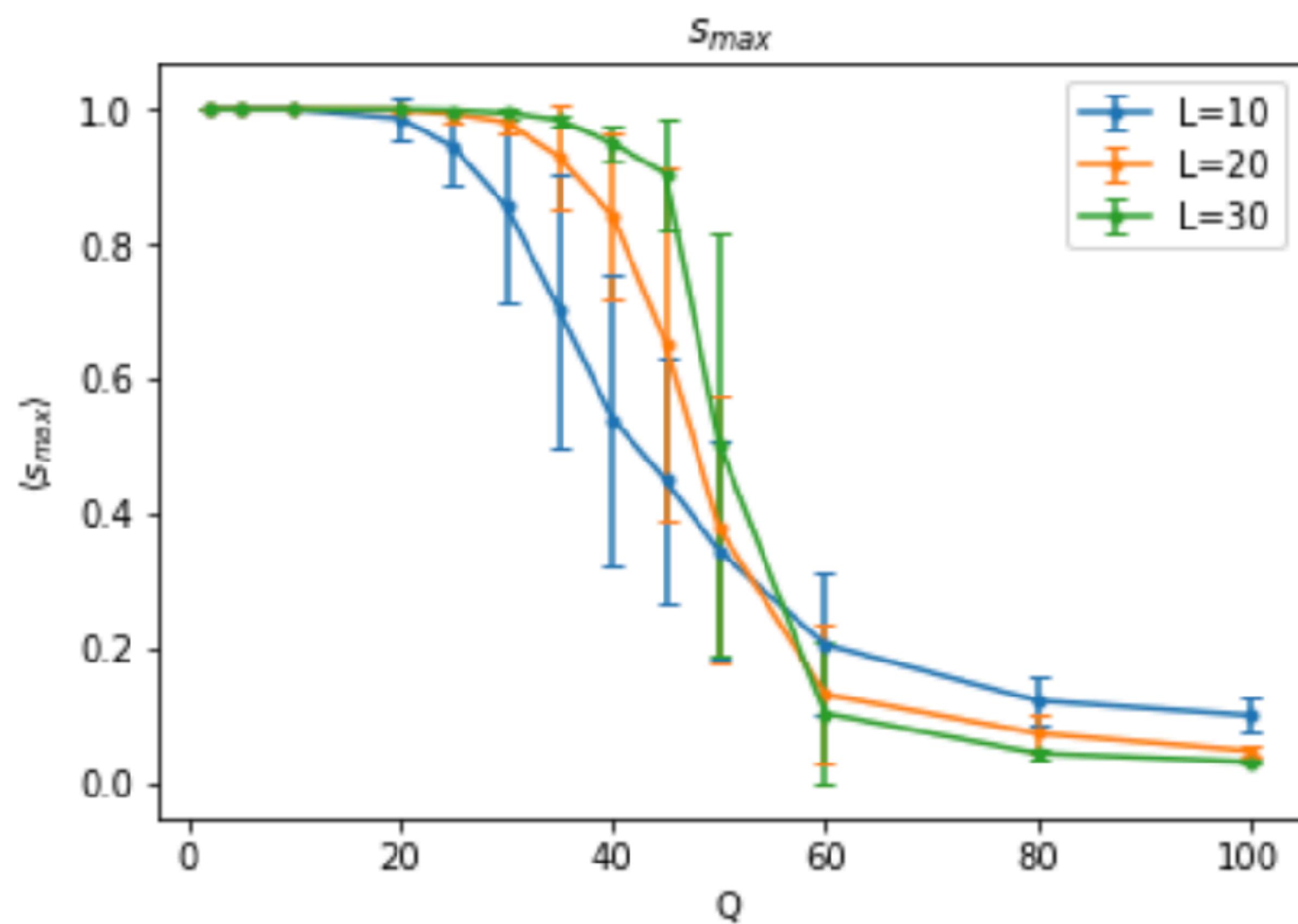
$N = L^2$ = # total agents

Absorbing States



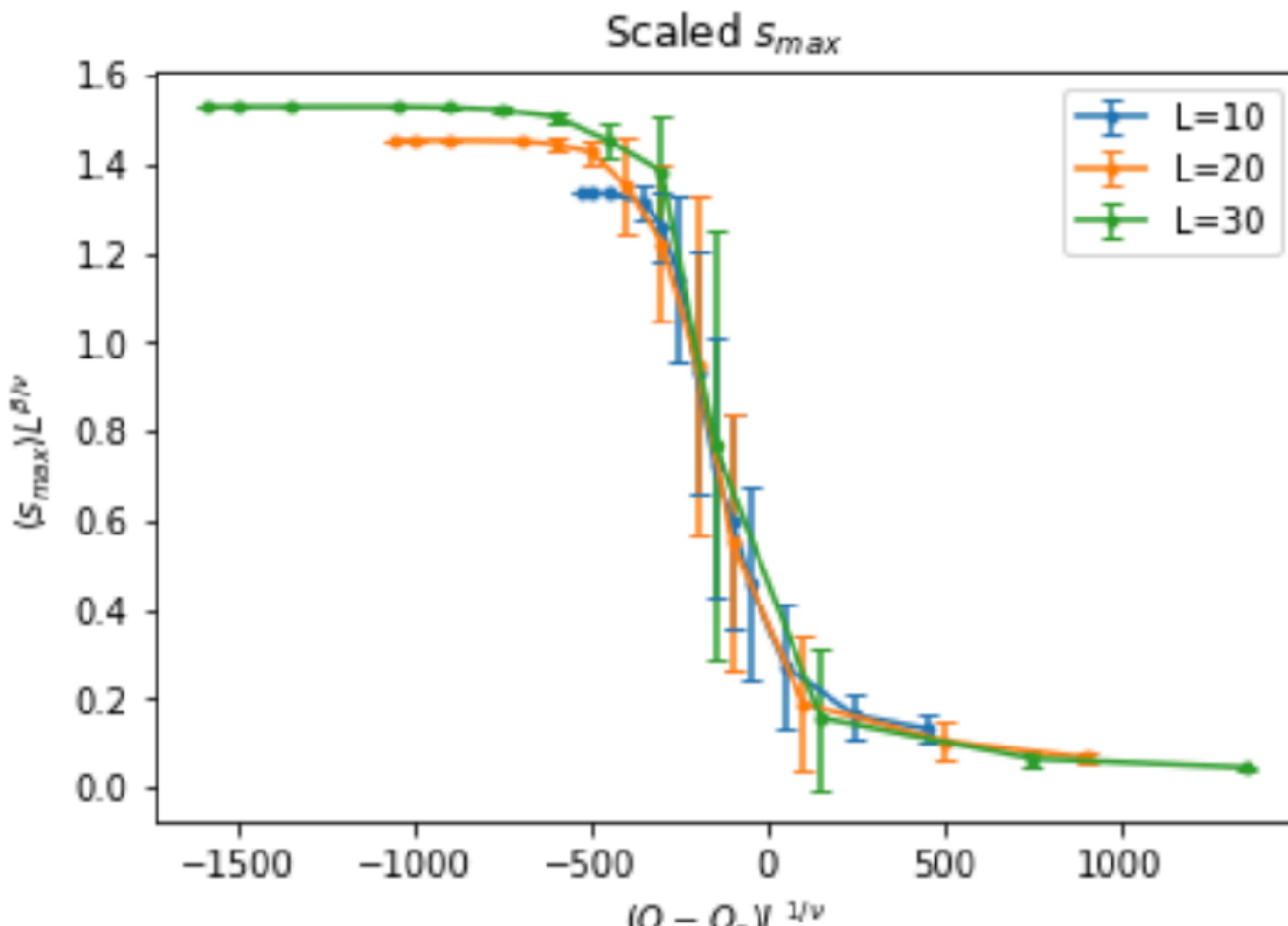
30 realizations, $L=20$

Absorbing States



30 realizations, $F=10$

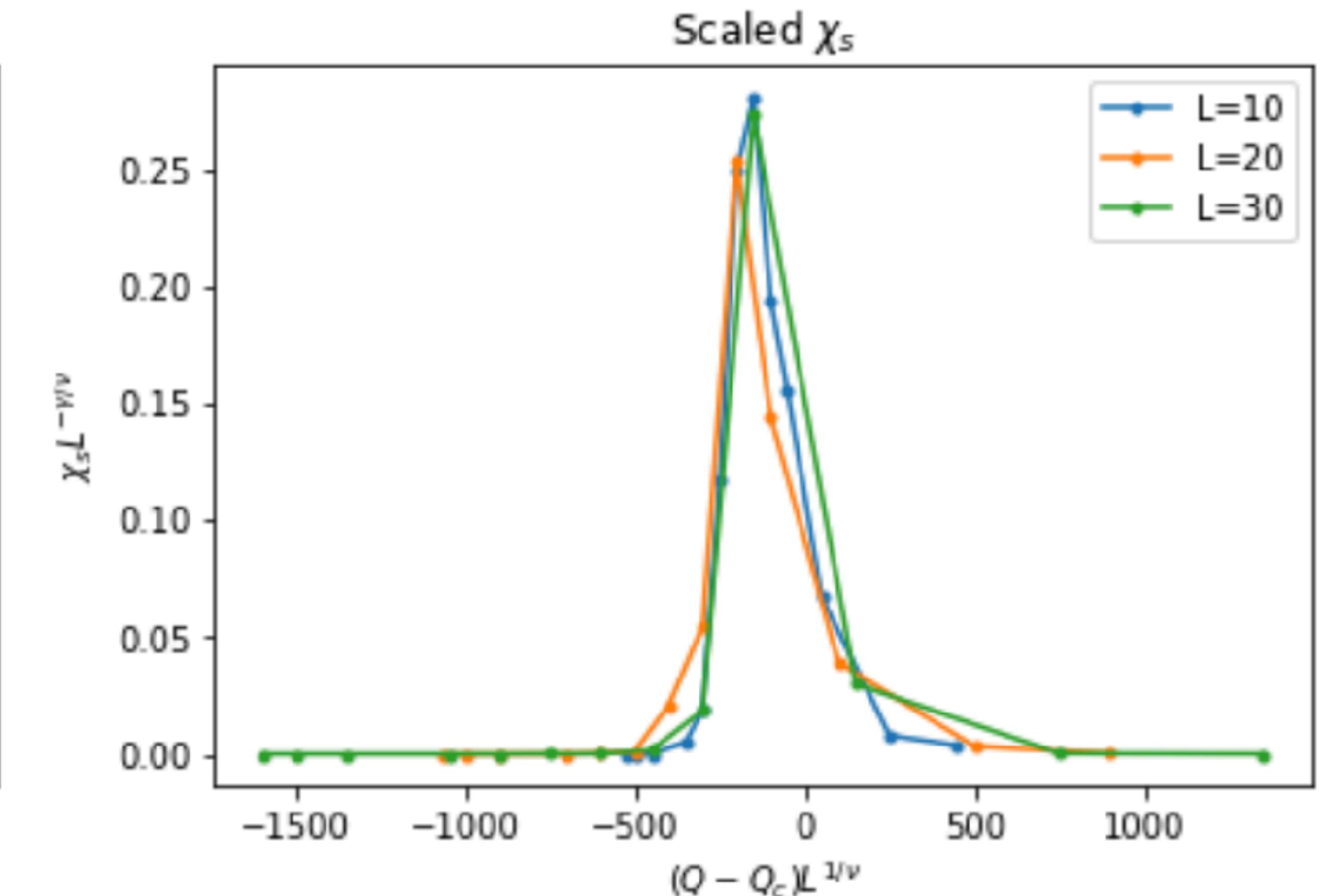
Absorbing States



