

Digital Image & Video Processing

Lecture 9 Image Segmentation



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9. Image Segmentation

9.1. Problem Statement

9.2. Method

9.3. Applications

9.1. Problem Statement

Let us suppose that an image domain I must be segmented in N different regions R_1, R_2, \dots, R_N .

It is necessary to determine a segmentation rule is a logical predicate of the form $P(R)$ having the following properties:

$$I = \bigcup_{i=1}^N R_i$$

$$R_i \cap R_j = \emptyset, \quad i \neq j$$

$$P(R_i) = \text{True}, \quad i = 1, 2, \dots, N$$

$$P(R_i \cup R_j) = \text{False}, \quad i \neq j$$

9.2. Method

9.2.1. Region growing method

Principle

Geometrical proximity + homogeneity -> connected image regions.

9.2. Method

9.2.1. Region growing method

Method

- Starting from some pixels (seeds) representing distinct image regions and to grow them, until they cover the entire image.
- In order to implement region growing, we need determine:
 - . Seeds
 - . A rule describing a growth mechanism.
 - . A rule checking the homogeneity of the regions after each growth step..

9.2. Method

9.2.1. Region growing method

Method

. Seeds

Based on the histogram, choose the seed points corresponding to the histogram peaks.

9.2. Method

9.2.1. Region growing method

Method

. A rule describing a growth mechanism
Growing based on 8-neighborhood.

9.2. Method

9.2.1. Region growing method

Method

. A rule checking the homogeneity of the regions after each growth step.

At each step k , for each region $R_i^{(k)}, i = 1, 2, \dots, N$

We check if there are unclassified pixels in the 8-neighbourhood of each pixel of the region border.

If $P(R_i^{(k)} \cup \{b_i^{(k)}(x, y)\}) = \text{True}$ assigning $b_i^{(k)}(x, y)$ to region $R_i^{(k)}$.

9.2. Method

9.2.1. Region growing method

Method

. A rule checking the homogeneity of the regions after each growth step.

$$|f(x, y) - m(R_i^{(k)})| < T$$

$$m(R_i^{(k)}) = (1 / N(R_i^{(k)})) \sum_{(k,l) \in R_i^{(k)}} f(k, l)$$

$$\sigma(R_i^{(k)}) = \left[(1 / N(R_i^{(k)})) \sum_{(k,l) \in R_i^{(k)}} (f(k, l) - m(R_i^{(k)}))^2 \right]^{1/2}$$

9.2. Method

9.2.1. Region growing method

Method

. A rule checking the homogeneity of the regions after each growth step.

$$m(R_i^{(k+1)}) = (1 / (N(R_i^{(k)}) + 1)) [f(x, y) + N(R_i^{(k)}) m(R_i^{(k)})]$$

$$\sigma(R_i^{(k+1)}) = \left[(1 / (N(R_i^{(k)}) + 1)) [N(R_i^{(k)}) \sigma^2(R_i^{(k)}) + (N(R_i^{(k)}) / (N(R_i^{(k)}) + 1)) (f(x, y) - m(R_i^{(k)}))^2] \right]^{1/2}$$

9.2. Method

9.2.1. Region growing method

Method

. A region merging rule.

$$|m(R_i^{(k+1)}) - m(R_{i'}^{(k+1)})| < k\sigma(R_i^{(k+1)})$$

$$|m(R_i^{(k+1)}) - m(R_{i'}^{(k+1)})| < k\sigma(R_{i'}^{(k+1)})$$

9.2. Method

9.2.2. K-means method

Principle

Unsupervised Clustering homogeneity regions -> Image Regions.

