

COMMUNICATING COOPERATING PROCESSES

The **producer-consumer** paradigm

- A buffer of items can be filled by the producer and emptied by the consumer.
- The producer and the consumer must be synchronized: the producer can produce one item while the consumer is consuming another item.
- The buffer can be unbounded or bounded. In the last case the consumer must wait if the buffer is empty and the producer must wait if the buffer is full.

The buffer may either be provided by the OS through an **Inter Process Communication (IPC)** facility or by explicitly coded by the application programmer with the use of **Shared Memory** solution.

SHARED-MEMORY SOLUTION

Cooperating Processes

Shared data

```
#define BUFFER_SIZE 10
typedef struct {
    ...
} item;
item buffer[BUFFER_SIZE];
int in = 0;
int out = 0;
```

Producer process

```
item nextProduced;
while (1) {
    while (((in + 1) % BUFFER_SIZE) == out); /* do nothing */
    buffer[in] = nextProduced;
    in = (in + 1) % BUFFER_SIZE;
}
```

Consumer process

```
item nextConsumed;
while (1) {
    while (in == out); /* do nothing */
    nextConsumed = buffer[out];
    out = (out + 1) % BUFFER_SIZE;
}
```

INTERPROCESS COMMUNICATION (IPC)

- ↳ Mechanism for processes to communicate and to synchronize their actions.
- ↳ Message-Passing system: processes communicate with each other without resorting to shared variables.
- ↳ IPC facility provides two operations:
 - Φ **send**(*message*) – message size fixed or variable
 - Φ **receive**(*message*)
- ↳ If *P* and *Q* wish to communicate, they need to:
 - Φ establish a *communication link* between them
 - Φ exchange messages via send/receive
- ↳ From the logical point of view, a communication link may be implemented in several ways:
 - Φ **Direct** (through process name) or **Indirect** communication (through *mailbox* or *port*)
 - Φ **Symmetric** or **Asymmetric** communication (the receiver knows the sender or not)
 - Φ **Synchronous** or **Asynchronous** communication (blocking or non blocking primitives)
 - Φ **Extended** or **Limited rendez-vous** communication (when both the send and the receive are blocking or not)
 - Φ **Unbuffering** or **Buffering** (with bounded or unbounded capacity) communication queue.

DIRECT COMMUNICATION

⇒ Processes must name each other explicitly:

Φ **send** (*P*, *message*) – send a message to process P

Φ **receive**(*Q*, *message*) – receive a message from process Q

⇒ Properties of communication link

Φ Links are established automatically.

Φ A link is associated with exactly one pair of communicating processes.

Φ Between each pair there exists exactly one link.

Φ The link may be unidirectional, but is usually bi-directional.

⇒ A variant employs asymmetry:

Φ **send** (*P*, *message*) – send a message to process P

Φ **receive**(*id*, *message*) – receive a message from any process; *id* is the name of the current process.

INDIRECT COMMUNICATION

⇒ Messages are directed and received from **mailboxes** (also referred to as **ports**).

- Φ Each mailbox has a unique id.

- Φ Processes can communicate only if they share a mailbox.

⇒ Properties of communication link

- Φ Link established only if processes share a common mailbox

- Φ A link may be associated with many processes.

- Φ Each pair of processes may share several communication links.

- Φ Link may be unidirectional or bi-directional.

⇒ Operations

- Φ **create** a new mailbox

- Φ **send** and **receive** messages through mailbox

- Φ **destroy** a mailbox

⇒ Primitives are defined as:

send(*A, message*) – send a message to mailbox A

receive(*A, message*) – receive a message from mailbox A

INDIRECT COMMUNICATION

↳ Mailbox owner

- Φ A process (the mailbox is part of its address space and it can only receive messages) or the OS
- Φ The owner process is that creates a new mailbox
- Φ When the owner process terminates, the mailbox disappears

↳ Mailbox sharing

- Φ P_1 , P_2 , and P_3 share mailbox A.
- Φ P_1 , sends; either P_2 or P_3 , but not both, will receive the message.

↳ Solutions

- Φ Allow a link to be associated with at most two processes.
- Φ Allow only one process at a time to execute a receive operation.
- Φ Allow the system to select arbitrarily the receiver. Sender is notified who the receiver was.

COMMUNICATION SYNCHRONIZATION

- ⊕ Message passing may be either blocking or non-blocking.
- ⊕ **Blocking** is considered **synchronous**
- ⊕ **Non-blocking** is considered **asynchronous**
- ⊕ **send** and **receive** primitives may be either blocking or non-blocking.

COMMUNICATION BUFFERING

- ↳ Queue of messages attached to the link; implemented in one of three ways.
 1. Zero capacity – 0 messages.
Sender must wait for receiver (rendezvous).
 2. Bounded capacity – finite length of n messages
Sender must wait if link full.
 3. Unbounded capacity – infinite length
Sender never waits.

