Edouard Castets

Machine and Deep Learning & Autonomous Systems Engineer

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EDUCATION

Illinois Institute of Technology - Chicago, IL, USA

(August 2022)

Master of Engineering in Aerospace Engineering – Machine Learning and Autonomous Systems (Double degree program)

Relevant coursework: Machine & Deep Learning, Tensor Calculus, Autonomous Systems, Optimization, Data Analysis, Cybersecurity

ISAE-ENSMA – Poitiers, France

(August 2022)

Diplôme d'Ingénieur (equivalent to Master's degree) in Aeronautical Engineering

Relevant coursework: Tensor Calculus, Signal Processing, Embedded Systems, Probabilities, Differential Calculus, Autonomous Systems, Data Managing, Computer Science (C++, Python, ADA)

TECHNICAL SKILLS

Languages: Python, C#, C++, Javascript, React JS, HTML, SQL, Matlab, ADA, PHP, Java

Data Science: Pytorch, Pytorch Profiler, Computer Vision(OpenCV & Torch Vision), Cafee, Pyspark, Databricks,

Tensorflow, Scikit-learn, Pandas, Numpy, Scipy, Deep Face Lab, Google Earth Engine API Technologies: : Linux, Git, Github Actions, VSC, Pytest, Docker, Kubernetes, TCP/IP/, ssh, BLE Software: Unity (MRTK), Google Earth Pro, CAO (CatiaV6, Fusion 360), Pack Office, MAMP

Hardware: Raspberry PI, HoloLens 2, Data Collection devices (Empatica E4, Pupil Core Device), drones FPV (Anafi)

Cloud: AWS (S3, Lambda,...), Azure Storage & Active Directory, Google Colab.

EXPERIENCE

THALES Thales SIX GTS - Vélizy, France

(June 2023 - Today)

Service Mission: Software Engineer Python/Java

> Development of a data validation solution

Skills: Java, JavaFx, Python, Git.

Pacte Novation – Issy Les Moulineaux, France

(May 2023 - Today)

Research in Machine and Deep Learning for cross-view geolocation (GEO-INT)

- Research and development on a deep learning model that correlates UAV images with a satellite view for geolocation. Model based on Swin-B & Focal Transformer.
- Scraping and building of a database for geolocation

Skills: Google Earth Pro, Google Earth Engine, XML, Python, Pytorch, Pytorch Profiler, GEOINT, Git, Research Methods.

Parrot Parrot SA – Paris, France

(March 2023 - May 2023)

Service Mission: Machine and Deep Learning in stereovision for UAV

- Built multiple Deep Learning vision models for depth estimation
- Database analysis and fine-tuning
- Development of a data visualization tool based on Napari

Skills: Deep Learning, Python, Computer Vision, Pytorch, Cafee, Embedded Systems, Git, Linus, Napari, Pandas.

Civil Engineering Laboratory – Illinois Institute of Technology Research in Machine and Deep Learning

(January 2022 - January 2023)

Built multiple Deep Learning models to assess users' cognitive abilities during problem-solving tasks in an augmented

- reality environment. Data collection on students (created an application for augmented reality environment, HoloLens 2), data ethics.
- Data collection system for real-time collection and inference.
- Research paper (ICCCBE 2022).

Skills: Deep Learning, Python, Unity (MRTK), C#, Python, Network, Embedded Systems, Research Methods.

PROJECTS €

- IA image generation, implementation DC-GAN & W-GAN with Mini-Batch Discrimination
- Deep learning model for heart rate prediction
- Turnover prediction for stores (for next 8 weeks) using LSTM
- Image classification for faces and for drone images both based on GoogLeNet implementation
- Optimization method with deep learning
- ReactJs portfolio

INTERESTS & MISCELLANEOUS

Languages Spoken: Native French speaker, fluent in English with 1 year spent in the USA (ETS TOIEC score 945/990 -C2 CECRL), Spanish (B1 CECRL)

Interests: New technologies, Cybersecurity, OSINT, Geopolitics, Swimming, Music, Video Games, Travel (USA, Ireland, Germany...)