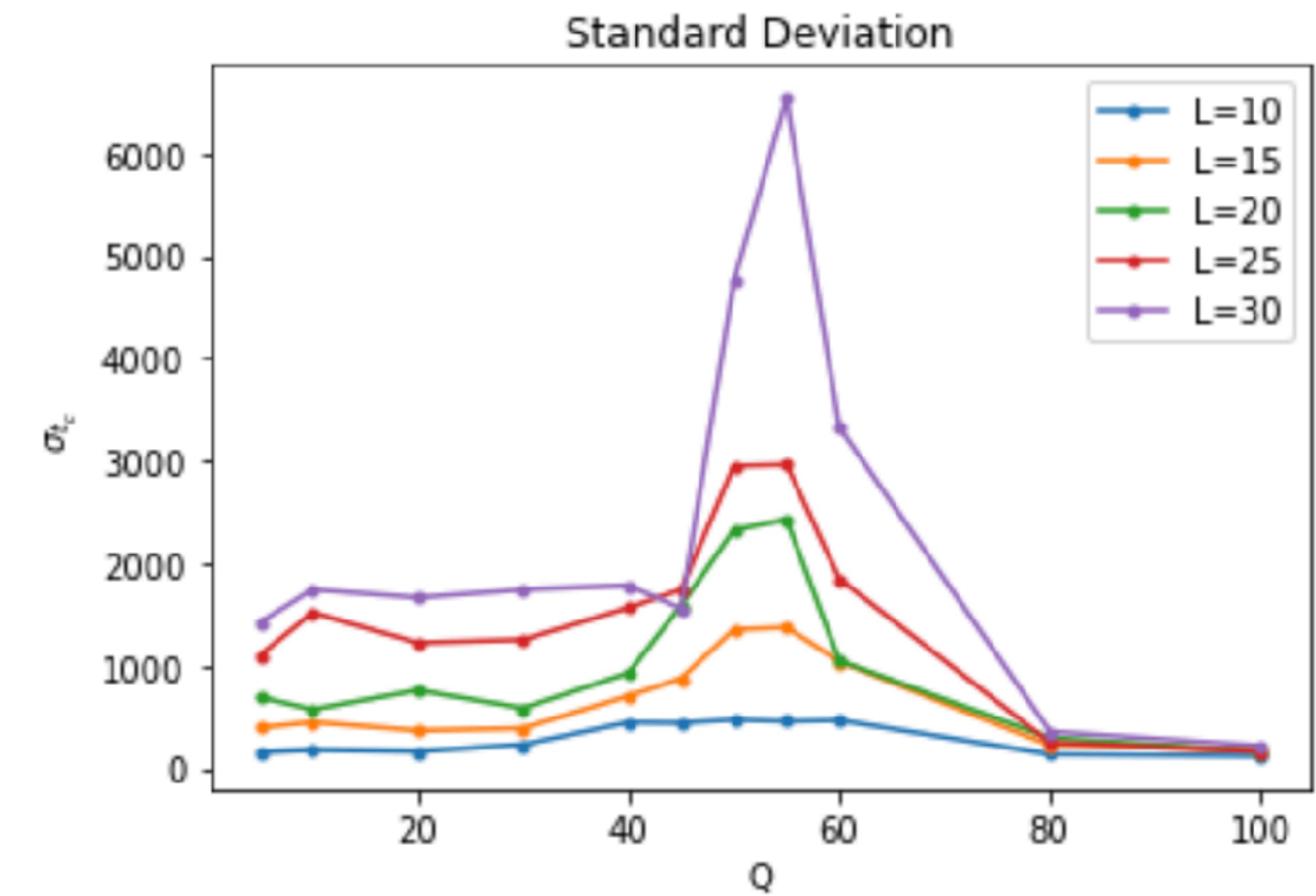
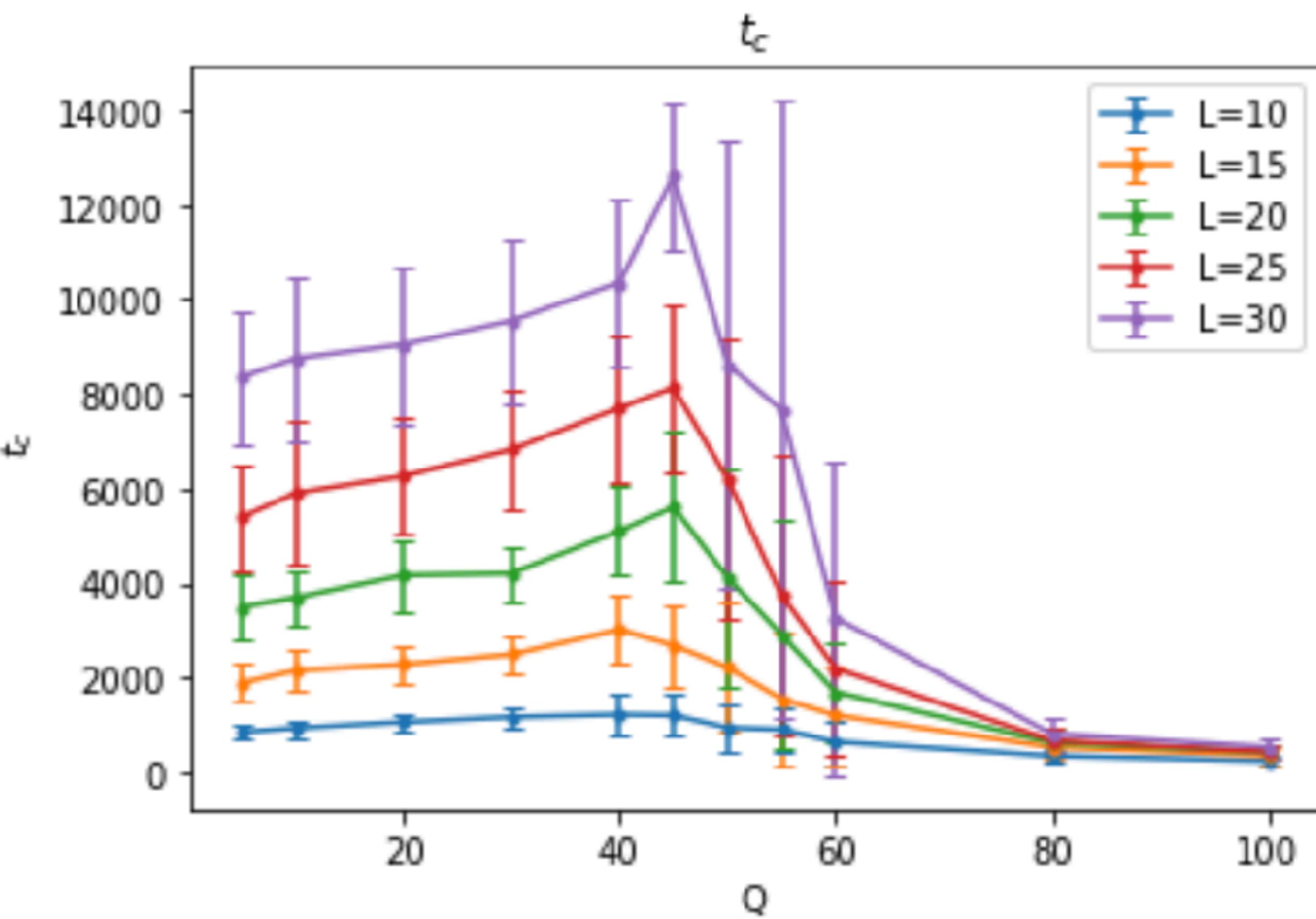
Critical Q :

$$Q_c \simeq 55$$

Critical exponents: $\beta/\nu \simeq 1/8$ e $\gamma/\nu \simeq 0.7$

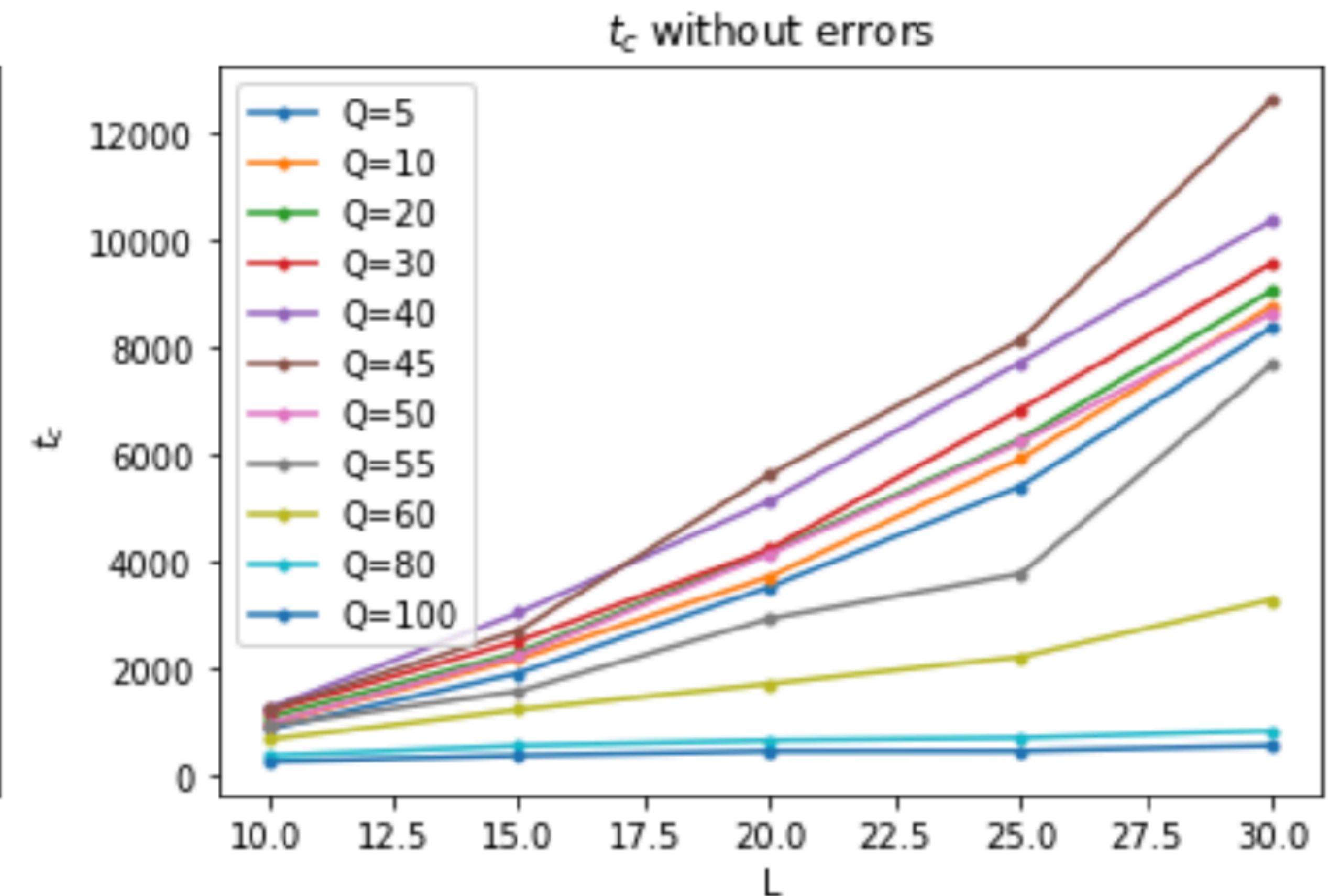
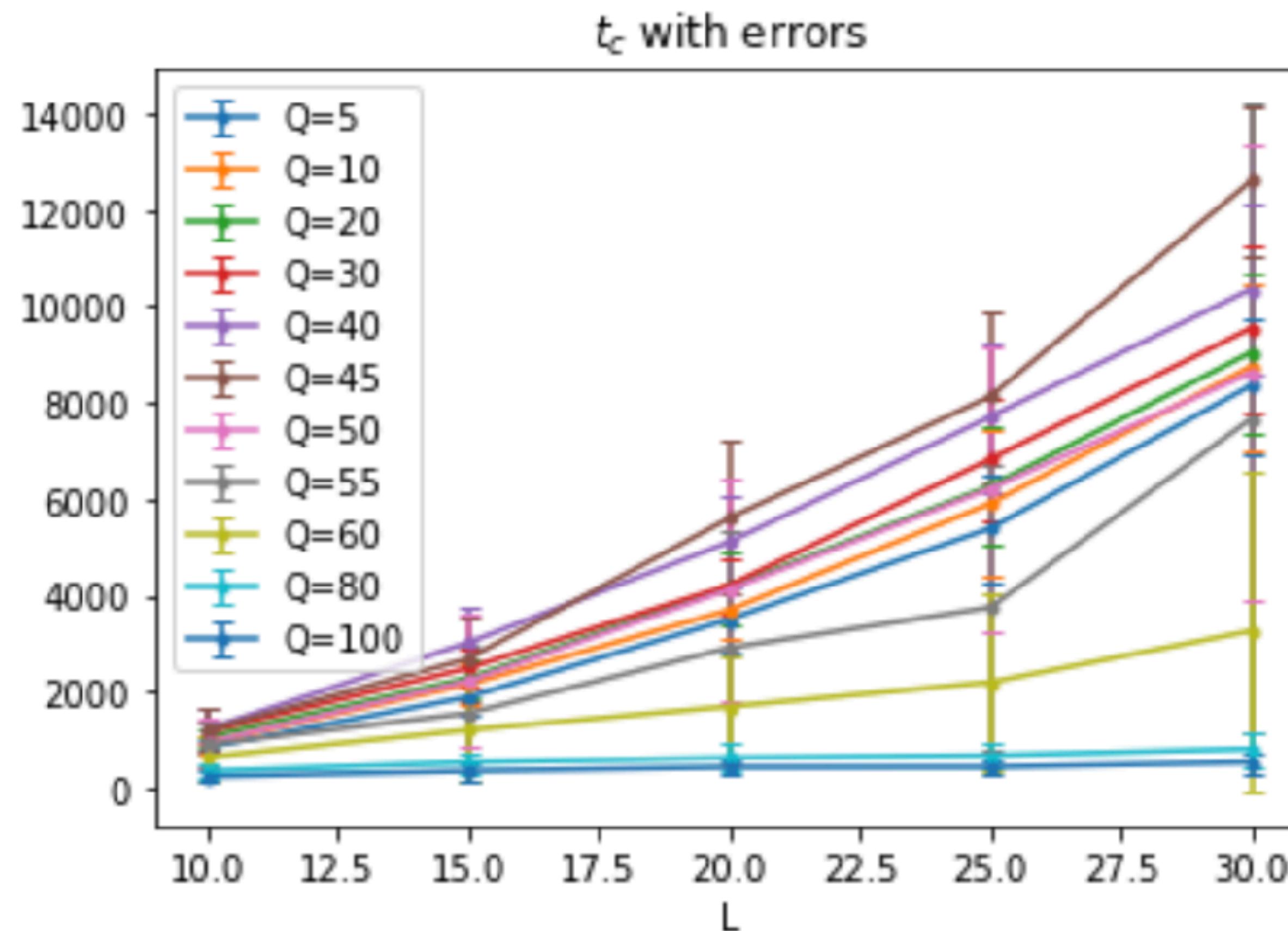