CLIENT-SERVER COMMUNICATION

↳ *Sockets*

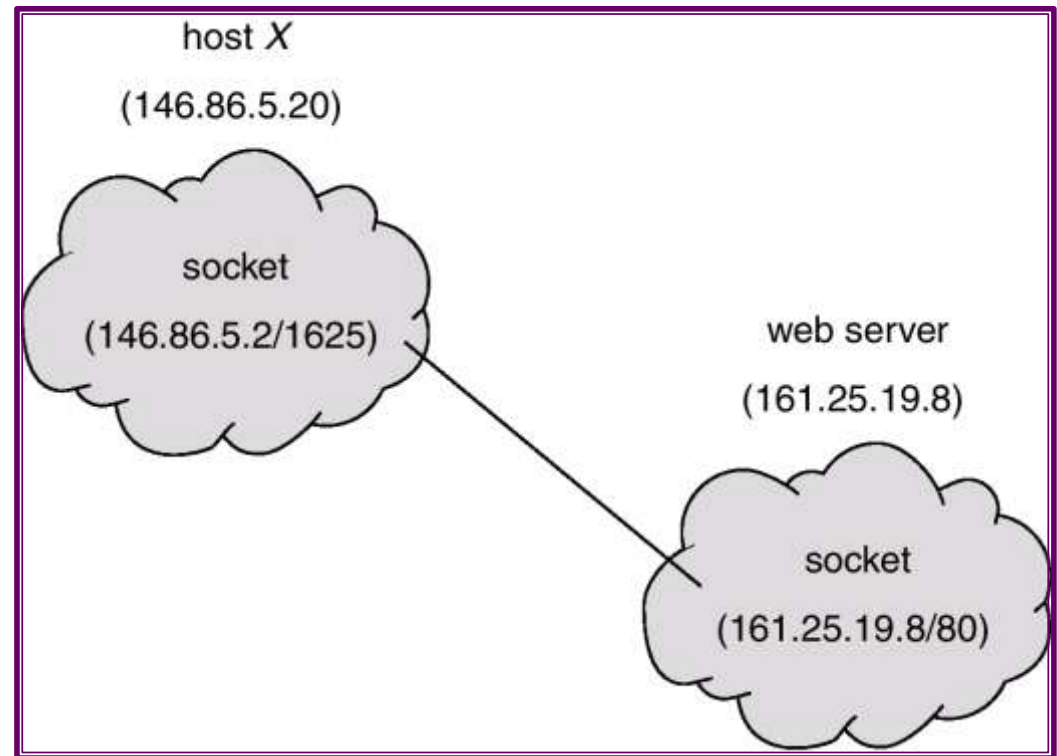
↳ *Remote Procedure Calls*

↳ *Remote Method Invocation* (Java)

CLIENT-SERVER COMMUNICATION

Socket

- Φ A socket is defined as an *endpoint for communication*.
- Φ A socket is made up of an IP address concatenated with a port number.
- Φ The socket **161.25.19.8:1625** refers to port **1625** on host **161.25.19.8**
- Φ Communication consists of a pair of sockets.
- Φ The server waits for incoming client requests by listening to a specified port, accepts the connection request from the client socket and completes the connection.
- Φ Servers offering specific services listen to well-known ports: port 80 for web or http, port 21 for ftp, port 23 for telnet).



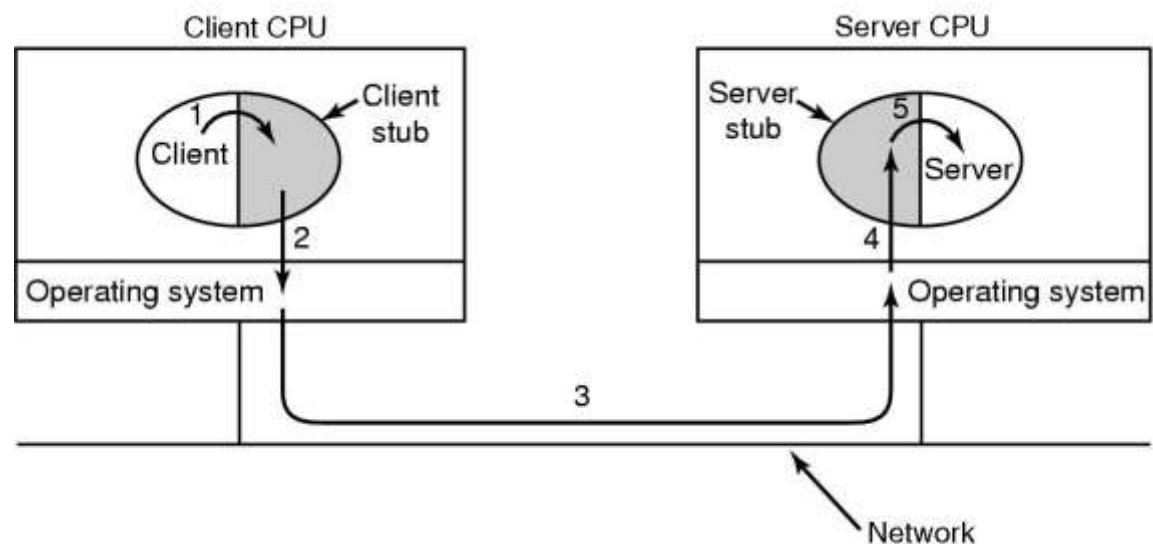
CLIENT-SERVER COMMUNICATION

Remote Procedure Call

- Φ Remote procedure call (RPC) abstracts procedure calls between processes on networked systems.
- Φ **Stubs** – client-side proxy for the actual procedure on the server.
- Φ The client-side stub locates the server and *marshalls* the parameters.
- Φ The server-side stub receives this message, unpacks the marshalled parameters, and performs the procedure on the server.

