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14-513

18-613

Exceptional Control Flow: Exceptions and Processes

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15-213/18-213/14-5

n to Computer Systems

19th Lecture, Novem

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Printers Used to Catch on Fire

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Highly Exceptional Control Flow

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<https://git.kernel.org/pub/scm/linux/kernel/git/torvalds/linux.git/tree/drivers/char/lp.c?h=v5.0-rc3>

Today

- **Exceptional Control Flow** CSAPP 8
- **Exceptions** CSAPP 8.1
- **Processes** CSAPP 8.2
- **Process Control** CSAPP 8.3-8.4

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Control Flow

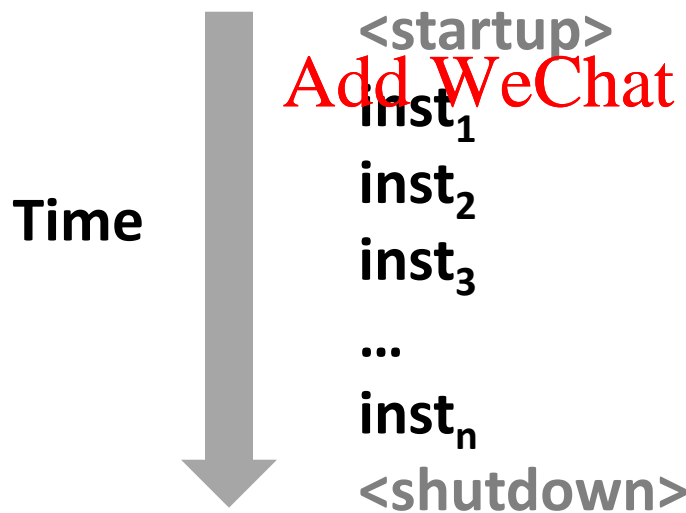
■ Processors do only one thing:

- From startup to shutdown, each CPU core simply reads and executes (interprets) a sequence of instructions, one at a time *
- This sequence is the CPU's *control flow* (or *flow of control*)

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- * Externally, from an architectural viewpoint (internally, the CPU may use parallel out-of-order execution)

Altering the Control Flow

■ Up to now: two mechanisms for changing control flow:

- Jumps and branches
- Call and return

React to changes in ~~program state~~

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■ Insufficient for <https://eduassistpro.github.io/>

Difficult to react to changes in s

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- Data arrives from a disk or a netwo
- Instruction divides by zero
- User hits Ctrl-C at the keyboard
- System timer expires

■ System needs mechanisms for “exceptional control flow”

Exceptional Control Flow

- **Exists at all levels of a computer system**
- **Low level mechanisms**
 - 1. **Exceptions**
 - Change in control flow in response to a system event (i.e., change
 - Implemented in hardware and OS software
- **Higher level mechanisms**
 - 2. **Process context switch**
 - Implemented by OS software and hardware timer
 - 3. **Signals**
 - Implemented by OS software
 - 4. **Nonlocal jumps**: `setjmp()` and `longjmp()`
 - Implemented by C runtime library

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Today

- Exceptional Control Flow
- **Exceptions**
- Processes
- Process Control

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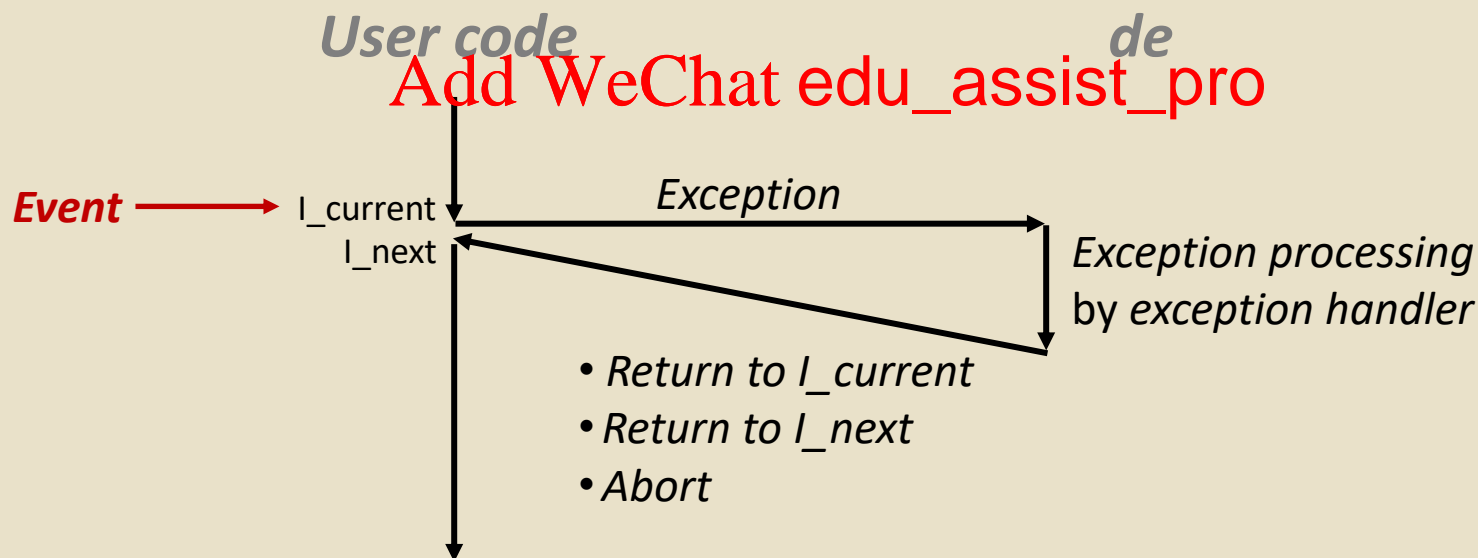
Exceptions

- An **exception** is a transfer of control to the OS *kernel* in response to some *event* (i.e., change in processor state)
 - Kernel is the memory-resident part of the OS
 - Examples of events: Divide by 0, arithmetic overflow, page fault, I/O request complet

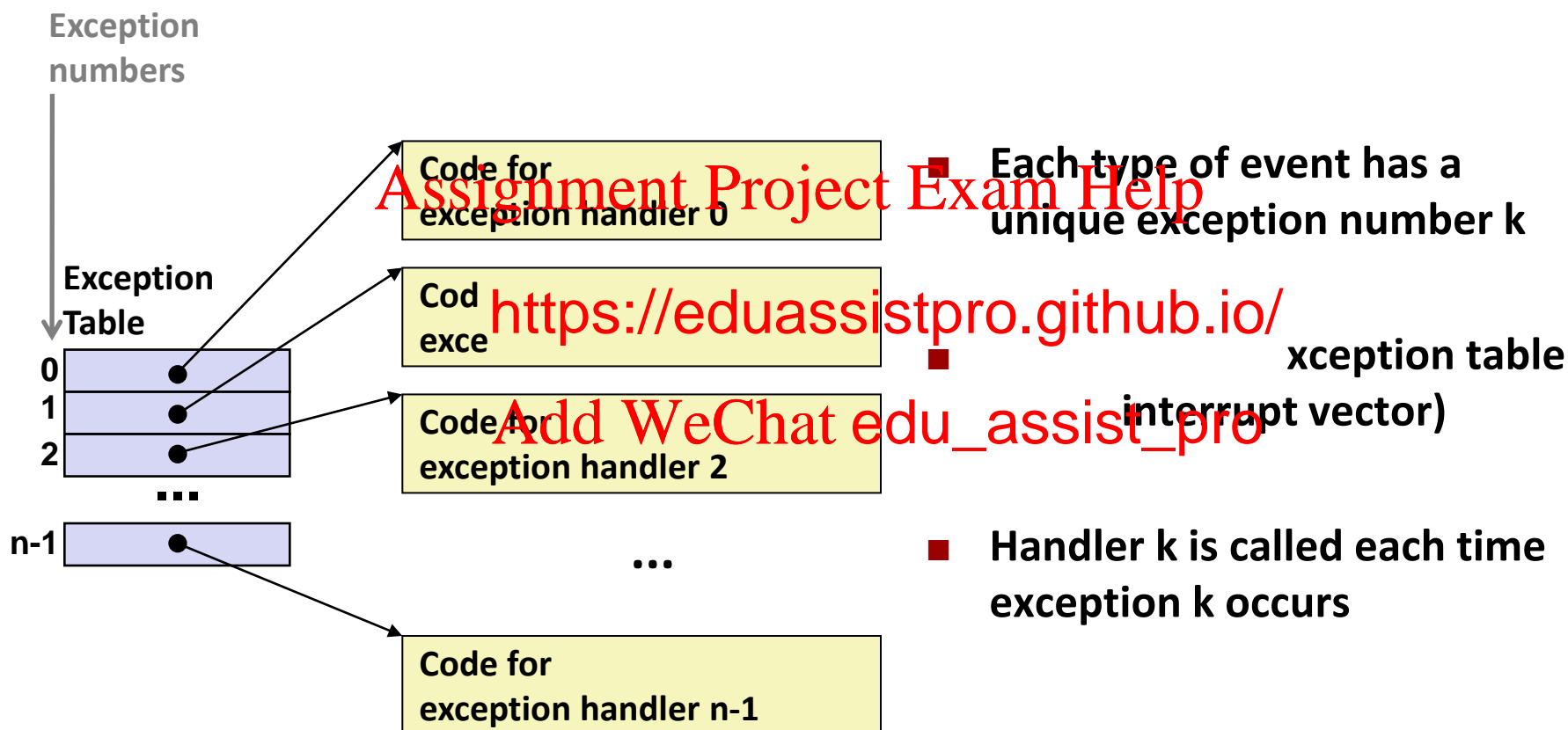
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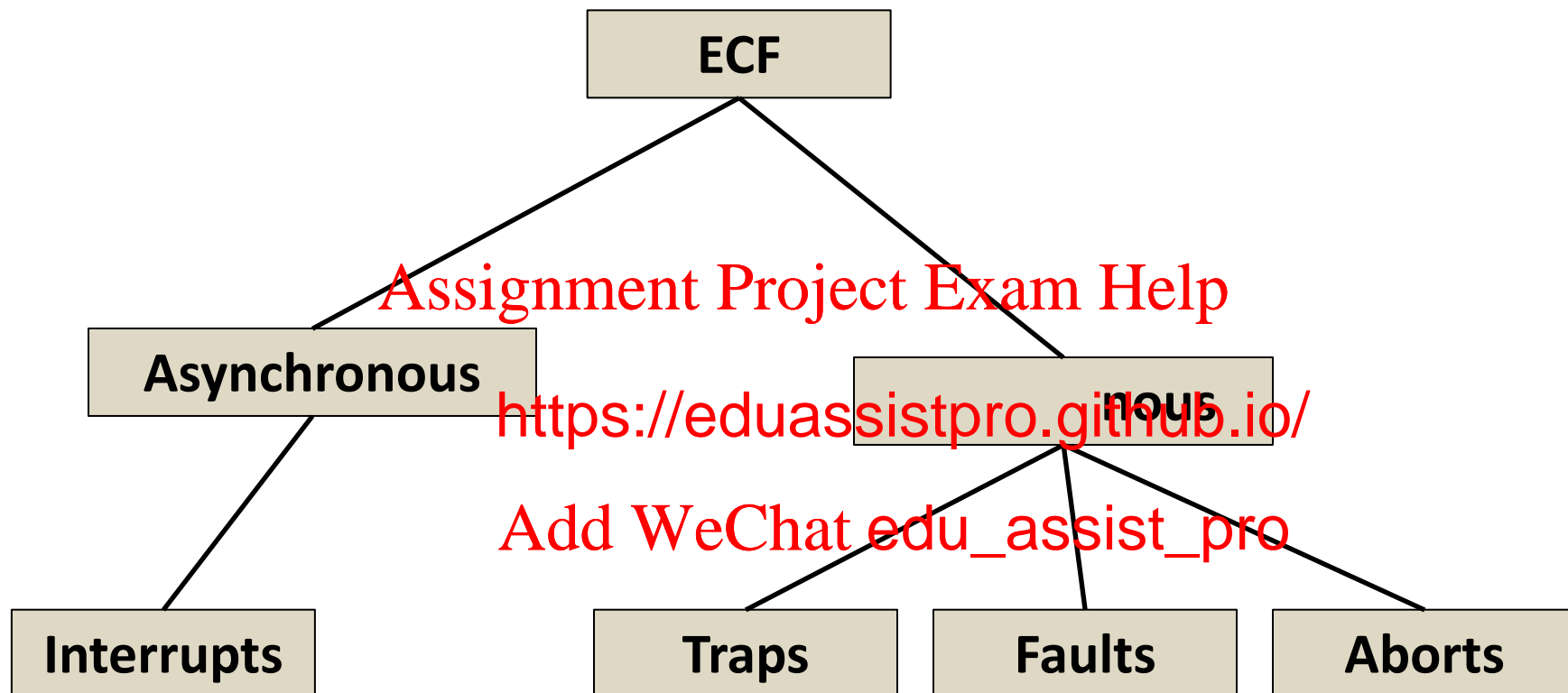
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Exception Tables