9.2. Method

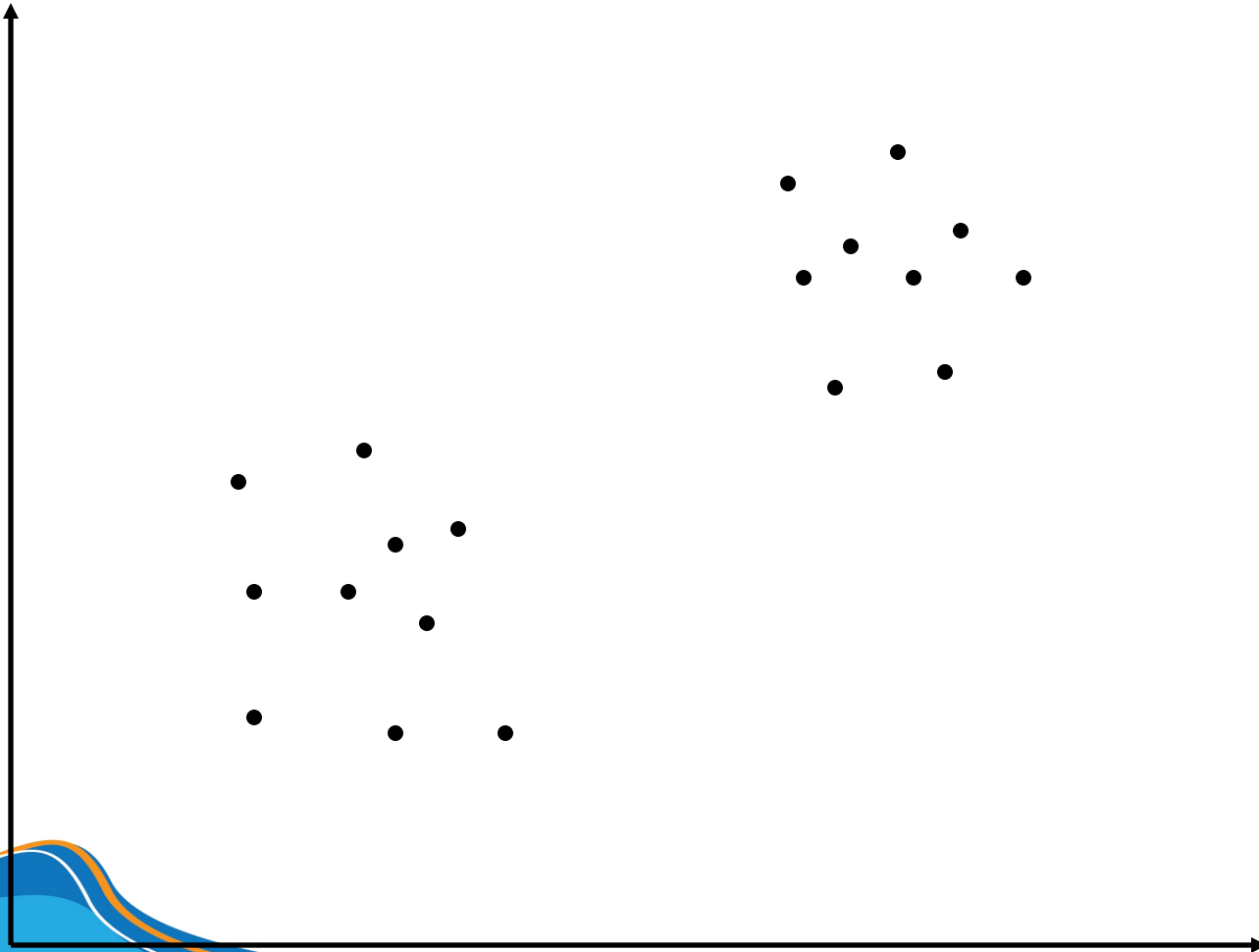
9.2.2. K-means method

Method

1. Partition the data points into K clusters randomly. Find the centroids of each cluster.
2. For each data point:
 - Calculate the distance from the data point to each cluster.
 - Assign the data point to the closest cluster.
3. Recompute the centroid of each cluster.
4. Repeat steps 2 and 3 until there is no further change in the assignment of data points (or in the centroids).