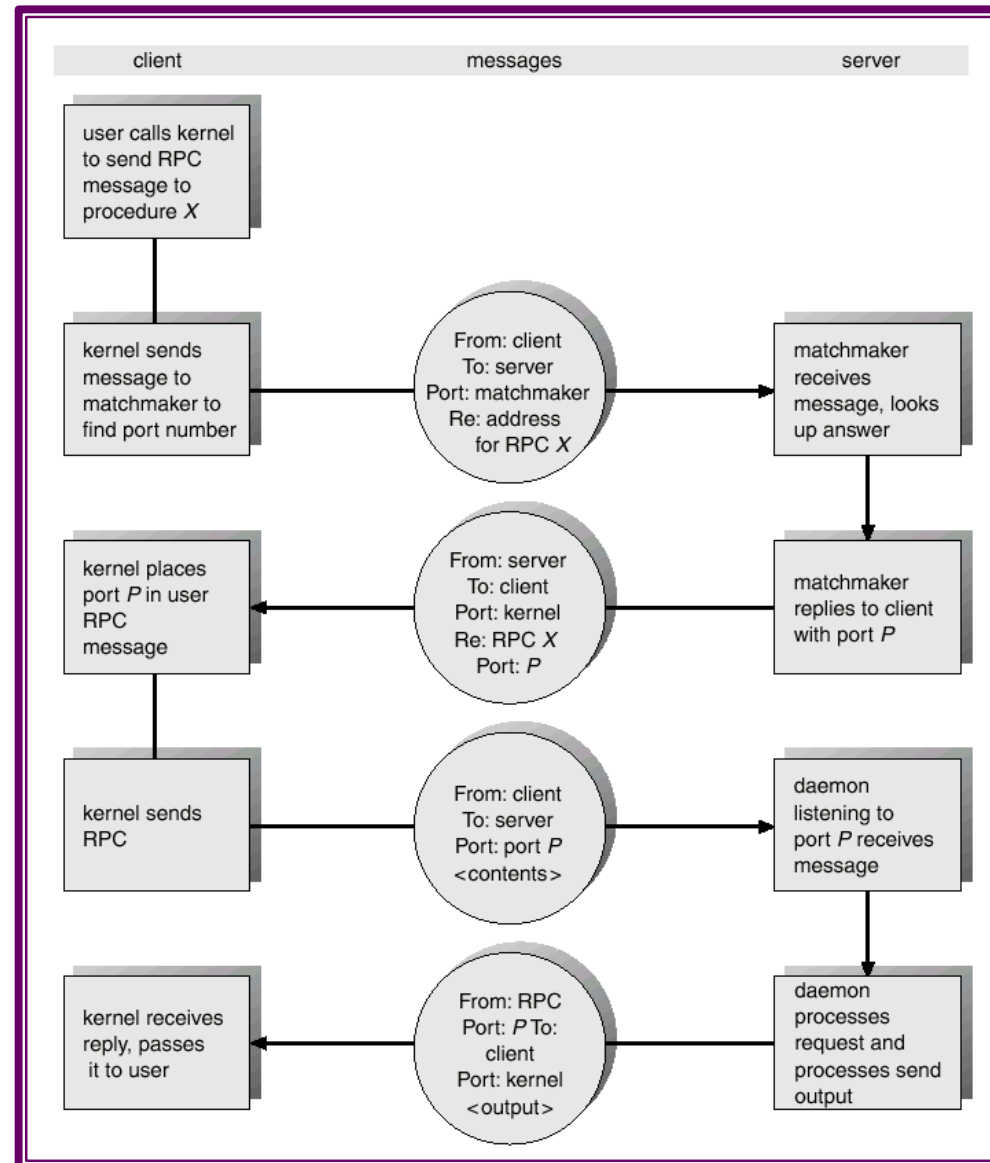
☞ Implementation Issues

- Cannot pass pointers
 - call by reference becomes call by copy-restore (but might fail)
- Weakly typed languages
 - client stub cannot determine size
- Not always possible to determine parameter types
- Cannot use global variables
 - may get moved to remote machine



CLIENT-SERVER COMMUNICATION

Remote Procedure Call



CLIENT-SERVER COMMUNICATION

Remote Method Invocation (RMI)

- Φ RMI is a Java mechanism similar to RPCs.
- Φ RMI allows a Java program on one machine to invoke a method on a remote object.