(partial) Taxonomy



Asynchronous Exceptions (Interrupts)

■ Caused by events external to the processor

- Indicated by setting the processor's *interrupt pin*
- Handler returns to “next” instruction

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■ Examples:

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- Timer interrupt
 - Every few ms, an external timer generates an interrupt
 - Used by the kernel to take back control from user programs
- I/O interrupt from external device
 - Hitting Ctrl-C at the keyboard
 - Arrival of a packet from a network
 - Arrival of data from a disk

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Synchronous Exceptions

■ Caused by events that occur as a result of executing an instruction:

■ *Traps*

- Intentional, set program up to “trip the trap” and do something
- Examples: *system calls*, gdb breakpoints
- Returns control to the instruction following the trap

■ *Faults*

- Unintentional but possibly recoverable
- Examples: page faults (recoverable), protection faults (unrecoverable), floating point exceptions
- Either re-executes faulting (“current”) instruction or aborts

■ *Aborts*

- Unintentional and unrecoverable
- Examples: illegal instruction, parity error, machine check
- Aborts current program

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System Calls

- Each x86-64 system call has a unique ID number
- Examples:

<i>Number</i>	<i>Name</i>	<i>Description</i>
0	read	Read file
1	write	
2	open	Op
3	close	Cl
4	stat	Get info about file
57	fork	Create process
59	execve	Execute a program
60	_exit	Terminate process
62	kill	Send signal to process

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System Call Example: Opening File

- User calls: `open(filename, options)`
- Calls `__open` function, which invokes system call instruction `syscall`

```
0000000000e5d70 <__open>:
```

```
...
```

```
e5d79: b8 02 00 00 00  mov $0x2,%eax # open is syscall #2
```

```
e5d7e: 0f 05          syscall # Return value in %rax
```

```
e5d80: 48 3d 01 f0 ff ff  c
```

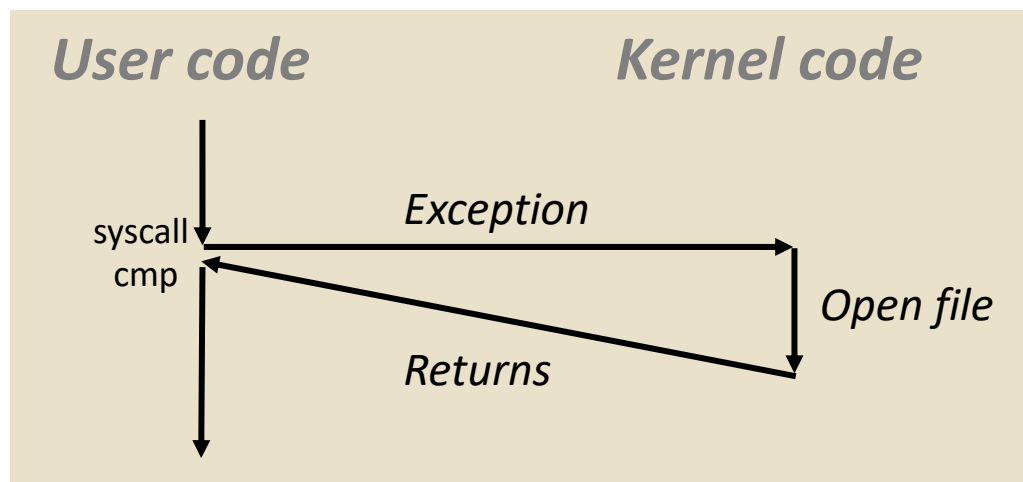
```
...
```

```
e5dfa: c3          retq
```

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- `%rax` contains syscall number
- Other arguments in `%rdi`, `%rsi`, `%rdx`, `%r10`, `%r8`, `%r9`
- Return value in `%rax`
- Negative value is an error corresponding to negative `errno`

System Call

- User calls: `open (f`
- Calls `__open` function

```
0000000000e5d70 <__op
...
e5d79: b8 02 00 00 00
e5d7e: 0f 05          syscall
e5d80: 48 3d 01 f0 ff ff  c
...
e5dfa: c3            retq
```

Almost like a function call

- Transfer of control
- On return, executes next instruction
- Passes arguments using calling convention
- Gets result in `%rax`

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One Important exception:

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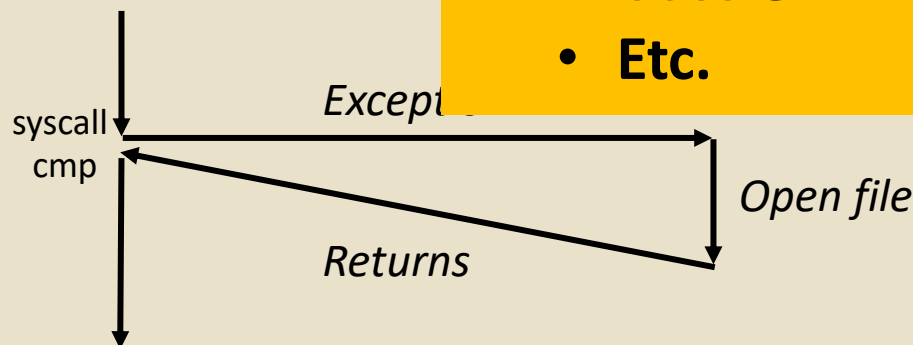
- And other dif
- E.g., “add”
- Uses `errno`
- Etc.

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“action” is in `%rax`

- Return value in `%rax`
- Negative value is an error corresponding to negative `errno`

User code



Fault Example: Page Fault

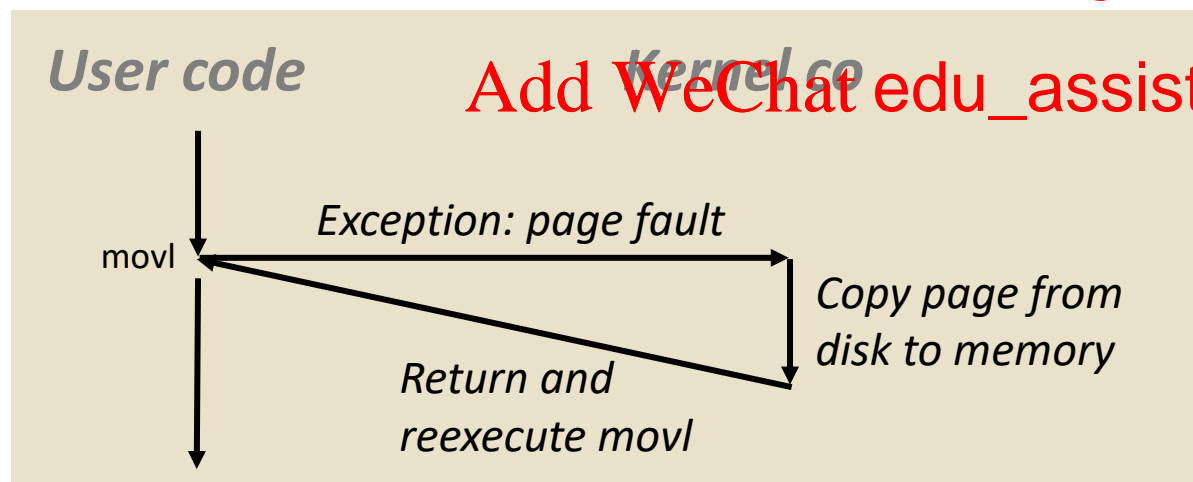
- User writes to memory location
- That portion (page) of user's memory is currently on disk

```
int a[1000];
main ()
{
    a[500] = 13;
}
```

80483b7: *Assignment Project Exam Help* `movl $0xd,0x8049d10`

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Fault Example: Invalid Memory Reference

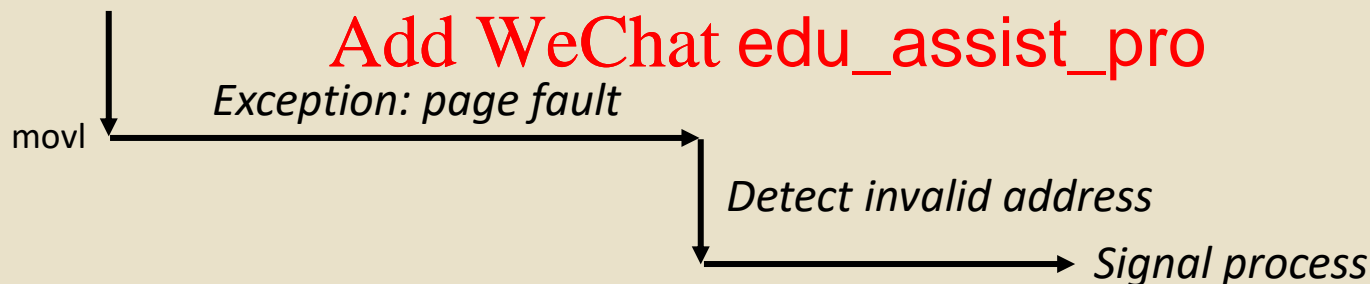
```
int a[1000];
main ()
{
    a[5000] = 13;
}
```

80483b7:

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```
e7 05 60 e3 04 08 0d movl $0xd,0x804e360
```

User code



- Sends **SIGSEGV** signal to user process
- User process exits with “segmentation fault”

Today

- Exceptional Control Flow
- Exceptions
- **Processes**
- Process Control

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Processes

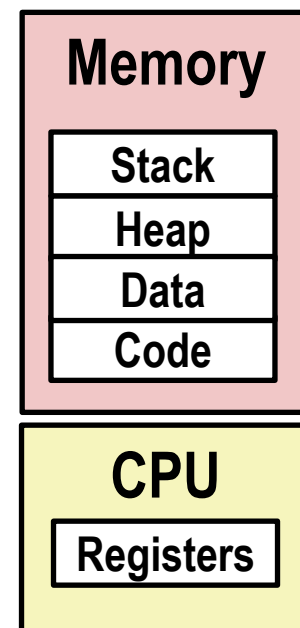
- **Definition:** A *process* is an instance of a running program.

- One of the most profound ideas in computer science
- Not the same as “program” or “processor”

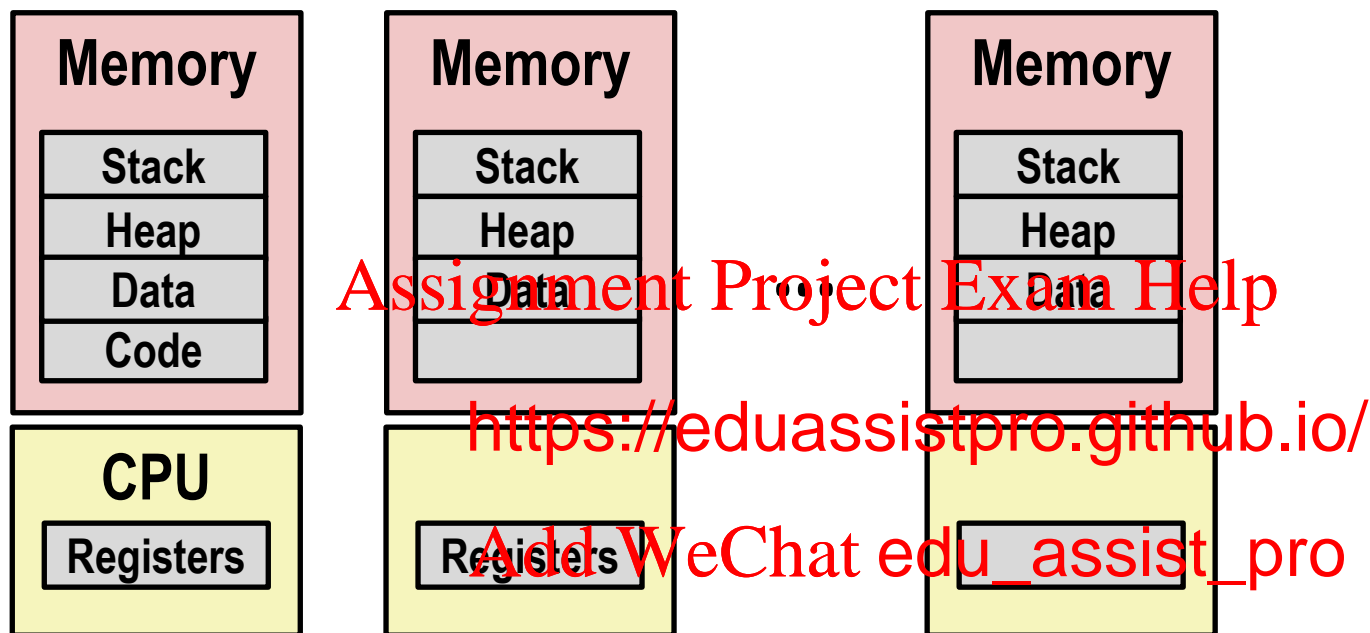
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- **Process provides** <https://eduassistpro.github.io/> **abstractions:**

- *Logical control flow*
 - Each program seems to have exclusive use of the CPU
 - Provided by kernel mechanism called *context switching*
- *Private address space*
 - Each program seems to have exclusive use of main memory.
 - Provided by kernel mechanism called *virtual memory*



Multiprocessing: The Illusion



■ Computer runs many processes simultaneously

- Applications for one or more users
 - Web browsers, email clients, editors, ...
- Background tasks
 - Monitoring network & I/O devices

Multiprocessing Example

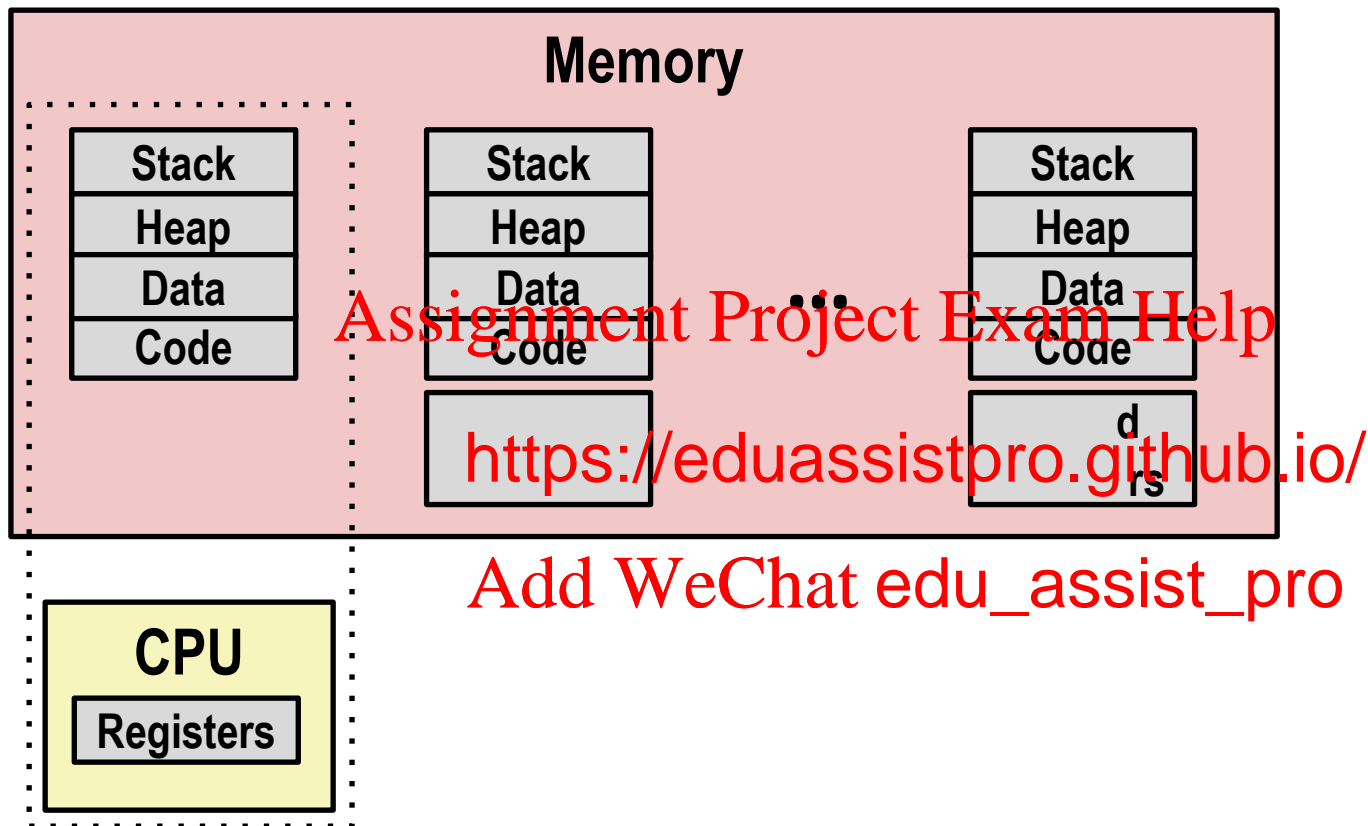