Freezing time



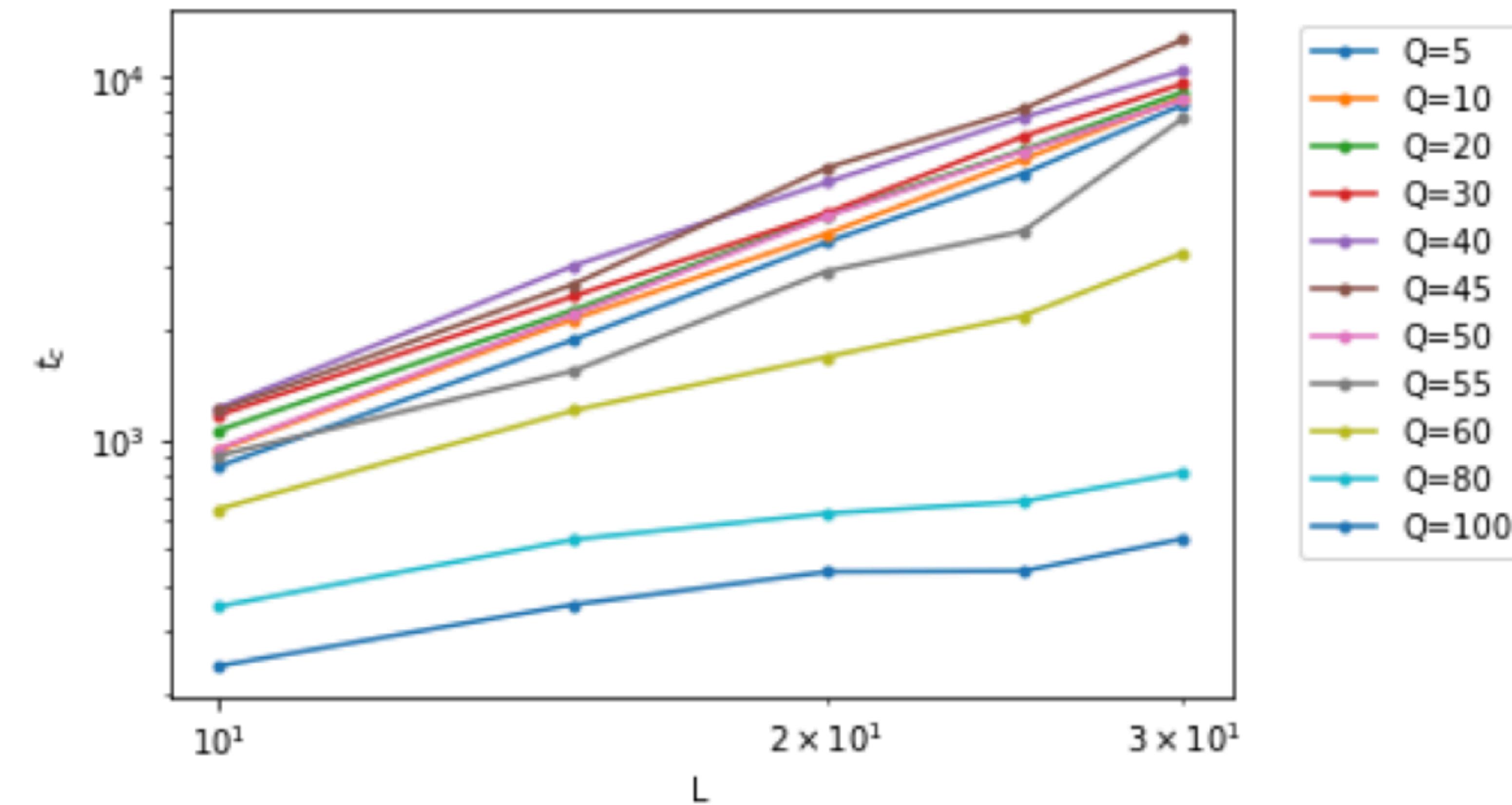
30 realizations, $F=10$

Freezing time



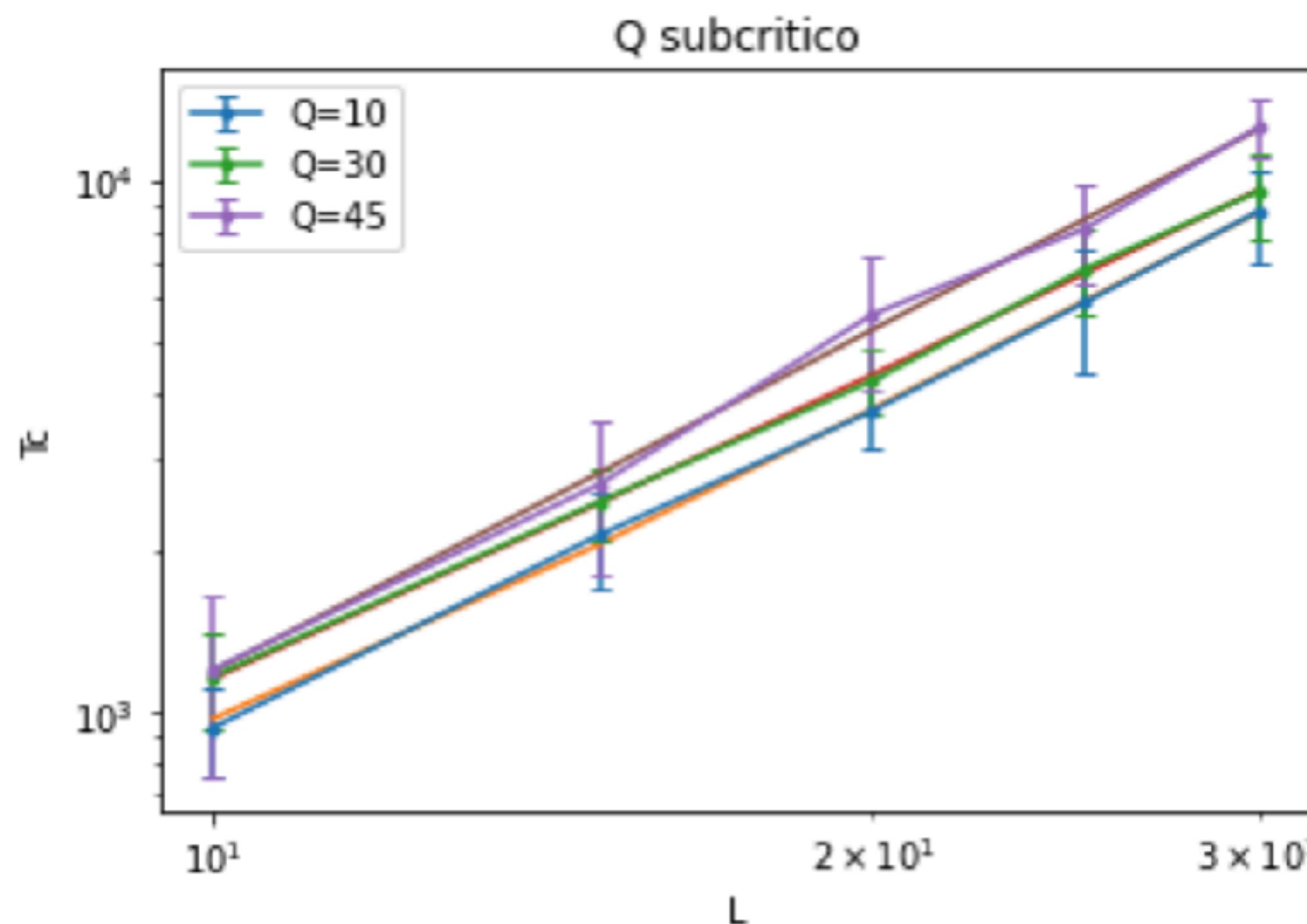
30 realizations, $F=10$

Freezing time

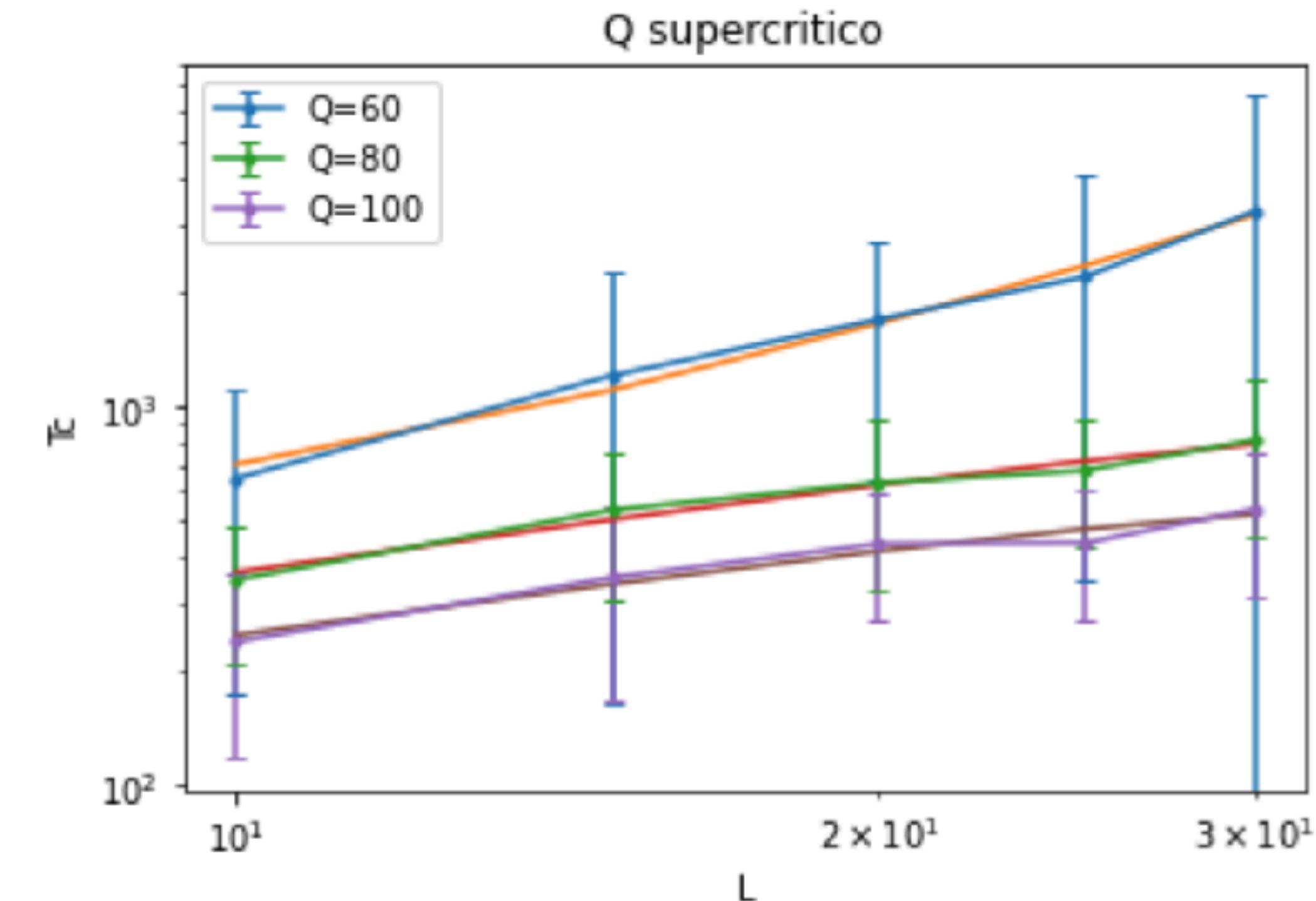


30 realizations, $F=10$, log-log scale

Freezing time



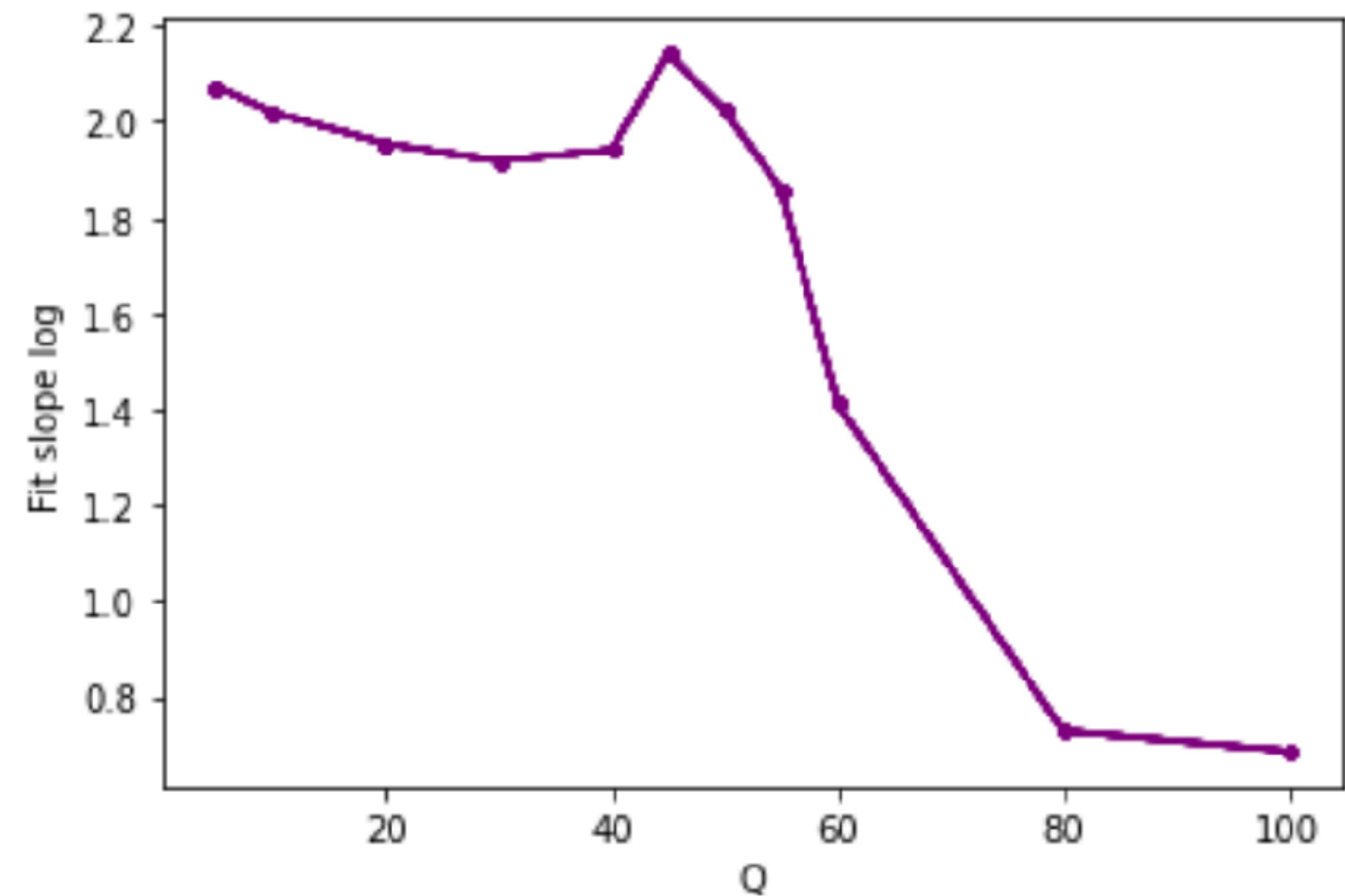
