#### SHARED DATA ACCESS RISKS

# Shared data #define BUFFER SIZE 10 typedef struct { . . . } item; item buffer[BUFFER SIZE]; int in = 0; int out = 0; int counter = 0; Producer process item nextProduced; while (1) { while (counter == BUFFER SIZE); /\* do nothing \*/ buffer[in] = nextProduced; in = (in + 1) % BUFFER SIZE; counter++; Consumer process Item nextConsumed; while (1) { while (counter == 0); /\* do nothing \*/ nextConsumed = buffer[out]; out = (out + 1) % BUFFER SIZE; counter--;

#### SHARED DATA ACCESS RISKS

```
The statements
counter++;
counter--;
must be performed atomically.
```

Atomic operation means an operation that completes in its entirety without interruption.

```
The statement "count ++" may be implemented in machine language as:
register1 = counter
register1 = register1 + 1
counter = register1

The statement "count --" may be implemented as:
register2 = counter
register2 = register2 - 1
counter = register2
```

If both the producer and consumer attempt to update the buffer concurrently, the assembly language statements may get interleaved.

Interleaving depends upon how the producer and consumer processes are scheduled.

### INTERLEAVING EFFECT

Assume **counter** is initially 5. One interleaving of statements is:

The value of **count** may be either 4 or 6, where the correct result should be 5.

#### THE RACE CONDITION

**Race condition**: The situation where several processes access – and manipulate shared data concurrently. The final value of the shared data depends upon which process finishes last.

- Frequente nei sistemi operativi multitasking, sia per dati in user space sia per strutture in kernel.
- Estremamente pericolosa: porta al malfunzionamento dei processi cooperanti, o anche (nel caso delle strutture in kernel space) dell'intero sistema.
- Difficile da individuare e riprodurre: dipende da informazioni astratte dai processi (decisioni dello scheduler, carico del sistema, utilizzo della memoria, numero di processori, . . . )

To prevent race conditions, concurrent processes must be **synchronized**.

G. Piscitelli Politecnico di Bari pag. 4 di 20

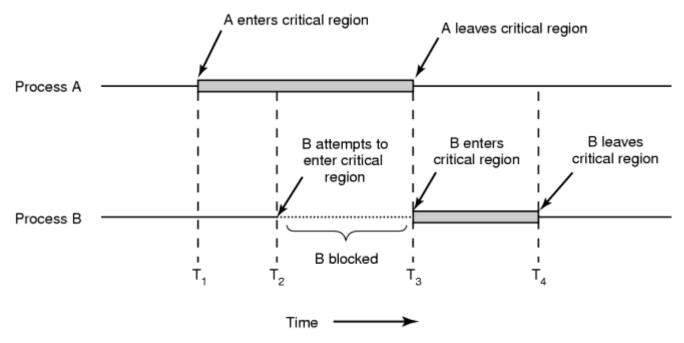
# THE CRITICAL-SECTION PROBLEM

- $\Rightarrow$  *n* processes all competing to use some shared data
- \( \brace \) Each process has a code segment, called *critical section*, in which the shared data is accessed.
- ▶ Problem to avoid a race condition, it is necessary to ensure that when one process is executing in its critical section, no other process is allowed to execute in its critical section.

G. Piscitelli Politecnico di Bari pag. 5 di 20

# SOLUTION TO CRITICAL-SECTION PROBLEM (1/2)

1. **Mutual Exclusion**. If process  $P_i$  is executing in its critical section, then no other processes can be executing in their critical sections. Each process must request permission to enter its critical section.



Mutual exclusion using critical regions

# SOLUTION TO CRITICAL-SECTION PROBLEM (2/2)

- 2. **Progress**. If no process is executing in its critical section and there exist some processes that wish to enter their critical section, then the selection of the processes that will enter the critical section next cannot be postponed indefinitely.
- 3. **Bounded Waiting**. A bound must exist on the number of times that other processes are allowed to enter their critical sections after a process has made a request to enter its critical section and before that request is granted.

Assume that each process executes at a nonzero speed

No assumption concerning relative speed of the *n* processes.

G. Piscitelli Politecnico di Bari pag. 7 di 20

# ATTEMPTS TO SOLVE THE CRITICAL-SECTION PROBLEM

```
Only 2 processes, P_i and P_j
```

```
General structure of process P_i (other process P_j)

do {

    entry section

        critical section

    exit section

    reminder section
} while (1);
```

Processes may share some common variables to synchronize their actions.

#### **ALGORITHM 1**

Satisfies mutual exclusion, but not progress requirement, since it requires strict alternation of processes in executing the critical section.

In fact, if turn == 0 and  $P_j$  is ready to enter its critical section, it cannot do so, even though  $P_i$  is in its remainder section.

# inadatto per processi con differenze di velocità

- è un esempio di busy wait: attesa attiva di un evento (es: testare il valore di una variabile).
- semplice da implementare
- può portare a consumi inaccettabili di cpu
- in genere, da evitare, ma a volte è preferibile (es. in caso di attese molto brevi)

#### **ALGORITHM 2**

## Shared variables:

## It is wrong.

In fact, the interleaving of the entry sections leads to a looping forever (deadlock) state for both the processes. Switching the instructions in the entry section will only lead to mutual exclusion violation.