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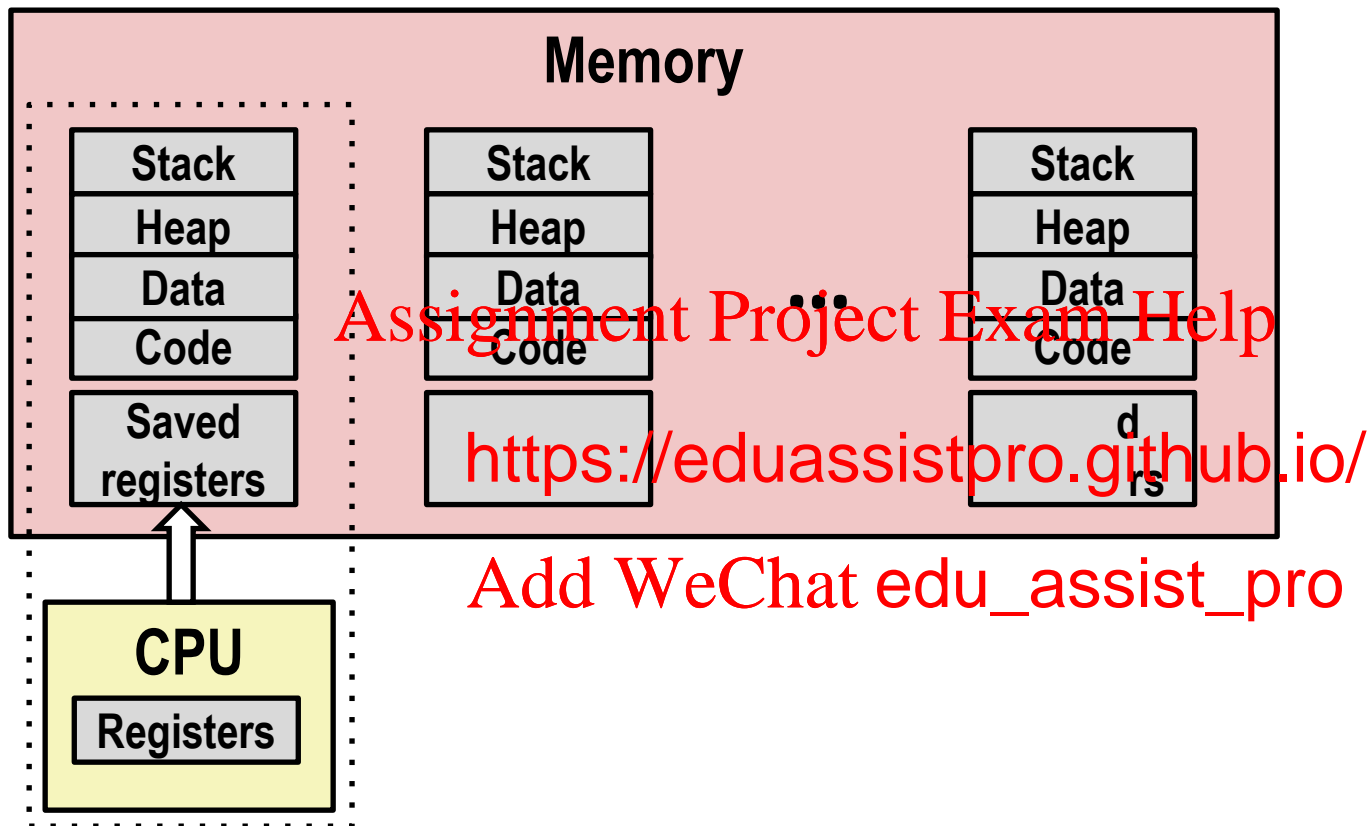
- **Running program “top” on Mac**
 - System has 123 processes, 5 of which are active
 - Identified by Process ID (PID)

Multiprocessing: The (Traditional) Reality



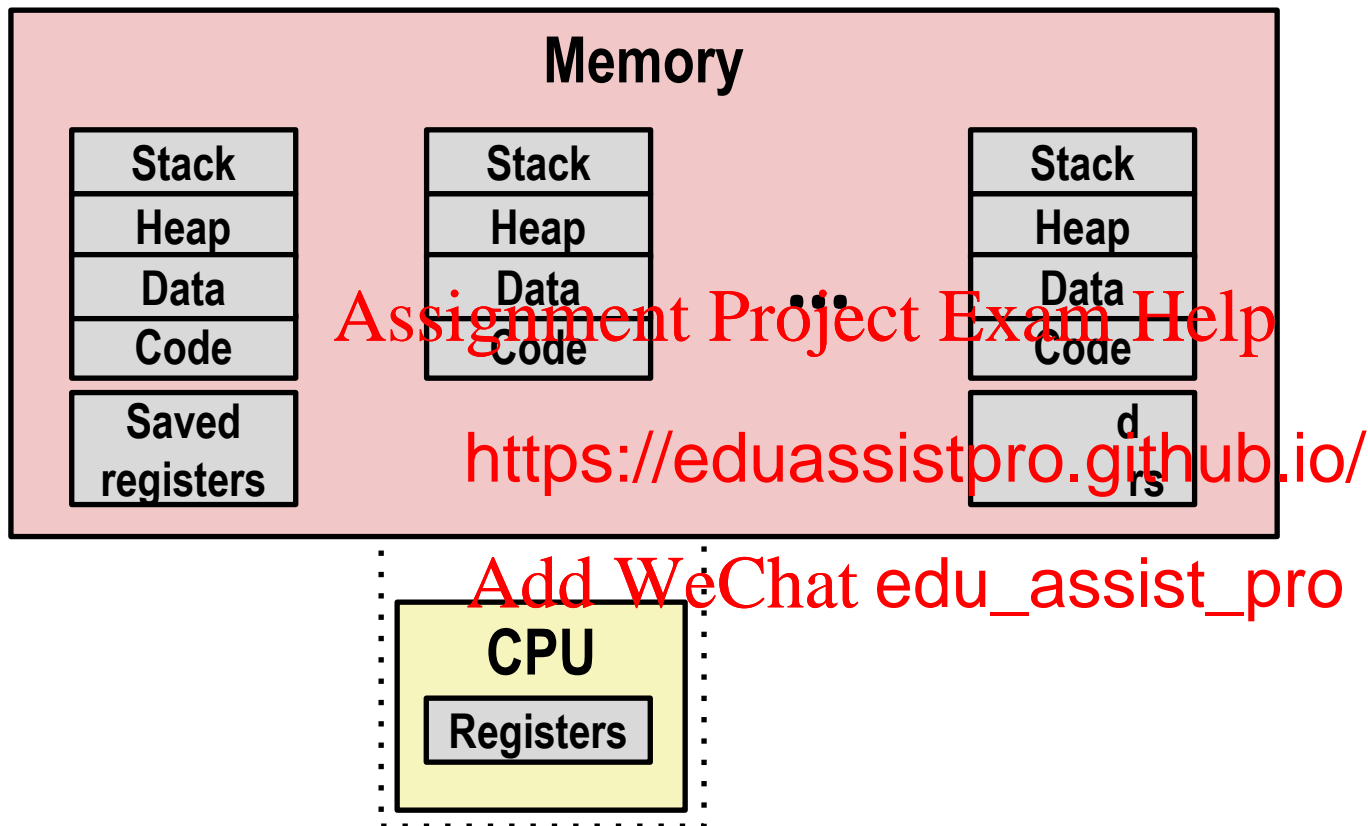
- **Single processor executes multiple processes concurrently**
 - Process executions interleaved (multitasking)
 - Address spaces managed by virtual memory system (like last week)
 - Register values for nonexecuting processes saved in memory

Multiprocessing: The (Traditional) Reality



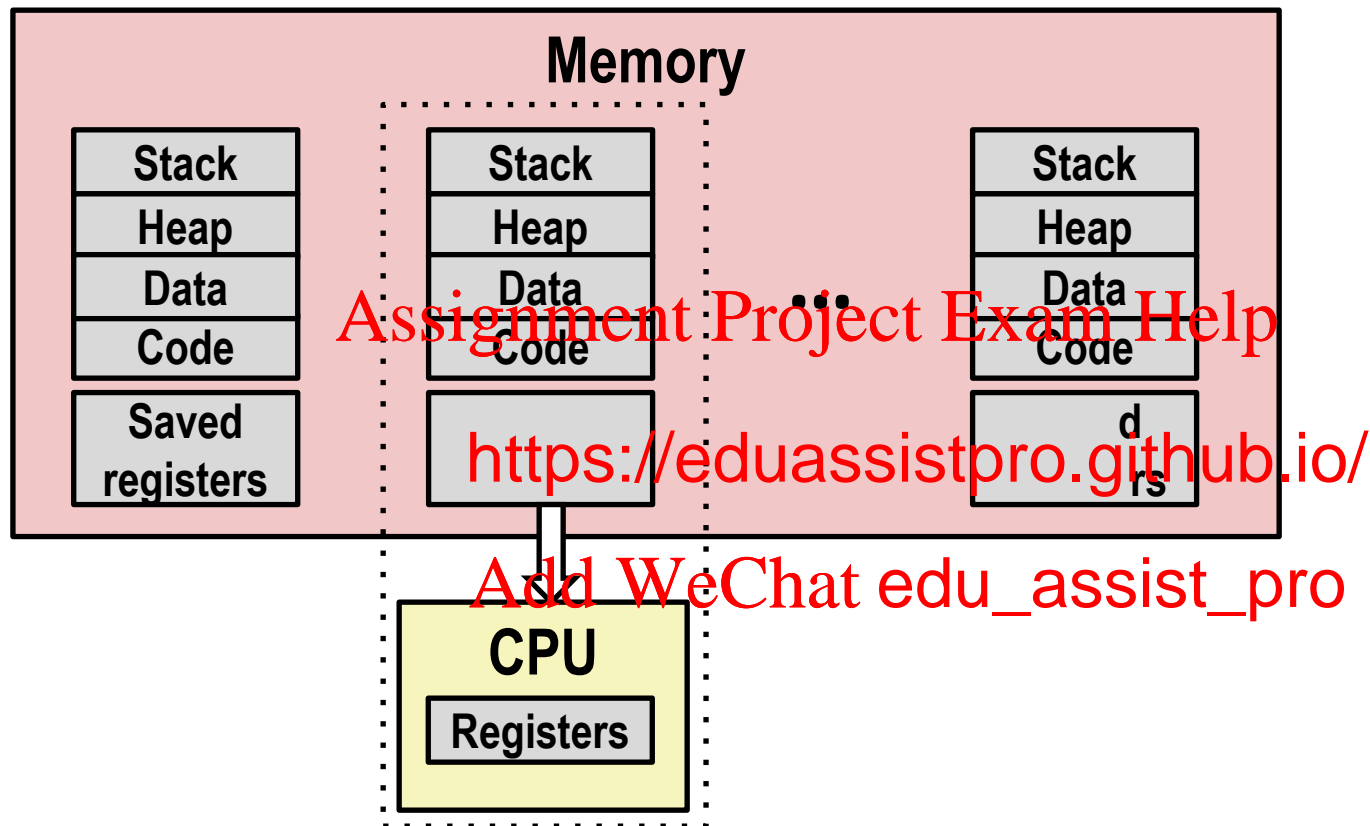
- Save current registers in memory

Multiprocessing: The (Traditional) Reality



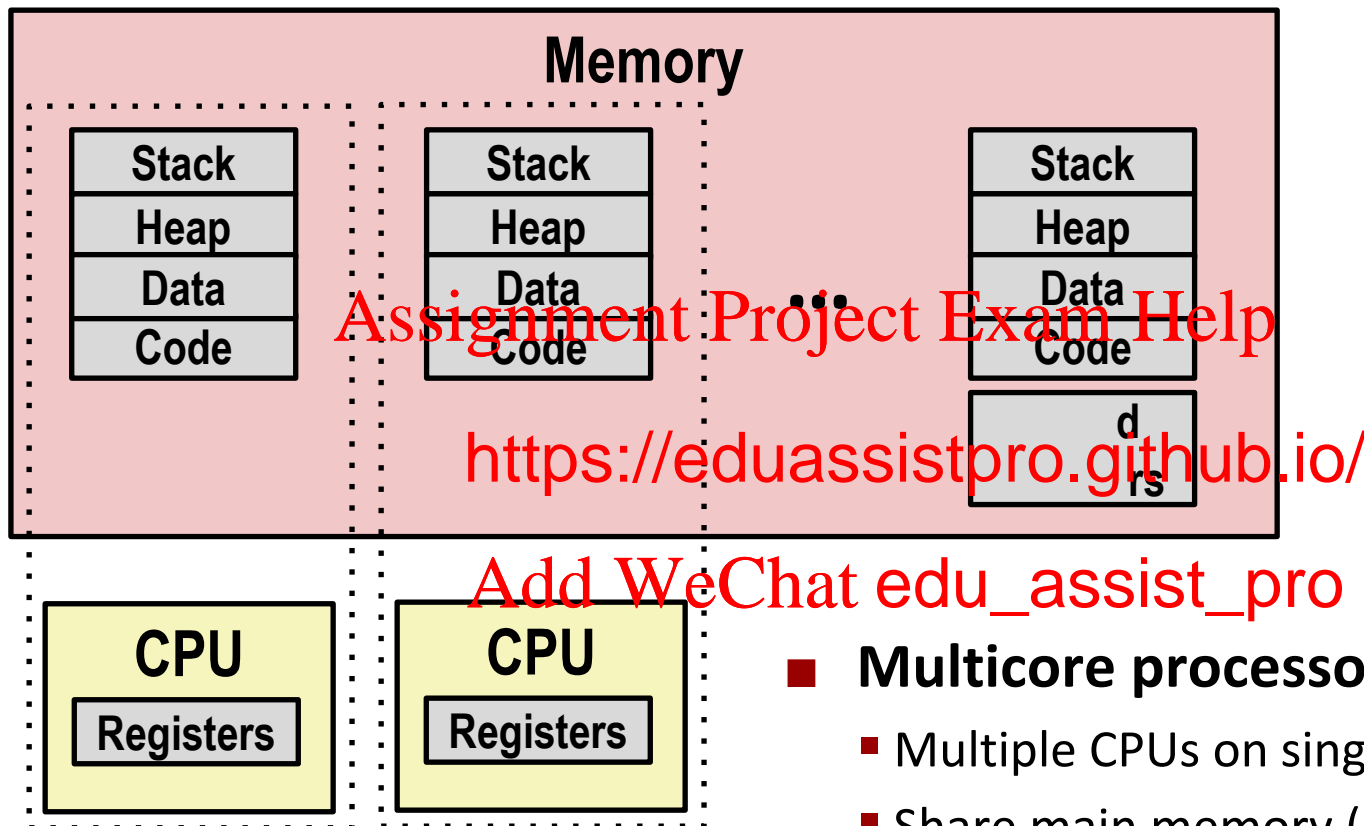
- **Schedule next process for execution**

Multiprocessing: The (Traditional) Reality



- Load saved registers and switch address space (context switch)

Multiprocessing: The (Modern) Reality

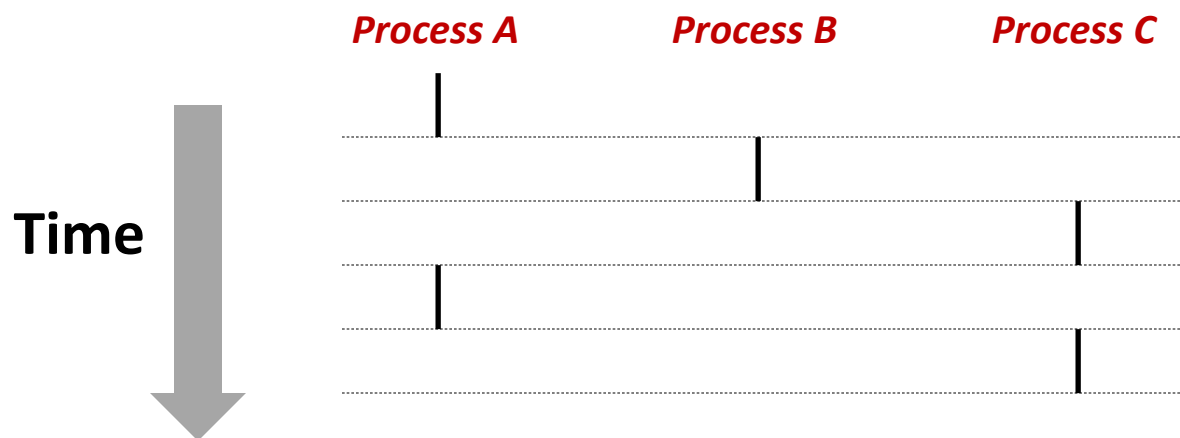


■ Multicore processors

- Multiple CPUs on single chip
- Share main memory (and some caches)
- Each can execute a separate process
 - Scheduling of processors onto cores done by kernel

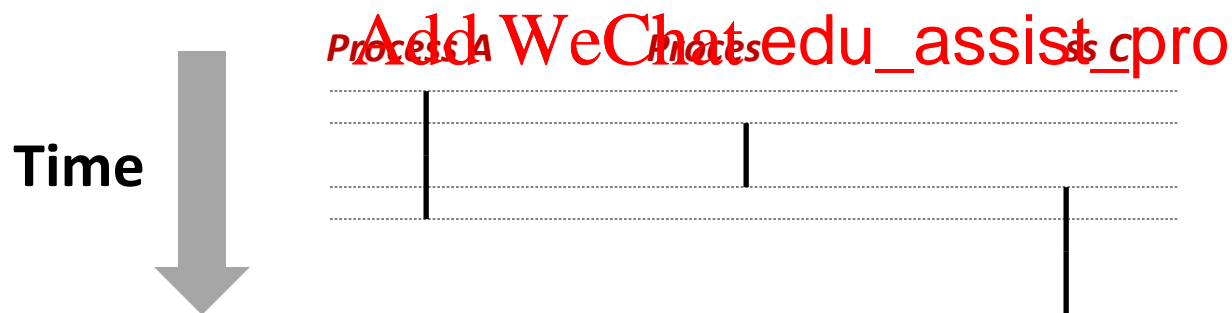
Concurrent Processes

- Each process is a logical control flow.