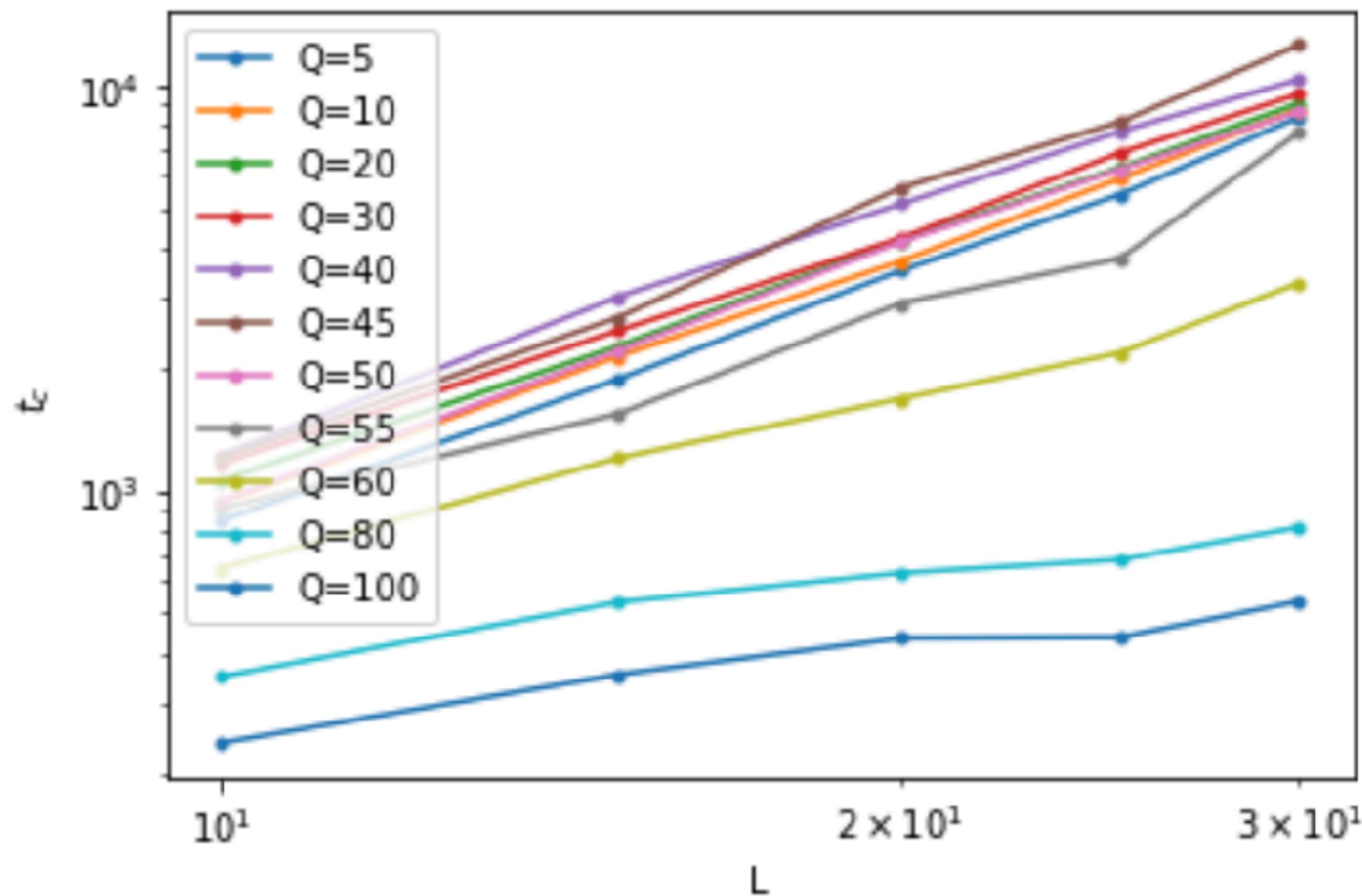
Q = 10: Fit Slope = 2.01968
Q = 30: Fit Slope = 1.91801
Q = 45: Fit Slope = 2.1415



Q = 60: Fit Slope = 1.41161
Q = 80: Fit Slope = 0.72877
Q = 100: Fit Slope = 0.68656

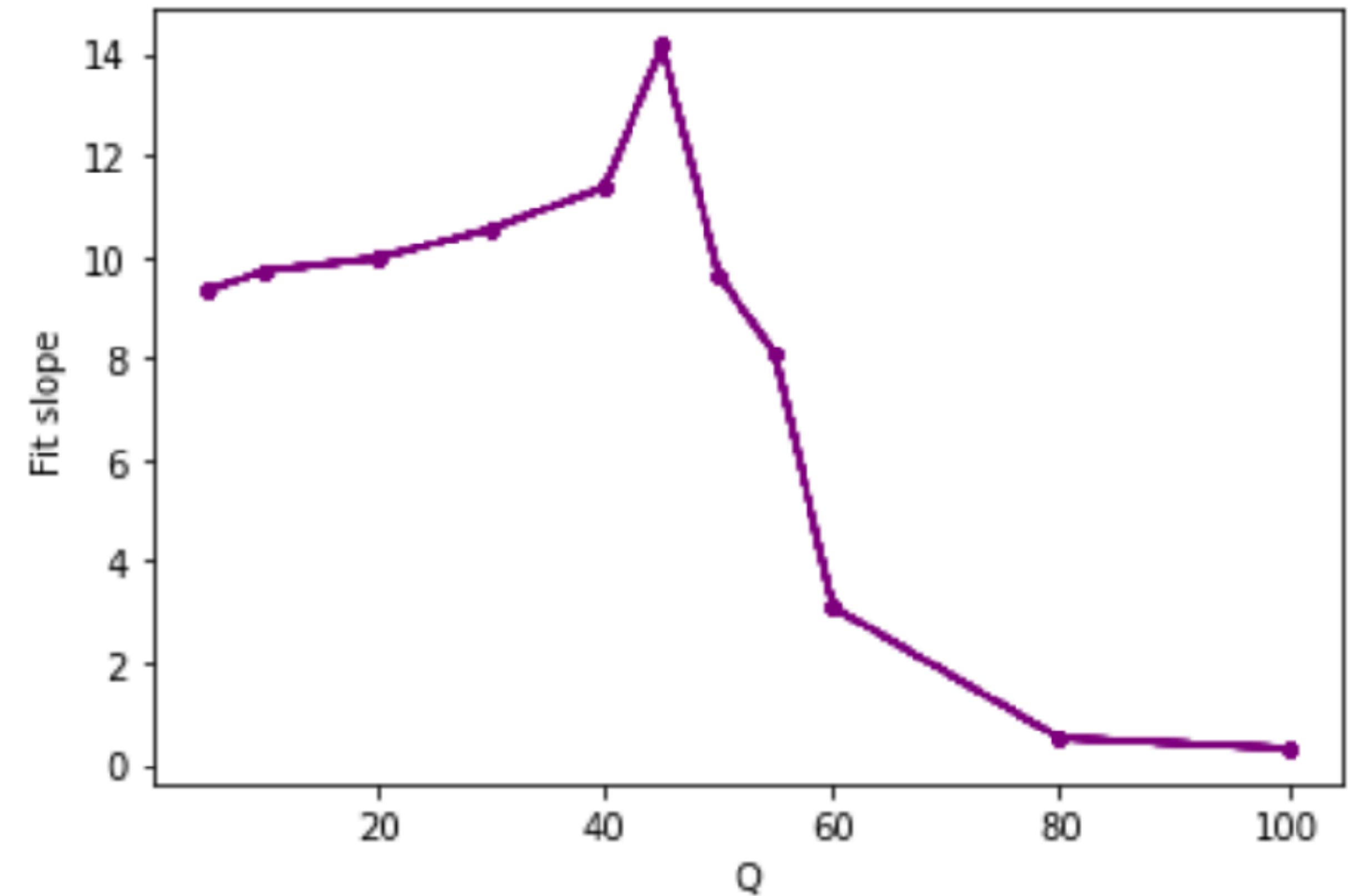
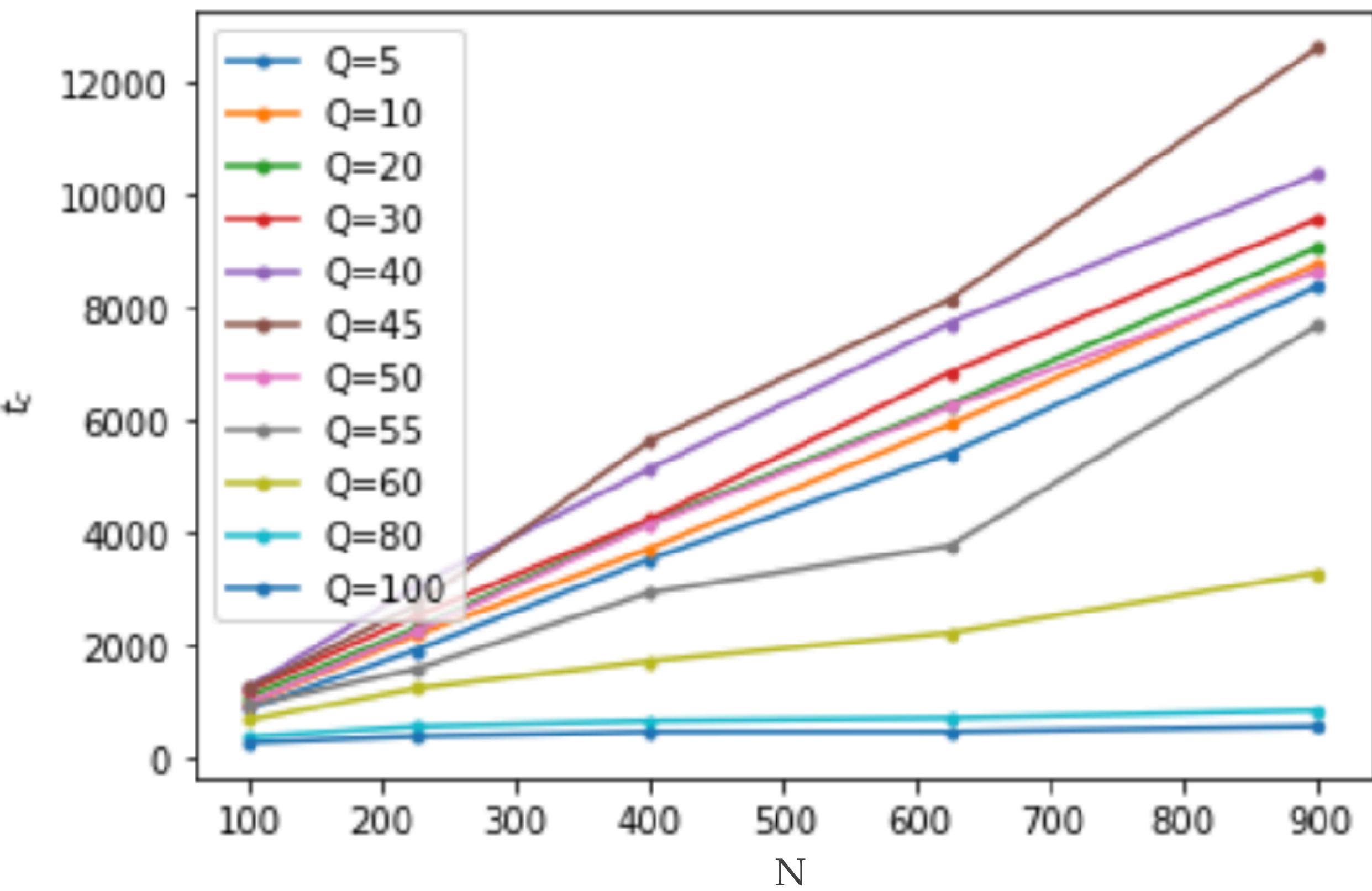
30 realizations, F=10

