Piece-wise exponential (Additive Mixed) Modeling Tools

ISCB41, 2020

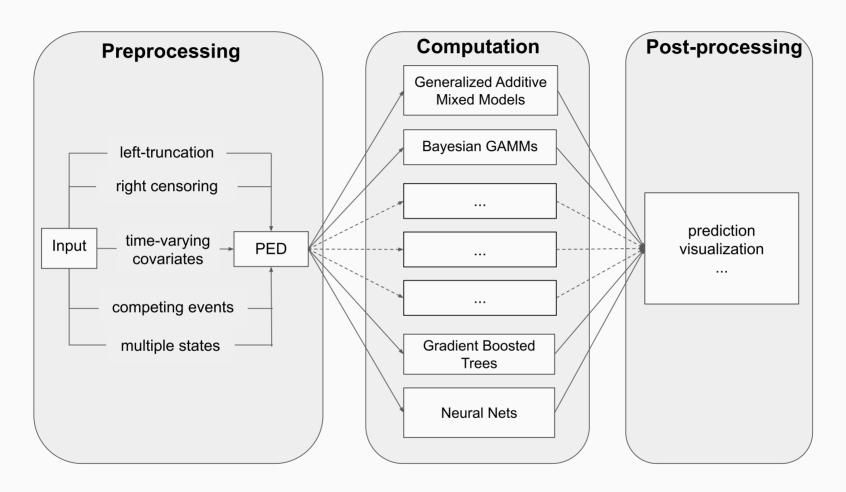
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Department of Statistics, LMU Munich

The framework is *general* in the sense that

- 1. it supports different Survival Tasks
 - right-censoring, left-truncation
 - time-varying effects, time-varying features
 - cumulative effects (weighted cumulative exposure, distributed lag models)
 - competing risks, multi-state models
- 2. does not require specialized Software, can be applied
 - across programming languages and
 - using any algorithm that supports optimization of the Poisson Likelihood



(source: Bender, et al. (2020))

Survival Analysis as Poisson Regression

ullet we observe $(t_i,\delta_i), i=1,\ldots,n$, where

$$\circ \ \ t_i = \min(T_i, C_i)$$
; $T_i \sim F \perp C_i \sim G; T_i, C_i > 0$

$$\circ \ \ \delta_i = I(T_i \leq C_i) \in \{0,1\}$$

To approximate

$$\lambda(t;\mathbf{x}_i) = \exp(g(\mathbf{x}_i(t),t)) \overset{PH}{=} \lambda_0(t) \exp(\mathbf{x}_i'oldsymbol{eta})$$

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- assume piece-wise constant hazards:

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- Estimation using
 - Piece-wise Exponential Model (PEM; e.g.: Laird, et al. (1981); Friedman (1982); Carstensen, et al. (2011))
 - Piece-wise exponential Additive Mixed Models (PAMM, e.g.: Cai, et al. (2002); Kauermann (2005); Argyropoulos, et al. (2015); Bender, et al. (2018))

Data in "standard" time-to-event format

| ID (i) | t(i) | status(i) | age(i) |
|--------|------|-----------|--------|
| 1 | 1.3 | 0 | 31 |
| 2 | 0.5 | 0 | 67 |
| 3 | 2.7 | 1 | 42 |

| ID (i) | j | interval | status(i,j) | t(i,j) | t(j) | age(i) |
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ight.$, $t_j := \kappa_j$

$$egin{aligned} \ell_i &= \log(\lambda(t_i; \mathbf{x}_i)^{\delta_i} S(t_i; \mathbf{x}_i)) \ &= \sum_{j=1}^{J_i} \left(\delta_{ij} \log \lambda_{ij} - \lambda_{ij} t_{ij}
ight) \end{aligned}$$

Data in PED format

| ID (i) | j | interval | status(i,j) | t(i,j) | t(j) | age(i) | |
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Working Assumption $\delta_{ij} \stackrel{iid}{\sim} Po(\mu_{ij} = \lambda_{ij}t_{ij})$:

$$egin{aligned} \ell_i &= \log\Biggl(\prod_{j=1}^{J_i} f(\delta_{ij})\Biggr) \ &= \sum_{j=1}^{J_i} \delta_{ij} \log(\lambda_{ij}) + \delta_{ij} \log(t_{ij}) - \lambda_{ij} t_{ij} \end{aligned}$$