- Two processes *run concurrently* (are concurrent) if their flows overlap in time
- Otherwise, they are sequential
- Examples (running concurrently)
 - Concurrent: A & B
 - Sequential: B & C



User View of Concurrent Processes

- Control flows for concurrent processes are physically disjoint in time
- However, we can think of concurrent processes as running in parallel



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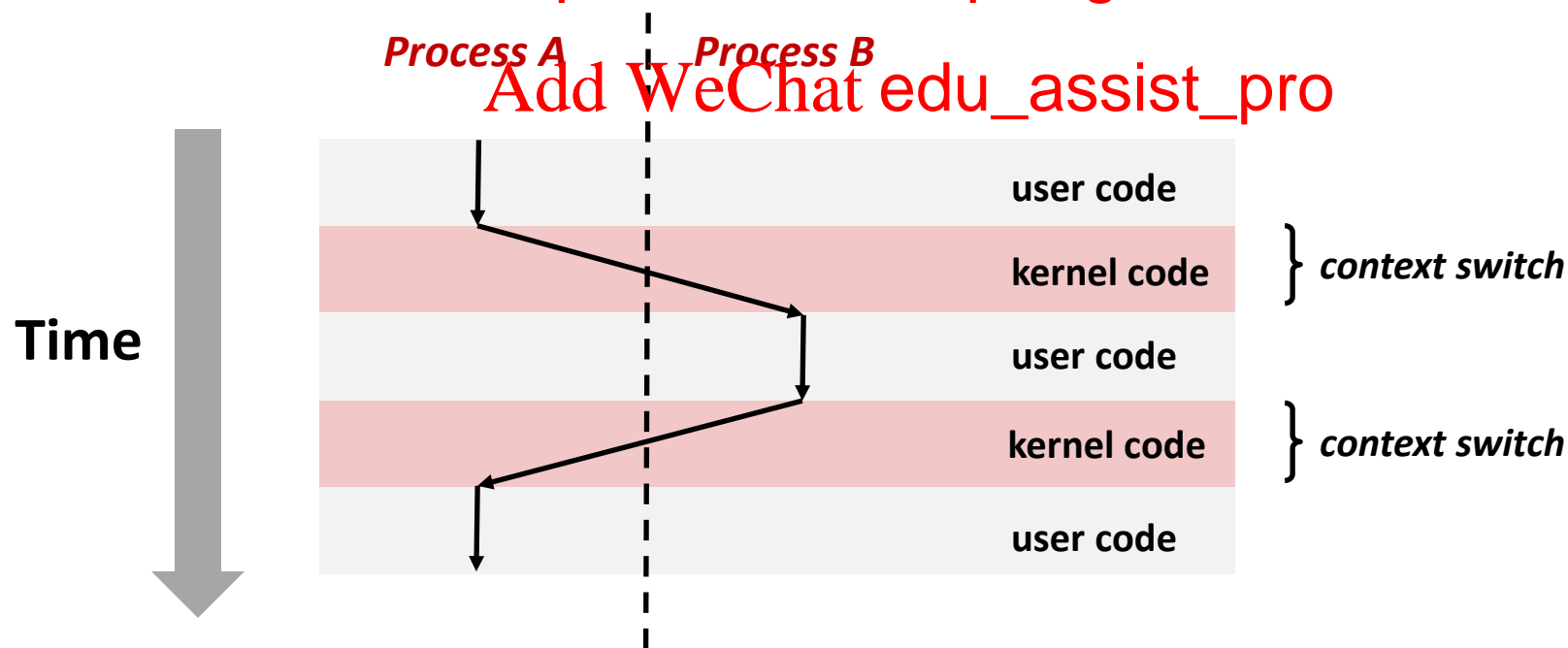
Context Switching

- Processes are managed by a shared chunk of memory-resident OS code called the *kernel*
 - Important: the kernel is not a separate process, but rather runs as part of some existing process.
- Control flow passes from one process to another via a *context switch*

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Today

- Exceptional Control Flow
- Exceptions
- Processes
- **Process Control**

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System Call Error Handling

- On error, Linux system-level functions typically return -1 and set global variable `errno` to indicate cause.
- Hard and fast rule:
 - You must check the return status of every system-level function
 - Only exception is the handful of functions that return `void`
- Example: <https://eduassistpro.github.io/>