Freezing time



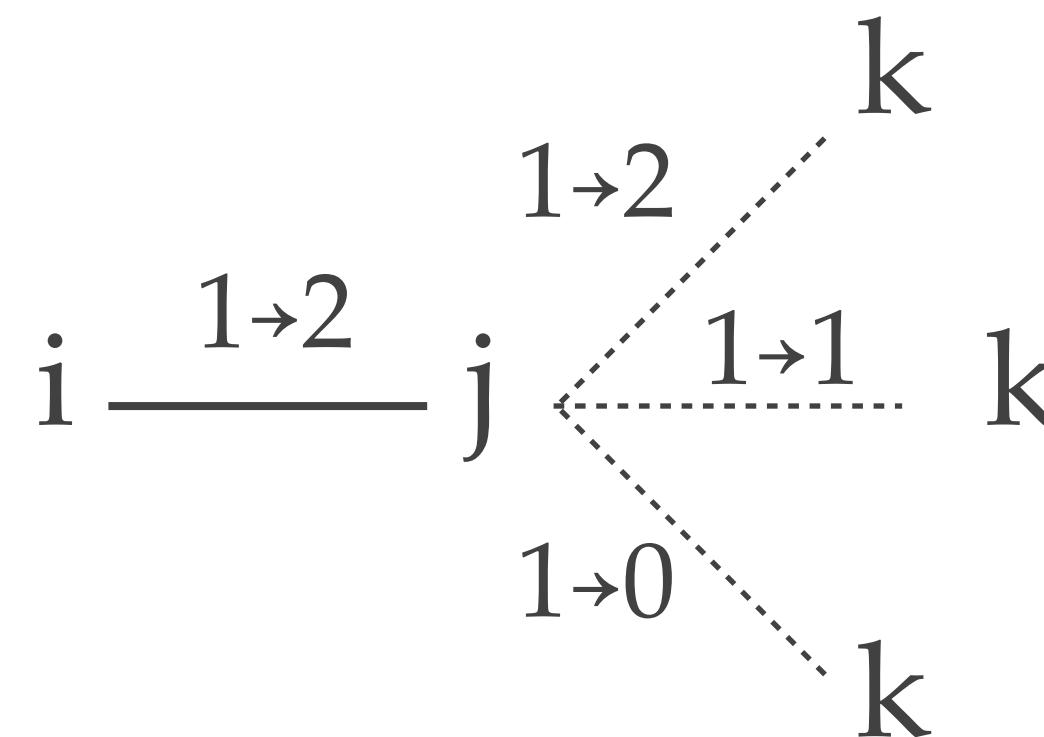
30 realizations, $F=10$

Freezing time



30 realizations, $F=10$

Axelrod Dynamics



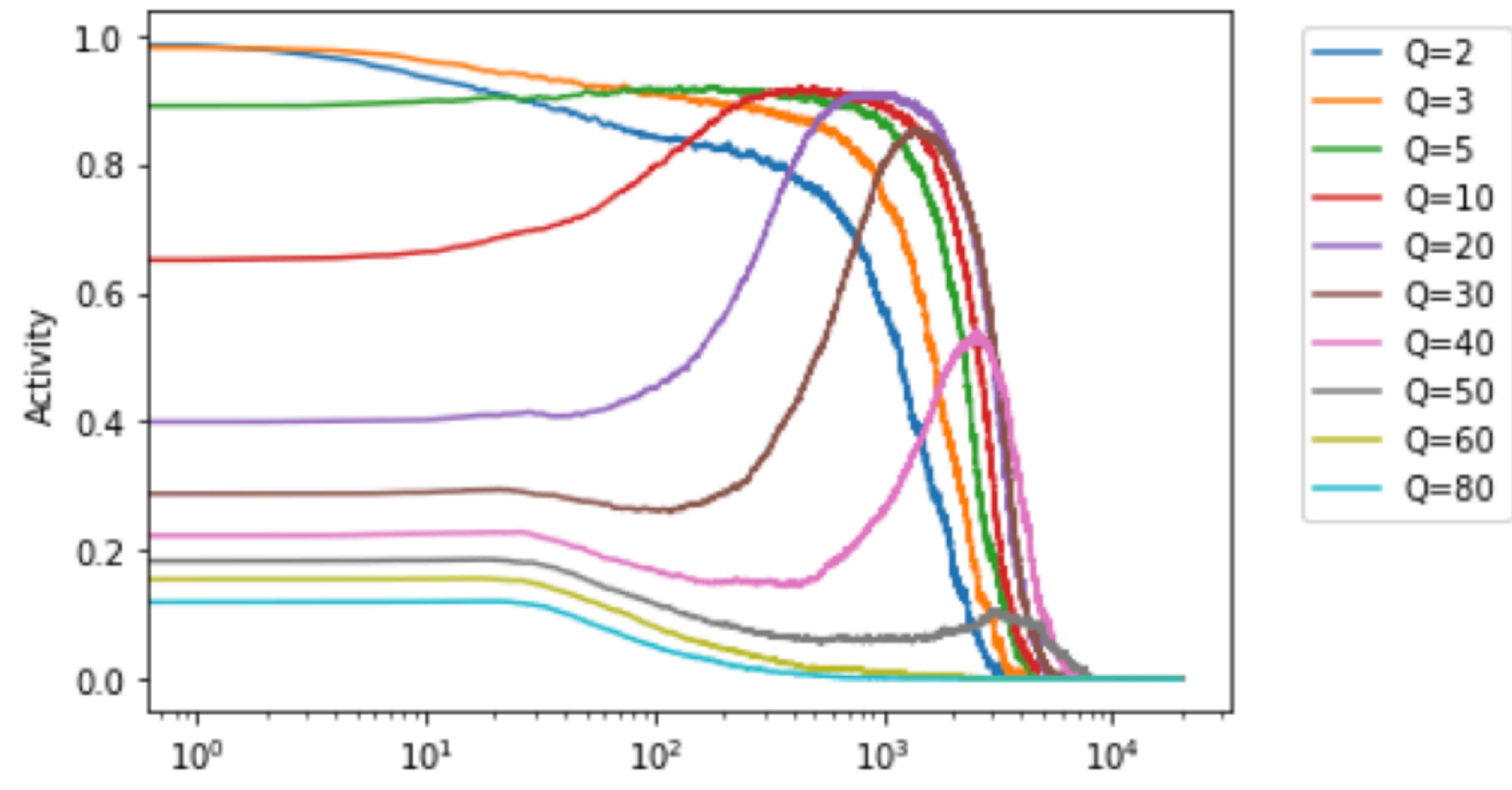
- Direct interaction

$$\Rightarrow \omega_{ij} \rightarrow \omega_{ij} + \frac{1}{F}$$

- Indirect interaction

$$\Rightarrow \omega_{jk} \rightarrow \omega_{jk}, \omega_{jk} \pm \frac{1}{F}$$

k nearest neighbour of j



30 realisations, $L=20, F=10$

Master Equation

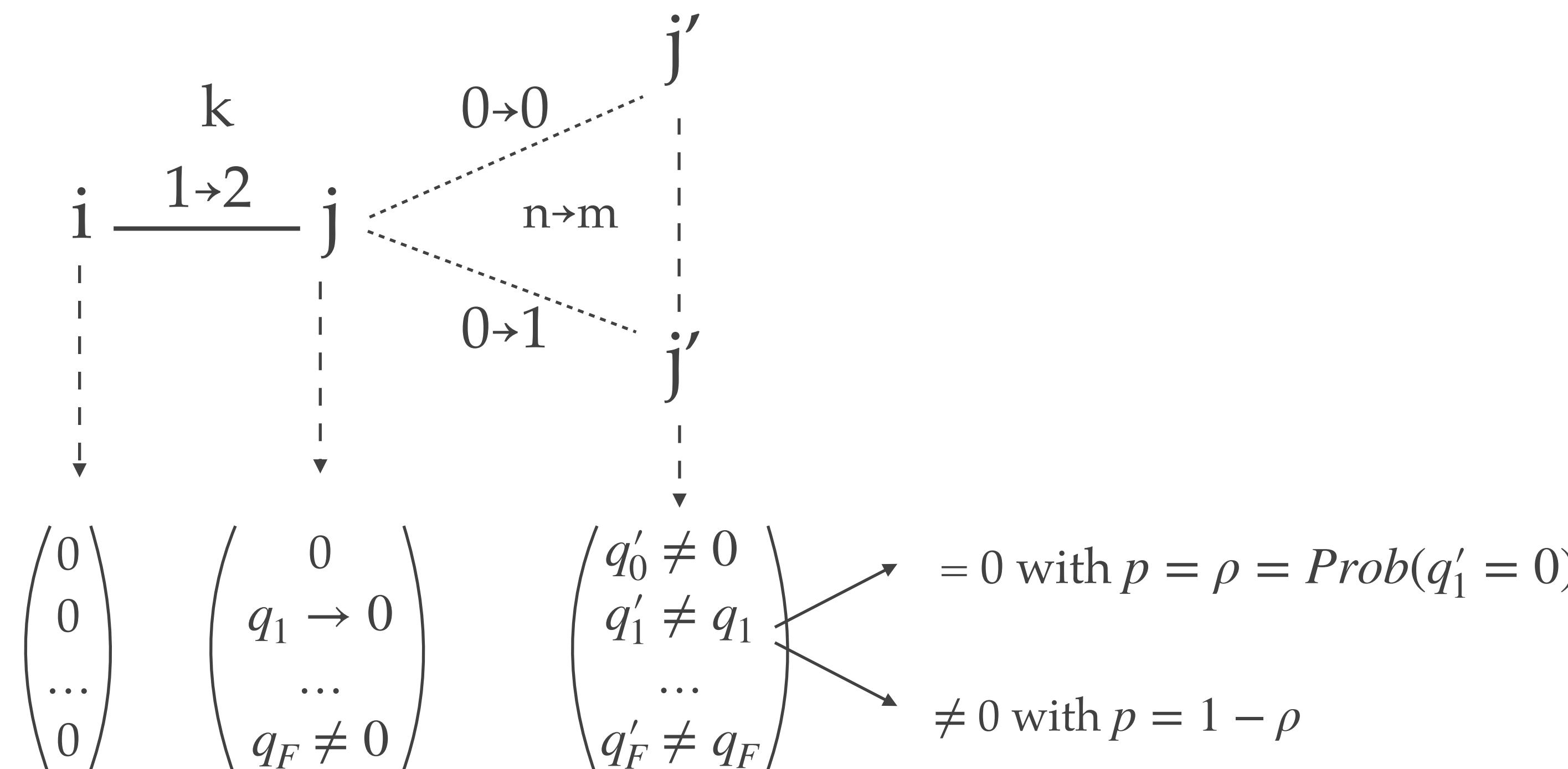
$$\frac{dP_m}{dt} = \sum_{k=1}^{F-1} \frac{k}{F} P_k [\delta_{m,k+1} - \delta_{m,k}] + (g-1) \sum_{n=0}^F (P_n W_{n,m}^{(k)} - P_m W_{m,n}^{(k)})$$