## **BAKERY ALGORITHM**

# Critical section for n processes

Before entering its critical section, process receives a number. Holder of the smallest number enters the critical section.

If processes  $P_i$  and  $P_j$  receive the same number, if i < j, then  $P_i$  is served first; else  $P_j$  is served first.

The numbering scheme always generates numbers in increasing order of enumeration; i.e., 1,2,3,3,3,4,5...

G. Piscitelli Politecnico di Bari pag. 11 di 20

Sistemi Operativi

## **SYNCHRONIZATION HARDWARE**

Hardware features can solve the critical-section problem effectively.

Test and modify the content of a word atomically.

```
boolean TestAndSet(boolean &target) {
               boolean rv = target;
                target = true;
               return rv;
Shared data:
boolean lock = false;
Process P_i
       do
               while (TestAndSet(lock)) ;
                       critical section
                lock = false;
                       remainder section
```

## **SYNCHRONIZATION HARDWARE**

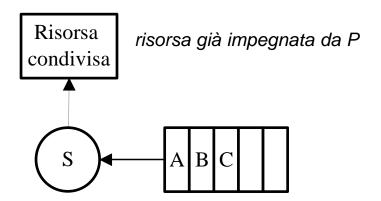
Atomically swap two variables.

```
void Swap(boolean &a, boolean &b) {
                boolean temp = a;
                a = b;
                b = temp;
Shared data (initialized to false):
boolean lock;
boolean waiting[n];
Process P_i
        do
                key = true;
                while (key == true)
                        Swap(lock,key);
                        critical section
                        lock = false;
                        remainder section
```

### **SEMAPHORES**

```
Synchronization tool that does not require busy waiting.
```

- $\$  Semaphore S integer variable
- \( \square\) can only be accessed via two indivisible (atomic) operations



coda dei processi in attesa

Normalmente, l'attesa è implementata spostando il processo in stato di wait, mentre la up(S) mette uno dei processi eventualmente in attesa nello stato di ready.

I nomi originali erano **P** (proberen, testare) e **V** (verhogen, incrementare)

# **COUNTING SEMAPHORES**

- *Counting* semaphore integer value can range over an unrestricted domain.
- \*\* Binary semaphore integer value can range only between 0 and 1; can be simpler to implement.
- $\mathcal{F}$  Can implement a counting semaphore S as a binary semaphore.

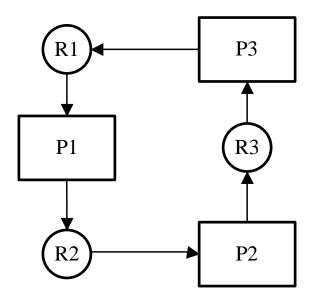
## IMPLEMENTING S AS A BINARY SEMAPHORE

```
Data structures:
        binary-semaphore S1, S2;
        int C:
Initialization:
        S1 = 1
        S2 = 0
        C = initial value of semaphore S
wait operation
        wait(S1);
        C--;
        if (C < 0) {
                         signal(S1);
                        wait(S2);
        signal(S1);
signal operation
        wait(S1);
        C ++;
        if (C \le 0)
                signal(S2);
        else
                signal(S1);
```

# **MUTUAL EXCLUSION RISKS**

## Deadlock and Starvation

Deadlock – two or more processes are waiting indefinitely for an event that can be caused by only one of the waiting processes.



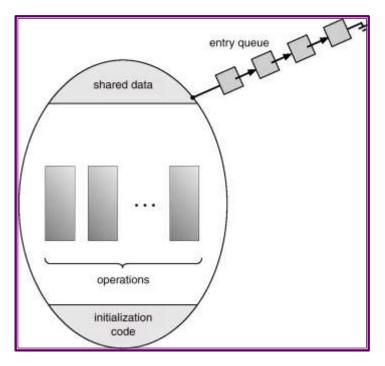
Starvation − indefinite blocking. A process may never be removed from the semaphore queue in which it is suspended.

#### **MONITOR**

High-level synchronization construct that allows the safe sharing of an abstract data type among concurrent processes.

- Un monitor è un tipo di dato astratto che fornisce funzionalità di mutua esclusione
  - collezione di dati privati e funzioni/ procedure per accedervi.
  - i processi possono chiamare le procedure ma non accedere alle variabili locali.
  - un solo processo alla volta può eseguire codice di un monitor
- Il programmatore raccoglie quindi i dati condivisi e tutte le sezioni critiche relative in un monitor; questo risolve il problema della mutua esclusione
- Implementati dal compilatore con dei costrutti per mutua esclusione

## **MONITOR**



To allow a process to wait within the monitor, a **condition** variable must be declared, as **condition x**, **y**;

Condition variable can only be used with the operations wait and signal.

The operation

```
x.wait();
```

means that the process invoking this operation is suspended until another process invokes

The **x.signal** operation resumes exactly one suspended process. If no process is suspended, then the **signal** operation has no effect.

```
x.signal();
```

Sistemi Operativi

# **MONITOR**