```
if ((pid = fork()) < 0) {  
    fprintf(stderr, "fork error: %s\n", strerror(errno));  
    exit(-1);  
}
```

Error-reporting functions

- Can simplify somewhat using an *error-reporting function*:

```
void unix_error(char *msg) /* Unix-style error */  
{  
    fprintf(stderr, "unix error: %s\n", msg, strerror(errno));  
    exit(-1);  
}
```

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```
if ((pid = fork()) < 0)  
    unix_error("fork error");
```

Note: csapp.c exits with 0.

- But, must think about application. Not always appropriate to exit when something goes wrong.

Error-handling Wrappers

- We simplify the code we present to you even further by using Stevens¹-style error-handling wrappers:

```
pid_t Fork(void)
{
    pid_t pid;

    if ((pid = fork()) < 0)
        unix_error("fork error");
    return pid;
}
```

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```
pid = Fork();
```

- NOT what you generally want to do in a real application

¹e.g., in “UNIX Network Programming: The sockets networking API” W. Richard Stevens

Obtaining Process IDs

- `pid_t getpid(void)`

- Returns PID of current process

- `pid_t getppid(void)`

- Returns PID of p

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Creating and Terminating Processes

From a programmer's perspective, we can think of a process as being in one of three states

■ Running

- Process is either *executing* and will eventually be scheduled by the kernel

■ Stopped

- Process execution is *suspended* and will not be scheduled until further notice (next lecture when we study signals)

■ Terminated

- Process is stopped permanently

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Terminating Processes

■ Process becomes terminated for one of three reasons:

- Receiving a signal whose default action is to terminate (next lecture)
- Returning from the **main** routine
- Calling the **exit** function

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■ `void exit(i` <https://eduassistpro.github.io/>

- Terminates with an *exit status* of `s`
- Convention: normal return status is 0, nonzero on error
- Another way to explicitly set the exit status is to return an integer value from the main routine

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■ `exit` is called **once** but **never** returns.

Creating Processes

- *Parent process* creates a new running *child process* by calling `fork`

- `int fork(void)`

- Returns 0 to the child process
- Child is *almost* identical to the parent process
 - Child get an identical (but separate) virtual address space.
 - Child gets identical copies of the parent's open file descriptors
 - Child has a different PID than the parent

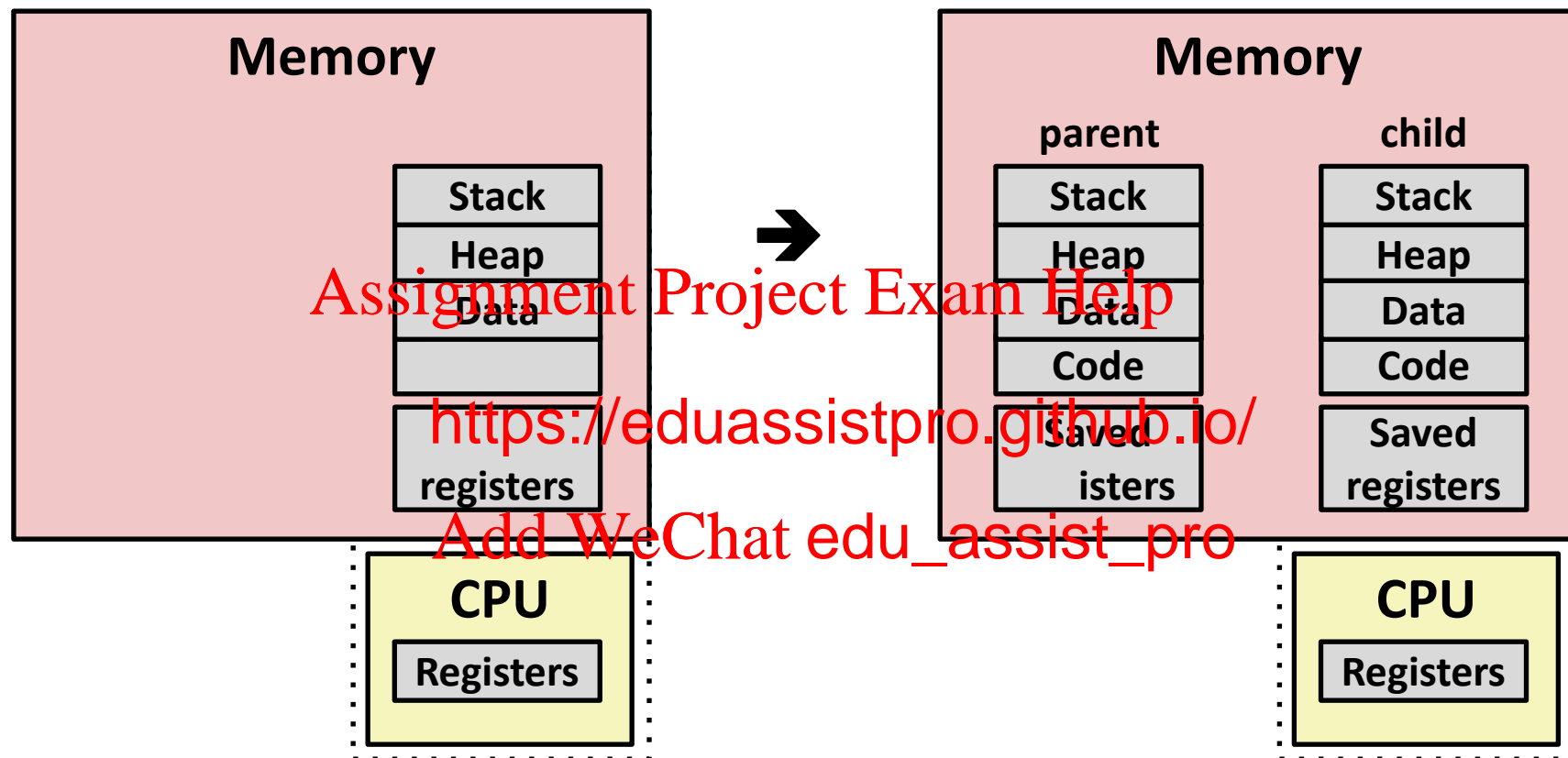
- `fork` is interesting (and often confusing) because it is called *once* but returns *twice*

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Conceptual View of fork



■ Make complete copy of execution state

- Designate one as parent and one as child
- Resume execution of parent or child

The fork Function Revisited

- VM and memory mapping explain how `fork` provides private address space for each process.
- To create virtual address for new process:
 - Create exact copy of `vm_area_struct`, and page tables.
 - Flag each page in both processes as private.
 - Flag each `vm_area_struct` in both processes as private COW
- On return, each process has exact copy of virtual memory.
- Subsequent writes create new pages using COW mechanism.

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fork Example

```
int main(int argc, char** argv)
{
    pid_t pid;
    int x = 1;

    pid = Fork();
    if (pid == 0) {
        printf("child\n");
        return 0;
    }

    /* Parent */
    printf("parent: x=%d\n", --x);
    return 0;
}
```

fork.c

- Call once, return twice
- Concurrent execution
 - Can't predict execution order of parent and child

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```
linux> ./fork
parent: x=0
child : x=2
```

```
linux> ./fork
child : x=2
parent: x=0
```

```
linux> ./fork
parent: x=0
child : x=2
```

```
linux> ./fork
parent: x=0
child : x=2
```

fork Example

```
int main(int argc, char** argv)
{
    pid_t pid;
    int x = 1;

    pid = Fork();
    if (pid == 0) {
        printf("child : x=%d\n", ++x);
        return 0;
    }

    /* Parent */
    printf("parent: x=%d\n", --x);
    return 0;
}
```

```
linux> ./fork
parent: x=0
child : x=2
```

- Call once, return twice
- Concurrent execution
 - Can't predict execution order of parent and child
- Duplicate but separate address space
 - x has a value of 1 when fork returns in parent and child
 - subsequent changes to x are independent
- Shared open files
 - stdout is the same in both parent and child

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Modeling fork with Process Graphs

- A *process graph* is a useful tool for capturing the partial ordering of statements in a concurrent program:
 - Each vertex is the execution of a statement
 - $a \rightarrow b$ means a happens before b
 - Edges can be labeled
 - `printf` vertex
 - Each graph begins with a vertex with
- Any *topological sort* of the graph leads to a feasible total ordering.
 - Total ordering of vertices where all edges point from left to right

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Process Graph Example

```

int main(int argc, char** argv)
{
    pid_t pid;
    int x = 1;

    pid = Fork();
    if (pid == 0) { /
        printf("child
        return 0;
    }

    /* Parent */
    printf("parent: x=%d\n", --x);
    return 0;
}

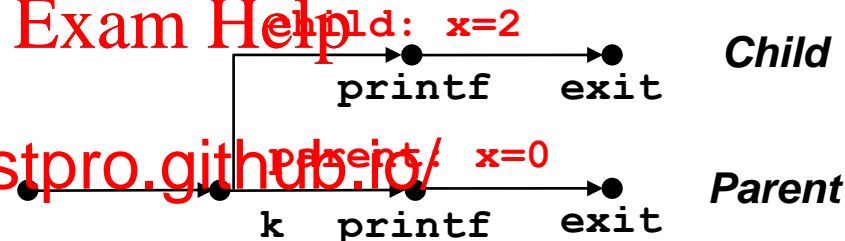
```

fork.c

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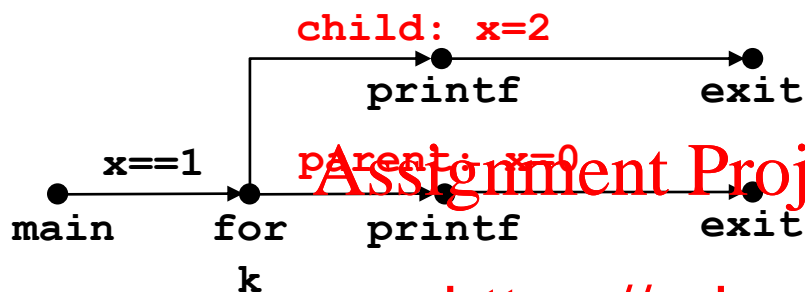
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Interpreting Process Graphs

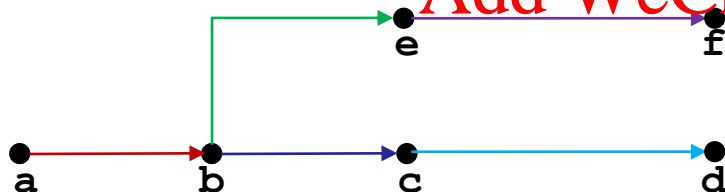
■ Original graph:



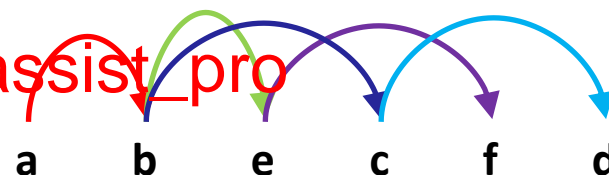
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<https://eduassistpro.github.io/> feasible total ordering:

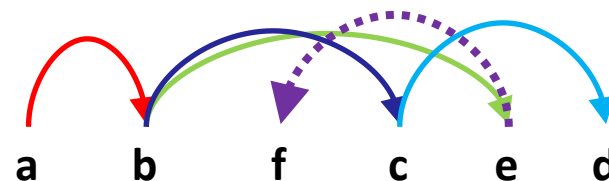
■ Relabled graph:



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Feasible or Infeasible?

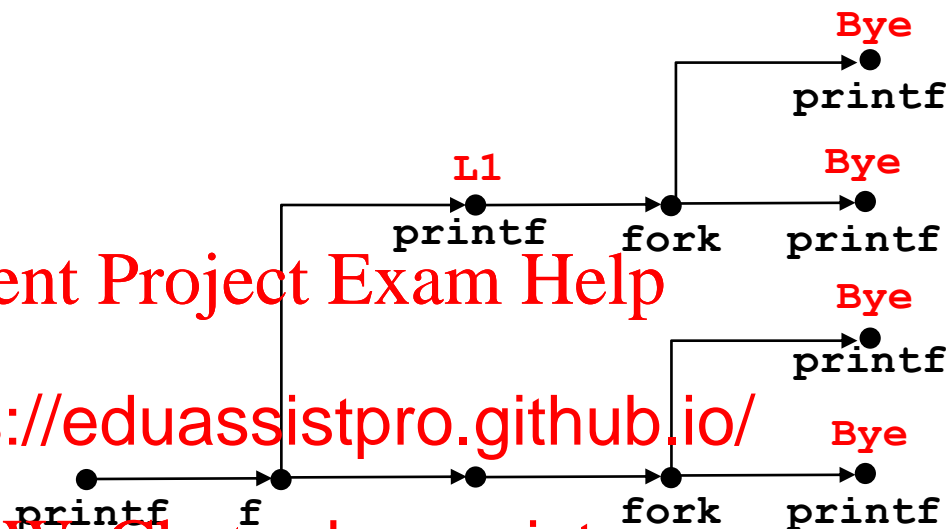


Infeasible: not a topological sort

fork Example: Two consecutive forks

```
void fork2 ()
{
    printf("L0\n");
    fork();
    printf("L1\n");
    fork();
    printf("Bye\n");
}
```

forks.c



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Feasible output:

L0
L1
Bye
Bye
L1
Bye
Bye

Infeasible output:

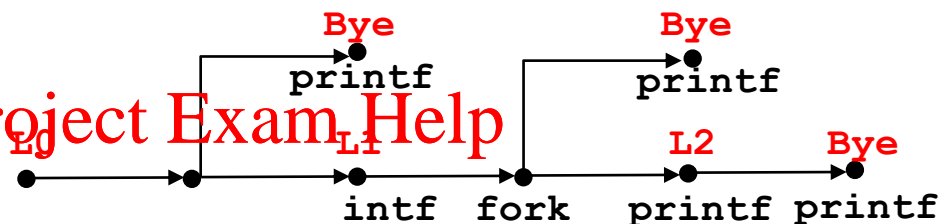
L0
Bye
L1
Bye
L1
Bye
Bye

fork Example: Nested forks in parent

```

void fork4()
{
    printf("L0\n");
    if (fork() != 0) {
        printf("L1\n");
        if (fork()
            printf(
        }
    }
    printf("Bye\n");
}
forks.c

```



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Feasible or Infeasible?

L0

Bye

L1

Bye

Bye

L2

Infeasible

Feasible or Infeasible?