- $\frac{k}{F} P_k$ probabilità di interazione
- Se $k = m - 1$ si crea un collegamento m
- Se $k = m$ viene distrutto
- Interazioni indirette

$$P_m(0) = \binom{F}{m} \rho_0^m (1 - \rho_0)^{F-m}$$

$$\rho_0 = \text{Prob}[q_{i,f} = q_{j,f}] = 1/Q$$

Master Equation



$$F=3: \quad W_{n,m}^{(0)} = W_{m,n}^{(0)} = 0 \quad W_{n,m}^{(3)} = W_{m,n}^{(3)} = 0 \quad W_{n,m}^{(1)} = W_{n,m}^{(2)} \quad \forall m, n$$

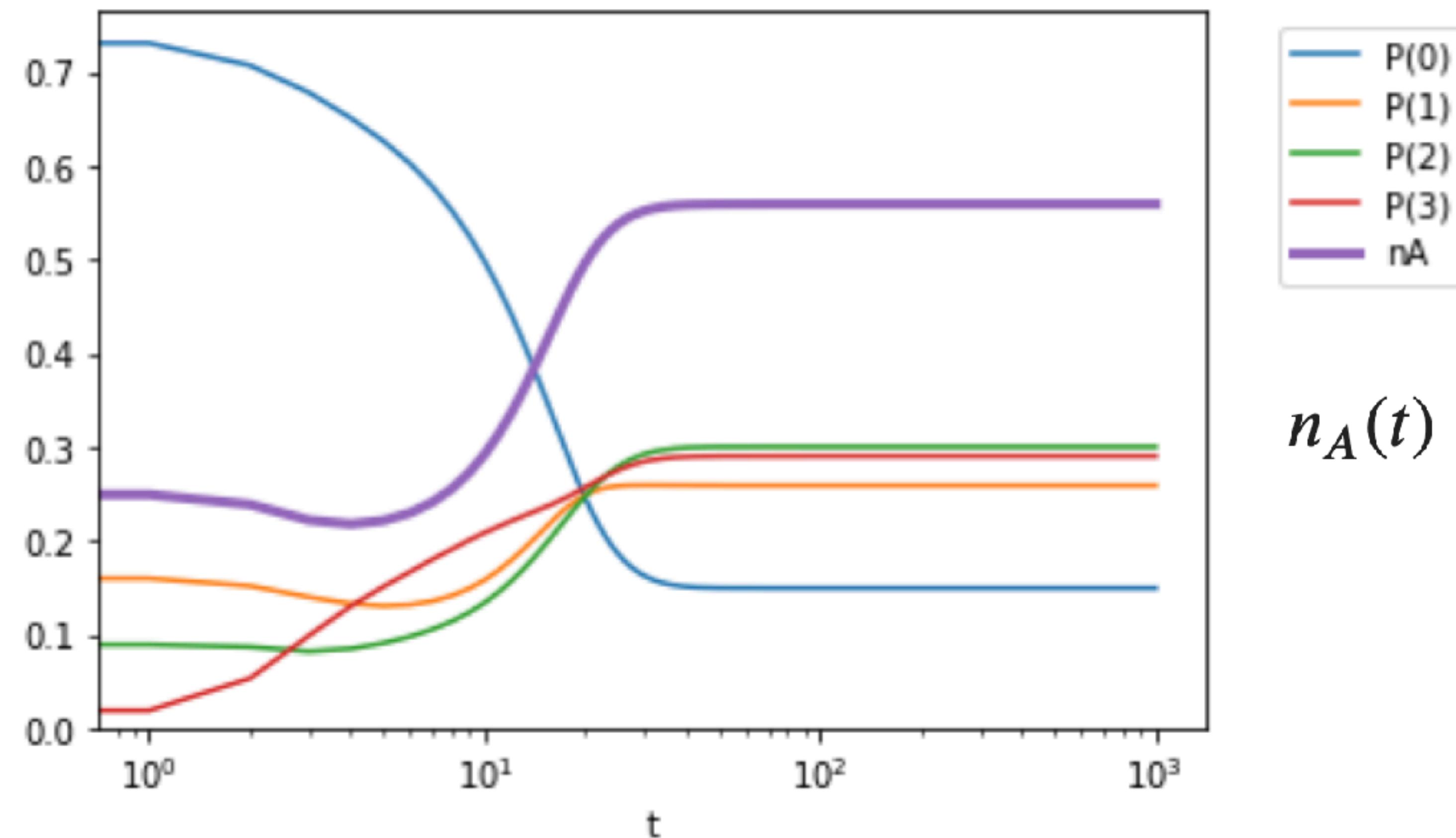
Master Equation

$$\begin{array}{lll} W_{0,0} = 1 - \rho & W_{0,1} = \rho \\ W_{1,0} = \frac{1}{3} & W_{1,1} = \frac{2}{3}(1 - \rho) & W_{1,2} = \frac{2}{3}\rho \\ W_{2,1} = \frac{2}{3} & W_{2,2} = \frac{1}{3}(1 - \rho) & W_{2,3} = \frac{1}{3}\rho \\ W_{3,2} = 0 & W_{3,3} = 1 \end{array}$$

$$\rho = \sum_k k P_k / F$$

$$\frac{dP_m}{dt} = \sum_{k=1}^{F-1} \frac{k}{F} P_k [\delta_{m,k+1} - \delta_{m,k} + (g-1) \sum_{n=0}^F (P_n W_{n,m}^{(k)} - P_m W_{m,n}^{(k)})]$$