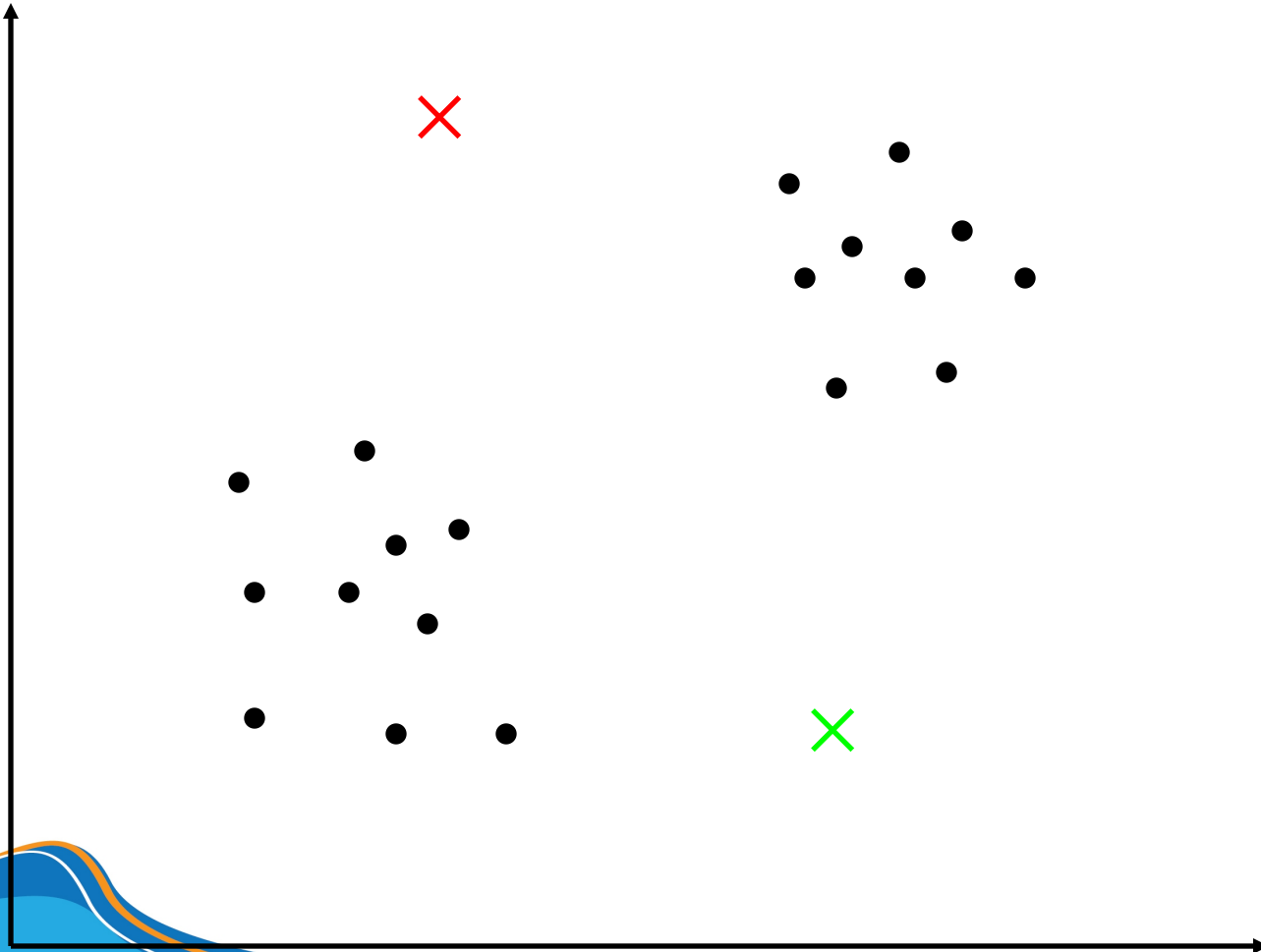
9.2. Method

9.2.2. K-means method



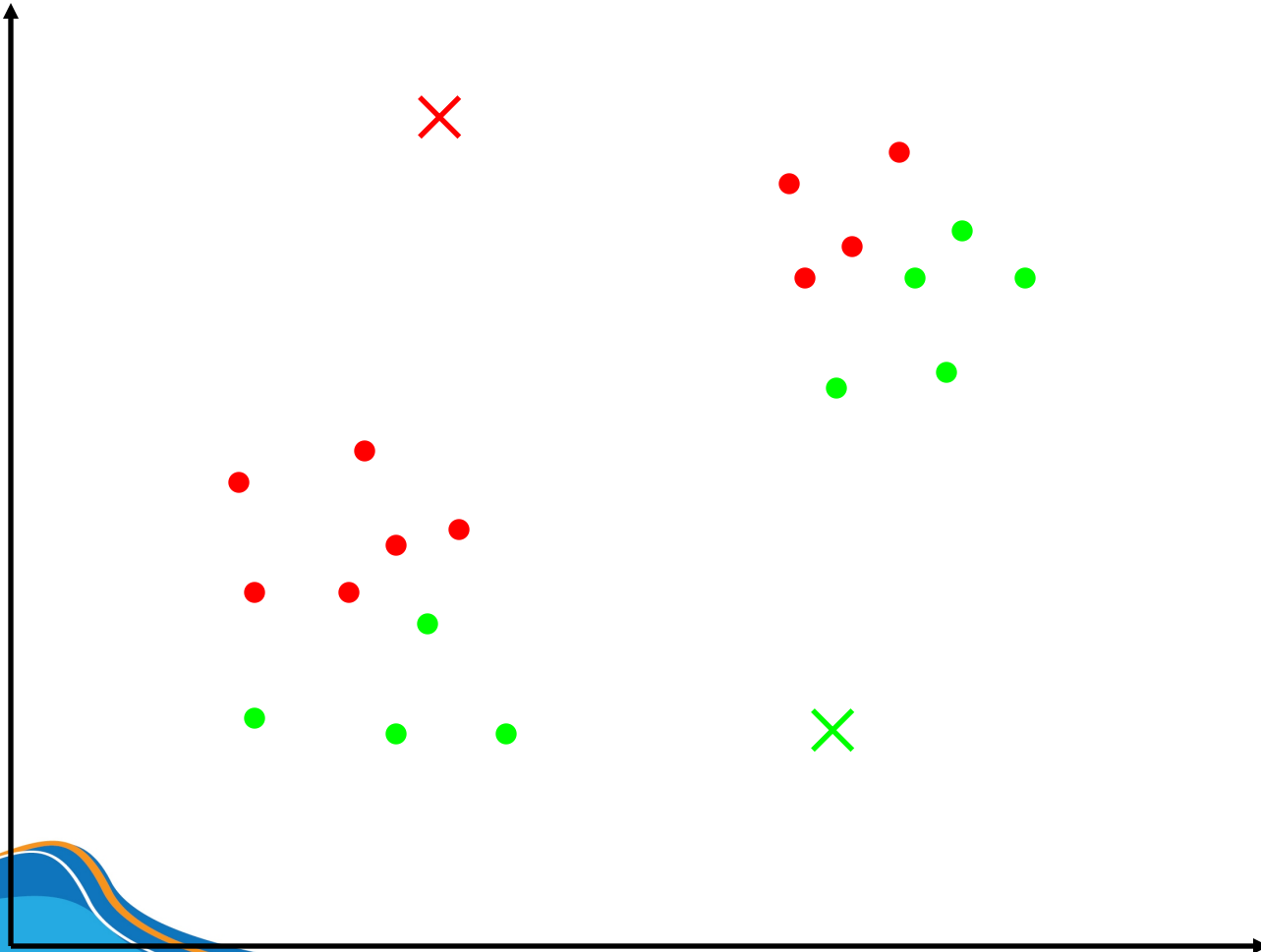
9.2. Method

9.2.2. K-means method



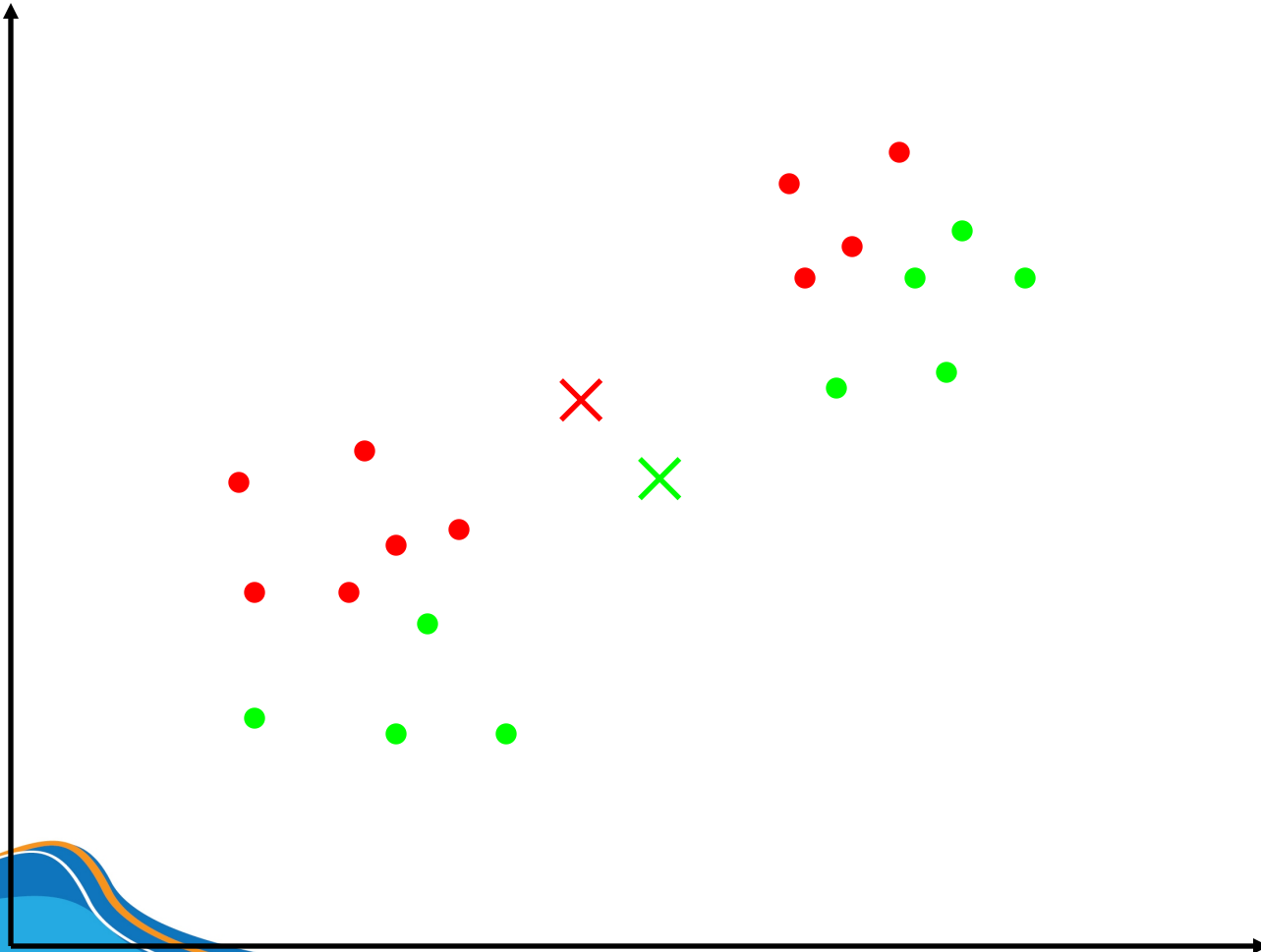
9.2. Method

9.2.2. K-means method



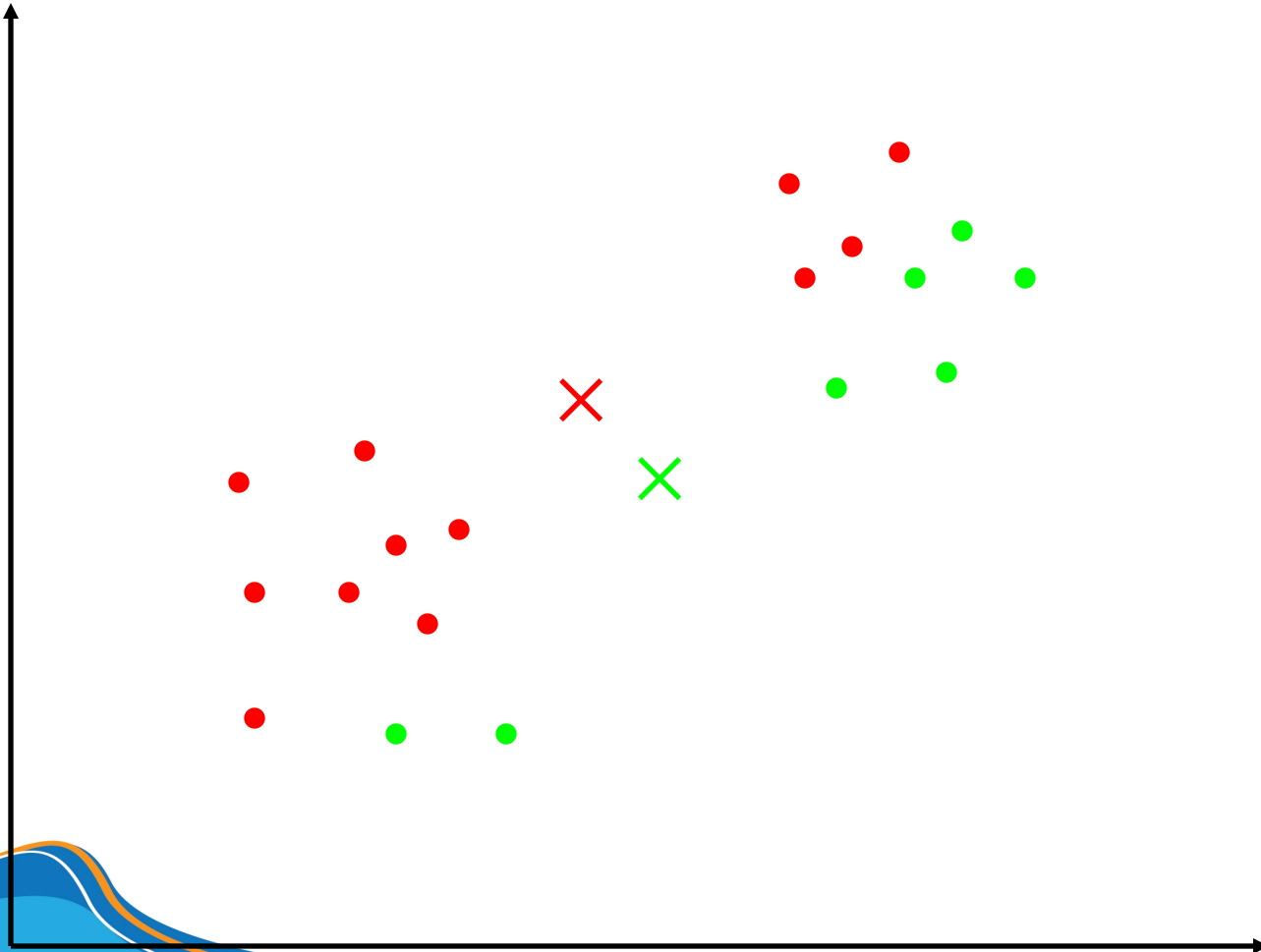