L0

L1

Bye

Bye

L2

Bye

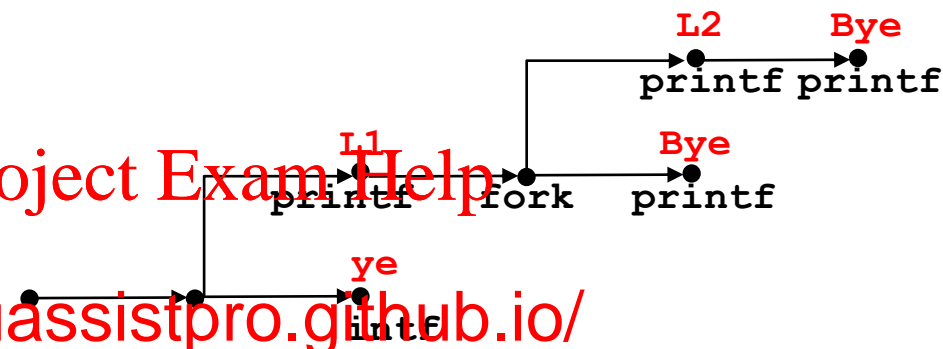
Feasible

fork Example: Nested forks in children

```

void fork5()
{
    printf("L0\n");
    if (fork() == 0) {
        printf("L1\n");
        if (fork()
            printf("
    }
}
printf("Bye\n");
}
forks.c

```



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Feasible or Infeasible?

L0

Bye

L1

Bye

Bye

L2

Infeasible

Feasible or Infeasible?

L0

Bye

L1

L2

Bye

Bye

Feasible

No Quiz Today

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...But let's <https://eduassistpro.github.io/> know

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Reaping Child Processes

■ Idea

- When process terminates, it still consumes system resources
 - Examples: Exit status, various OS tables
- Called a “zombie”
 - Living corpse, half alive and half dead

■ Reaping

- Performed by parent (e.g. `wait` or `waitpid`)
- Parent is given exit status information
- Kernel then deletes zombie child process

■ What if parent doesn't reap?

- If any parent terminates without reaping a child, then the orphaned child should be reaped by `init` process (`pid == 1`)
 - Unless `ppid == 1`! Then need to reboot...
- So, only need explicit reaping in long-running processes
 - e.g., shells and servers

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Zombie Example

```
void fork7() {
    if (fork() == 0) {
        /* Child */
        printf("Terminating Child, PID = %d\n", getpid());
        exit(0);
    } else {
        printf("Running Parent, PID = %d\n", getpid());
        while (1)
            ; /* Infinite loop */
    }
}
```

```
linux> ./forks 7 &
[1] 6639
```

```
Running Parent, PID =
```

```
Terminating Child, PID =
```

```
linux> ps
```

PID	TTY	TIME	CMD
6585	ttyp9	00:00:00	tcsh
6639	ttyp9	00:00:03	forks
6640	ttyp9	00:00:00	forks <defunct>
6641	ttyp9	00:00:00	ps

```
linux> kill 6639
```

```
[1] Terminated
```

```
linux> ps
```

PID	TTY	TIME	CMD
6585	ttyp9	00:00:00	tcsh
6642	ttyp9	00:00:00	ps

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shows child process as
“defunct” (i.e., a zombie)

■ Killing parent allows child to
be reaped by **init**

Non-terminating Child Example

```
void fork8()
{
    if (fork() == 0) {
        /* Child */
        printf("Running Child, PID = %d\n",
               getpid());
        while (1)
            ; /* Infinite loop */
    } else {
        printf("Terminating Parent, PID = %d\n",
               getpid());
        exit(0);
    }
}
```

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```
linux> ./forks 8
```

```
Terminating Parent, PID = 6675
```

```
Running Child, PID = 6676
```

```
linux> ps
```

PID	TTY	TIME	CMD
6585	ttyp9	00:00:00	tcsh
6676	ttyp9	00:00:06	forks
6677	ttyp9	00:00:00	ps

```
linux> kill 6676
```

```
linux> ps
```

PID	TTY	TIME	CMD
6585	ttyp9	00:00:00	tcsh
6678	ttyp9	00:00:00	ps

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■ till active even though parent has terminated

■ Must kill child explicitly, or else will keep running indefinitely

wait: Synchronizing with Children

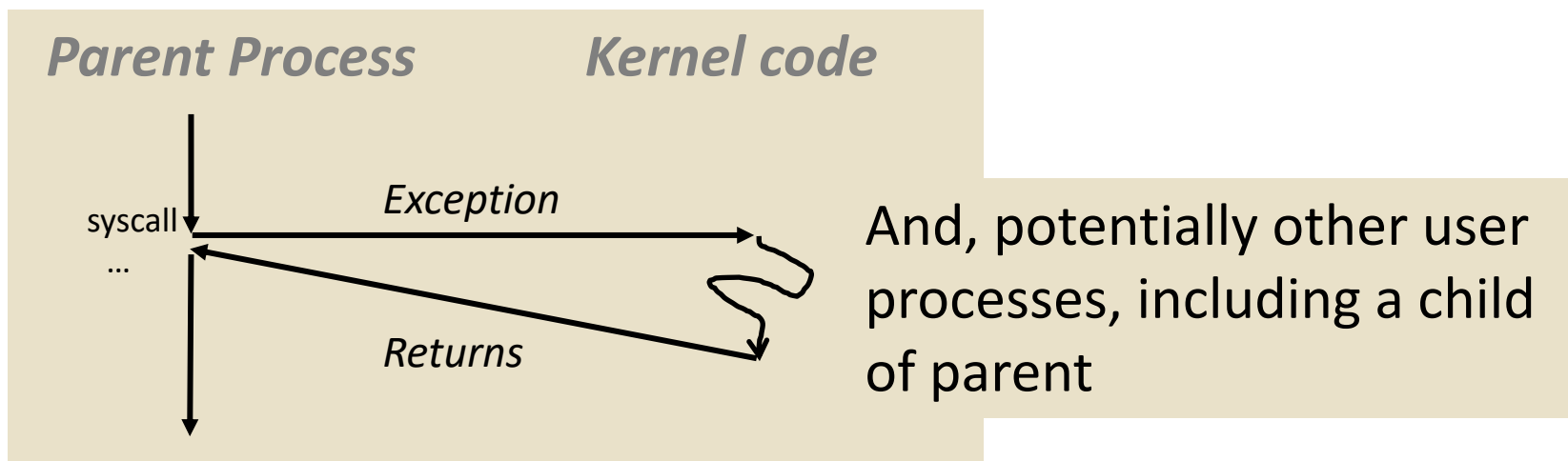
- Parent reaps a child by calling the `wait` function

- `int wait(int *child status)`

- Suspends current process until one of its children terminates
- Implemented as

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wait: Synchronizing with Children

- Parent reaps a child by calling the `wait` function

- `int wait(int *child_status)`

- Suspends current process until one of its children terminates
- Return value is `t` terminated
- If `child_status` is not `NULL`, it points to will be set to a value that indicates reason the child terminated and the exit status:
 - Checked using macros defined in `wait.h`
 - `WIFEXITED`, `WEXITSTATUS`, `WIFSIGNALED`, `WTERMSIG`, `WIFSTOPPED`, `WSTOPSIG`, `WIFCONTINUED`
 - See textbook for details

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wait: Synchronizing with Children

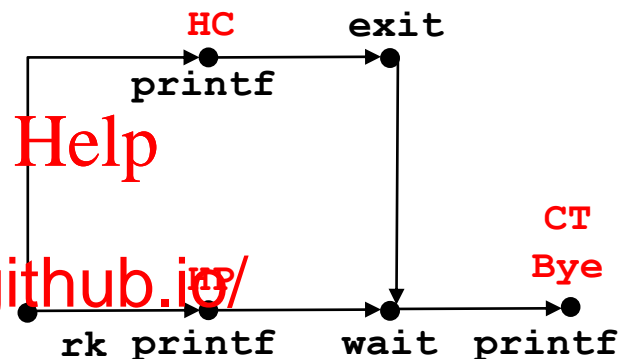
```

void fork9() {
    int child_status;

    if (fork() == 0) {
        printf("HC: hello from child\n");
        exit(0);
    } else {
        printf("HP: he
        wait(&child_status);
        printf("CT: child has terminat
    }
    printf("Bye\n");
}

```

forks.c



Feasible output(s):

HC	HP
HP	HC
CT	CT
Bye	Bye

Infeasible output:

HP
CT
Bye
HC

Another wait Example

- If multiple children completed, will take in arbitrary order
- Can use macros WIFEXITED and WEXITSTATUS to get information about exit status

```

void fork10() {
    pid_t pid[N];
    int i, child_status;

    for (i = 0; i < N; i++) {
        if ((pid[i] = fork()) == 0)
            exit(100+i); /* child */
    }

    for (i = 0; i < N; i++) { /* Parent */
        pid_t wpid = wait(&child_status);
        if (WIFEXITED(child_status))
            printf("Child %d terminated with exit status %d\n",
                wpid, WEXITSTATUS(child_status));
        else
            printf("Child %d terminate abnormally\n", wpid);
    }
}

```

forks.c

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waitpid: Waiting for a Specific Process

- `pid_t waitpid(pid_t pid, int *status, int options)`
 - Suspends current process until specific process terminates
 - Various options (see textbook)

```

void fork11() {
    pid_t pid[N];
    int i;
    int child_status;