Competing risks setting with event types $k \in \{1,2\}$

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ightarrow transform to PED using $\kappa_0=0, \kappa_1=1, \kappa_2=1.5, \kappa_3=3$

ightarrow estimate $\lambda(t|\mathbf{x},k) = \exp(f(\mathbf{x}(t),t,k)), \; k \in \{1,2\}$

Data in PED format

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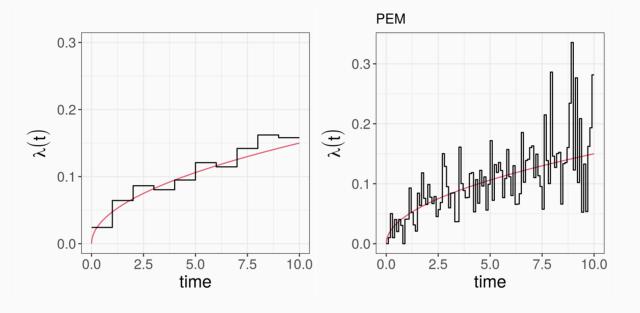
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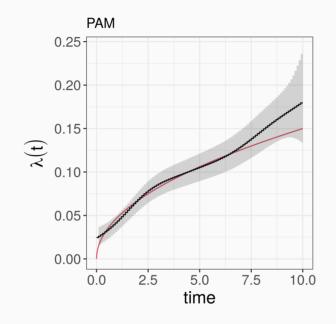
| 2 3.33 22 707111010 | | | | | | |
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PEM/GLM: $\lambda(t) = \lambda_{0j} = \exp(eta_{0j}), orall t \in (\kappa_{j-1},\kappa_j], j=1,\ldots,J$



- trade of w.r.t. to number of split points (less flexible/more robust vs. more flexible/less robust)
- computationally inefficient (one parameter for each interval), especially when considering time-varying effects
- results sensitive to number and placement of interval cut points

PAMM/GAMM: $\lambda(t)=\lambda_{0j}=\exp(f_0(t_j)), orall t\in (\kappa_{j-1},\kappa_j], j=1,\ldots,J; \ f_0(t_j)=\sum_{q=1}^Q eta_{0q}B_{0q}(t_j)$



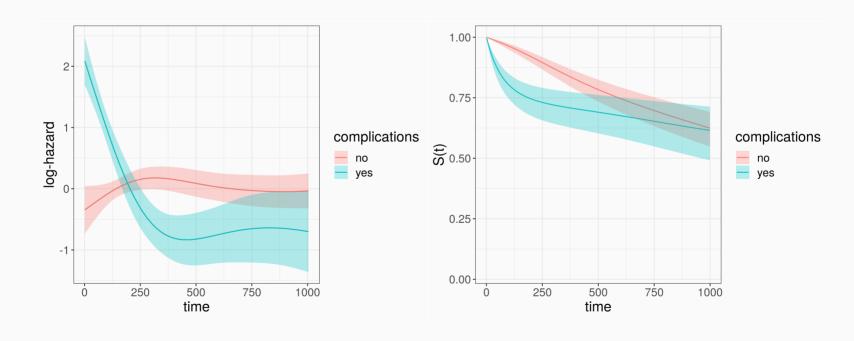
- large differences between neighboring coefficients/baseline hazards of neighboring intervals are penalized
- insensitive to number and placement of split points
- ullet number of parameters to estimate determined by basis dimension Q, not number of intervals J

Time-varying effects

In the PEM/PAMM framework, time-varying effects are simply interactions of time t_i and other covariates.

$$\log(\lambda(t|x)) = f_{01}(t_j)I(complications = yes) + f_{02}(t_j)I(complications = no)$$

 $pam_tumor \leftarrow mgcv::gam(formula=ped_status \sim s(tend, by=complications), data=ped_tumor, family=poisson(), offset=offset)$



```
# "Regular" GAM
mgcv::gam(formula=ped_status~s(tend, by=complications), data=ped_tumor, family=poisson(), offset=offset)
# GAM with monotinicity constraints
scam::scam(formula=ped_status~s(tend, by=complications, bs = "mpd"), data=ped_tumor, family=poisson(), offset=offset)
# Bayesian GAM
brms::brm(formula=ped_status~s(tend, by=complications) + offset(offset), data=ped_tumor, family=poisson())
```