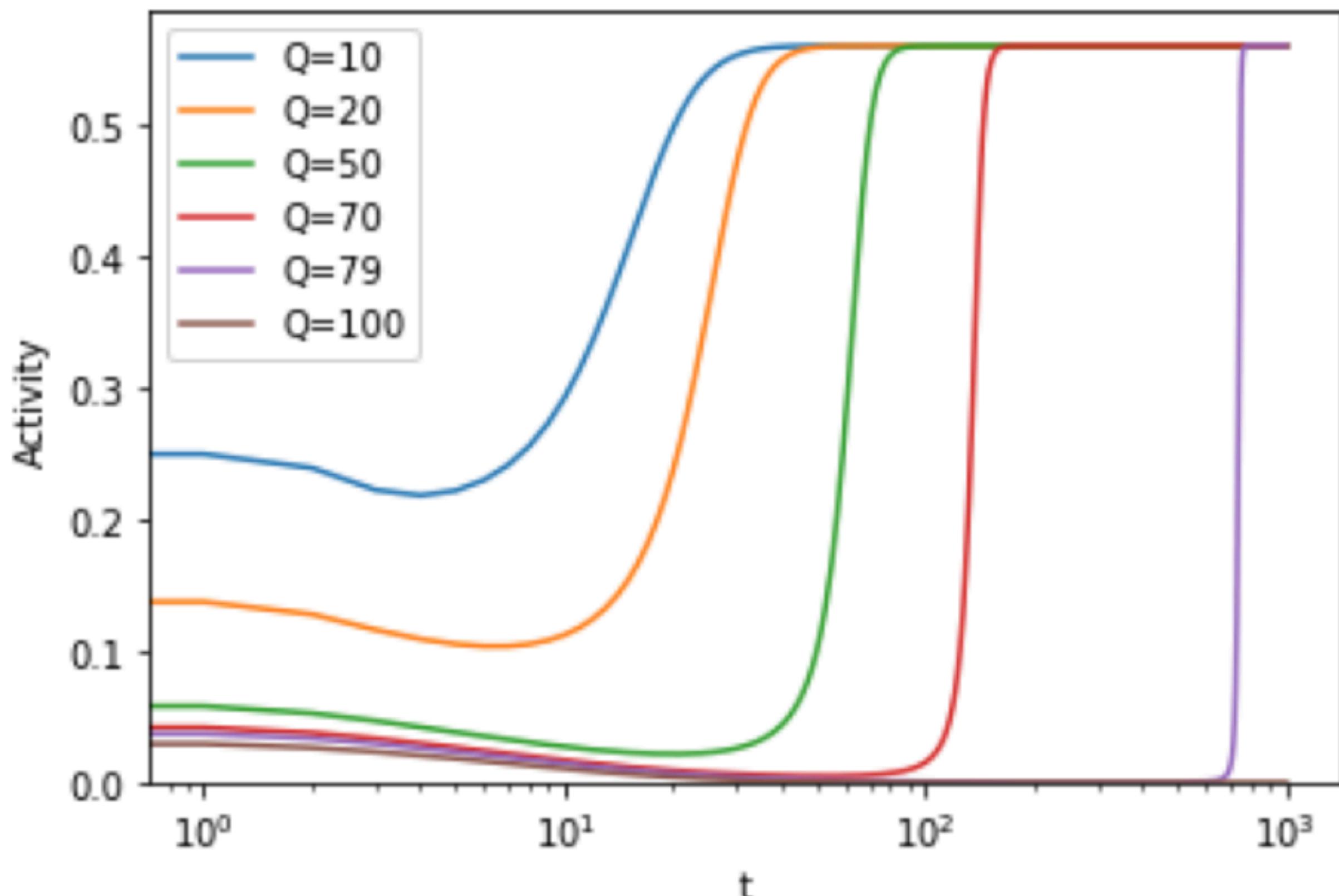
Master Equation



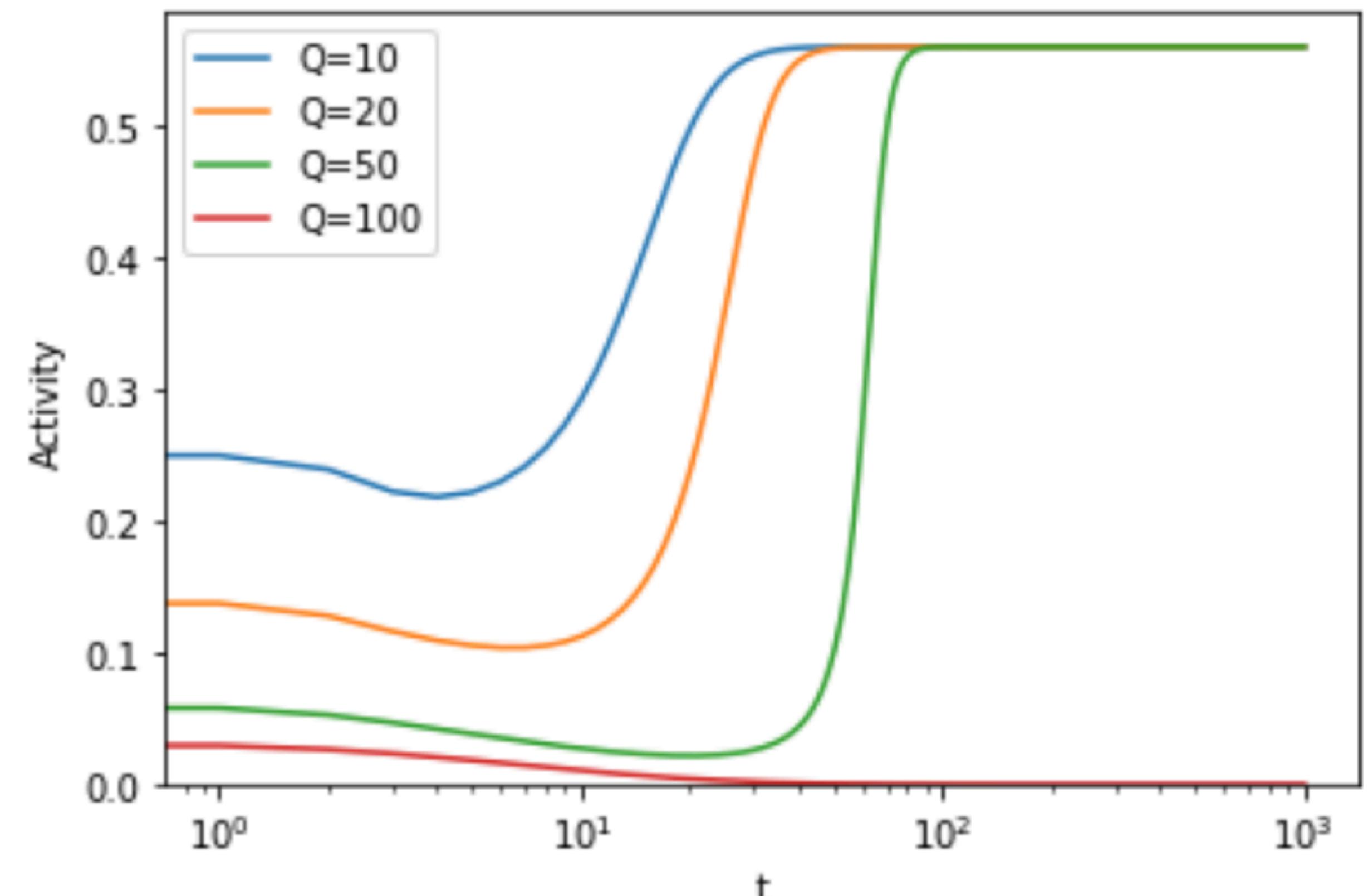
$$n_A(t) = \sum_{k=1}^{F-1} P_k(t)$$

$F=3, Q=10$

Master Equation

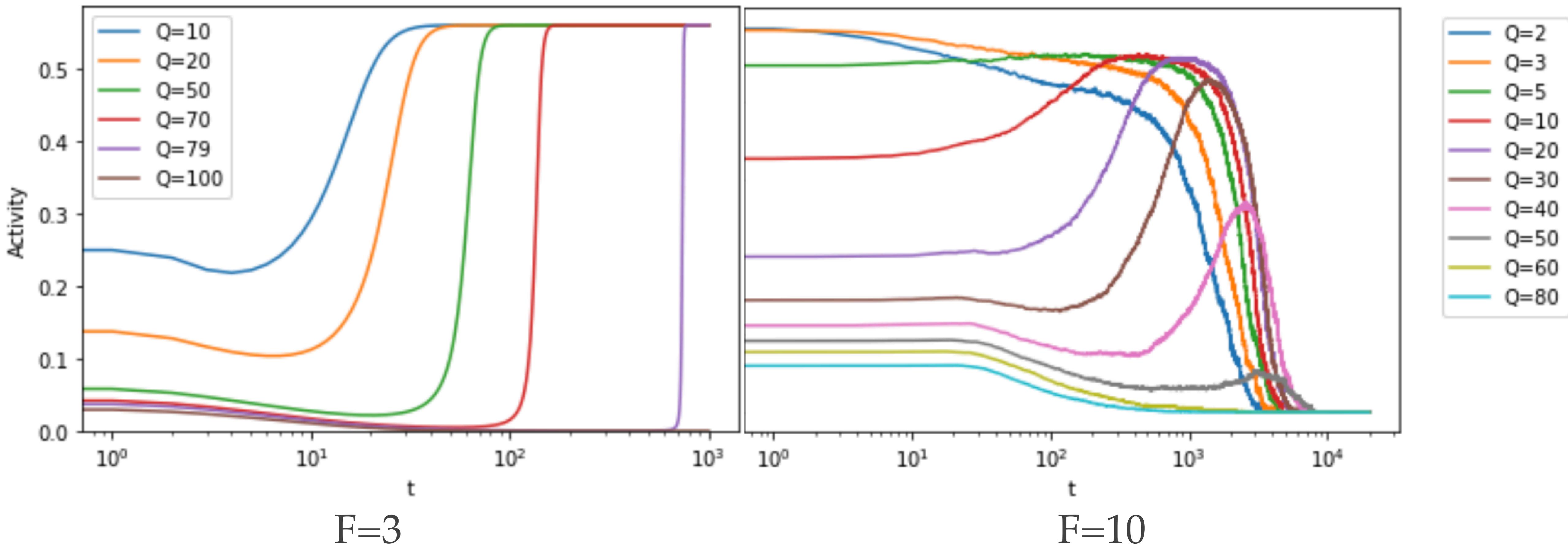


$F=3$

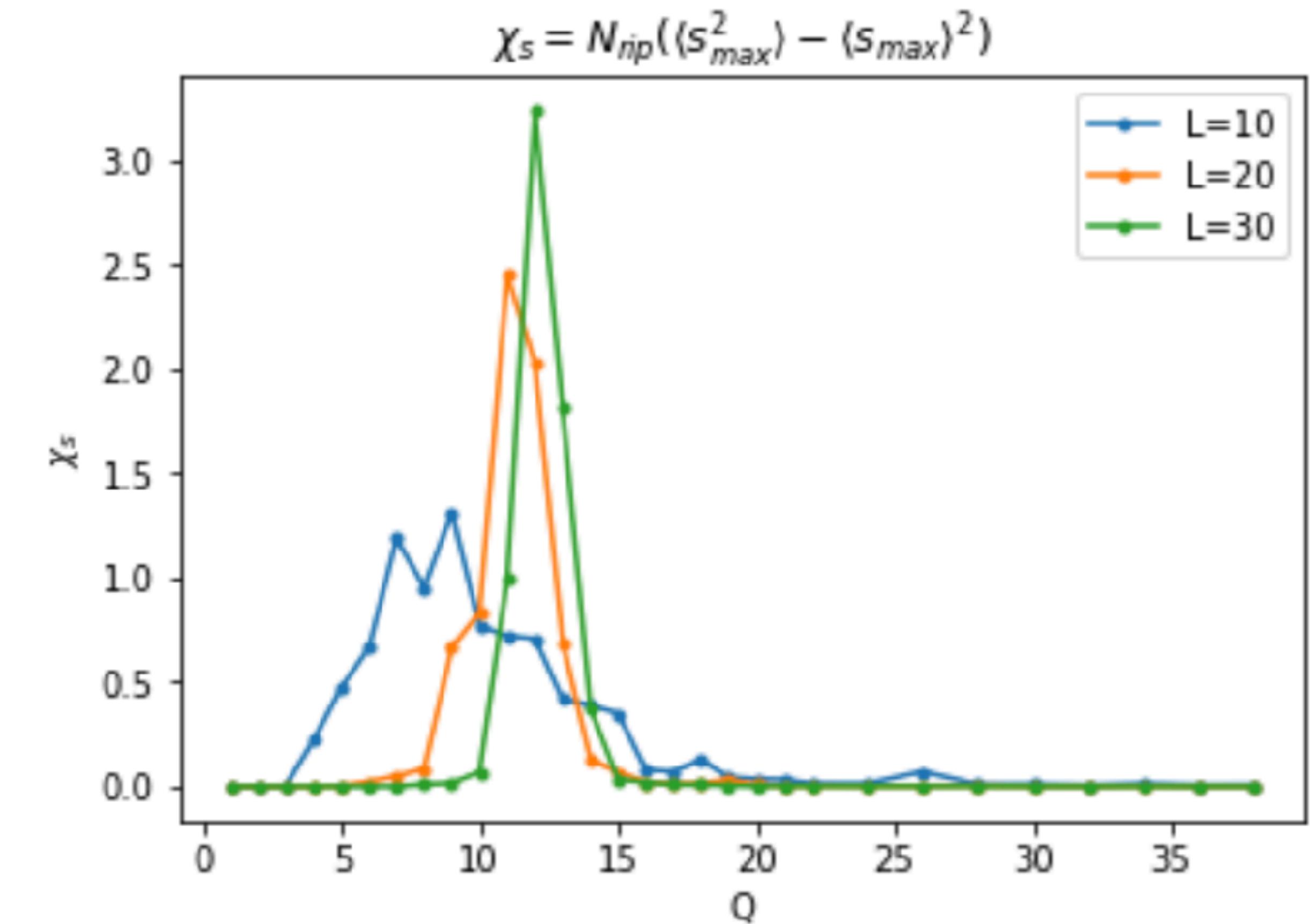
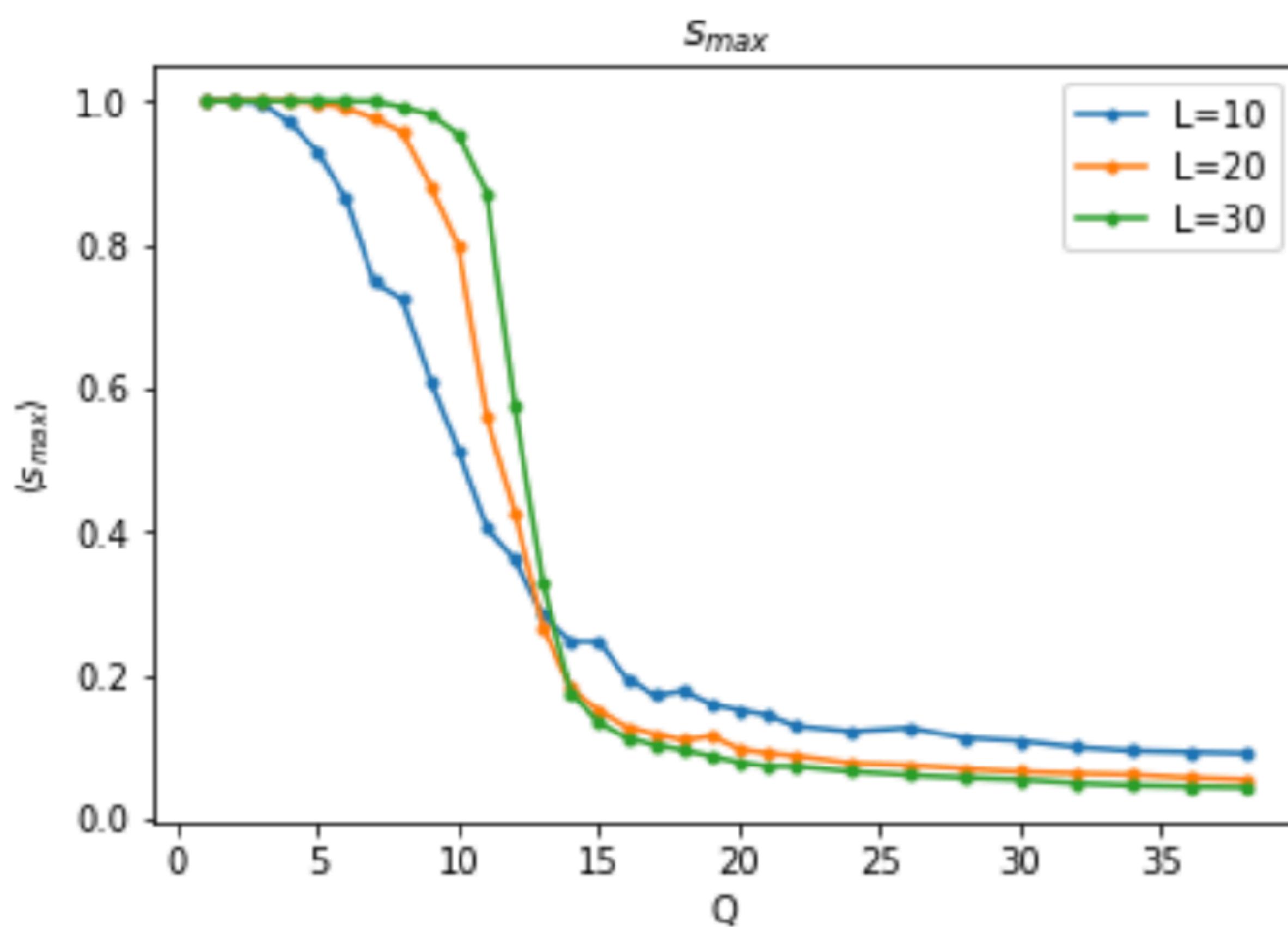