9.2. Method

9.2.2. K-means method



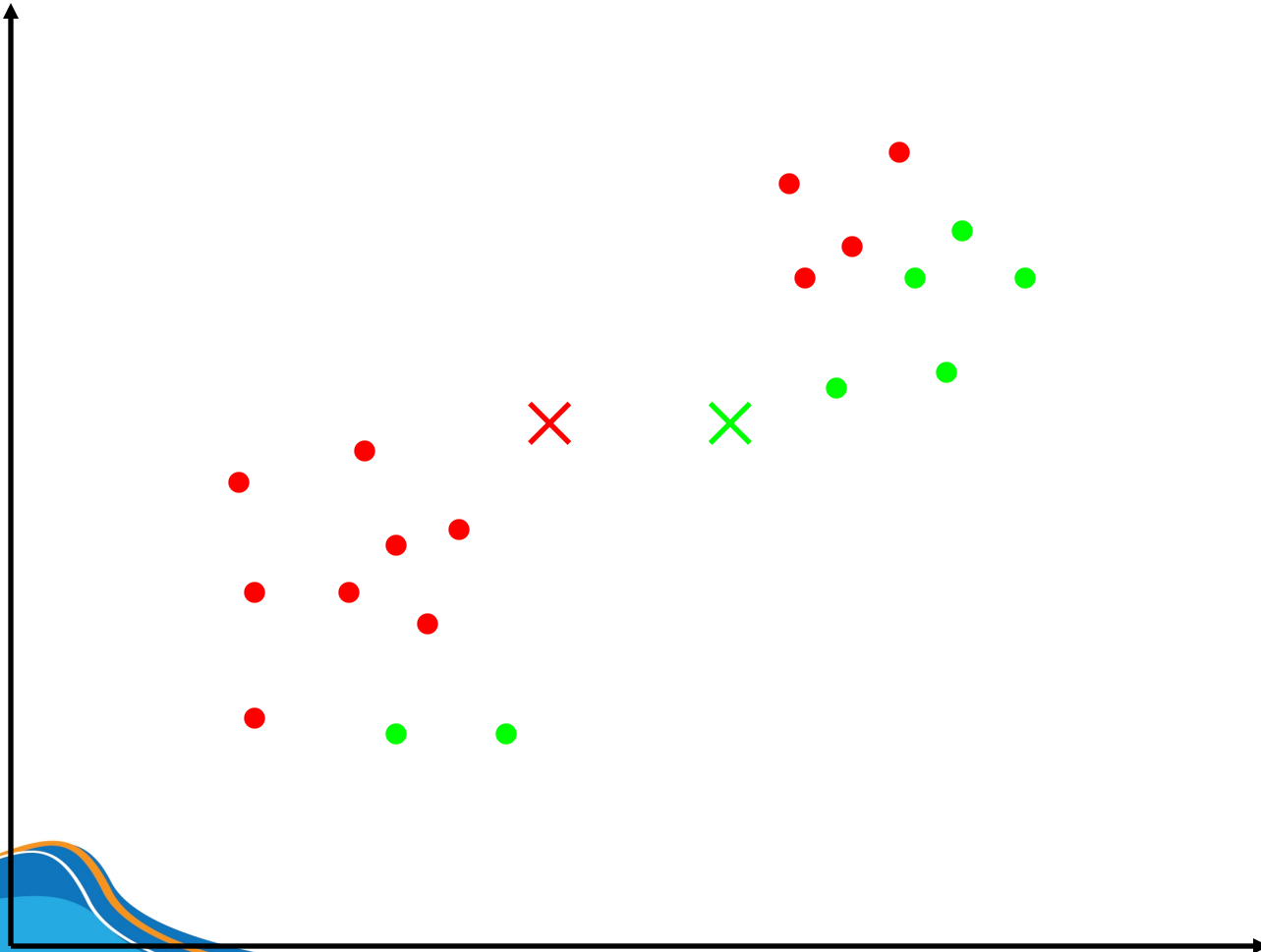
9.2. Method

9.2.2. K-means method



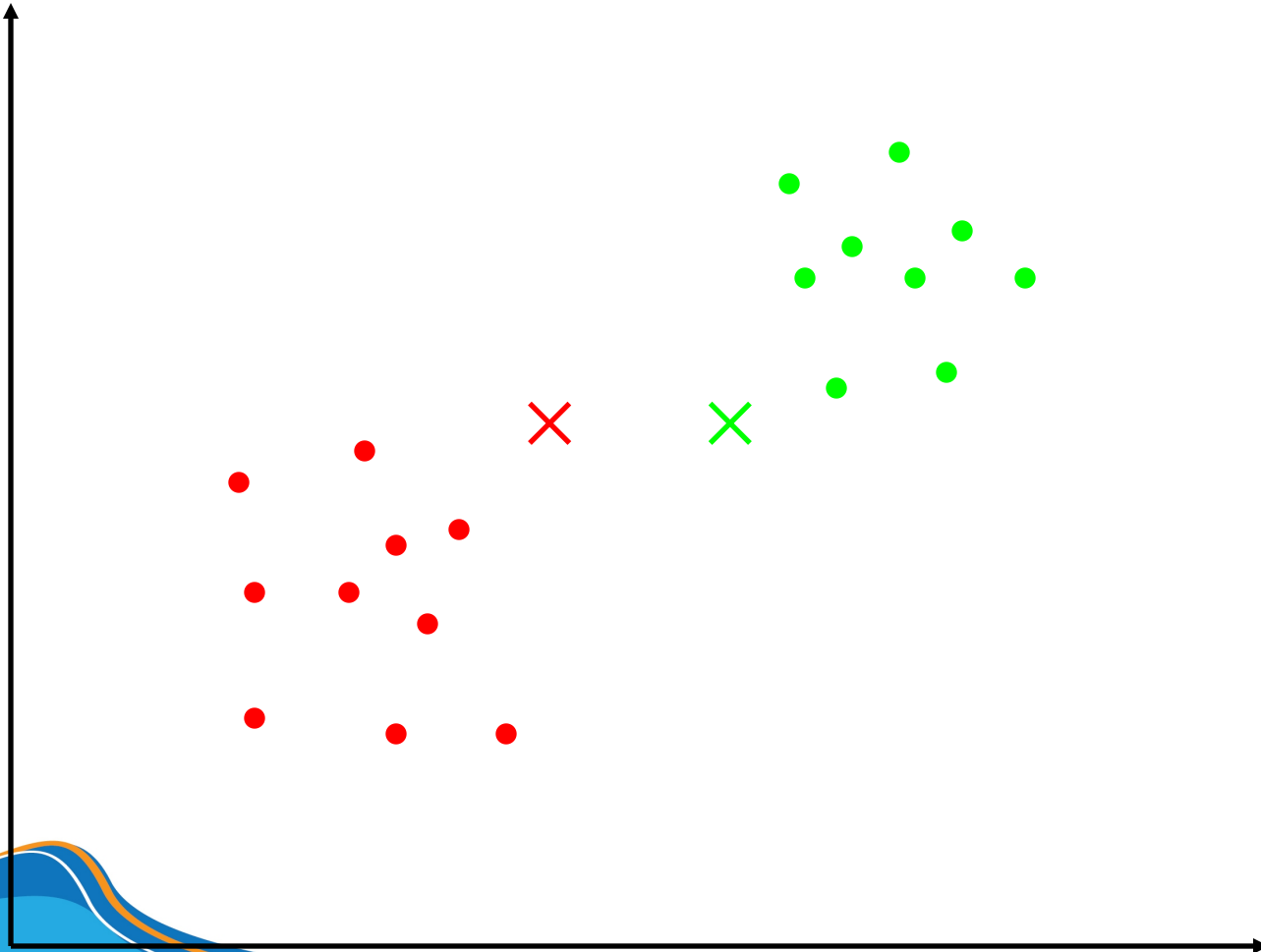
9.2. Method

9.2.2. K-means method



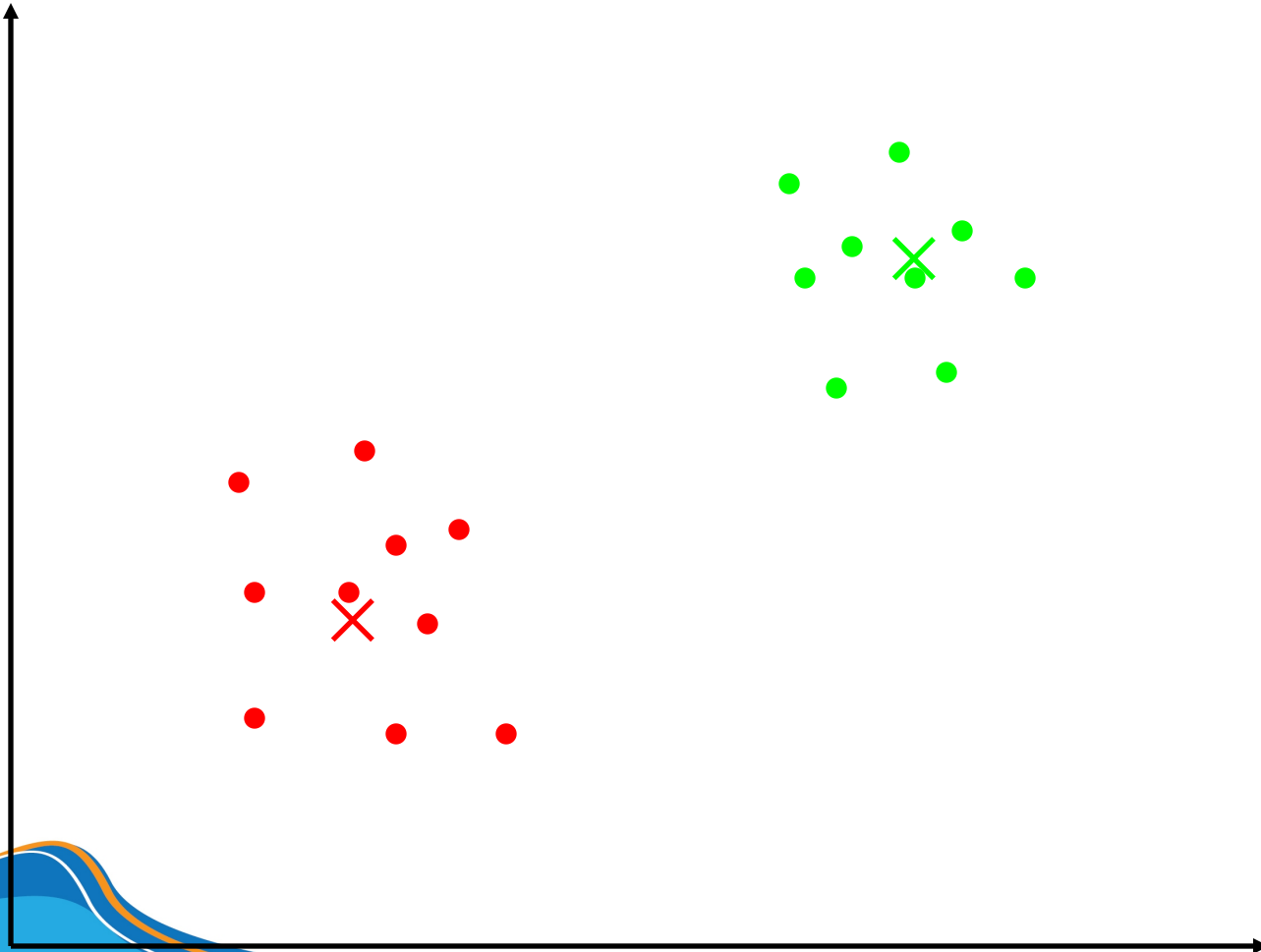
9.2. Method

9.2.2. K-means method