    for (i = 0; i < N; i++)
        if ((pid[i] = fork()) == 0)
            exit(100+i); /* Child */
    for (i = N-1; i >= 0; i--) {
        pid_t wpid = waitpid(pid[i], &child_status, 0);
        if (WIFEXITED(child_status))
            printf("Child %d terminated with exit status %d\n",
                wpid, WEXITSTATUS(child_status));
        else
            printf("Child %d terminate abnormally\n", wpid);
    }
}

```

forks.c

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execve : Loading and Running Programs

- `int execve(char *filename, char *argv[], char *envp[])`
- Loads and runs in the current process:
 - Executable file `filename`
 - Can be object file or script file beginning with `#!`: interpreter (e.g., `#!/bin`
 - ...with argument list `argv`
 - By convention `argv[0] == filename`
 - ...and environment variable list `envp`
 - “name=value” strings (e.g., `USER=droh`)
 - `getenv`, `putenv`, `printenv`
- Overwrites code, data, and stack
 - Retains PID, open files and signal context
- Called **once** and **never** returns
 - ...except if there is an error

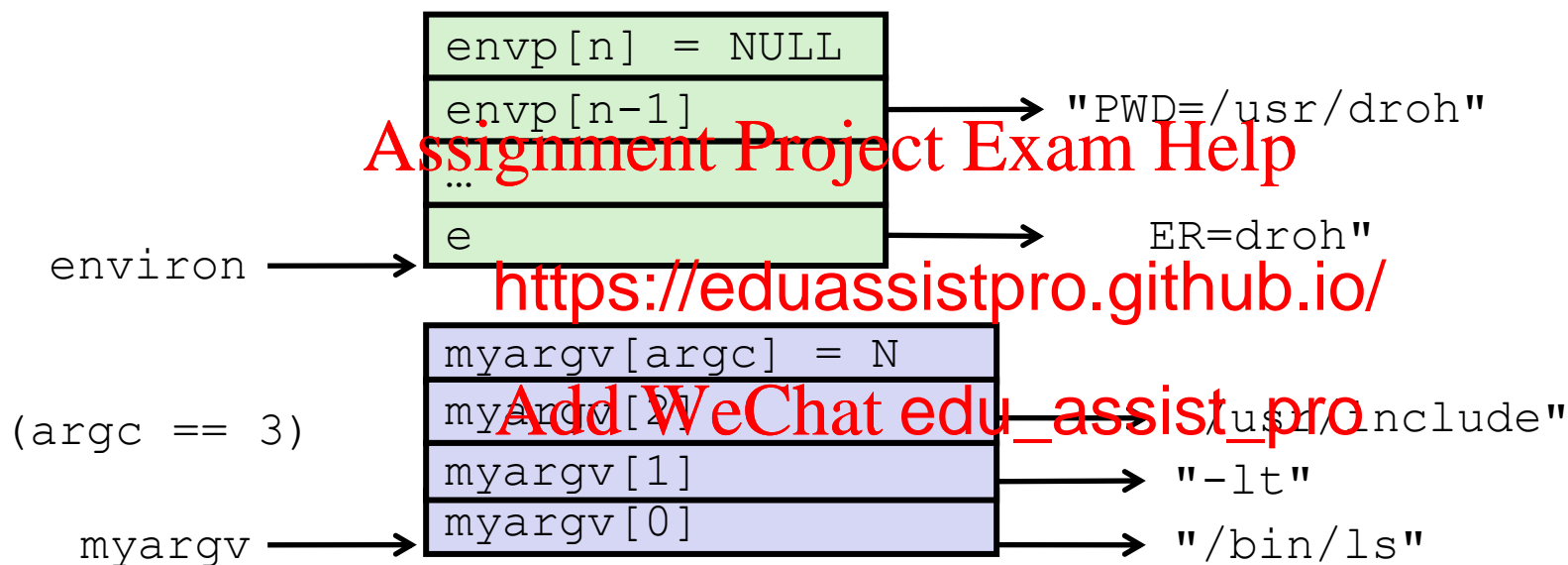
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execve Example

- Execute `"/bin/ls -lt /usr/include"` in child process using current environment:

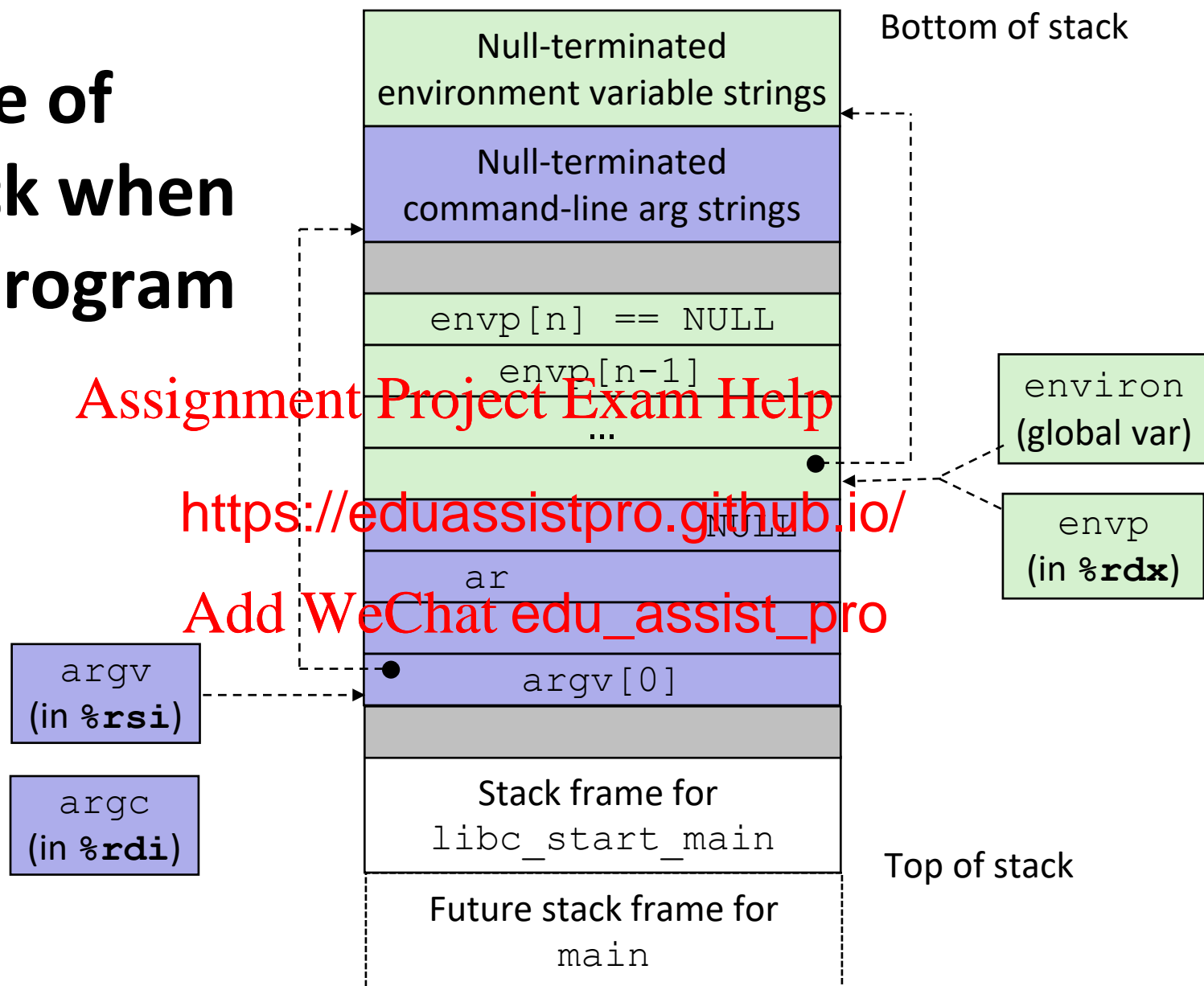


```

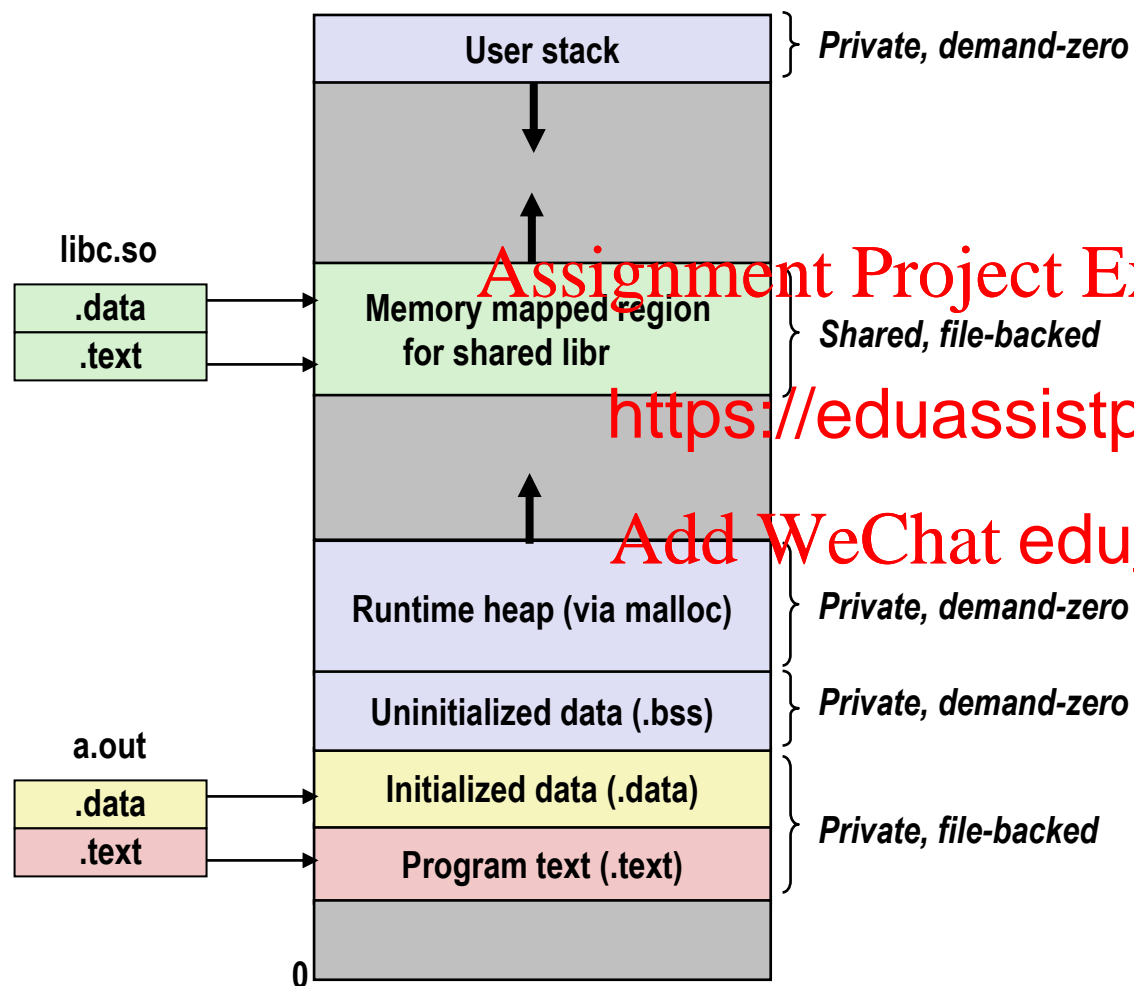
if ((pid = Fork()) == 0) {    /* Child runs program */
    if (execve(myargv[0], myargv, environ) < 0) {
        printf("%s: Command not found.\n", myargv[0]);
        exit(1);
    }
}

```

Structure of the stack when a new program starts



The execve Function Revisited



- To load and run a new program `a.out` in the current process using `execve`:

- Free `vm_area_struct`'s and page tables for old areas

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- Set PC to entry point in `.text`
- Linux will fault in code and data pages as needed.

Summary

■ Exceptions

- Events that require nonstandard control flow
- Generated externally (interrupts) or internally (traps and faults)

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■ Processes

- At any given time
- Only one can execute at a time on
- Each process appears to have total control of processor + private memory space

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rocesses

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Summary (cont.)

■ Spawning processes

- Call `fork`
- One call, two returns

■ Process completion

- Call `exit`
- One call, no ret

■ Reaping and waiting for process

- Call `wait` or `waitpid`

■ Loading and running programs

- Call `execve` (or variant)
- One call, (normally) no return

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Making fork More Nondeterministic

■ Problem

- Linux scheduler does not create much run-to-run variance
- Hides potential race conditions in nondeterministic programs
 - E.g., does fork return to child first, or to parent?

■ Solution

- Create custom <https://eduassistpro.github.io/> inserts random delays along different branches
 - E.g., for parent and child in `fork`
- Use runtime interpositioning to have program use special version of library code

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Variable delay fork

```

/* fork wrapper function */
pid_t fork(void) {
    initialize();
    int parent_delay = choose_delay();
    int child_delay = choose_delay();
    pid_t parent_pid = getpid();
    pid_t child_pid_or_zero = real_fork();
    if (child_pid_or_zero
        /* Parent */
        if (verbose) {
            printf(
"Fork. Child pid=%d, delay = %dms. Pa", child_pid_or_zero, c
            parent_pid, parent_delay);
            fflush(stdout);
        }
        ms_sleep(parent_delay);
    } else {
        /* Child */
        ms_sleep(child_delay);
    }
    return child_pid_or_zero;
}

```

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myfork.c