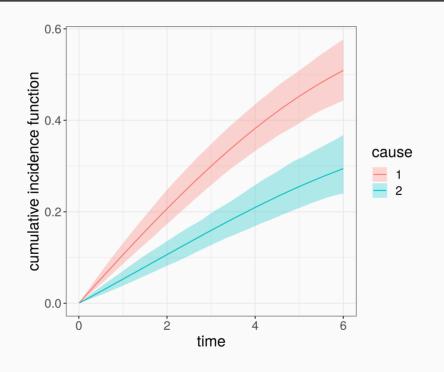
y@adibender

Competing Risks

$$\log(\lambda(t|x)) = f_{01}(t_j)I(k=1) + f_{01}(t_j)I(k=2)$$

Cause specific hazards are time-varying effects of time t_j and covariate "event type" k

pam_cr ← mgcv::gam(formula = ped_status ~ s(tend, by = cause), data = ped_stacked, family = poisson(), offset = offset)



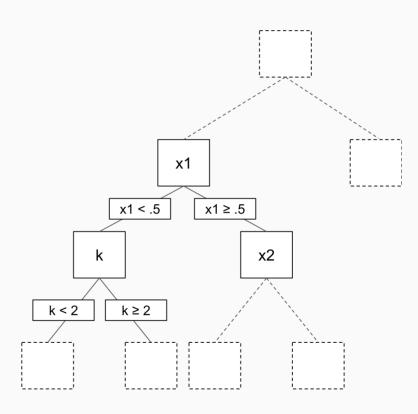
Tree based methods

Time-varying effects

(A) x1 x1 < .5 x1 ≥ .5 x2 t < 3 t ≥ 3

Shared vs. cause-specific effects (in CR)

(B)



(source: Bender, et al. (2020))

The pammtools package

PEMs/PAMMs powerfull framework for survival analysis, but cumbersome to work with

pammtools facilitates

- data transformation (as_ped):
 - right-censoring
 - cumulative effects
 - competing risks
- post-processing:
 - prediction (add_hazard, add_surv_prob, add_cif),
 - model evaluation (integrated brier score via pec)
- convenience functions for visualisation, ...

Reference

Articles ▼

News

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pammtools: Piece-Tools

Installation

Install from CRAN or GitHub using:

CRAN
install.packages("pammtools")

GitHub

devtools::install_github("adibe

Data transformation

Estimating the baseline hazard

Basic modeling

Workflow and convenience functions

Stratified models

Non-linear effects (penalized splines)

Time-varying effects (TVEs)

Frailties (random effects)

Time-dependent covariates (TDCs)

Model evaluation

Cumulative effects/Exposure-Lag-Response Associations

Competing Risks

Paper: A generalized additive model approach to time-to-event analysis

deling

Links

Download from CRAN at

https://cloud.r-project.org/ package=pammtools

Browse source code at

https://github.com/adibender/pammtools/

Report a bug at

https://github.com/adibender/pammtools/issues

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Citation

Citing pammtools

Developers

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Author, maintainer (i)

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Philipp Kopper

Author

Overview

pammtools facilitates the estimation of Piece-wise exponential Additive Mixed Models (PAMMs) for time-to-event data. PAMMs can be represented as generalized additive models and can therefore be estimated using GAM software (e.g. mgcv), which, compared to other packages for survival analysis, often offers more flexibility w.r.t. to the specification of covariate effects (e.g. non-linear, time-varying effects, cumulative effects, etc.).

To get started, see the Articles section.



Outlook

- support for multi-state models
- facilitate extensions: S3 functions for calculation of hazard for other packages (e.g. mbooost, brms)
- Prototype for PEMs using **xgboost** available: https://github.com/adibender/pem.xgb
- However, ML algorithms need a different infrastructure (resampling, tuning, benchmarking)
 - → Development will probably continue in mlr3 and mlr3proba (Lang, et al. (2019); Sonabend, et al. (2020))

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