## Briefly on Bottom-up [Algoritmi da]

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**Definition 0.1.** Let Q, V, and  $\tau$  be, respectively, the set of states, the vocabulary, and the transition function of a characteristic automaton. Also, let  $\mathcal{LA}_i$  be an actual instance of the lookahead function. Then, the parsing table for the pair constisting of the given characteristic automaton and the given lookahead function is the matrix  $Q \times (V \cup \{\$\})$  obtained by filling in each entry (P, Y) after the following rules.

- Insert "Shift Q" if Y is a terminal and  $\tau(P,Y) = Q$ .
- Insert "Reduce  $A \to \beta$ " if P contains a reducing item for  $A \to \beta$  and  $Y \in \mathcal{L}A_i(P, A \to \beta)$ .
- Set to "Accept" if P contains the accepting item and Y = \$.
- Set to "Error" if Y is a terminal or \$, and none of the above applies.
- Set to "Goto Q" if Y is a nonterminal and  $\tau(P,Y) = Q$ .

# **Algorithm 1:** Construction of either LR(0)-automaton or LR(1)-automaton ( $P_0$ and closure( $\bot$ ) to be instantiated accordingly)

```
initialize Q to contain P_0;
tag P_0 as unmarked;
while there is an unmarked state P in Q do
    \max P;
    {\bf foreach} \ \ {\it grammar \ symbol \ } Y \ {\bf do}
        Tmp \longleftarrow \emptyset;
                                 /* Compute the kernel-set of the Y-target of P */
        for
each A \to \alpha \cdot Y\beta \in P do
        add A \to \alpha Y \cdot \beta to Tmp;
        if Tmp \neq \emptyset then
                            /* Check whether \tau(P,Y) has already been collected */
            if Tmp = kernel(Q) for some Q in Q then
            \tau(P,Y) \longleftarrow Q;
            else
                New\_state \leftarrow closure(Tmp);
                \tau(P,Y) \longleftarrow New\_state;
                add New\_state as an unmarked state to Q;
```

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### **Algorithm 2:** Computation of $closure_0(Q)$

```
function \operatorname{closure_0}(P)

tag every item in P as unmarked;

while there is an unmarked item I in P do

mark I;

if I has the form A \to \alpha \cdot B\beta then

foreach B \to \gamma \in \mathcal{P}' do

if B \to \cdot \gamma \notin P then

add B \to \cdot \gamma as an unmarked item to P;

return P;
```

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#### **Algorithm 3:** Computation of closure<sub>1</sub>(P)

```
function closure<sub>1</sub>(P)

tag every item in P as unmarked;

while there is an unmarked item I in P do

mark I;

if I has the form [A \to \alpha \cdot B\beta, \Delta] then

\Delta_1 \longleftarrow \bigcup_{d \in \Delta} \operatorname{first}(\beta d);
foreach B \to \gamma \in \mathcal{P}' do

if B \to \gamma \notin \operatorname{prj}(P) then

\operatorname{add} [B \to \gamma, \Delta_1] \text{ as an unmarked item to } P;
else

if ([B \to \gamma, \Gamma] \in P \text{ and } \Delta_1 \not\subseteq \Gamma) then

\operatorname{update} [B \to \gamma, \Gamma] \text{ to } [B \to \gamma, \Gamma \cup \Delta_1] \text{ in } P;
\operatorname{set} [B \to \gamma, \Gamma \cup \Delta_1] \text{ as unmarked};

return P;
```

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#### **Algorithm 4:** Construction of the symbolic automaton

```
x_0 \longleftarrow \text{newVar}();
Vars \longleftarrow \{x_0\};
P_0 \leftarrow \text{closure}_1(\{[S' \rightarrow \cdot S, \{x_0\}]\});
initialize Eqs to contain the equation x_0 \doteq \{\$\};
initialize Q to contain P_0;
tag P_0 as unmarked;
while there is an unmarked state P in Q do
    \max P;
    foreach grammar symbol Y do
                                      /* Compute the kernel-set of the Y-target of P */
         Tmp \longleftarrow \emptyset;
         \mathbf{foreach} \ \ [A \to \alpha \cdot Y\beta, \Delta] \ in \ P \ \mathbf{do}
          add [A \to \alpha Y \cdot \beta, \Delta] to Tmp;
         if Tmp \neq \emptyset then
              if prj(Tmp) = prj(kernel(Q)) for some Q in Q then
                                          /* Refine Eqs to let Q be the Y-target of P */
                  foreach ([A \to \alpha Y \cdot \beta, \Delta] \in Tmp, [A \to \alpha Y \cdot \beta, \{x\}] \in kernel(Q)) do
                   update (x \doteq \Gamma) to (x \doteq \Gamma \cup \Delta) in Eqs;
                  \tau(P,Y) \longleftarrow Q;
              else
                                                                  /* Generate the Y-target of P */
                  foreach [A \to \alpha Y \cdot \beta, \Delta] \in Tmp \ do
                       x \leftarrow \text{newVar}();
                       Vars \longleftarrow Vars \cup \{x\};
                       enqueue (x \doteq \Delta) into Eqs;
                       replace [A \to \alpha Y \cdot \beta, \Delta] by [A \to \alpha Y \cdot \beta, \{x\}] in Tmp;
                  \tau(P, Y) \longleftarrow \text{closure}_1(Tmp);
                  add \tau(P, Y) as an unmarked state to Q;
```

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#### **Algorithm 5:** Reduced system of equations REqs for the variables in $RVars \subseteq Vars$

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#### **Algorithm 6:** Computation of the actual values of variables

```
foreach x do
D(x) \longleftarrow 0;
foreach x in RVars do
   if D(x) = 0 then
       traverse(x);
where
function traverse(x)
   push x onto stack S;
   depth \leftarrow number of elements in S;
   D(x) \longleftarrow depth;
   val(x) \longleftarrow init(x);
   foreach x' such that there is an edge in G from x to x' do
       if D(x') = 0 then
        traverse(x')
       D(x) \longleftarrow min(D(x), D(x'));
       val(x) \longleftarrow val(x) \cup val(x');
   if D(x) = depth then
       repeat
           D(top(S)) \longleftarrow \infty;
           val(top(S)) \longleftarrow val(x) ;
       until pop(S) = x;
```

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