$F=3$

Master Equation

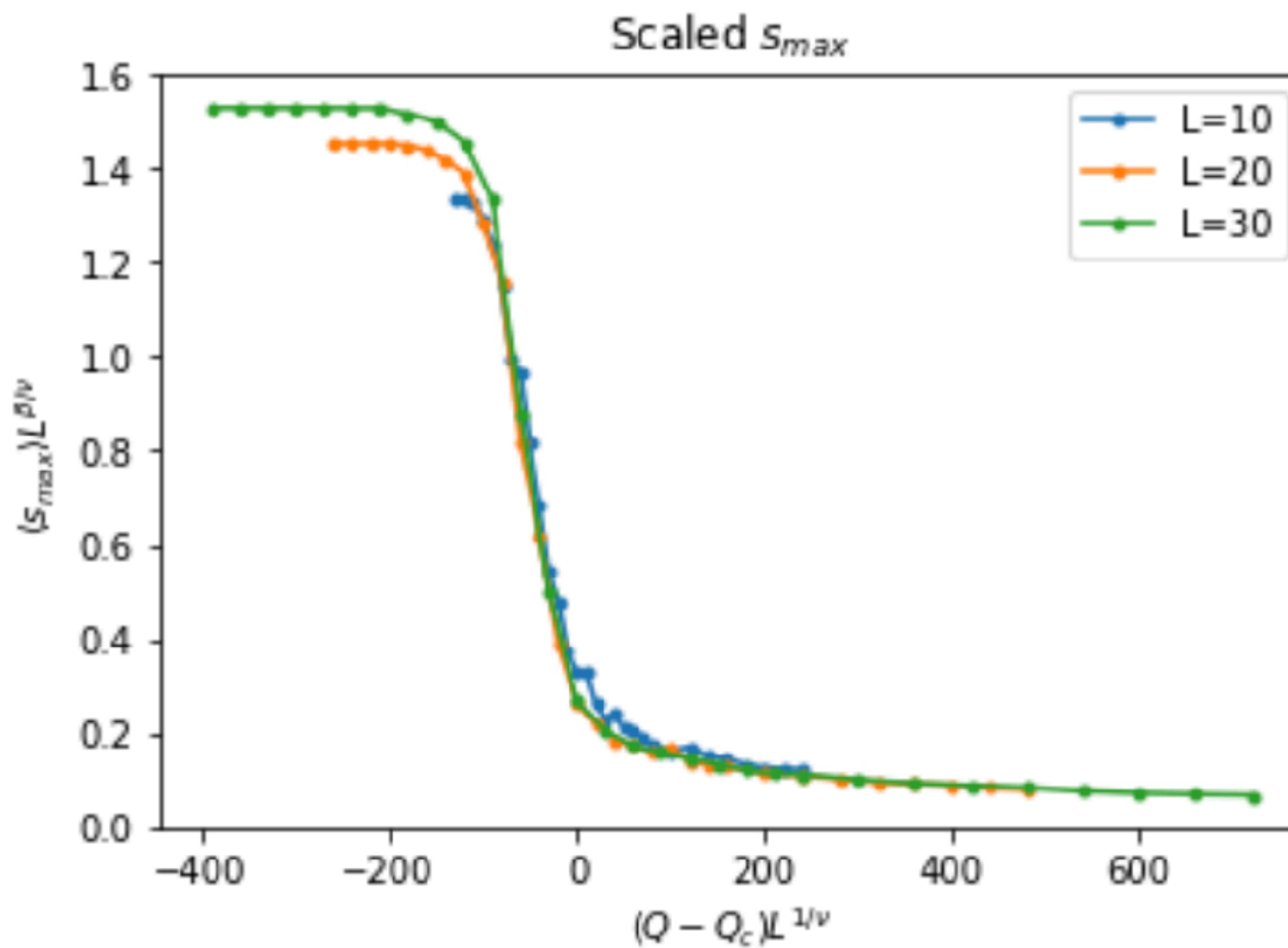


Master Equation



$F=3$

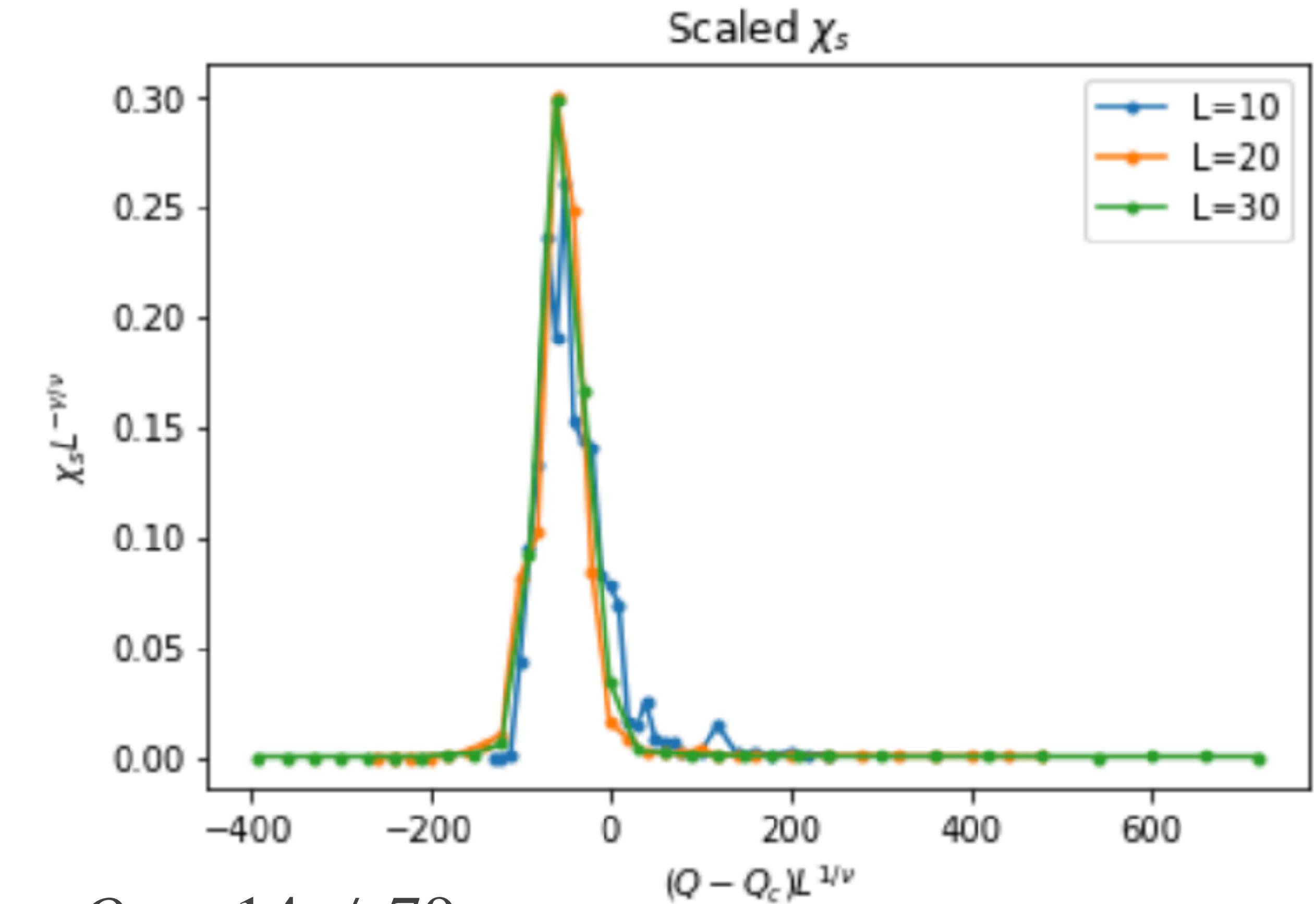
Differences



Critical Q :

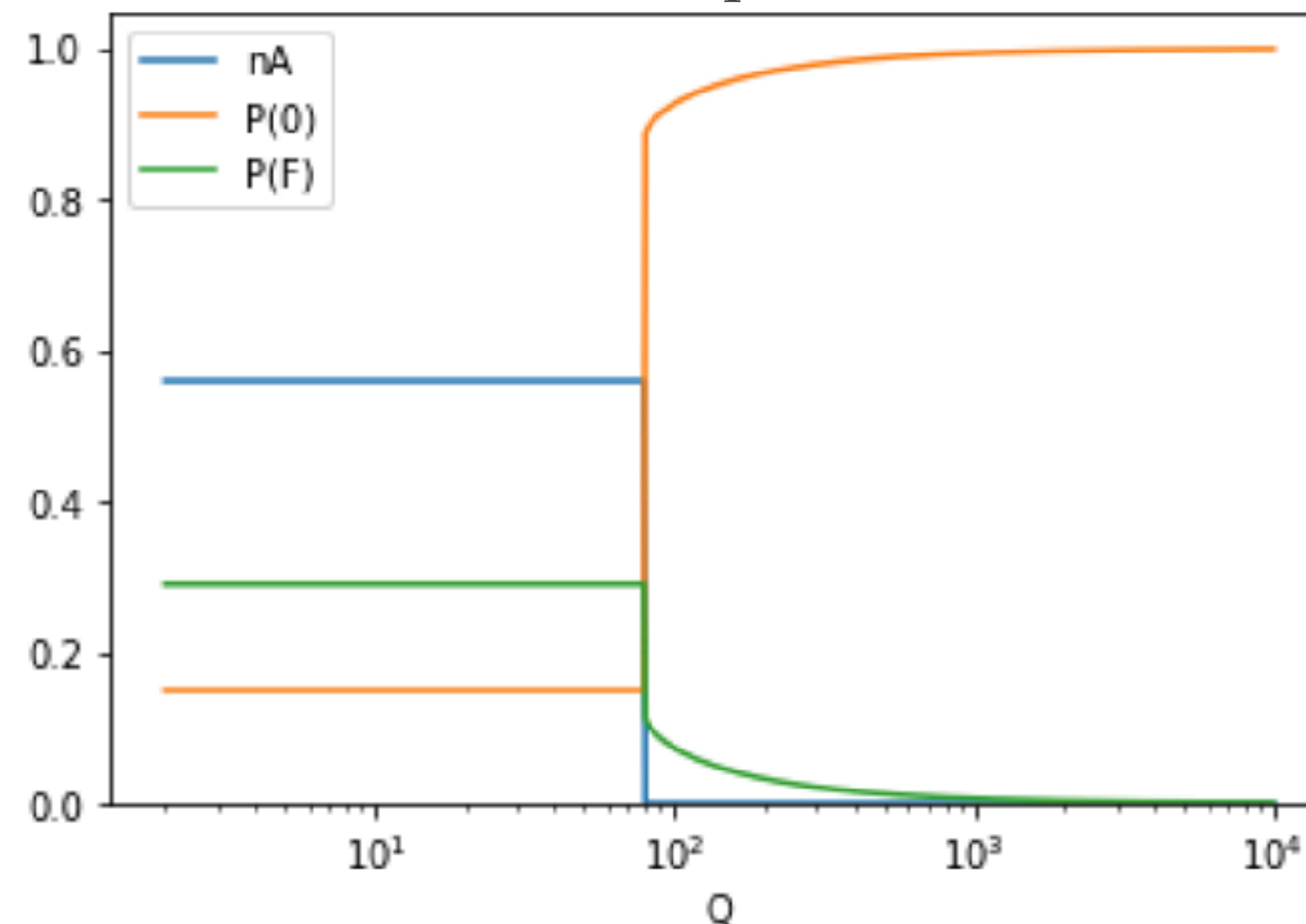
$$Q_c \approx 14 \neq 79$$

Critical exponents: $\beta/\nu \approx 1/8$ e $\gamma/\nu \approx 0.7$.



Master Equation

Discontinuous phase transition



Conclusion

Comparison simulation - Master Equation qualitatively correct.

Variants:

- Implementation on complex network
- Property 2 stringent
- Non trivial probabilities for $q_{i,f}$
- Correlations between features

Bibliography

- [1] Axelrod, R., 1997, J. Conflict Resolut. 41(2), 203.
- [2] C. Castellano, M. Marsili, and A. Vespignani, 2000, Phys. Rev. Lett. 85(16), 3536.
- [3] C. Castellano, S. Fortunato and V. Loreto, “Statistical Physics of Social Dynamics”, 2009, Rev. Mod. Phys. 81, 591.

Report of this presentation, with explanation and codes, on the web page:
https://edoarder.github.io/Sistemi_Complessi/

Thanks for your attention