9.2. Method

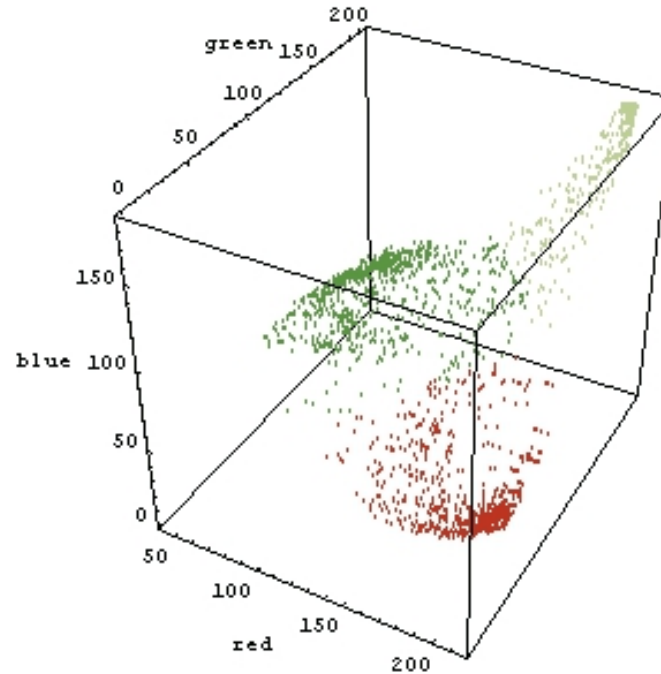
9.2.2. K-means method



9.2. Method

9.2.2. K-means method

- RGB vector



K-means clustering minimizes

$$\sum_{i \in \text{clusters}} \left\{ \sum_{j \in \text{elements of } i\text{'th cluster}} \|x_j - \mu_i\|^2 \right\}$$

9.2. Method

9.2.2. K-means method

- Example



Original



K=5



K=11

9.2. Method

9.2.2. K-means method

Algorithm

Function $K - means()$

Initialize k prototypes (w_1, \dots, w_k) such that $w_j = i_l, j \in \{1, \dots, k\}, l \in \{1, \dots, n\}$

Each cluster C_j is associated with prototype w_j

Repeat

For each input vector i_l , where $l \in \{1, \dots, n\}$,

do

Assign i_l to cluster C_{j^*} with nearest prototype w_{j^*}

For each cluster C_j , where $j \in \{1, \dots, k\}$, do

Update the prototype w_j to the centroid of all samples

currently in C_j , so that $w_j = \sum_{i_l \in C_j} i_l / |C_j|$

Computer the error function :

$$E = \sum_{j=1}^k \sum_{i_l \in C_j} |i_l - w_j|^2$$

Until E does not change significantly or cluster membership no longer changes